

# .NET Conference 2016

## Spain

# 50 piezas de Lego

No recomendada para mayores de 18 años

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Patrocinadores

alTRan

avanade®

Danysoft  
Haciendo visible lo invisible

DevsDNA

encamina  
PIENSA EN COLORES

ilitia  
technologies

Insight

intelequia  
SOFTWARE SOLUTIONS

plain concepts

SOGETI

東京' TOKIOTA

Colaboradores

pue

ticjob.es

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# Agenda



Lego Mindstorms



¿Es solo un juego de niños?



¡Todos queremos jugar!



DEMO

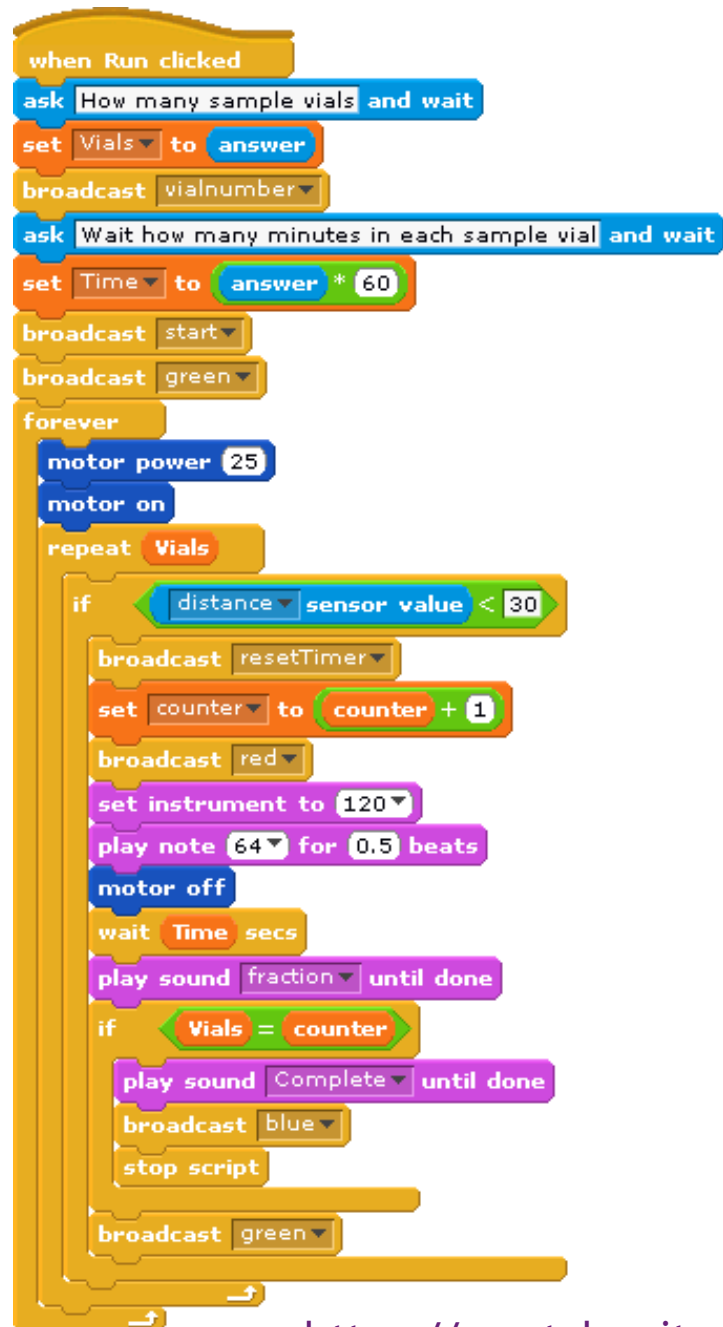


Otros detalles técnicos

¿Quién no ha querido  
un Lego de pequeño?

# Lego WeDo

Para niños  
de 7 a 11 años



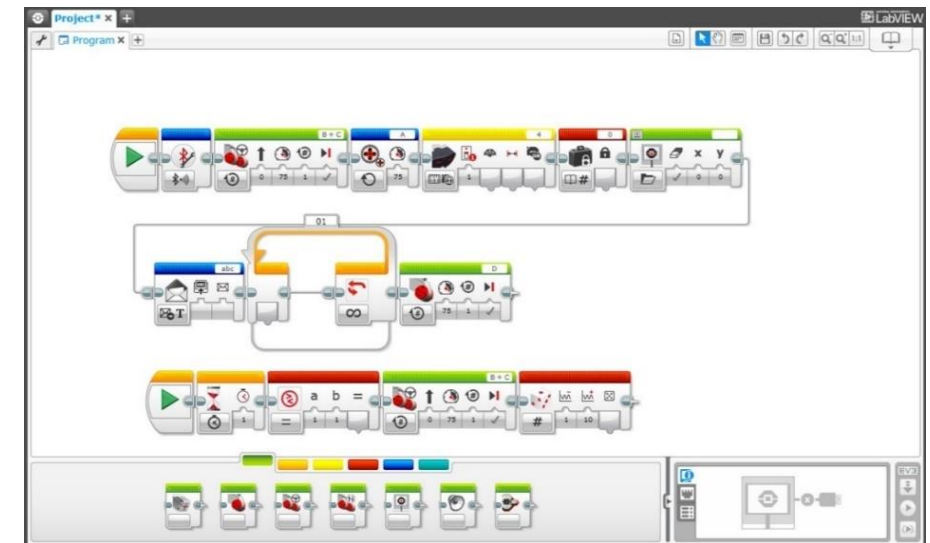
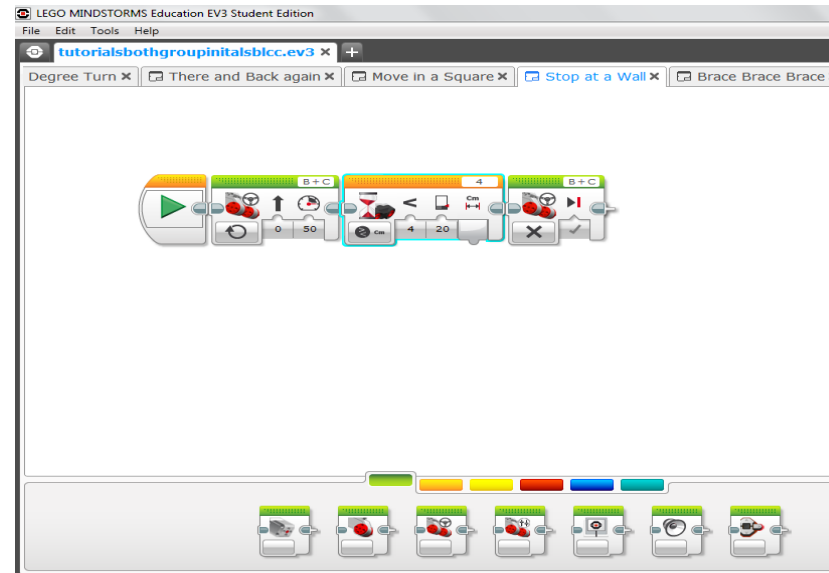
<https://scratch.mit.edu/>



