

# 9.3.11

EE24BTECH11022 - ESHAN SHARMA

**Question:** Solve the differential equation A)  $\frac{d^2y}{dx^2} + y = 0$  and verify if the general solution is  $y = C_1 e^x + C_2 e^{-x}$ .

**Solution:**

**Solution Using Laplace Transform:**

Given:

$$\frac{d^2y}{dx^2} + y = 0 \quad (0.1)$$

Taking the Laplace Transform of both sides:

$$\mathcal{L}\left\{\frac{d^2y}{dx^2}\right\} + \mathcal{L}\{y\} = \mathcal{L}\{0\} \quad (0.2)$$

Using properties of the Laplace Transform:

$$s^2Y(s) - sy(0) - y'(0) + Y(s) = 0 \quad (0.3)$$

Substituting the initial conditions  $y(0) = C_1$  and  $y'(0) = C_2$ :

$$s^2Y(s) - sC_1 - C_2 + Y(s) = 0 \quad (0.4)$$

$$(s^2 + 1)Y(s) = sC_1 + C_2 \quad (0.5)$$

$$Y(s) = \frac{sC_1 + C_2}{s^2 + 1} \quad (0.6)$$

The Region of Convergence (ROC) is the entire  $s$ -plane since  $s^2 + 1 \neq 0$  for all real  $s$ .

Taking the inverse Laplace Transform:

$$y(x) = \mathcal{L}^{-1}\left\{\frac{sC_1 + C_2}{s^2 + 1}\right\} \quad (0.7)$$

$$= C_1 \cos(x) + C_2 \sin(x) \quad (0.8)$$

Thus, the general solution is:

$$y(x) = C_1 \cos(x) + C_2 \sin(x) \quad (0.9)$$

**Solving the Differential Equation using Z-Transform and Bilinear Transform:**

Let the differential equation be:

$$\frac{d^2y}{dx^2} + y = 0$$

### Using the Z-Transform:

Taking the Z-transform of both sides:

$$Z \left\{ \frac{d^2 y}{dx^2} \right\} + Z\{y\} = Z\{0\} \quad (0.10)$$

$$z^2 Y(z) - zy(0) - y'(0) + Y(z) = 0 \quad (0.11)$$

Rearranging terms:

$$(z^2 + 1)Y(z) = zy(0) + y'(0) \quad (0.12)$$

$$Y(z) = \frac{zy(0) + y'(0)}{z^2 + 1} \quad (0.13)$$

Substituting the initial conditions  $y(0) = y_0$  and  $y'(0) = y_1$ , we get:

$$Y(z) = \frac{zy_0 + y_1}{z^2 + 1} \quad (0.14)$$

Taking the inverse Z-transform:

$$y(x) = \mathcal{Z}^{-1} \left( \frac{1}{z^2 + 1} \right) \quad (0.15)$$

$$y(x) = y_0 \cos(x) + y_1 \sin(x) \quad (0.16)$$

Thus, the solution using Z-transform is:

$$y(x) = y_0 \cos(x) + y_1 \sin(x) \quad (0.17)$$

### Using the Bilinear Transform:

The Bilinear Transform is a method used to convert a continuous-time system (in the Laplace domain) into a discrete-time system (in the Z-domain). The mapping is given by the relation:

$$s = \frac{2}{T} \cdot \frac{1 - z^{-1}}{1 + z^{-1}}$$

where  $T$  is the sampling period, and  $z^{-1}$  is the inverse Z-transform variable.

The continuous-time transfer function for the system is:

$$H(s) = \frac{1}{s^2 + 1}$$

#### Step 1: Apply the Bilinear Transform

Substitute the Bilinear Transform relationship for  $s$  into the continuous-time transfer function  $H(s)$ :

$$H(z) = \frac{1}{\left( \frac{2}{T} \cdot \frac{1 - z^{-1}}{1 + z^{-1}} \right)^2 + 1}$$

This equation expresses the continuous-time transfer function  $H(s)$  in terms of  $z$ , mapping the system to the discrete-time domain.

#### Step 2: Deriving the Difference Equation

Simplify the denominator by expanding the square and combining terms:

$$H(z) = \frac{(1 + z^{-1})^2}{(1 + z^{-1})^2 + \frac{4}{T^2}(1 - z^{-1})^2}$$

Using partial fraction decomposition, we can determine the coefficients of  $H(z)$  and express it in terms of powers of  $z$ . The resulting expression provides the difference equation:

$$y[n + 2] - 2y[n + 1] + y[n] = 0$$

where  $T$  determines the sampling rate.

### Step 3: Verifying the Solution

The discrete-time system matches the sinusoidal behavior of the continuous-time system for sufficiently small  $T$ , with the general solution:

$$y[n] = C_1 \cos\left(\frac{\pi n}{T}\right) + C_2 \sin\left(\frac{\pi n}{T}\right)$$

### Using Difference Equation to Approximate Solution:

This method approximates the solution by discretizing the function.

From the definition of the second-order differentiation:

$$\frac{d^2y}{dx^2} \approx \frac{y(x_{i+1}) - 2y(x_i) + y(x_{i-1}))}{h^2} \quad (0.18)$$

Substituting into the differential equation:

$$\frac{d^2y}{dx^2} + y = 0 \quad (0.19)$$

$$\frac{y_{n+1} - 2y_n + y_{n-1}}{h^2} + y_n = 0 \quad (0.20)$$

Simplifying:

$$y_{n+1} = 2y_n - y_{n-1} - h^2y_n \quad (0.21)$$

Let  $x_0 = 0$ ,  $y_0 = C_1$ ,  $y_1 = C_1 + hC_2$ . For small step size  $h$ , iteratively calculate  $y_{n+1}$ .

By comparing the plots, the numerical solution matches the exact solution, verifying the correctness. Additionally, the plot of the given question does not match our solution, so Option A is not correct.

