note: M = max /f"(x) / x \in [4, b] =) / [en(x)] < M/2 Note: This result says: If the nodes Xo, X, -, Xn are very close, then his small, and error can be small Problems with Linear Splines · They are NOT smooth. That is, although s(x) is continuous for all X, S'(x) is NOT continuous at breakpoints (think of solutions of ODEs/PDEs) High-degree Splines - properties of degree m spline 1) Domain is a closed interval [a, B) z) s(x), s'(x), ..., $s^{(m-1)}(x)$ are continuous on $[\alpha, \beta]$ 3) [a, B] is partioned s.t. Q= X. < X, < X2 < ... < Xn = B where SCX) is a polynomial of degree at most m on [xi-1, Xi] Pn (x) P. (x) P. (x) χ_1 · · · χ_2 · · · χ_3 · · - ·

Terminology

Knots = Greek points That is, points where you switch from one poly. to another

Nodes = points where spline interpolates data Often knots = nodes

Cubic Splines: Used often in applications.

How do ve construct these?

Basic Idea:

· Suppose we

· Find S(X) satisfy ing

 $S(x) = \begin{cases} f_1(x) \\ f_2(x) \\ \vdots \\ f_n(x) \end{cases}$

and $S(X_i) = f(X_i)$.

To find s(x), we need to find

are given interpolation data {(xi, fi)}i=0

X. EXCXI XIEXZXL

Kn-1 & X & Xn

where $P_i(x) = Q_i + b_i(x - x_i) + C_i(x - x_i)^2 + d_i(x - x_i)^3$

ai, bi, ci, di, i=1,2,...,n => have 4n unknowns => need 4n equations.

Conditions to be satisfied

1) Interpolation: s(xi) = fi , i=0,1,..., n Note P:(x) = 9i + 6i (x-xi) + ci (x-xi)2 + di (x-xi)3 $P_{n}(x_{o}) = f_{o}$

 $(x_0 + b_1)(x_0 - x_1) + c_1(x_0 - x_1)^2 + d_1(x_0 - x_1)^3 = f_0$

This gives 2) Continuity of S(x): $P_{i+1}(x_i) = P_i(x_i)$, i=1,2,...,n-1

 $\begin{array}{c|c}
P_{L}(X_{1}) = f_{1} \\
P_{L}(X_{2}) = f_{L}
\end{array}$ $P_n(X_n) = f_n$

 $\rho_n(x_{n-1}) = \rho_{n-1}(x_{n-1})$ $\alpha_n + \delta_n(x_{n-1} - x_n) + C_n(x_{n-1} - x_n)^2 + d_n(x_{n-1} - x_n)^2 = \alpha_n$

This gives n-1 equations

n+1 equations

 $= f_0$

= f2

= fn

(St)

3) Continuity of
$$S'(x)$$
: $P_{i+1}^{1}(x_{i}) = P_{i}^{1}(x_{i})$, $i=1,...,n-1$

Note: $P_{i}^{1}(x) = b_{i} + 2c_{i}(x-x_{i}) + 3d_{i}(x-x_{i})^{2}$
 $P_{i}^{1}(x) = P_{i}^{1}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{1}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{1}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{1}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i-1}^{1}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i-1}^{1}(x_{i-1})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i+1}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i-1}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_{i})$
 $P_{i}^{2}(x_{i}) = P_{i}^{2}(x_$

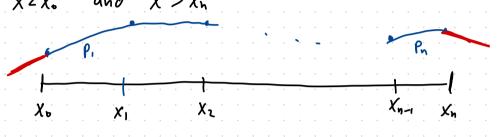
we specify extra boundary conditions.

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5) End Conditions (Several Options)

a) Natural (or Free) boundary conditions

Assume S(x) is a linear polynomial (line) for $X < X_0$ and $X > X_0$



 $S'(X_0) = 0 \implies P_1''(X_0) = 0$ $S''(X_0) = 0 \implies P_n''(X_0) = 0$ $P_n''(X_0) = 0$ $P_n''(X_0) = 0$ This means:

$$= 2c_{1} + 6d_{1}(x_{0} - x_{1}) = 0$$

$$2c_{1} = 0$$

b) Clamped End conditions (1st deviv. condition) Here, we specify slope at endpoints. That is, we suppose we want the slope at xo to be So and slope at xn to b dn

