

$$L_{2,1}(X) = \frac{(X-X_0)(X-X_2)}{(X_1-X_0)(X_1-X_2)} = \frac{-16}{15} (X-2)(X-4) \quad (66)$$

$$L_{2,2}(X) = \frac{(X-X_0)(X-X_1)}{(X_2-X_0)(X_2-X_1)} = \frac{2}{5} (X-2)(X-2.75)$$

$$\Rightarrow P_2(X) = \sum_{i=0}^2 L_{2,i}(X) \cdot f(X_i)$$

A better error estimate using Lagrange Polynomials:

Thm: Suppose X_0, X_1, \dots, X_n are $n+1$ distinct numbers in the interval $[a, b]$ and $f \in C^{(n+1)}[a, b]$. Then for each $x \in [a, b]$, there exists $\xi(x) \in [a, b]$ between X_0, X_1, \dots, X_n , s.t.

$$f(x) = p(x) + \underbrace{\frac{f^{(n+1)}(\xi(x))}{(n+1)!} (x-X_0)(x-X_1)\dots(x-X_n)}_{R_L}$$

where $p(x) = \sum_{k=0}^n f(X_k) \cdot L_{n,k}(x)$

Remark: 1) Lagrange error R_L is similar to Taylor poly. error:

$$\frac{f^{(n+1)}(\xi(x))}{(n+1)!} (x-X_0)^{n+1} \text{ vs. } \frac{f^{(n+1)}(\xi(x))}{(n+1)!} (x-X_0)\dots(x-X_n)$$

but error in R_L is "spread" across different nodes.

Ex: Given $x_0 = 2$, $x_1 = 2.75$, $x_2 = 4$ for $f(x) = \frac{1}{x}$

(67)

a) Determine the error form for Lagrange polynomial $p(x)$

b) Determine the maximum error when $p(x)$ is used to approximate $f(x)$ for $x \in [2, 4]$

Sol: a) $f'(x) = -\frac{1}{x^2}$, $f''(x) = \frac{2}{x^3}$, $f'''(x) = -\frac{6}{x^4}$

$$\Rightarrow \text{Error: } R_2(x) = \frac{f'''(\xi(x))}{3!} \underbrace{(x-x_0)(x-x_1)(x-x_2)}_{g(x)} \\ = \frac{-6}{3!} (\xi(x))^{-4} (x-2)(x-2.75)(x-4) \quad \xi(x) \in (2, 4).$$

b) Want to find $\max_{x \in (2, 4)} |R_2(x)|$

Note: $|\xi(x)^{-4}| \leq 2^{-4} = \frac{1}{16}$

$$\text{Let } g(x) = (x-2)(x-2.75)(x-4) = x^3 - \frac{35}{4}x^2 + \frac{49}{2}x - 22$$

To find max. vals of g in $[2, 4]$, need to find crit. pts.

$$g'(x) = 3x^2 - \frac{35}{2}x + \frac{49}{2} = \frac{1}{2}(3x-7)(2x-7)$$

$$\Rightarrow \text{critical pts occur at } x = \frac{7}{3} \text{ with } g\left(\frac{7}{3}\right) = \frac{25}{108}$$

$$\text{and } x = \frac{7}{2} \text{ with } g\left(\frac{7}{2}\right) = -\frac{9}{16}$$

$$\left(\frac{9}{16}\right) > \left(\frac{25}{108}\right)$$

At boundary values $g(2) = g(4) = 0$.

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$\Rightarrow \max_{x \in (2,4)} |g(x)| \leq \frac{9}{16}$. Hence, max. error is

$$R_2(x) \leq |g(x)|^4 \cdot |g(x)| \leq \left| \frac{1}{16} \right| \cdot \left| \frac{9}{16} \right|$$

