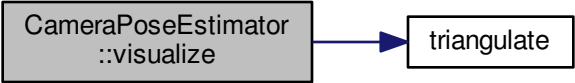


CameraPoseEstimator
::visualize



```
graph LR; A[CameraPoseEstimator::visualize] --> B[triangulate]
```

A diagram illustrating a function call. On the left, a gray rectangular box with a black border contains the text "CameraPoseEstimator" on the top line and "::visualize" on the bottom line. A dark blue arrow points from the right side of this box to a white rectangular box with a black border on the right. This second box contains the text "triangulate".

triangulate