

Compilation (#8):

Register Allocation + Data Flow Analyses

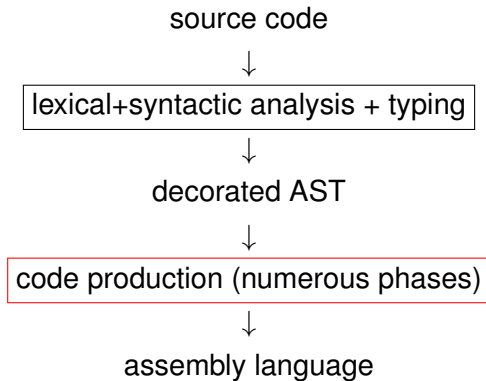
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Where are we ?



- We work on IRs (Middle-end).

- 1 Register allocation - Intro
- 2 Live-range Information: Liveness Analysis
- 3 Register Allocation with graph coloring

Credits

Fernando Pereira's course on register allocation:

[http://homepages.dcc.ufmg.br/~fernando/classes/dcc888/ementa/slides/
RegisterAllocation.pdf](http://homepages.dcc.ufmg.br/~fernando/classes/dcc888/ementa/slides/RegisterAllocation.pdf)

What for ?

- Finding storage locations to the values manipulated by the program ► registers or memory.
 - registers are fast but in small quantity.
 - memory is plenty, but slower access time.
- A good register allocator should strive to keep in registers the variables used more often.

"Because of the central role that register allocation plays, both in speeding up the code and in making other optimizations useful, it is one of the most important - if not the most important - of the optimizations."



Hennessy and Patterson (2006) - [Appendix B; p. 26]

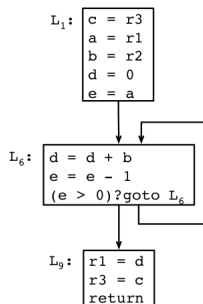
What for?

Expected behavior of **register allocation**:

- Input: a CFG with basic blocks with 3-address code (and pseudo-registers, aka temporaries)
- Output: same CFG but without temporaries:
 - replace with physical registers as much as possible.
 - if not **spill**, ie allocate a place in memory.
 - all copies assigned to the same physical registers (“moves”) can be removed: **coalescing** (**optional**).

Register constraints

Some variable are assigned to some specific registers (compiler, architecture constraints)



► r1,r2,r3 are used to pass function arguments here (thus should be reserved in the allocation)

The key notion: liveness

Observation

Two variables that are simultaneously **alive** must be assigned different registers.

(formal definition of alive follows)

Register assignment is NP-complete

Problem to solve

Given P a program and K general purpose registers, is there an assignment of the variables P in registers, such that (i) every variable gets at least one register along its entire live range, and (ii) simultaneously live variables are given different registers ?

Gregory Chaitin has shown, in the early 80's, that the register assignment problem is NP-Complete (register allocation via coloring, 1981)

3-phase algorithm

- **Liveness analysis**

- When is a given value necessary for the rest of the computation?

- **Interference graph**

- A graph that encodes which temporaries cannot be mapped to the same location.

- **Graph coloring** then register allocation.

- The effective allocation: physical registers and stack allocation for temporaries.

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Liveness analysis

In the sequel we call **variable** a temporary or a physical register.

Definition (Alive Variable)

In a given program point, a variable is said to be alive if the value it contains may be used in the rest of the execution.

“May”, and non-decidable property \Rightarrow overapproximation.

Important remark: here a block = a statement/program point. We have the same kind of analyses with block=basic block.

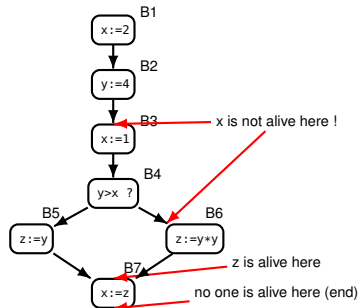
An example for live ranges

Definition

A variable is **live** at the exit of a block if there exists a path from the block to a use of the variable that does not redefine the variable.

```

x:=2;
y:=4;
x:=1;
if (y>x)
    then z:=y
    else z:=y*y ;
      x:=z;
  
```



► The information flow is **backward**: from uses to definitions.

Data flow expressions

Definition

A variable that appears on the left hand side of an assignment is **killed** by the block. Tests do not kill variables.