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# Lego MindStorms

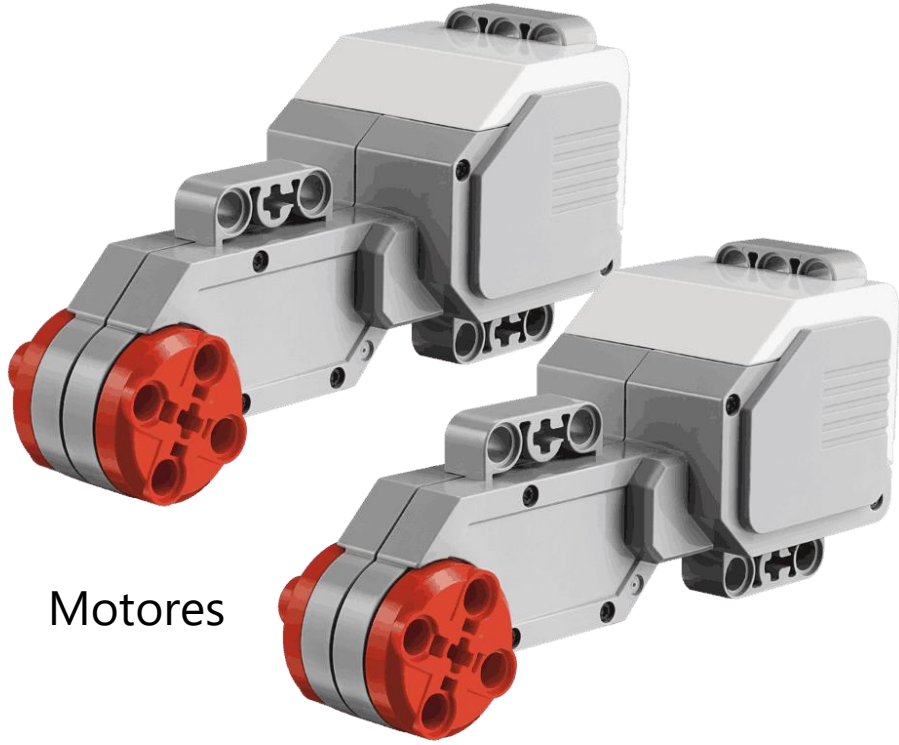
A partir de 10 años



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# Lego MindStorms



