An Introduction to Bayesian Methods for Survival **Analysis**

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The Bayesian Paradigm

Begin with a probability model for your data given a set of unknown parameters $\boldsymbol{\theta}$, with corresponding likelihood function $L(\boldsymbol{\theta}|\text{data})$. Next, assume that $\boldsymbol{\theta}$ is random and has a prior distribution $\pi(\boldsymbol{\theta})$. The posterior distribution combining this prior distribution and observed data is obtained from Bayes' Theorem and has the form

$$\pi(oldsymbol{ heta}|\mathsf{data}) = rac{L(oldsymbol{ heta}|\mathsf{data})\pi(oldsymbol{ heta})}{\int_{\Theta} L(oldsymbol{ heta}|\mathsf{data})\pi(oldsymbol{ heta})doldsymbol{ heta}}$$

where Θ denotes the parameter space of $\boldsymbol{\theta}$. ¹

- Note: the denominator here is the marginal distribution of the data, which often does not have a closed form.
- Without this, it is difficult to analytically solve for $\pi(\boldsymbol{\theta}|\text{data})$.



The Bayesian Paradigm

¹Ibrahim, et al. (2001)

Connecting the Prior and Posterior

We can see that $\pi(\boldsymbol{\theta}|\text{data})$ is proportional to the likelihood $L(\boldsymbol{\theta}|\text{data})$ multiplied by the prior $\pi(\boldsymbol{\theta})$

$$\pi(\boldsymbol{\theta}|\mathsf{data}) \propto L(\boldsymbol{\theta}|\mathsf{data})\pi(\boldsymbol{\theta})$$

The posterior distribution receives contributions from the data and the prior through the likelihood and prior distributions, respectively.



MCMC Posterior Sampling

The Problem with Marginal Distributions

Marginal distributions and posteriors often do not have closed forms. Methods to overcome this and sample from the posterior distribution without knowing the marginal include Gibbs sampler and other Markov chain Monte Carlo sampling algorithms.

■ The idea in Gibbs sampling is to generate posterior samples by sweeping through each variable (or block of variables) to sample from its conditional distribution with the remaining variables fixed to their current values 2

²Yildirim (2012)



Gibbs Sampler

We have $\boldsymbol{\theta} = (\theta_1, \theta_2, \dots, \theta_p)'$ be a *p*-dimensional vector of parameters, and $\pi(\boldsymbol{\theta}|\text{data})$ is the posterior distribution of $\boldsymbol{\theta}$ given our data.

- Step 0. Choose an arbitrary starting point $\theta_0 = (\theta_{1,0}, \theta_{2,0}, \dots, \theta_{p,0})'$, and set i = 0.
- Step 1. Generate $\boldsymbol{\theta}_{i+1} = (\theta_{1,i+1}, \theta_{2,i+1}, \dots, \theta_{p,i+1})'$ as follows:
 - Generate $\boldsymbol{\theta}_{1,i+1} \sim \pi(\theta_1|\theta_{2,i},\ldots,\theta_{p,i},\mathsf{data})$
 - Generate $\boldsymbol{\theta}_{2,i+1} \sim \pi(\theta_2|\theta_{1,i+1},\theta_{3,i},\ldots,\theta_{p,i},\mathsf{data})$

 - Generate $\boldsymbol{\theta}_{p,i+1} \sim \pi(\theta_p|\theta_{1,i+1},\theta_{2,i+1},\dots,\theta_{p-1,i+1},\mathsf{data})$
- Step 2. Set i = i + 1, and go to Step 1. Repeat until distribution becomes apparent (n > 1000).



¹Ibrahim, et al. (2001)

Consider 20 subjects in an observational study. Denote the number dead due to natural causes as random variable $D \sim Bin(20,\theta)$. Suppose a previous study found that, on average, 40% of people die due to natural causes. Based on this, we impose a beta prior on θ , i.e. $\theta \sim Beta(a,b)$. We choose parameters a and b such that

$$E(\theta) = \frac{a}{a+b} = 0.40$$

This gives us a=4 and b=6. We want to be able to sample from the posterior distribution for θ |data.