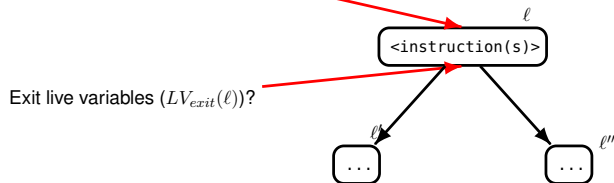
Definition

A **generated** variable is a variable that appears in the block (read-only!)

- We precompute the sets : $kill_{LV}(block)$ and $gen_{LV}(block)$ for all blocks.

Dataflow equations

Entry live variables ($LV_{entry}(\ell)$)?



$$LV_{exit}(\ell) = \begin{cases} \emptyset & \text{if } \ell \text{ is final} \\ \bigcup_{\ell' \in succ_G(\ell)} LV_{entry}(\ell') & \text{else} \end{cases}$$

$$LV_{entry}(\ell) = (LV_{exit}(\ell) \setminus kill_{LV}(\ell)) \cup gen_{LV}(\ell)$$

Dataflow equations: solving

Important Remark

Fixpoint equations $X = F(X)$!

Here:

- Initialise LV sets to \emptyset .
 - Compute LV_{entry} sets, then LV_{exit} , and continue.
 - Stop when a fix point is reached.
- (vector of) Sets are strictly growing, and the live range set is at most the set of all variables, thus **this algorithm terminates**.

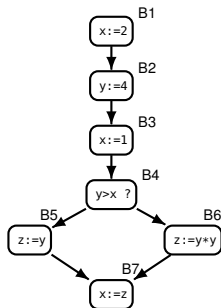
Steps

$LV_{entry}(\ell)$ denoted by $In(\ell)$, $LV_{exit}(\ell)$ by $Out(\ell)$ initialisation to emptysets is not depicted.

			Step 1		Step 2		Step 3 (stable)
ℓ	$kill(\ell)$	$gen(\ell)$	$In(\ell)$	$Out(\ell)$	$In(\ell)$	$Out(\ell)$	$In(\ell)$
1	$\{x\}$	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset
2	$\{y\}$	\emptyset	\emptyset	\emptyset	\emptyset	$\{y\}$	\emptyset
3	$\{x\}$	\emptyset	\emptyset	$\{x, y\}$	$\{y\}$	$\{x, y\}$	$\{y\}$
4	\emptyset	$\{x, y\}$	$\{x, y\}$	$\{y\}$	$\{x, y\}$	$\{y\}$	$\{x, y\}$
5	$\{z\}$	$\{y\}$	$\{y\}$	$\{z\}$	$\{y\}$	$\{z\}$	$\{y\}$
6	$\{z\}$	$\{y\}$	$\{y\}$	$\{z\}$	$\{y\}$	$\{z\}$	$\{y\}$
7	$\{x\}$	$\{z\}$	$\{z\}$	\emptyset	$\{z\}$	\emptyset	$\{z\}$

Final result and use

Backward analysis and we want the smallest sets, here is the final result : (we assume all vars are dead at the end).



ℓ	$LV_{entry}(\ell)$	$LV_{exit}(\ell)$
1	\emptyset	\emptyset
2	\emptyset	$\{y\}$
3	$\{y\}$	$\{x, y\}$
4	$\{x, y\}$	$\{y\}$
5	$\{y\}$	$\{z\}$
6	$\{y\}$	$\{z\}$
7	$\{z\}$	\emptyset

► Use : Dead code elimination !

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Step 2: Interferences

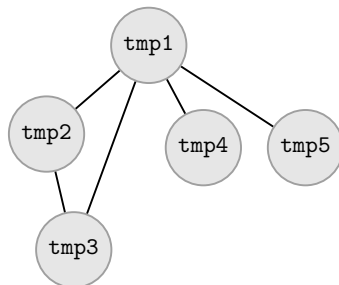
Here is the output of the liveness analysis for $a + (b + c)$:

	<i>tmp1</i>	<i>tmp2</i>	<i>tmp3</i>	<i>tmp4</i>	<i>tmp5</i>	<i>tmp6</i>
load <i>tmp1</i> , <i>la</i>						
load <i>tmp2</i> , <i>lb</i>						
load <i>tmp3</i> , <i>lc</i>						
ADD <i>tmp4</i> , <i>tmp2</i> , <i>tmp3</i>						
MV <i>tmp5</i> , <i>tmp4</i>						
ADD <i>tmp6</i> , <i>tmp1</i> , <i>tmp5</i>						
⋮						

- *tmp1* is in conflict with *tmp2* (because of instruction 3) denoted by $tmp_1 \bowtie tmp_2$.