Motores



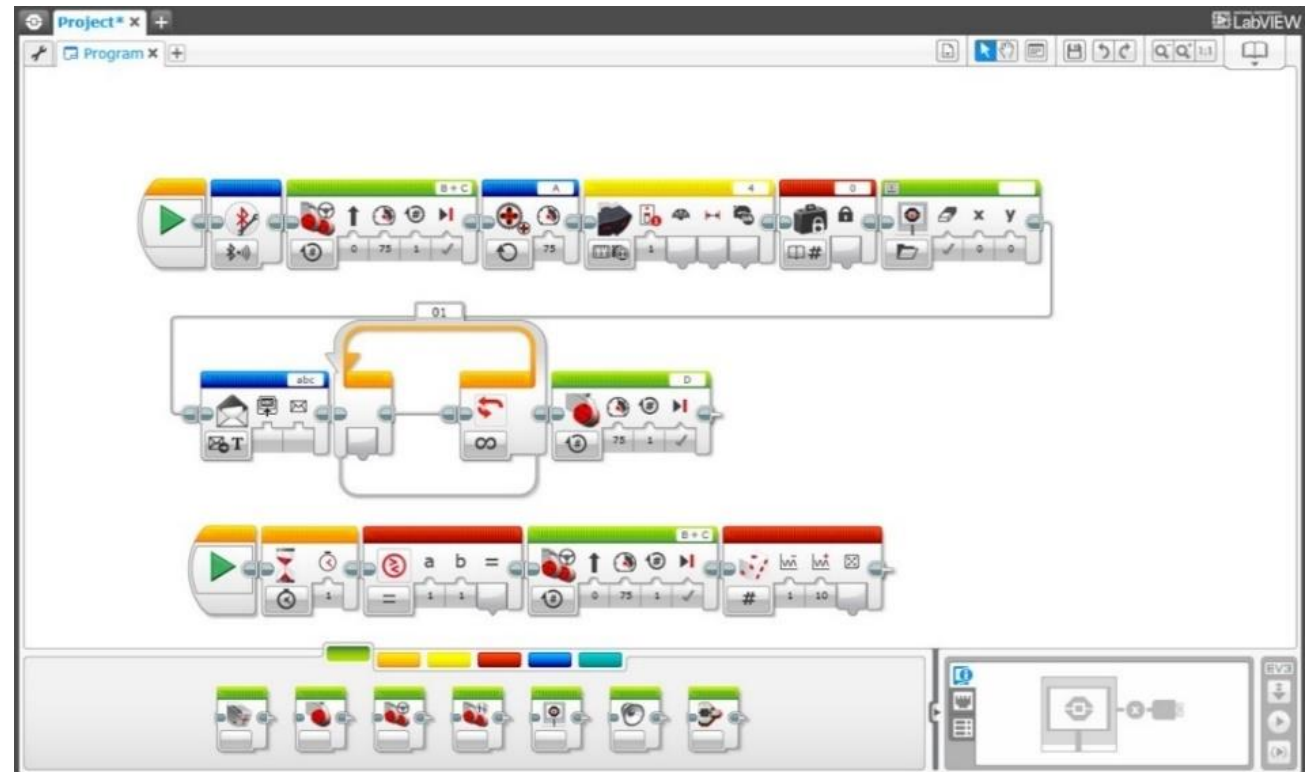
IR



Brick

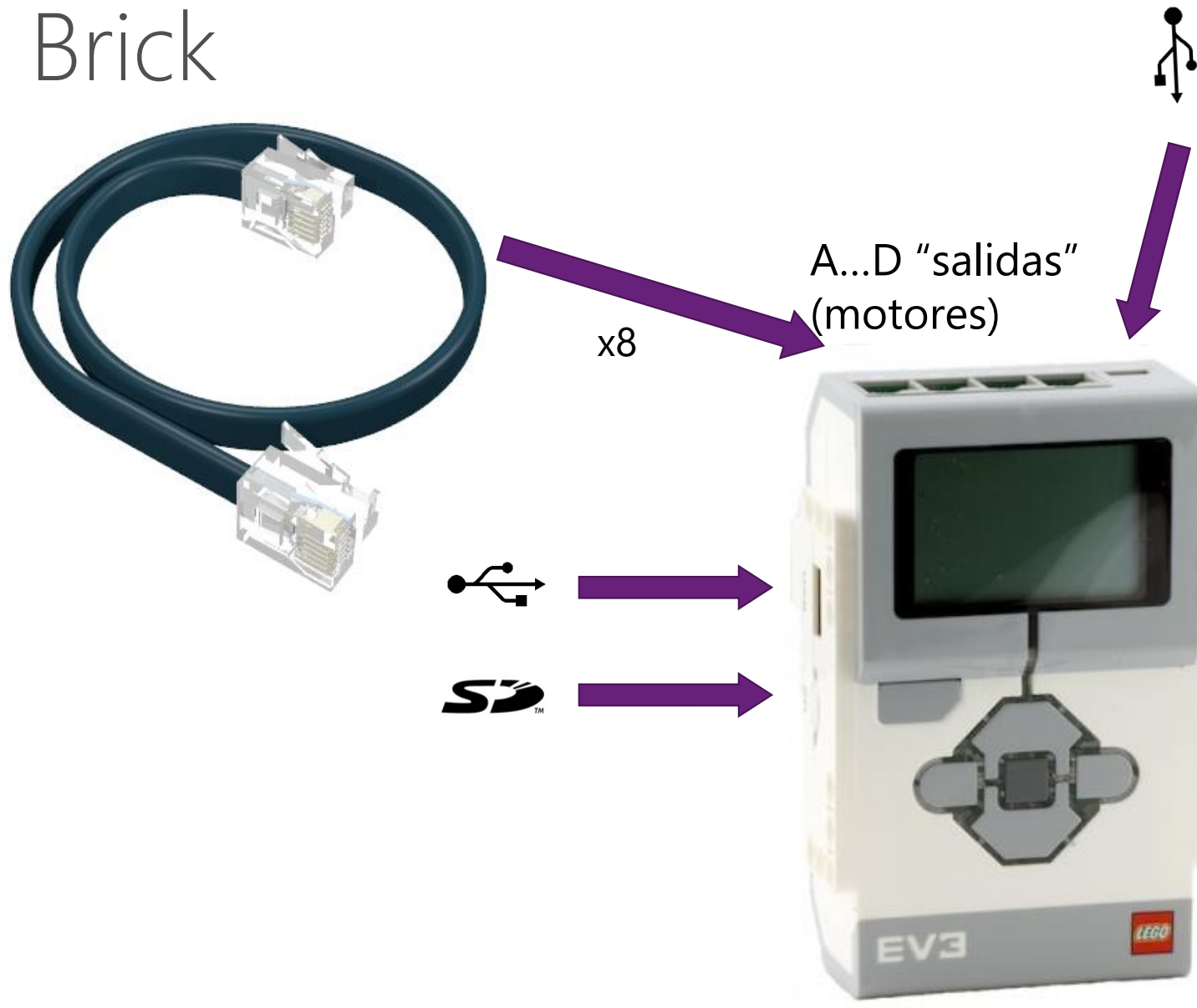
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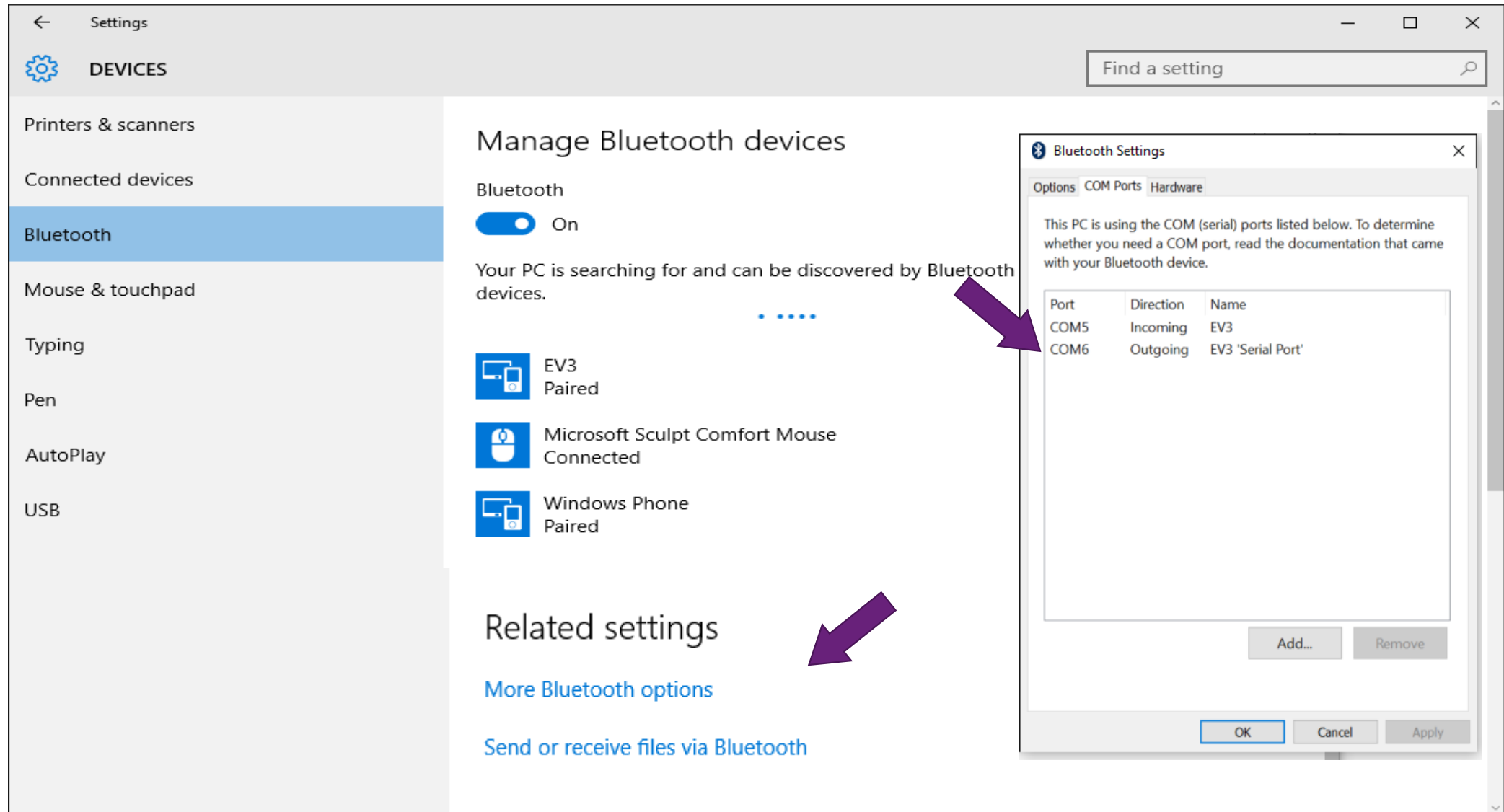
# El Brick