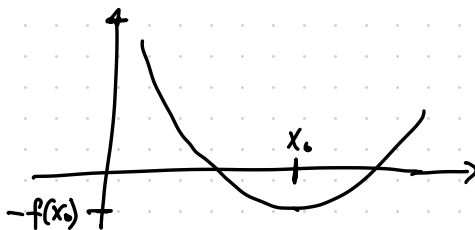
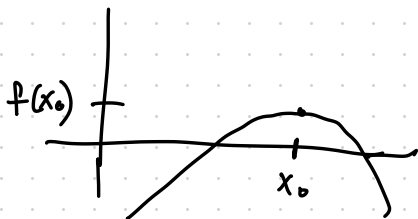
Remarks: 1) Power series form of $p(x) \equiv$ Lagrange form but with different basis:

$$\{x^n, x^{n-1}, \dots, x', 1\} \quad \text{vs.} \quad \{L_{n,n}(x), L_{n,n-1}(x), \dots, L_{n,1}(x), L_{n,0}(x)\}$$

Power series Lagrange

2) Can use fmin bound (f_{\min} , x_1, x_2) to find maximum of a function in interval (x_1, x_2) .

Note: $\max_x f(x) = - \min_x (-f(x))$



3) Adding a new node x_j changes all bases $L_{n,i}$'s to $L_{n+1,i}$'s

3.3 Divided Differences and Newton's Form

(69)

Q: Given data (x_i, f_i) for $i=0, 1, \dots, n$, how to find a_i 's s.t. the polynomial

$$P_n(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)(x-x_1) + \dots + a_n(x-x_0)(x-x_1)\dots(x-x_{n-1})$$

(Newton Form)

interpolates (x_i, f_i) ?

Forward Divided Differences

• zeroth divided difference of f w.r.t. x_i :

$$f[x_i] = f(x_i)$$

• 1st div. diff. of f w.r.t. x_i, x_{i+1} :

$$f[x_i, x_{i+1}] = \frac{f[x_{i+1}] - f[x_i]}{x_{i+1} - x_i}$$

• 2nd div. diff. of f w.r.t. x_i, x_{i+1}, x_{i+2} :

$$f[x_i, x_{i+1}, x_{i+2}] = \frac{f[x_{i+1}, x_{i+2}] - f[x_i, x_{i+1}]}{x_{i+2} - x_i}$$

• k^{th} div. diff. w.r.t. $x_i, x_{i+1}, \dots, x_{i+k}$

$$f[x_i, x_{i+1}, \dots, x_{i+k}] = \frac{f[x_{i+1}, \dots, x_{i+k}] - f[x_i, \dots, x_{i+k-1}]}{x_{i+k} - x_i}$$

In particular,

$$f[x_0, x_1, \dots, x_n] = \frac{f[x_1, \dots, x_n] - f[x_0, \dots, x_{n-1}]}{x_n - x_0} \quad (1)$$

Thm: Let p_n be the n^{th} degree polynomial s.t.

$p_n(x_i) = f(x_i)$ for $i=0, 1, \dots, n$. Then

$$p(x) = f[x_0] + f[x_0, x_1](x-x_0) + f[x_0, x_1, x_2](x-x_0)(x-x_1) \\ + \dots + f[x_0, \dots, x_n](x-x_0)\dots(x-x_{n-1}) \quad (*)$$

$$p(x) = f[x_0] + \sum_{j=1}^n \left[f[x_0, \dots, x_j] \left(\prod_{i=0}^{j-1} (x-x_i) \right) \right]$$

Remarks: (*) referred to as Newton form of polynomial

2) obtain $f[x_0, \dots, x_j]$ recursively using (1)

Another way to obtain Newton Coefficients:
equivalent

Recall:
$$p_n(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)(x-x_1) + \dots \\ + a_n(x-x_0)(x-x_1)\dots(x-x_{n-1})$$

$$\begin{array}{l}
 p(x_0) = f(x_0) \\
 p(x_1) = f(x_1) \\
 \vdots \\
 p(x_n) = f(x_n)
 \end{array}
 \left\{
 \begin{array}{l}
 a_0 \\
 a_0 + a_1(x_1 - x_0) \\
 \vdots \\
 a_0 + a_1(x_n - x_0) + a_2(x_n - x_0)(x_n - x_1) + \dots \\
 + a_n(x_n - x_0)(x_n - x_1) \dots (x_n - x_{n-1})
 \end{array}
 \right.$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 1 & (x_1 - x_0) & 0 & \dots & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & (x_n - x_0) & (x_n - x_0)(x_n - x_1) & \dots & (x_n - x_0)(x_n - x_1) \dots (x_n - x_{n-1}) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}$$

$$L \underline{a} = \underline{f}$$

Remarks : 1) This can be easily solved by forward substitution

$$2) \det(L) = 1 \cdot [(x_1 - x_0)] \cdot [(x_2 - x_0)(x_2 - x_1)] \dots [(x_n - x_0)(x_n - x_1) \dots (x_n - x_{n-1})]$$

