

Chpt 1

Goal: Avoid errors due to finite precision

- underflow / overflow
- loss of significant digits
- truncation error (Taylor's Thm)

1.3 Convergence Rate of

- Sequences: $\alpha_n = \alpha + O(n^{-p})$
 - Functions: $F(h) = L + O(h^p)$
- } generally interested in largest p

$$|\alpha_n - \alpha| \leq K n^{-p} \quad n \geq n_0$$

$$|F(h) - L| \leq K h^p \quad h \leq h_0$$

Chp 2: Root finding / Fixed points.

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Goal: find p s.t. $f(p) = 0$
or p s.t. $g(p) = p$

Tools: IVT, MVT

Algorithms:

• Bisection

- requirements: $f \in C[a, b]$, $f(a) \cdot f(b) < 0$
- linearly convergent
- limited to 1D (generally)

• Fixed Point Iteration: $p_n = g(p_{n-1})$

• require:

- $g \in C[a, b]$, $g(x) \in [a, b] \ \forall x \in [a, b]$
(existence)

- $|g'(x)| \leq k < 1$ for $k \in (0, 1)$

$\forall x \in [a, b]$ (uniqueness)

- Error bound

$$|p_n - p| \leq k^n \max \{|p_0 - a|, |p_0 - b|\}$$

$$|p_n - p| \leq \frac{k^n}{1-k} |p_1 - p_0|$$

• Newton's Method

$$p_n = p_{n-1} - \frac{f(p_{n-1})}{f'(p_{n-1})}$$

- Converges quadratically if simple root ($f'(p) \neq 0$) and p_0 close enough to p

• Secant Method

$$p_n = p_{n-1} - \frac{f(p_{n-1}) (p_{n-1} - p_{n-2})}{f(p_{n-1}) - f(p_{n-2})}$$

- superlinear convergence

• Method False Position (secant with root bracketing)

• Convergence Rate/Order

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linear if

$$\lim_{n \rightarrow \infty} \frac{|p_{n+1} - p|}{\underbrace{|p_n - p|}_{\lambda_n}} = \lambda \quad 0 \leq \lambda \leq 1$$

Superlinear if $\lambda = 0$

linear if $0 < \lambda < 1$

sublinear if $\lambda = 1$

quadratic if

$$\lim_{n \rightarrow \infty} \frac{|p_{n+1} - p|}{|p_n - p|^2} = \lambda$$

• Modified Newton:

• apply Newton's to $M(x) = \frac{f(x)}{f'(x)}$

- $p_n = p_{n-1} - \frac{M(p_{n-1})}{M'(p_{n-1})}$
 - root always simple \Rightarrow quadratic convergence.
-

Accelerating linearly-convergent sequences $\{p_n\}$.

Aitken's Δ^2 method:

$$\hat{p}_n = p_n - \frac{(p_{n+1} - p_n)^2}{p_{n+2} - 2p_{n+1} + p_n} = \{\Delta^2\}(p_n)$$

(superlinear)

Steffensen's

$$k=0 \quad p_0^{(0)}, \quad p_1^{(0)} = g(p_0^{(0)}), \quad p_2^{(0)} = g(p_1^{(0)})$$

$$k=1 \quad p_0^{(1)} = \{\Delta^2\} p_0^{(0)}, \quad p_1^{(1)} = g(p_0^{(1)}), \quad p_2^{(1)} = g(p_1^{(1)})$$

• Quadratic convergence if p_0 close

Horners Method: fast evaluation of poly.

Deflation: estimate all roots of poly.

by successively applying Newton's

Chpt 3: Interpolation.

Goal: given $(x_0, f_0), (x_1, f_1), \dots, (x_n, f_n)$.

Find function (polynomial) $p_n(x)$ s.t.

$$p_n(x_i) = f_i \quad i = 0, 1, \dots, n$$

Polynomial interpolation

Power series: $p_n(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$

Newton Form: $p_n(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)(x-x_1) + \dots + a_n(x-x_0)\dots(x-x_{n-1})$

Lagrange Poly:

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$$L_{n,j}(x) = \frac{(x-x_0) \cdots (x-x_{j-1})(x-x_{j+1}) \cdots (x-x_n)}{(x_j-x_0) \cdots (x_j-x_{j-1})(x_j-x_{j+1}) \cdots (x_j-x_n)}$$

$$P_n(x) = \sum_{j=0}^n f_j L_{n,j}(x)$$

Linear Splines: linear interpolation on each subinterval

Cubic Splines: cubic interpolation on each subinterval

Cubic B-Splines: use basis $B_j(x)$ for cubic splines
↑ smooth and accurate!

Num. Diff.

Fwd Diff: $f'(x) = \frac{f(x+h) - f(x)}{h} + O(h)$

Bwd Diff: $f'(x) = \frac{f(x) - f(x-h)}{h} + O(h)$

Centered Diff : $f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$ (140)

$$f''(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} + O(h^2)$$

Num Integration

NC Rules : Equidistant Nodes

Open Rules : exclude boundary pts

Closed Rules : include boundary pts

Common rules (Midpt., Trap., Simpson's)

Composite NC Rules

- Use low order NC rule on partitioned subinterval

Gauss Rules

- optimized nodes/weights for DOP $2n+1$
- nodes are the roots of Legendre Polynomials.