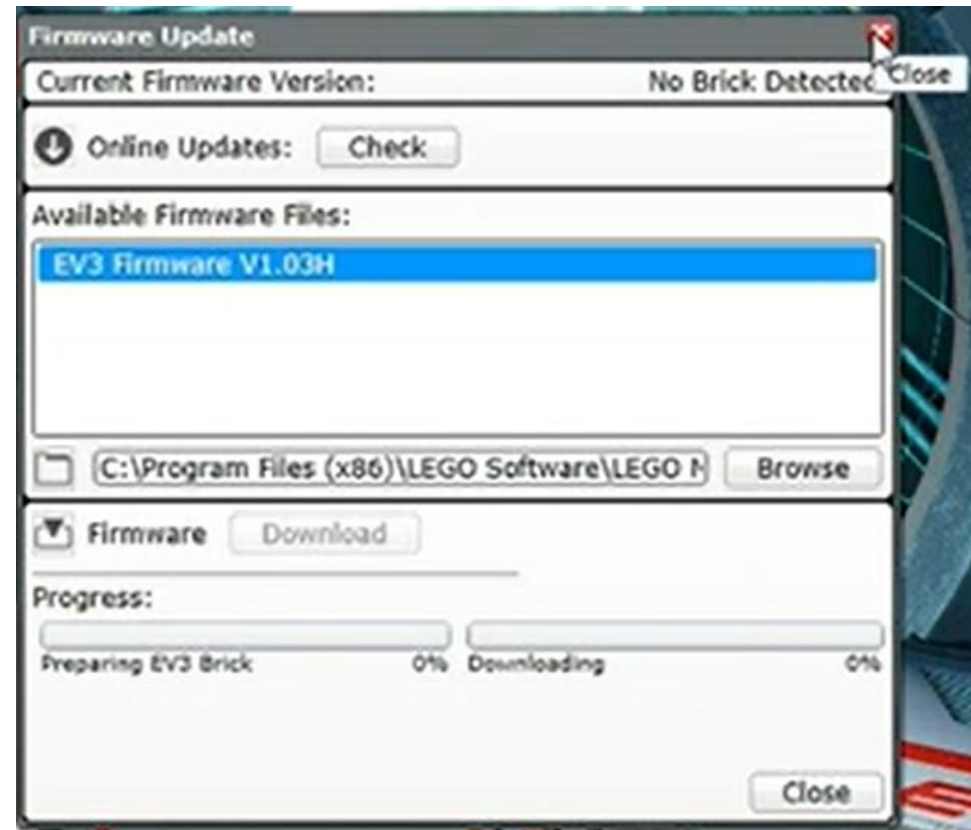
1...4 "entradas"  
para sensores

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# Conectar por BT desde Windows 10



# No olvides actualizar el firmware



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# Para empezar...



Crear un proyecto nuevo WPF

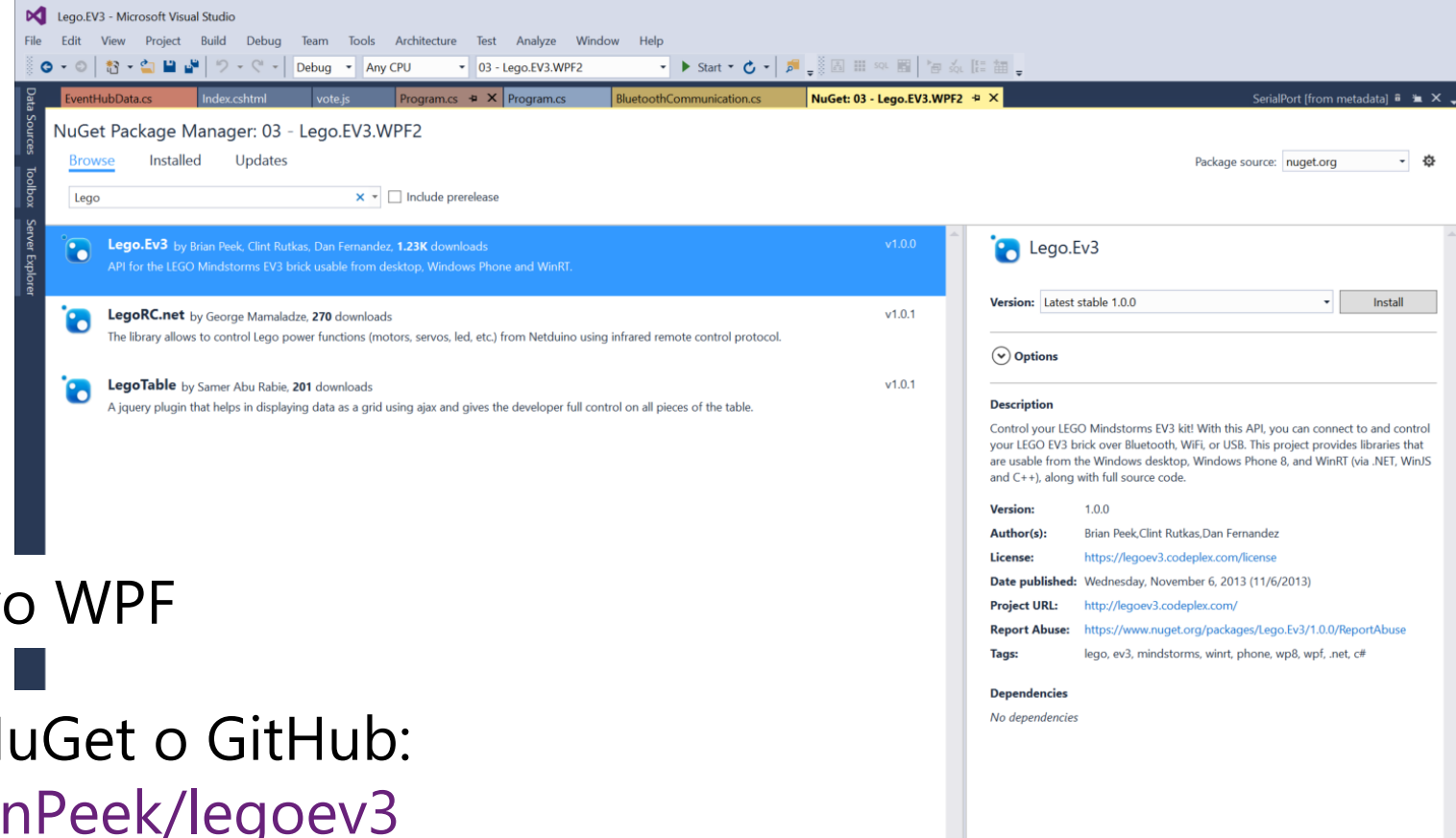


Descargar SDK desde NuGet o GitHub:  
<https://github.com/BrianPeek/legoev3>



Using it!

```
using System.Windows.Navigation;  
using System.Windows.Shapes;  
using Lego.Ev3.Core;  
using Lego.Ev3.Desktop;
```