\Rightarrow If all x_i are distinct, L is nonsingular

$\Rightarrow L \underline{a} = \underline{f}$ has unique sol.

Ex: Given $(0,0), (\frac{\pi}{2}, 1), (\pi, 0)$. Find Newton for
 of poly. $p(x) = a_0 + a_1(x - x_0) + a_2(x - x_0)(x - x_1)$
 $= a_0 + a_1(x) + a_2(x)(x - \frac{\pi}{2})$

$$p(0)=0 \Rightarrow a_0=0$$

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$$p\left(\frac{\pi}{2}\right)=1 \Rightarrow 0 + a_1 \frac{\pi}{2} = 1 \Rightarrow a_1 = \frac{2}{\pi}$$

$$p(\pi)=0 \Rightarrow a_0 + \frac{2}{\pi}(\pi) + a_2 \cdot \pi \cdot \left(\frac{\pi}{2}\right) \Rightarrow a_2 = \frac{-4}{\pi^2}$$

$$\Rightarrow p(x) = 0 + \frac{2}{\pi}x - \frac{4}{\pi^2}x\left(x - \frac{\pi}{2}\right)$$

← double check!

Recap: We have seen three forms of $p(x)$:

- power series (Vandermonde)
- Lagrange
- Newton

Although these may look different, they each give the same $p(x)$.

A general form for interpolation

- Given data $\{(x_i, f_i)\}_{i=0}^n$
- and a basis of polynomials of degree n :

$$\{\phi_0(x), \phi_1(x), \phi_2(x), \dots, \phi_n(x)\}$$

Find coefficients a_0, a_1, \dots, a_n s.t.

$$p(x) = a_0 \phi_0(x) + a_1 \phi_1(x) + \dots + a_n \phi_n(x)$$

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and $p(x_i) = f_i$

To find a_0, a_1, \dots, a_n , we need to solve a linear system:

$$\left. \begin{array}{l} p(x_0) = f_0 \\ p(x_1) = f_1 \\ \vdots \\ p(x_n) = f_n \end{array} \right\} \Rightarrow \begin{bmatrix} \phi_0(x_0) & \phi_1(x_0) & \dots & \phi_n(x_0) \\ \phi_0(x_1) & \phi_1(x_1) & \dots & \phi_n(x_1) \\ \vdots & \vdots & & \vdots \\ \phi_0(x_n) & \phi_1(x_n) & \dots & \phi_n(x_n) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}$$

$$M \underline{a} = \underline{f}$$

Ex: a) Power series basis $\{1, x, x^2, \dots, x^n\}$

$\Rightarrow M = V =$ Vandermonde matrix $O(n^3)$

b) Newton Basis: $\{1, x-x_0, (x-x_0)(x-x_1), \dots, (x-x_0)\dots(x-x_{n-1})\}$

$\Rightarrow M = L =$ lower triangular $O(n^2)$

c) Lagrange basis: $\{L_{n,0}(x), L_{n,1}(x), \dots, L_{n,n}(x)\}$

where $L_{n,j} = \frac{(x-x_0)(x-x_1)\dots(x-x_{j-1})(x-x_{j+1})\dots(x-x_n)}{(x_j-x_0)(x_j-x_1)\dots(x_j-x_{j-1})(x_j-x_{j+1})\dots(x_j-x_n)}$

In this case, $M = I =$ identity matrix.

d) Chebyshev Basis $\{T_0(x), T_1(x), \dots, T_n(x)\}$

where

$$T_j(x) = \cos(j \cdot \arccos(x)), \quad -1 \leq x \leq 1$$

In this case, M does not have any special structure.

Solve $M \underline{g} = \underline{f}$

Question Why different bases?