Then
$$S'(x) = S - S$$

For example, if we choose So=Sn=0, then

$$S'(x_0) = S_0$$
 => $P_1'(x_0) = S_0$
 $S'(x_0) = S_0$ => $P_n'(x_0) = S_0$
 $S_1'(x_0) = S_0$

$$S'(x_n) = \delta_n = P_n'(x_n) = \delta_n$$

 $\delta_1 + 2 c_1(x_0 - x_1) + 3 d_1(x_0)$

$$S(x_n) = d_n$$
 $P_n'(x_n) = d_n$
 $b_1 + 2c_1(x_0 - x_1) + 3d_1(x_1)$

our spline might look like:

$$= \frac{b_1 + 2c_1(x_6 - x_1) + 3d_1(x_6 - x_1)^2 = \delta_0}{b_n = \delta_n}$$

$$(x_6-x_1)+3d_1(x_6)$$

c) Can similarly clamp 2nd derivative

$$(x_6-x_1)+3d$$
, (x_6)

Cubic B-Splines ("Basis" Splines)

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Reall from polynomial interpolation, we find

- $\rho(x)$ s.t. $\rho(x_i) = f_i$
- P(x) is unique, but can write in different ways
 (different bases)
- Newton Basis
 { 1, (x-x0), (x-x0)(x-x1), ..., (x-x0)(x-x1)--(x-x0-1)}

$$P(x) = \sum_{i=0}^{h} \left[6_{i} \frac{i-1}{II} (x-x_{i}) \right]$$

- Lagrange Basis $\left\{ L_{n,o}(x), L_{n,i}(x), ..., L_{n,n}(x) \right\} \qquad \rho(x) = \left\{ i L_{n,i}(x) \right\}$ i = 0

Question: Can we find a basis for cubic Splines?

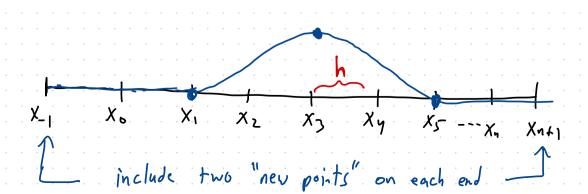
That is, instead of writing $\begin{cases}
P_{i}(x) \\
P_{2}(x)
\end{cases}$ $S_{3,n}(x) = \begin{cases}
P_{n}(x)
\end{cases}$

We want to find basis function $\left\{ B_{1}(x), B_{0}(x), \ldots, B_{n}(x), B_{n+1}(x) \right\}$

 $S_{3,n}(x) = \underbrace{\begin{cases} n+1 \\ \leq \alpha_i \\ i=-1 \end{cases}} \alpha_i B_i(x) \leftarrow \text{Called } B\text{-Spline}$

Basic Idea:

• Use equally-spaced points



· Define cubic polynomials on

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$$[X_{i-2}, X_{i+2}] = [X_i - 2h, X_i + 2h]$$

$$B_i(x) = 0$$
 for $X \notin [X_i-2h, X_i+2h]$

$$(x_i-2h_0), (x_{i,1}), (x_i+2h_0)$$

 $\frac{1}{4h^3} \left(x - x_{i+2} \right)^3$

$$(\chi - \chi_{i-1})^3$$

$$\left(\frac{1}{4h^3} \left(\chi - \chi_{i-1}\right)^3\right)$$

 $\frac{-1}{4h^3} \left(x - x_{i+2} \right)^3 + \frac{1}{h^3} \left(x - x_{i+1} \right)^3$

 $\frac{1}{4h^{3}} \left(X - X_{i-2} \right)^{3} - \frac{1}{h^{3}} \left(X - X_{i-1} \right)^{3} X_{i-1} \leq X \leq X_{i}$

Xinz & X < Xin

 $X_i \leq X \leq X_{i+1}$

Xi+1 & XEXitz

else



. Then, we find 9: s.t.

j=0,1,...,n

Note: Bi, i=-1,..., not, are the set of all B-spline basis which are non-zero in interval

[xi -2h, Xi+2h] Observe

 $\beta_{j-2}(X_j) = 0$ $\beta_{j-1}(x_j) = y_j$ $a_{j-1} B_{j-1} (x_j) + a_j b_j (x_j)$

 $(B_j \cdot (x_j)) = 1$ + 9j+1 Bj+1 (Xj) = fj $\beta_{j+1}(x_j) = /\gamma$ J= 0, 1, ..., h Bjtz(xj) = 0

 $0r = \frac{1}{4}q_{j-1} + q_j + \frac{1}{4}q_{j+1} = f_j$, $j = q_1, ..., h$ This gives not equs but have not 3 unknown:

9-1, 90, 91, ..., 9n, 9n+1 Need two more equations

In the case of natural end (Free boundary) conditions $S''(x_0) = S''(x_0) = 0$

Note that
$$\frac{\partial}{\partial x} \left(\frac{1}{4h^3} (x - x_{i-2})^3 \right) = \frac{3}{4h^3} (x - x_{i-2})^2$$

$$\Rightarrow \frac{\partial^2}{\partial x^2} \left(\frac{1}{4h^3} (x - x_{i-2})^5 \right) = \frac{3}{2h^3} (x - x_{i-2})$$

$$S''(x_0) = 0 \implies \frac{3}{2h^2} q_{-1} - \frac{3}{h^2} q_0 + \frac{3}{2h^2} q_1 = 0$$

$$S''(x_0) = 0 \implies \frac{3}{2h^2} q_{n-1} - \frac{3}{h^2} q_0 + \frac{3}{2h^2} q_{n+1} = 0$$

$$1 + 3 \text{ linear eqn can be solved using Gaussian Elim.}$$

n+3 linear ean can be solved using But we can simplify the egns.