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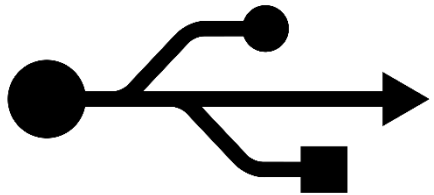
# Conectar con nuestro robot



System.IO.Ports

SerialPort : Component

```
public BluetoothCommunication(string port)
{
    _serialPort = new SerialPort(port, 115200);
}
```



```
connect()
disconnect()
SerialPortDataReceived()
WriteAsync()
```



(Accesorio no incluido)

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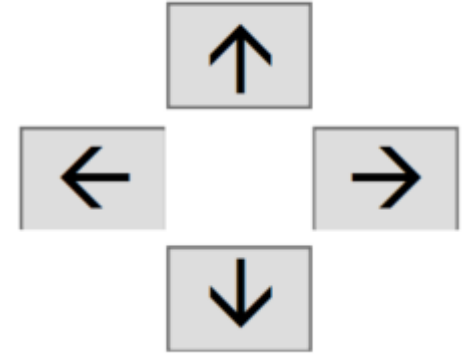


# Hello Piiiiiiiiiiiiiiiiiiiiiii!

```
Brick _brick;
```

```
_brick = new Brick(new BluetoothCommunication("COM6"));  
_brick.BrickChanged += _brick_BrickChanged;  
await _brick.ConnectAsync();  
await _brick.DirectCommand.PlayToneAsync(100, 3, 300);
```

# Motores

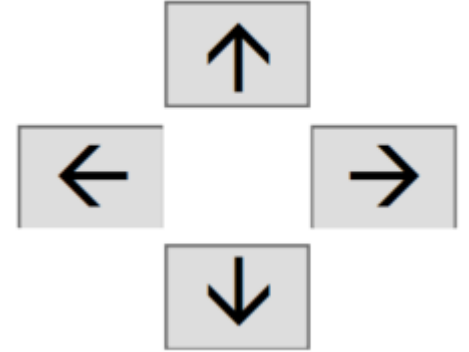


```
private void ForwardButton_Click(object sender, RoutedEventArgs e){  
    _brick.DirectCommand.TurnMo  
}
```

- TurnMotorAtPowerAsync
- TurnMotorAtPowerForTimeAsync
- TurnMotorAtSpeedAsync
- TurnMotorAtSpeedForTimeAsync

(awaitable) Task DirectCommand.TurnMotorAtPowerAsync(OutputPort ports, int power)  
Turn the motor connected to the specified port or ports at the specified power.  
Usage:  
await TurnMotorAtPowerAsync(...);

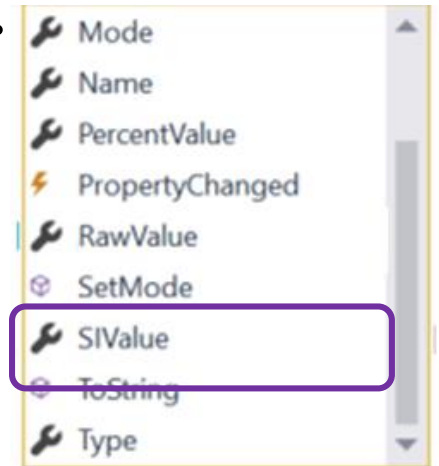
# Motores



```
private void ForwardButton_Click(object sender, RoutedEventArgs e) {  
    _brick.DirectCommand.TurnMotorAtPowerForTimeAsync(  
        OutputPort.B | OutputPort.C, _forward, _time, false);  
}
```

# Hello Sensors!

```
private void brick_BrickChanged(object sender, BrickChangedEventArgs e) {  
    txtDistance.Content = e.Ports[InputPort.Four].  
}  
}
```



# Play Sounds

*//upload file*

```
await _brick.SystemCommand.CopyFileAsync("Overpower.rsfx",  
                                          "../prjs/Tester/Overpower.rsfx");
```

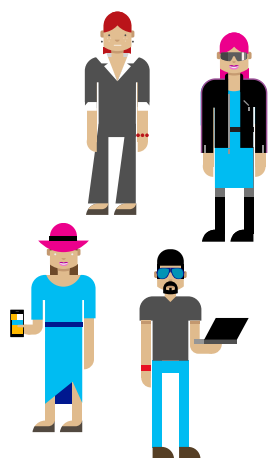
*//play file*

```
await _brick.DirectCommand.PlaySoundAsync(50,  
                                           "../prjs/Tester/Overpower");
```

# DEMO

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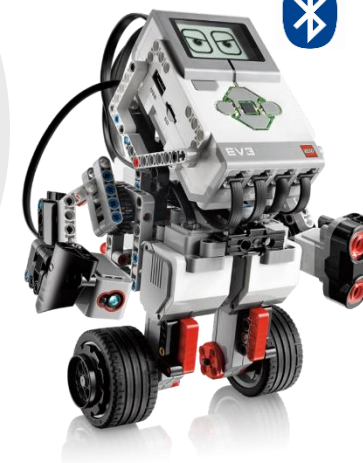