- In some cases, easier to solve $M \underline{g} = \underline{f}$
- In some cases, M is better conditioned
 \Rightarrow solving $M \underline{g} = \underline{f}$ may produce less errors in \underline{g}

MATLAB:
 $p = \text{polyfit}(\underline{x}_{\text{nodes}}, \underline{f}_{\text{nodes}}, n)$
 $\text{polyval}(p, \underline{x})$

Error in Poly. interpolation

Given $\{(x_i, f_i)\}_{i=0}^n$, $f_i = f(x_i)$.

Let $p_n(x)$ be poly. of deg. n with $p_n(x_i) = f_i$

Recall Thm:

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Let $[a, b]$ be interval containing x_0, x_1, \dots, x_n and $f \in C^{n+1}(a, b)$. Then

$$e_n(x) = f(x) - p_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \underbrace{(x-x_0)(x-x_1)\dots(x-x_n)}_{w_{n+1}(x)}$$

where ξ between x_0, x_1, \dots, x_n .

Remarks: 1) At interpolating points x_0, x_1, \dots, x_n , $e_n(x_i) = 0$.

2) We may have little information, or control over the size of $\left| \frac{f^{(n+1)}(\xi)}{(n+1)!} \right|$

\Rightarrow We might investigate how to make small:

$$|w_{n+1}(x)| = |(x-x_0)(x-x_1)\dots(x-x_n)|$$

- With equally spaced points, x_0, x_1, \dots, x_n ,

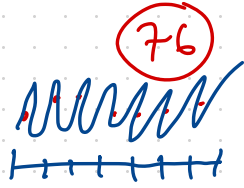
$w_{n+1}(x)$ tends to oscillate, with growing amplitudes near endpoints

- A different choice of points can reduce this. A good choice of points is often Chebyshev points, e.g.,

$$x_i = \frac{b+a}{2} - \frac{b-a}{2} \cos\left(\frac{2i+1}{2n+2} \pi\right), \quad i = 0, 1, \dots, n$$

on interval $[a, b]$

Problems with polynomial interpolation

- High degree poly. tend to oscillate 
- ⇒ large errors can occur (will see how)
- Low degree poly. do not oscillate as much, but be poor approx. to functions that do oscillate.

Splines (piece-polynomial) Interpolation

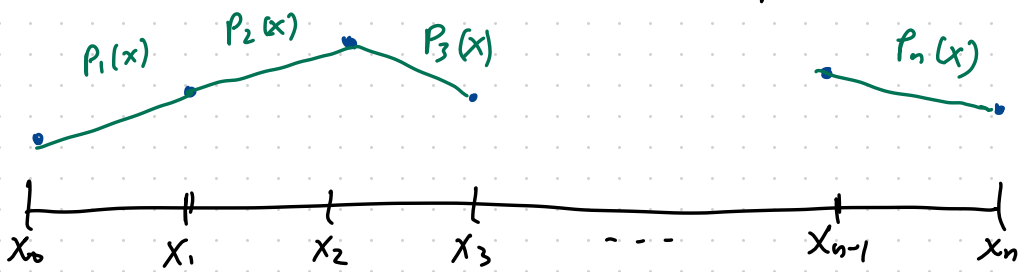
- partition interval into pieces
- Construct low degree poly. approx. on each subinterval
- connect poly. pieces together

Linear Splines

Given $\{(x_i, f_i)\}_{i=0}^n$, define $s(x)$ as

$$s(x) = \begin{cases} p_1(x) & \text{if } x \in [x_0, x_1] \\ p_2(x) & \text{if } x \in [x_1, x_2] \\ \vdots & \\ p_n(x) & \text{if } x \in [x_{n-1}, x_n] \end{cases}$$

where each $p_i(x)$ is a linear polynomial (line)



How to find $p_i(x)$?

