

CameraPoseEstimator  
::calcCameraPose



```
graph LR; A[CameraPoseEstimator::calcCameraPose] --> B[triangulate]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'CameraPoseEstimator' on the top line and '::calcCameraPose' on the bottom line. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'triangulate'.

triangulate