Interference graph

The relation \bowtie defines a conflict/interference graph:



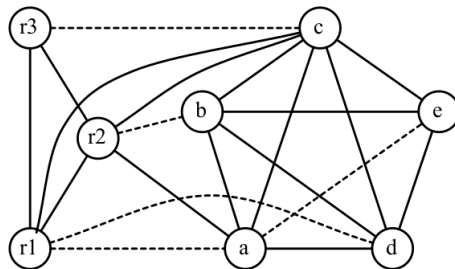
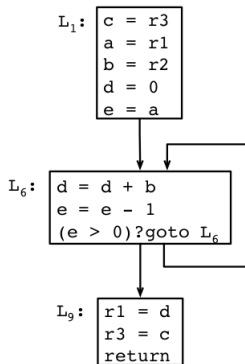
We want a **correct allocation** with respect to \bowtie :

$$tmp_1 \bowtie tmp_2 \implies Alloc(tmp_1) \neq Alloc(tmp_2).$$

► Graph coloring.

Running example

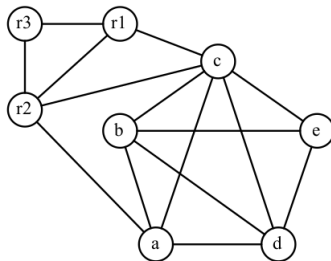
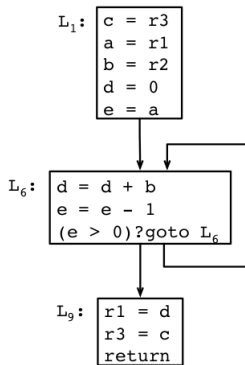
Important: in this example consider the r_i as temporary registers, like the others.



Dashed edges represent moves!

Running example

Important: in this example consider the r_i as temporary registers, like the others.



Let's look at the graph without moves first

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Kempe's simplification algorithm 1/2

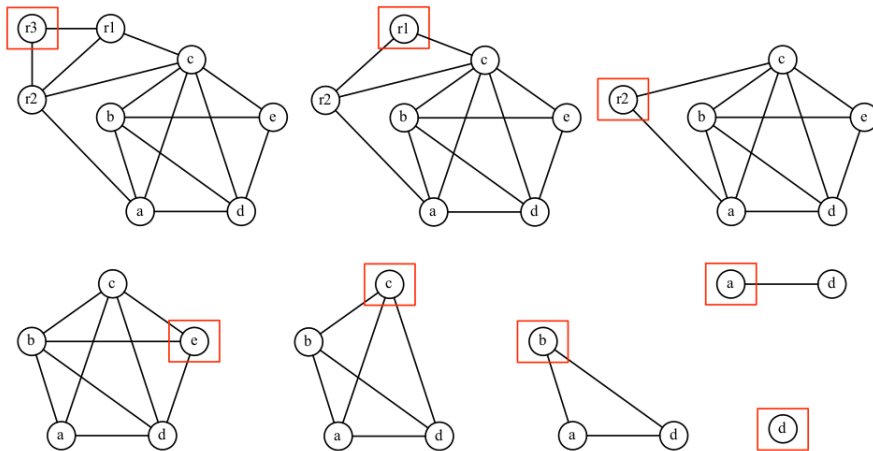
On the interference graph (without coalesce edges):

Proposition (Kempe 1879)

Suppose the graph contains a node m with fewer than K neighbours. Then if $G' = G \setminus \{m\}$ can be K -colored, then G can be K -colored as well.

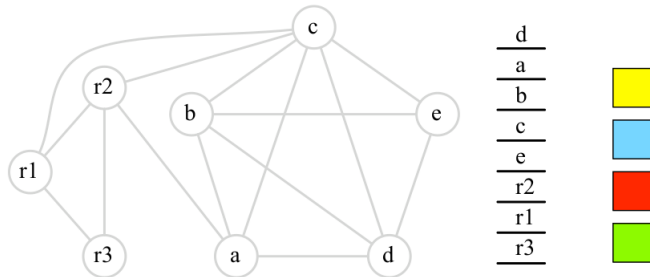
► Pick a low degree node, and remove it, and continue until remove all (the graph is K -colorable) or ...