Web App

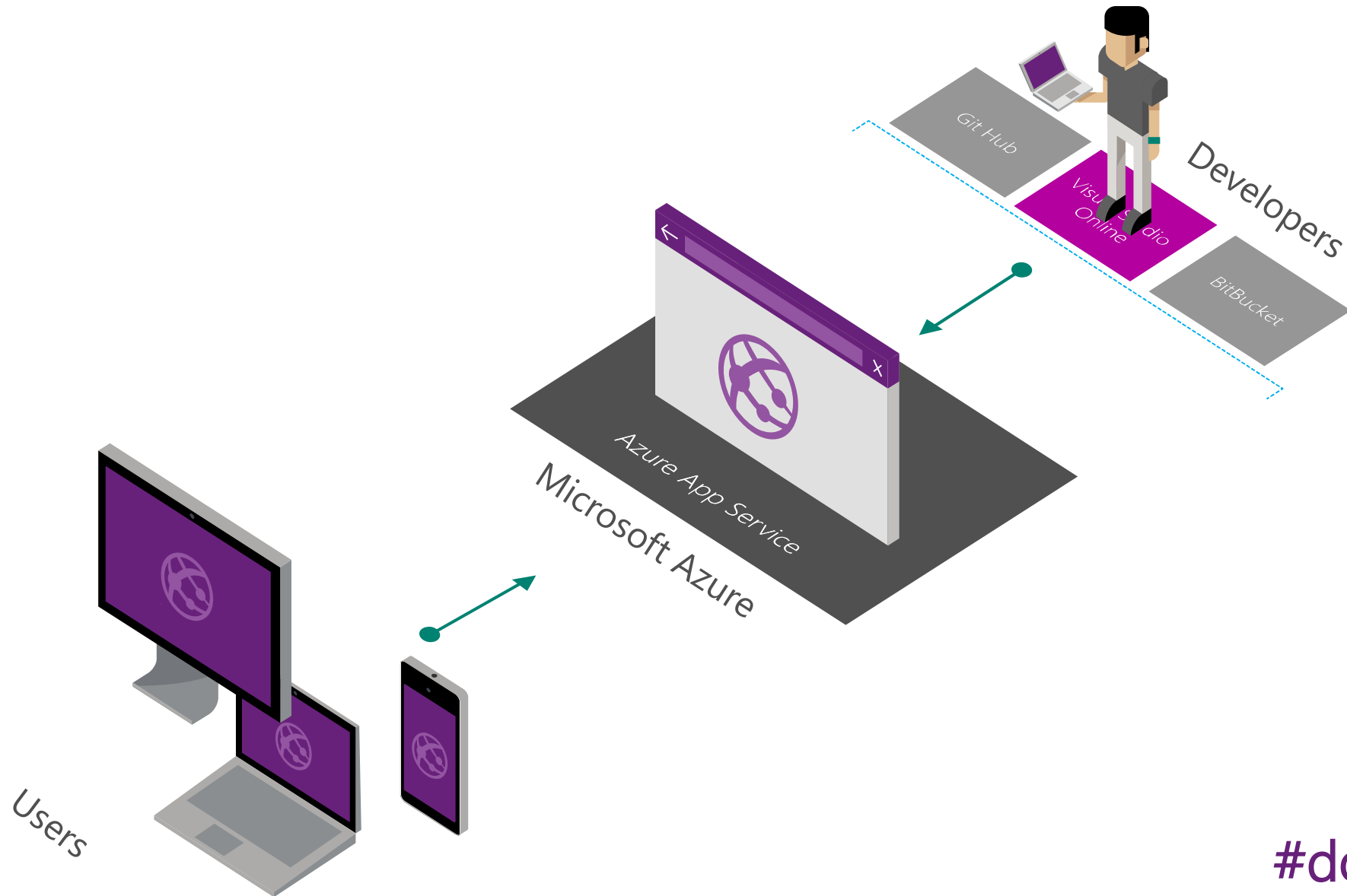


Movimiento

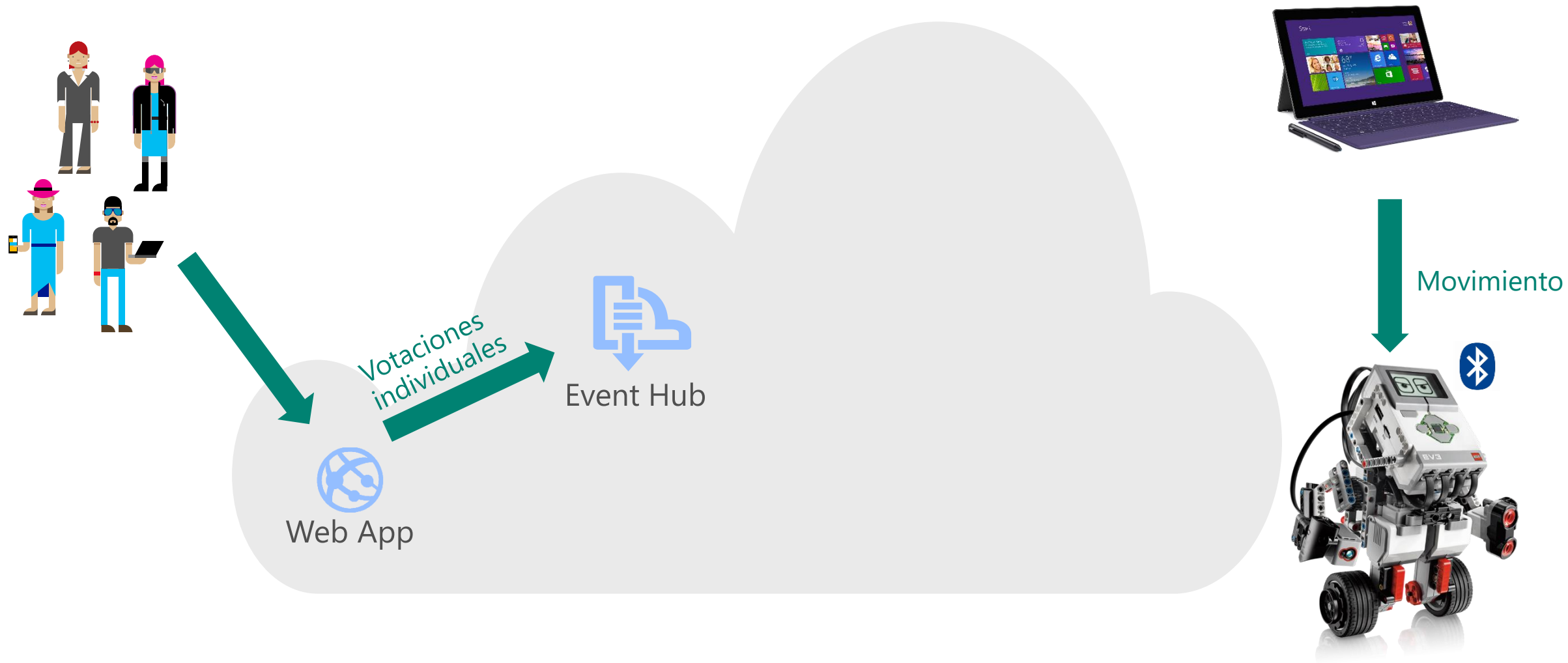


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# Azure Web Apps

