

Due: *Tue Nov 23*

You may paste screenshot of output to cover these tables (instead of filling them).

Rec (%)	Title

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$$P\left(\left\{R_j=r_j^{(t)}\right\}_{j\in\Omega_t}\right) =$$
$$P\left(Z=i\left|\left\{R_j=r_j^{(t)}\right\}_{j\in\Omega_t}\right.\right)=$$

(d) **M-step**

(e) **Implementation**

iteration	log-likelihood \mathcal{L}
0	-27.0358
1	-17.5604
2	
4	
8	
16	-14.2638
32	
64	
128	
256	

(f) **Personal movie recommendations**

(g) **Source code**

8.2 Mixture model decision boundary

(a) **Posterior probability**

$$P(y = 1|\vec{x}) =$$

(b) **Decision boundary**

(c) **Shifting hyperplane**

8.3 Gradient ascent versus EM

(a) **Log likelihood**

(b) **Gradient**

(c) **Noisy-OR**

(d) **Chain rule**

(e) **Gradient ascent versus EM**

8.4 Similarity learning with logistic regression

(a) **Inference for similar examples**

(b) **Inference for dissimilar examples**

(c) **E-Step**

$$(\quad) \quad P(y = 1 | \vec{x}, \vec{x}', s = 1) \quad =$$

$$(\quad) \quad P(y' = 1 | \vec{x}, \vec{x}', s = 1) \quad =$$

$$(\quad) \quad P(y = 1 | \vec{x}, \vec{x}', s = 0) \quad =$$

$$(\quad) \quad P(y' = 1 | \vec{x}, \vec{x}', s = 0) \quad =$$

(d) **Log-likelihood**

(e) **M-step**

8.5 Logistic regression across time

(a) Likelihood

$$\alpha_{j,t+1} =$$

(b) Most likely hidden states

$$\ell_{j,t+1}^* =$$

(c) Prediction

$$\begin{array}{l} \text{for } t = 1 \text{ to } T-1 \\ \quad \text{for } j = 0 \text{ to } 1 \\ \qquad \Phi_{t+1}(j) = \operatorname{argmax}_{i \in \{0,1\}} \left[\right. \\ \text{for } t = T-1 \text{ to } 1 \\ \quad y_t^* = \left[\right. \end{array}$$