Kempe's simplification algorithm 2/2

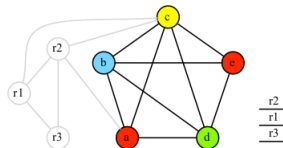
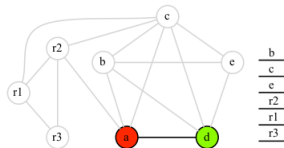
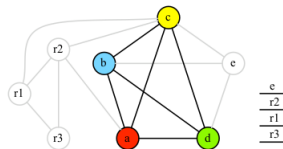
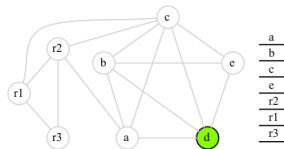
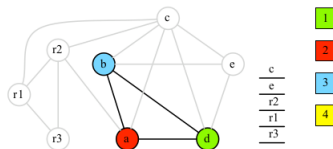
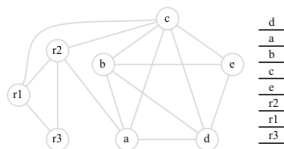


Let's color! (“Kempe’s heuristic”)

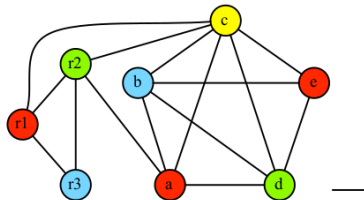
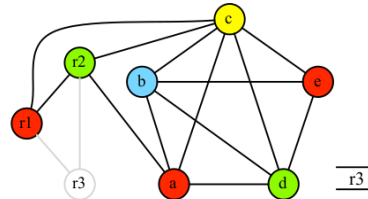
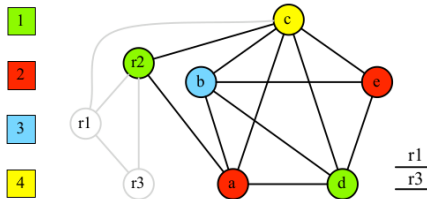
- We assign colors to the nodes greedily, in the reverse order in which nodes are removed from the graph.
- The color of the next node is the first color that is available, i.e. not used by any neighbour.



Greedy coloring example 1/2



Greedy coloring example 2/2



On the number of colors (K)

In the last example, we chose $K=4$, and this is nice, because the graph is 4-colorable.

- The given heuristic may fail to color the graph with K colors: it doesn't mean that the graph is not K -colorable (**heuristic!**).
- We can chose:
 - either to eliminate the “non-colorable node” of the graph and continue with the other nodes inside the node stack.
 - either to augment the K parameter.

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Recall memories - Final code generation

With a 3 address code + allocation, rewrite each 3 address instruction into “real code”:

- Each temporary is rewritten into his allocated physical register.
- If the temporary is in memory (Spilling), we generate code with appropriate loads and stores.

If the graph was not successfully colored

Non-colored variables¹ are named **spilled temporaries**.
There are many solutions to handle spilled variables.

¹either not colored at all or colored with number $>K$

A naive solution: also color memory!

- Launch the coloration algorithm with an infinite number of colors:
 - first colors are mapped to registers (used in priority by the coloring algorithm)
 - other colors are mapped to offsets in the stack, i.e. spilled to memory
- Drawback: we need a few registers to implement the spilling

More sophisticated: Live range splitting

Idea: Modify the code to lower the number of simultaneously alive registers.
Invent 2 versions of the same variable (**live-range splitting**), and modify the code into:

```
ADD temp51, temp4, temp3
STORE temp51, [locationinmemory] # replace with actual location
..
LOAD temp52, [locationinmemory] #same
ADD temp6, temp52, #5
```

► But now we have to allocate these two new variables!

