

# MAT 417 - Lesson 22 - Extra Credit

Jacob Kutch

April 2020

## 1

Transform the vibrating string problem (22.5) into dimensionless form (22.6) by means of the transformations

$$\xi = \frac{x}{L}, \quad \tau = \frac{\alpha t}{L} \quad (1)$$

Equation 22.5:

$$\text{PDE} \quad u_{tt} = \alpha^2 u_{xx}, \quad 0 < x < L, \quad 0 < t < \infty$$

$$\text{BCs} \quad \begin{cases} u(0, t) = 0, & 0 < t < \infty \\ u(L, t) = 0 \end{cases}$$

$$\text{ICs} \quad \begin{cases} u(x, 0) = \sin(\frac{\pi x}{L}) + 0.5 \sin(\frac{3\pi x}{L}) \\ u_t(x, 0) = 0, & 0 \leq x \leq L \end{cases}$$

First, transforming the boundaries, we see that  $0 < L\xi < L \Rightarrow 0 < \xi < 1$  in the PDE and  $0 \leq \xi \leq 1$  in the IC.

Also, the time interval becomes  $0 < \frac{L\tau}{\alpha} < \infty \Rightarrow 0 < \tau < \infty$  in the PDE. The BCs become

$$u(0, t) = 0 \Rightarrow u(0, \frac{L\tau}{\alpha}) = 0 \Rightarrow u(0, \tau) = 0 \text{ since both are equal to 0.}$$

and

$$u(L, t) = 0 \Rightarrow u(1, \tau) = 0 \text{ since again, the BC is equal to 0.}$$

Similarly, the first IC may be transformed to

$$u(x, 0) = \sin\left(\frac{\pi x}{L}\right) + 0.5\sin\left(\frac{3\pi x}{L}\right) \Rightarrow u(\xi, 0) = \sin(\pi\xi) + 0.5\sin(3\pi\xi)$$

since we may substitute the  $\frac{x}{L}$  part for  $\xi$  in the parameter list of each term

Since  $\xi$  is a function of  $x$  and  $\tau$  is a function of  $t$ , and we want to transform  $u(x, t)$  into dimensionless form  $u(\xi(x), \tau(t))$ , we know that the derivatives of the new problem can be found with the chain rule.

$$u_t = \frac{d\tau}{dt} u_\tau \Rightarrow u_t = \left(\frac{\alpha}{L}\right) u_\tau \Rightarrow u_\tau = \frac{L}{\alpha} u_t$$

$$u_{tt} = \frac{\alpha}{L} \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial \tau} \right) = \frac{\alpha}{L} \left( \frac{\partial^2 u}{\partial \tau^2} \left( \frac{d\tau}{dt} \right) \right) = \frac{\alpha^2}{L^2} u_{\tau\tau} \text{ by substitution}$$

Then the derivative w.r.t  $x$  can be found in the same manner.

$$u_x = \frac{d\xi}{dx} u_\xi \Rightarrow u_x = \left(\frac{1}{L}\right) u_\xi \Rightarrow u_\xi = \frac{u_x}{L}$$

$$u_{xx} = \frac{1}{L} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial \xi} \right) = \frac{1}{L} \left( \frac{\partial^2 u}{\partial \xi^2} \left( \frac{d\xi}{dx} \right) \right) = \frac{1}{L^2} u_{\xi\xi}$$

Lastly, the second IC can now be found with  $u_t$ ,

$$u_t(x, 0) = 0 \Rightarrow u_t(x, 0) = \frac{\alpha}{L} u_\tau(\xi, 0) = 0 \Rightarrow u_\tau(\xi, 0) = 0$$

Now substitutions produce the dimensionless form, (Equation 22.6)

$$\textbf{PDE} \quad u_{\tau\tau} = u_{\xi\xi}, \quad 0 < \xi < 1, \quad 0 < \tau < \infty$$

$$\textbf{BCs} \quad \begin{cases} u(0, \tau) = 0, & 0 < \tau < \infty \\ u(1, \tau) = 0 \end{cases}$$

$$\textbf{ICs} \quad \begin{cases} u(\xi, 0) = \sin(\pi\xi) + 0.5\sin(3\pi\xi) \\ u_\tau(\xi, 0) = 0, & 0 \leq \xi \leq 1 \end{cases}$$

## 2

Find the dimensionless formulation for the problem

$$\begin{aligned}
 \text{PDE} \quad & u_t = \alpha^2 u_{xx}, \quad 0 < x < L \\
 \text{BCs} \quad & \begin{cases} u(0, t) = T_1, & 0 < t < \infty \\ u(L, t) = 0 \end{cases} \\
 \text{ICs} \quad & u(x, 0) = T_2, \quad 0 \leq x \leq L
 \end{aligned}$$

since  $u(x, t)$  is a linear, finite wave equation, using Lagrange interpolation on the boundary conditions to produce a change of variables.

$$w(x, t) = \frac{u(x, t) - T_1}{0 - T_1} \Rightarrow \frac{u(x, t) - T_1}{-T_1} \quad (2)$$

Since the given length is  $L$ , we can use  $\xi = \frac{x}{L}$  for the dimensionless unit of length. Similarly,  $\tau = \frac{\alpha^2 t}{L^2}$  for the dimensionless unit of time. Now the system is

Now by substitution, the BCs and IC become

$$w(0, t) = 0 \Rightarrow w(0, \tau) = 0$$

$$w(L, t) = 1 \Rightarrow w(1, t) = 1$$

$$w(\xi, 0) = \frac{T_2 - T_1}{-T_1}$$

$$\begin{aligned}
 w_x &= \frac{u_x}{-T_1} \Rightarrow w_\xi = \frac{u_\xi}{-LT_1} \\
 w_{xx} &= \frac{u_{xx}}{-T_1} \Rightarrow w_{\xi\xi} = \frac{u_{\xi\xi}}{-L^2T_1} \\
 w_t &= \frac{u_t}{-T_1} \Rightarrow w_\tau = \frac{L^2 u_\tau}{-\alpha^2 T_1} \\
 w_{tt} &= \frac{u_{tt}}{-T_1} \Rightarrow w_{\tau\tau} = \frac{L^2 u_{\tau\tau}}{-\alpha^2 T_1}
 \end{aligned}$$

Letting the interval be defined by the change of variables, we have  $0 < \xi < 1$  in the PDE and  $0 \leq \xi \leq 1$  in the IC.

Also, the time interval becomes  $0 < \tau < \infty$  in the PDE. So we know the problem becomes

$$\mathbf{PDE} \quad u_\tau = u_{\xi\xi}, \quad 0 < \xi < 1, \quad 0 < \tau < \infty$$

$$\mathbf{BCs} \quad \begin{cases} w(0, t) = 0 \Rightarrow w(0, \tau) = 0 & 0 < \tau < \infty \\ w(L, t) = 1 \Rightarrow w(1, t) = 1 \end{cases}$$

$$\mathbf{ICs} \quad w(\xi, 0) = \frac{T_2 - T_1}{-T_1}, 0 \leq \xi \leq 1$$