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Recall: Given two points (x_{i-1}, f_{i-1}) , (x_i, f_i) ,
point-slope form eqn. of line:

$$y - f_i = \frac{f_i - f_{i-1}}{x_i - x_{i-1}} (x - x_i)$$

$$\Rightarrow p_i(x) = f_i + \frac{f_i - f_{i-1}}{x_i - x_{i-1}} (x - x_i)$$

We will use notation:

$$a_i = f_i, \quad b_i = \frac{f_i - f_{i-1}}{x_i - x_{i-1}}$$

$$\text{So } p_i(x) = a_i + b_i (x - x_i)$$

A linear spline for the data $\{(x_i, f_i)\}_{i=0}^n$ can be represented as

$$S(x) = \begin{cases} a_1 + b_1(x - x_1) & \text{if } x_0 \leq x < x_1 \\ a_2 + b_2(x - x_2) & \text{if } x_1 \leq x < x_2 \\ \vdots & \\ a_n + b_n(x - x_n) & \text{if } x_{n-1} \leq x \leq x_n \end{cases}$$

where

$$a_i = f_i, \quad b_i = \frac{f_i - f_{i-1}}{x_i - x_{i-1}}$$

Ex: Construct a linear spline for data

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x_i	-1	0	1
f_i	0	1	3

$$a_1 = 1, \quad a_2 = 3$$

$$b_1 = \frac{f_1 - f_0}{x_1 - x_0} = 1, \quad b_2 = 2$$

$$s(x) = \begin{cases} 1 + (x-0) = 1+x & -1 \leq x < 0 \\ 3 + 2(x-1) = 1+2x & 0 \leq x \leq 1 \end{cases}$$

Error for Linear Splines

Recall: • For linear interpolation, we use two points:

$$(x_{i-1}, f_{i-1}), (x_i, f_i)$$

• From thm, the error is

$$|f(x) - p_i(x)| = \left| \frac{f''(\xi_i)}{2!} \right| \cdot |(x-x_{i-1})(x-x_i)|, \quad \xi_i \in [x_{i-1}, x_i]$$

• Let $M_i = \max_{x_{i-1} \leq x \leq x_i} |f''(x)|$

Then $|f(x) - p_i(x)| \leq \frac{M_i}{2} |(x-x_{i-1})(x-x_i)|$

• Can we find an upper bound on $|(x-x_{i-1})(x-x_i)|$?

$$\text{Let } w_i(x) = (x-x_{i-1})(x-x_i) = x^2 - (x_{i-1}+x_i)x + x_{i-1} \cdot x_i$$

$$w_i'(x) = 2x - (x_{i-1} + x_i) = 0 \Rightarrow x = \frac{x_{i-1} + x_i}{2}$$

- Notice that $|w_i(x)|$ is largest either at crit. pt. (79) $x = \frac{x_{i-1} + x_i}{2}$, or at one of the endpts. x_{i-1}, x_i .

$$|w_i(x_{i-1})| = 0, \quad |w_i(x_i)| = 0$$

$$\begin{aligned} \left| w_i\left(\frac{x_{i-1} + x_i}{2}\right) \right| &= \left| \left(\frac{x_{i-1} + x_i}{2} - x_{i-1}\right) \left(\frac{x_{i-1} + x_i}{2} - x_i\right) \right| \\ &= \frac{(x_i - x_{i-1})^2}{4} \leftarrow \text{largest} \end{aligned}$$

\Rightarrow For linear interpolation, the error for $x \in [x_{i-1}, x_i]$

$$\begin{aligned} \text{is } |f(x) - p_i(x)| &\leq \frac{1}{2} M_i |w_i(x)| \leq \frac{1}{2} \cdot \frac{1}{4} M_i (x_i - x_{i-1})^2 \\ &= \frac{1}{8} M_i h_i^2 \end{aligned}$$

$$\text{where } h_i = x_i - x_{i-1}$$

Now consider linear splines

$$s(x) = \begin{cases} p_1(x) & x \in [x_0, x_1] \\ p_2(x) & x \in [x_1, x_2] \\ \vdots & \vdots \\ p_n(x) & x \in [x_{n-1}, x_n] \end{cases}$$

$$\text{Let } |e_n(x)| = |f(x) - s(x)| \leq \max_i \frac{M_i}{8} \cdot h_i^2 = \frac{M}{8} \cdot h^2$$

$$\text{where } h = \max_i h_i, \quad M = \max_i M_i.$$