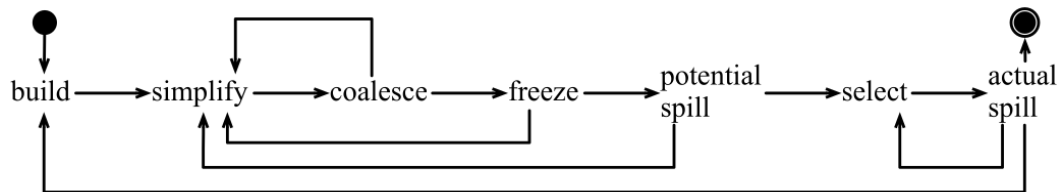
We relaunch the coloring algorithm. This is called **Iterative Register Allocation**.

To go further: Iterative Register Coalescing²

Two new optimizations to improve register allocation further

- 1 Register coalescing
- 2 Clever spilling

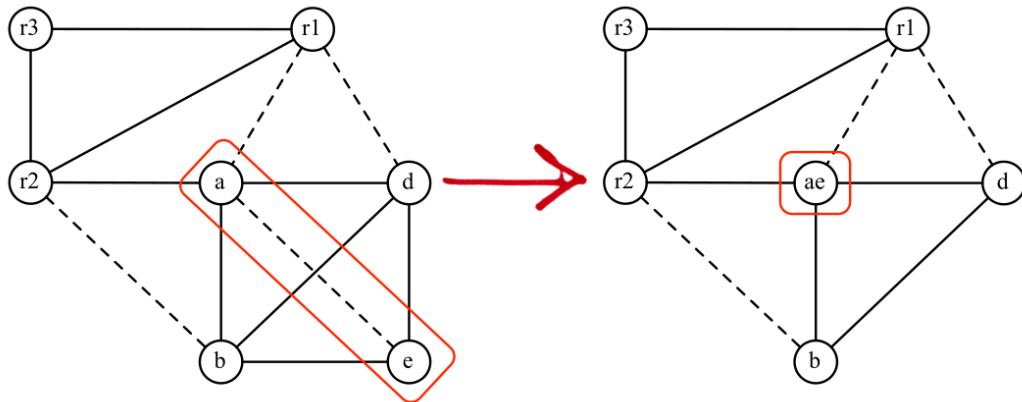
An iterative algorithm with many steps:



²Iterated Register Coalescing, TOPLAS (1996)

Iterative Register Coalescing – Coalescing

Coalescing consists of collapsing two move related nodes together

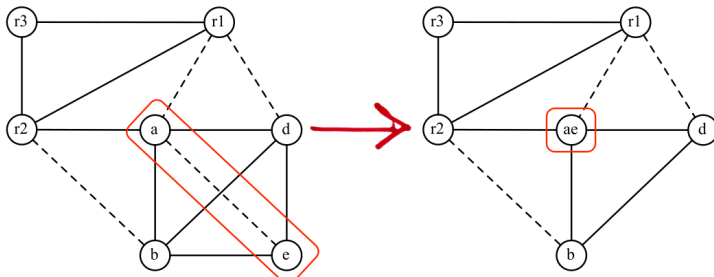


Iterative Register Coalescing – Coalescing

Two heuristics for coalescing safely:

Briggs Nodes a and b can be coalesced if the resulting node ab will have fewer than K neighbors of high degree (i.e., $\text{degree} \geq K$ edges)

George Nodes a and b can be coalesced if, for every neighbor t of a , either t already interferes with b , or t is of low degree.



Iterative Register Coalescing – Spilling

- ▶ How to choose which variables to spill ? This is actually really hard:
 - We want to spill variables that are less used dynamically
 - We only have static information

We can use a heuristic:

`SPILLCOST(v)`

`cost = 0`

`foreach definition or use in block B`

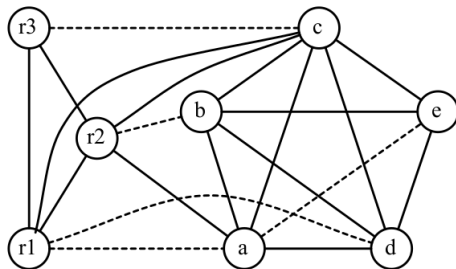
`cost += 10N/D, where`

`N is B's loop nesting factor`

`D is v's degree in the interference graph`

Other Algorithms

- **Linear scan**: greedy coloring of interval graphs. (see Fernando Pereira's slides on register allocation: 18 to 35)
- Plenty of other heuristics for spilling.



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