Gibbs Sampler Example: Posterior Distribution

For a beta-binomial model, we have the following conjugate posterior

$$\pi(\theta|D) = \frac{f(d;\theta)\pi(\theta)}{f(d)}$$

$$= \frac{\binom{20}{d}\theta^d(1-\theta)^{20-d}\frac{\Gamma(4+6)}{\Gamma(4)\Gamma(6)}\theta^{4-1}(1-\theta)^{6-1}}{\binom{20}{d}\frac{\Gamma(4+6)}{\Gamma(4)\Gamma(6)}\frac{\Gamma(4+d)\Gamma(6+20-d)}{\Gamma(4+6+20)}}$$

$$= \frac{\Gamma(4+6+20)}{\Gamma(4+d)\Gamma(6+20-d)}\theta^{4+d-1}(1-\theta)^{26-d-1}$$

Which we recognize as posterior distribution $\theta | D \sim Beta(4+d,26-d)$.

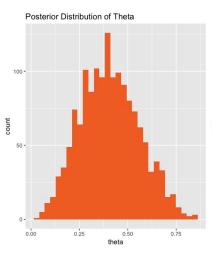


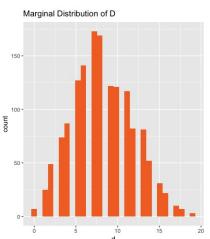
Gibbs Sampler Example: R Code³

```
n <- 20; a <- 4; b <- 6 #setup parameters
it <- 1500 #number of iterations
d <- rep(NA,it); theta <- rep(NA,it)</pre>
d[1] <- 1; theta[1] <- 0.5 # set arbitrary initial values
# Perform Gibbs iterations
for (i in 2:it)
{
  d[i] <- rbinom(1,size=n,prob=th[i-1])
  theta[i] \leftarrow rbeta(1,a+d[i],b+n-d[i])
}
```



³Huerta (2012)







Power Priors

The power prior is defined to be the likelihood function based on historical data raised to a power a_0 where $0 \le a_0 \le 1$.

• Scalar parameter a_0 controls the influence of the historical data on the current data.

The power prior distribution of θ is

$$\pi(oldsymbol{ heta}|\mathsf{data}_0,a_0)\propto L(oldsymbol{ heta}|\mathsf{data}_0)^{oldsymbol{a}_0}\pi_0(oldsymbol{ heta}|c_0)$$

- data₀: historical data from a similar previous study
- a_0 : relative precision parameter for historical data, data₀
- c_0 : a specified hyperparameter for the initial prior that controls the impact of $\pi_0(\boldsymbol{\theta}|c_0)$ on the entire prior $\pi(\boldsymbol{\theta}|data)$



- When $a_0 = 1$, the power prior distribution corresponds to the posterior distribution of θ from the historical study (no change for current study).
- When $a_0 = 0$, the power prior distribution does not depend on the historical data at all (i.e. no incorporation of historical data for current study).
- Thus, a_0 allows the investigator to select the influence of historical data on the current study.
 - Want a₀ closer to 1 when the studies are very similar.
 - Want a_0 closer to 0 when sample sizes are different or there is heterogeneity between studies.



Incorporate a prior for a_0 , $\pi(a_0|\gamma_0)$, into the prior for $\theta|data_0, a_0|$ to get

$$\pi(\boldsymbol{\theta}, a_0|\mathsf{data}_0) \propto L(\boldsymbol{\theta}|\mathsf{data}_0)^{a_0} \pi_0(\boldsymbol{\theta}|c_0) \pi(a_0|\boldsymbol{\gamma}_0)$$

where γ_0 is a specified vector of hyperparameters. A natural choice for $\pi(a_0|\gamma_0)$ is a beta prior.