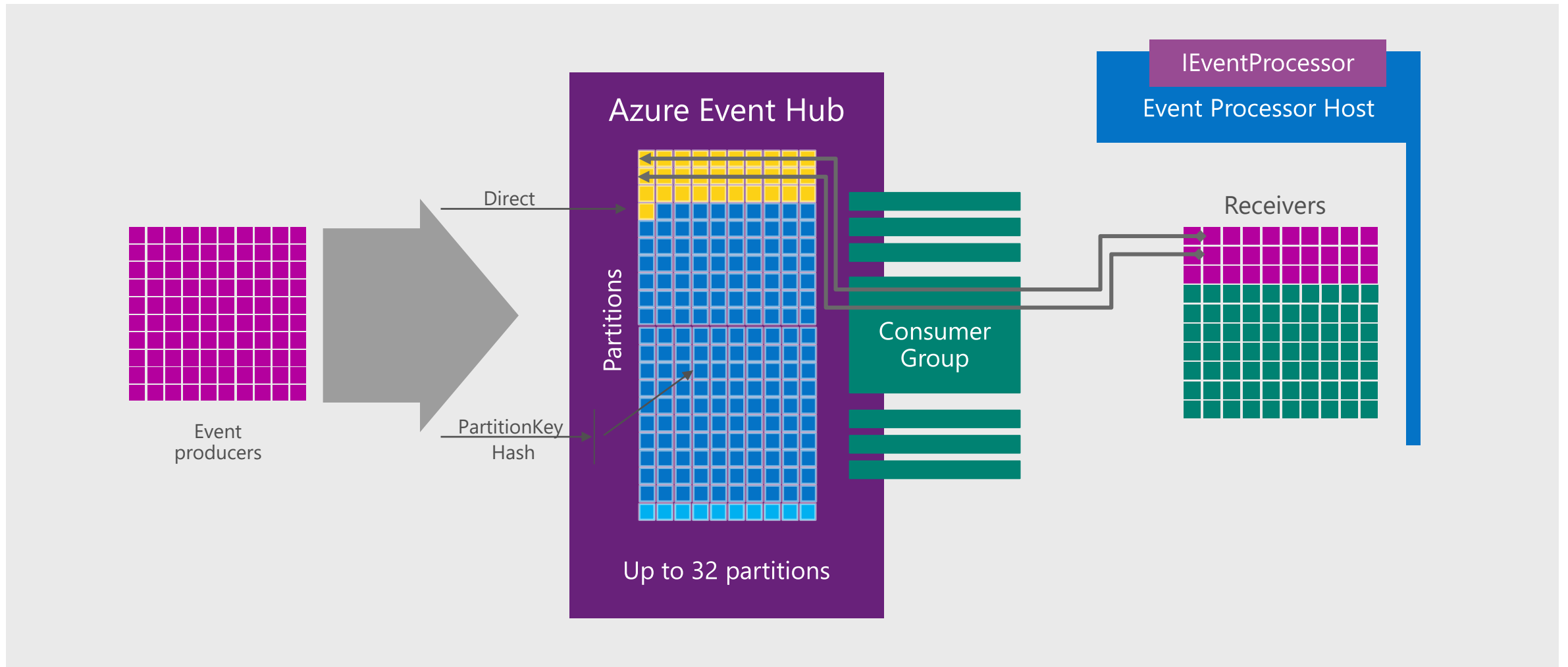


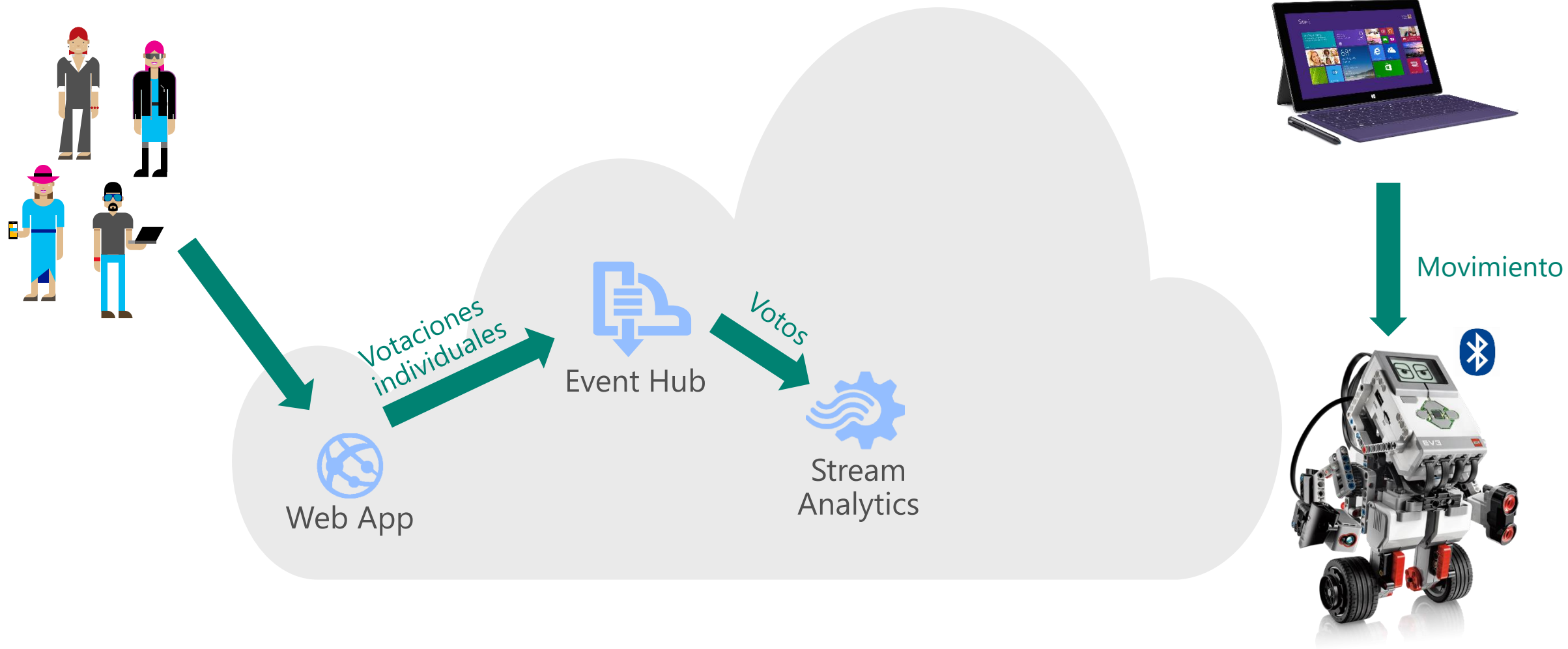
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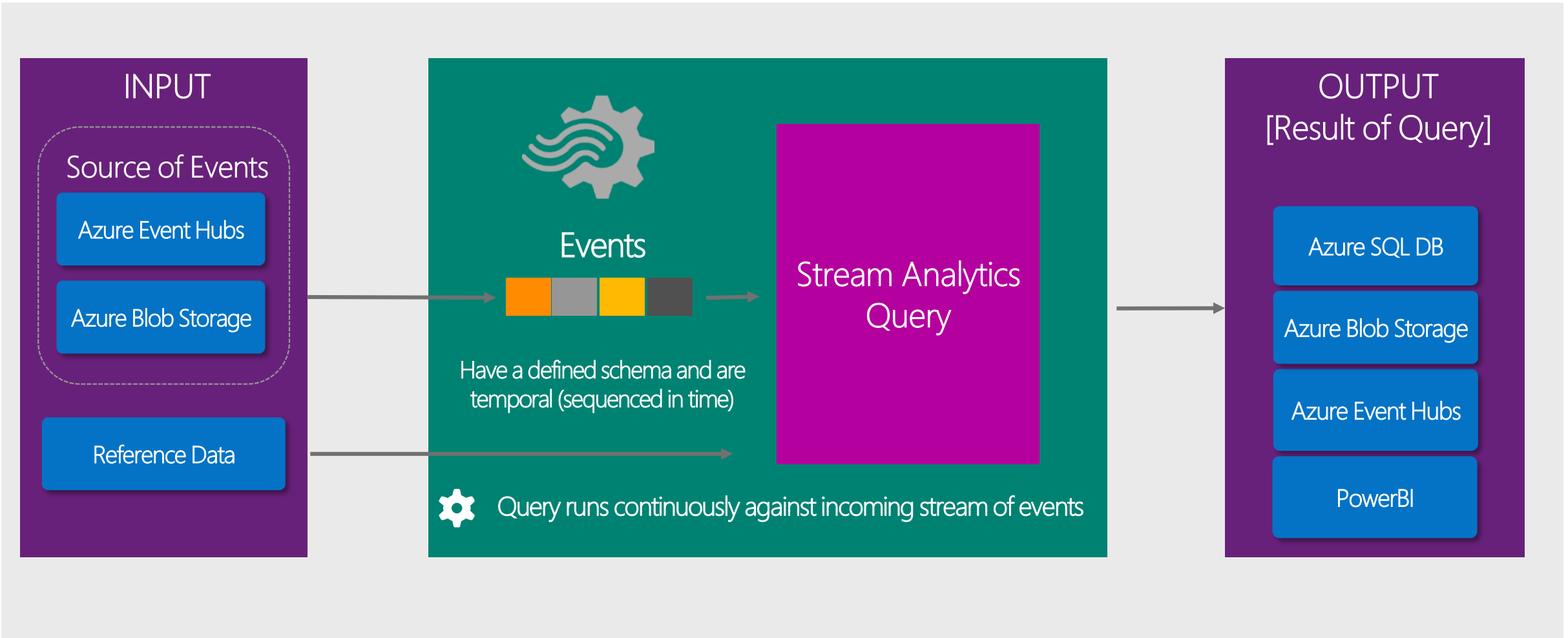
# Service Bus Event Hub