Adding first two equations:

$$\frac{3}{2}q_{-1} - 3q_{0} + \frac{3}{2}q_{1} = 0$$
 \Rightarrow $q_{0} = \frac{2}{3}f_{0}$
 $\frac{1}{4}q_{-1} + q_{0} + \frac{1}{4}q_{1} = f_{0}$

Similarly, adding last two egns:
$$\left[q_{1}=\frac{2}{3} t_{1}\right] \left[q_{1}\right]$$

So we have (recall $\frac{1}{4}q_{0}+q_{1}+\frac{1}{4}q_{2}=f_{1}\right)$
 $q_{1}+\frac{1}{4}q_{2}=f_{1}-\frac{1}{6}f_{0}$

$$\frac{q_{1} + \overline{q} q_{2}}{\overline{q}_{1} + q_{2} + \overline{q} q_{3}} = f_{2}$$
 $\frac{1}{q_{1}} + q_{2} + \frac{1}{q} q_{3} = f_{2}$
 $\frac{1}{q_{2}} + q_{3} + \frac{1}{q} q_{4} = f_{3}$

$$\frac{1}{4}g_1 + \alpha_3 + \frac{1}{4}g_4 = f_3$$

$$\vdots$$

$$_{3} + 9_{n-2} + \frac{1}{4} 9_{n-1} = 1$$

$$\frac{1}{4}q_{n-3} + q_{n-2} + \frac{1}{4}q_{n-1} = f_{n-2}$$

$$+ 9_{n-2} + \frac{1}{y} 9_{n-1} =$$

$$\frac{1}{y} q_{n-3} + q_{n-2} + \frac{1}{y} q_{n-1} = \frac{1}{y} q_{n-2} + q_{n-2} + q_{n-1} = \frac{1}{y} q_{n-2} + q_{n-2} + q_{n-1} = \frac{1}{y} q_{n-2} + q_{n-2} + q_{n-2} + q_{n-2} + q_{n-2} = \frac{1}{y} q_{n-2} + q_{n-2} +$$

$$\Rightarrow \text{ To find coeffs. } \alpha_{1}, \dots, \alpha_{n-1} \text{ , we solve}$$

$$\begin{bmatrix} 1 & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} \end{bmatrix} \begin{bmatrix} \alpha_{1} \\ \alpha_{2} \\ \vdots \\ \alpha_{n-2} \\ \alpha_{n-1} \end{bmatrix} \begin{bmatrix} f_{1} - \frac{1}{6}f_{0} \\ f_{2} \\ \vdots \\ f_{m-1} - \frac{1}{6}f_{n} \end{bmatrix}$$

$$= f_{n-1} - \frac{1}{6} f_n$$

Tridiagonal system can be efficiently (92) computed using, e.g., Thomas Algorithm

(O(n) instead of O(n²) FLOPs)

Gaussian Elimination

Finally, compute the values of 9-1 and

9111 from (**)

Numerical Differentiation Chapter 4:

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and Integration

Differentiation:

 $f'(x) = \lim_{h \to \infty} \frac{f(x+h) - f(x)}{h}$ Calculus Definition:

Idea: approximate numerically using small h.

Finite Difference Approximation

Consider Taylor series centered at x

(A) $f(x+h) = f(x) + f'(x) \cdot h + \frac{f''(x)}{2!} h^2 + \frac{f'''(x)}{3!} h^3 + \cdots$ (B) $f(x-h) = f(x) - f'(x) \cdot h + f'(x) h^2 - \frac{f''(x)}{3!} h^3 + \cdots$

Forward Difference Approximation Use series (A):

 $f(x+h) = f(x) + f'(x) \cdot h + \frac{f''(x)}{2!} h^2 + \frac{f'''(x)}{3!} h^3 + \cdots$

$$= \frac{f(x+h) - f(x)}{h} = f'(x) + \frac{f''(x)}{2!} h + \frac{f'''(x)}{3!} h^{2} + \cdots$$

$$= \frac{f'(x)}{h} \approx \frac{f(x+h) - f(x)}{h} \quad \text{with approximation error}$$

$$= \frac{f'(x)}{h} \approx \frac{f(x+h) - f(x)}{h} \quad \text{with approximation error}$$

 $\Rightarrow \frac{f(x+h)-f(x)}{}$