

## Maths 761 Lecture 8 Summary

### Topic for today

Stability of fixed points in linear maps  
Linearisation in nonlinear maps

### Reading for today's lecture

Glendinning: §6.1, §6.5

### Recommended problems

Glendinning: §6: 3,4,5

### Reading for next lecture

Glendinning: §11.3-5

## Stability of Fixed Points in Linear Maps

Consider the linear difference equation  $x_{n+1} = Ax_n$ , where  $A$  is an  $m \times m$  constant matrix. The origin  $x = 0$  is a fixed point of this map. If  $\lambda$  is an eigenvalue of  $A$  with eigenvector  $v$ , then  $x_n = \lambda^n v$  is a solution to the difference equation. In the case that all the eigenvalues of  $A$  are distinct, the general solution to the difference equation is:

$$x_n = c_1 \lambda_1^n v_1 + c_2 \lambda_2^n v_2 + \dots + c_m \lambda_m^n v_m$$

where the eigenvalues are  $\lambda_1, \lambda_2, \dots, \lambda_m$  and the eigenvectors are  $v_1, v_2, \dots, v_m$ . The case that there are repeated eigenvalues is more complicated - see Worksheet 4.

If all the eigenvalues  $\lambda_i$  of  $A$  have  $|\lambda_i| < 1$  then all solutions of the difference equation tend to the origin as  $n \rightarrow \infty$ .

The stable, unstable and centre subspaces (or manifolds) for fixed points of linear maps are defined in an analogous way to the corresponding subspaces for flows. Thus, we define:

1.  $E^u(0)$ , the *unstable manifold (or subspace) of the origin*, is the span of the eigenvectors and generalised eigenvectors corresponding to the eigenvalues of  $A$  with modulus greater than one.
2.  $E^s(0)$ , the *stable manifold (or subspace) of the origin*, is the span of the eigenvectors and generalised eigenvectors corresponding to the eigenvalues of  $A$  with modulus less than one.

3.  $E^c(0)$ , the *centre manifold (or subspace) of the origin*, is the span of the eigenvectors and generalised eigenvectors corresponding to the eigenvalues of  $A$  with modulus equal to one.

## Stability of Fixed Points in Nonlinear Maps

Consider the map

$$x_{j+1} = f(x_j)$$

with a fixed point at  $x_j = x^*$ . A fixed point  $x^*$  of the map is *hyperbolic* if and only if  $|\lambda_i| \neq 1$  for all eigenvalues  $\lambda_i$  of the matrix  $Df(x^*)$ .

The fixed point is asymptotically stable if all  $|\lambda_i| < 1$ . If some  $|\lambda_i| < 1$  and some  $|\lambda_i| > 1$  the fixed point is a saddle. If all  $|\lambda_i| > 1$ , the fixed point is a source.