Bayesian Parametric Models

Consider event times $X_i \stackrel{iid}{\sim} Expo(\lambda)$ for i = 1, ..., n. Define:

- lacksquare X_i : time on study for observation i
- δ_i : event indicator for observation i (= 0 if right censored, = 1 if event observed)
- T_i : time to event for observation i (if $\delta_i = 1$, $X_i = T_i$)
- C_i : time to right censoring for observation i (if $\delta_i = 0$, $X_i = C_i$)



Exponential Model: Likelihood

$$L(\lambda|\text{data}) = \prod_{i=1}^{n} f(x_{i}|\lambda)^{\delta_{i}} S(x_{i}|\lambda)^{1-\delta_{i}}$$

$$= \prod_{i=1}^{n} (\lambda \exp\{-\lambda x_{i}\})^{\delta_{i}} (\exp\{-\lambda x_{i}\})^{1-\delta_{i}}$$

$$= (\lambda \exp\{-\lambda x_{i}\})^{\sum_{i=1}^{n} \delta_{i}} (\exp\{-\lambda x_{i}\})^{n-\sum_{i=1}^{n} \delta_{i}}$$

$$= (\lambda^{\sum_{i=1}^{n} \delta_{i}} \exp\{-\sum_{i=1}^{n} \delta_{i} \lambda x_{i}\}) (\exp\{-(n-\sum_{i=1}^{n} \delta_{i}) \lambda x_{i}\})$$

$$= \lambda^{d} \exp\{-\lambda \sum_{i=1}^{n} x_{i}\} \text{ where we let } d = \sum_{i=1}^{n} \delta_{i}$$



For exponential event times, the conjugate prior is the gamma distribution: $\lambda \sim \text{Gamma}(\alpha_0, \lambda_0)$ with density

$$\pi(\lambda|\alpha_0,\lambda_0) \propto \lambda^{\alpha_0-1} \exp\{-\lambda_0 \cdot \lambda\}.$$



Based on this prior, we have posterior distribution for λ

$$egin{array}{lll} \pi(\lambda|\mathsf{data}) & \propto & L(\lambda|\mathsf{data})\pi(\lambda|lpha_0,\lambda_0) \\ & \propto & \left(\lambda^{\sum_{i=1}^n\delta_i}\exp\left\{-\lambda\sum_{i=1}^nx_i
ight\}
ight)\left(\lambda^{lpha_0-1}\exp(-\lambda_0\lambda)
ight) \\ & \propto & \lambda^{lpha_0+d-1}\exp\left\{-\lambda(\lambda_0+\sum_{i=1}^nx_i)
ight\} \end{array}$$

We recognize this as a $Gamma(\alpha_0 + d, \lambda_0 + \sum_{i=1}^n x_i)$ distribution.



Exponential Model: Posterior Mean and Variance

Based on the posterior $\lambda | \text{data} \sim \text{Gamma}(\alpha_0 + d, \lambda_0 + \sum_{i=1}^n x_i)$ we have the following estimates for the mean and variance of the parameter λ in $X_i \sim Expo(\lambda)$.

$$\blacksquare \mathsf{E}(\lambda|\mathsf{data}) = \frac{\alpha_0 + d}{\lambda_0 + \sum_{i=1}^n x_i}$$

$$extbf{Var}(\lambda|\mathsf{data}) = rac{lpha_0 + d}{(\lambda_0 + \sum_{i=1}^n x_i)^2}$$



Conclusion

- Historical data can be formally incorporated into the current analysis through a power prior.
- Model comparisons can be made between non-nested models, and without asymptotic assumptions, via Bayes Factors,

$$BF_{\text{model A,model B}} = \frac{P(\text{data}|\text{model A})}{P(\text{data}|\text{model B})}$$

 MCMC sampling techniques allow us to make exact inference for any sample size without relying on asymptotic approximations.



Questions?

References

- 1 Ibrahim, Joseph George, et al. Bayesian Survival Analysis. Springer, 2010.
- 2 Yildirim, Ilker. Bayesian Inference: Gibbs Sampling. 2012, Bayesian Inference: Gibbs Sampling.
- 3 Huerta, Gabriel. Some Examples on Gibbs Sampling and Metropolis-Hastings methods. 2012, Some Examples on Gibbs Sampling and Metropolis-Hastings methods.