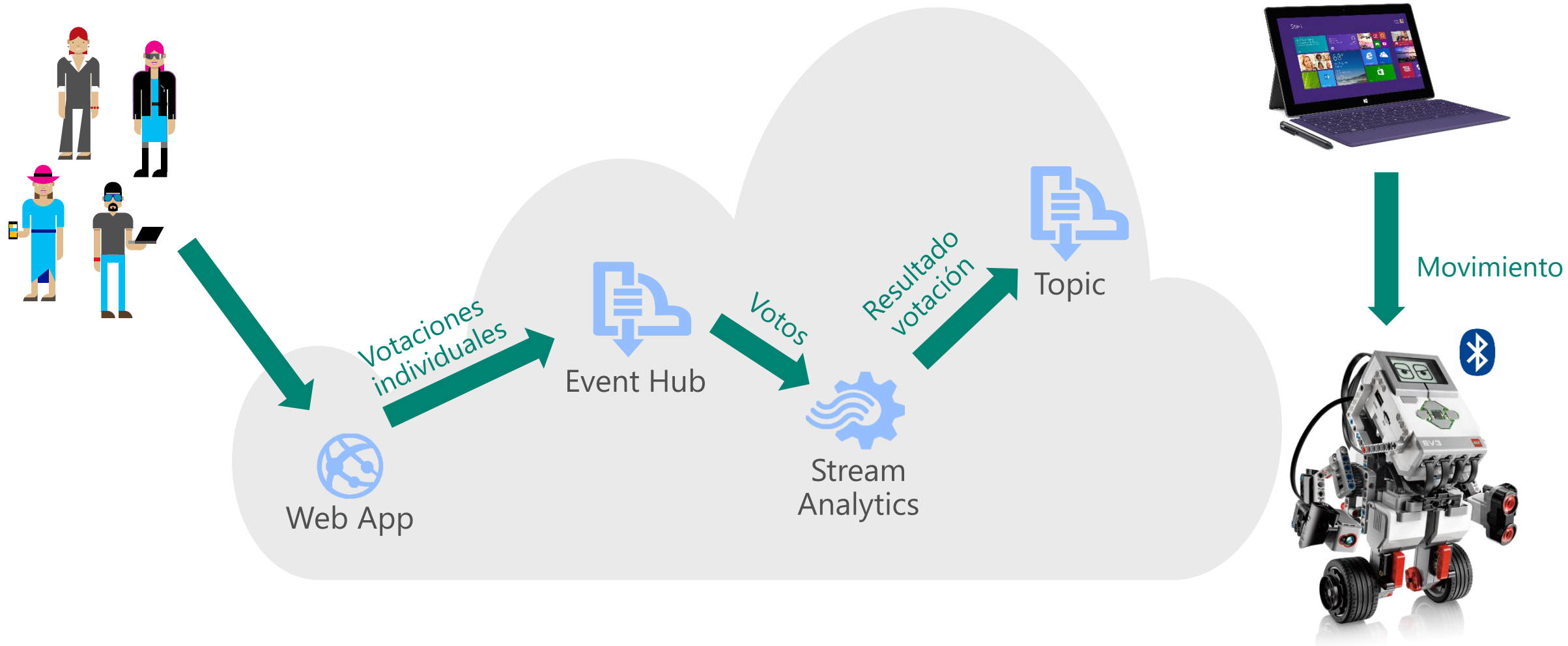


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# Stream Analytics

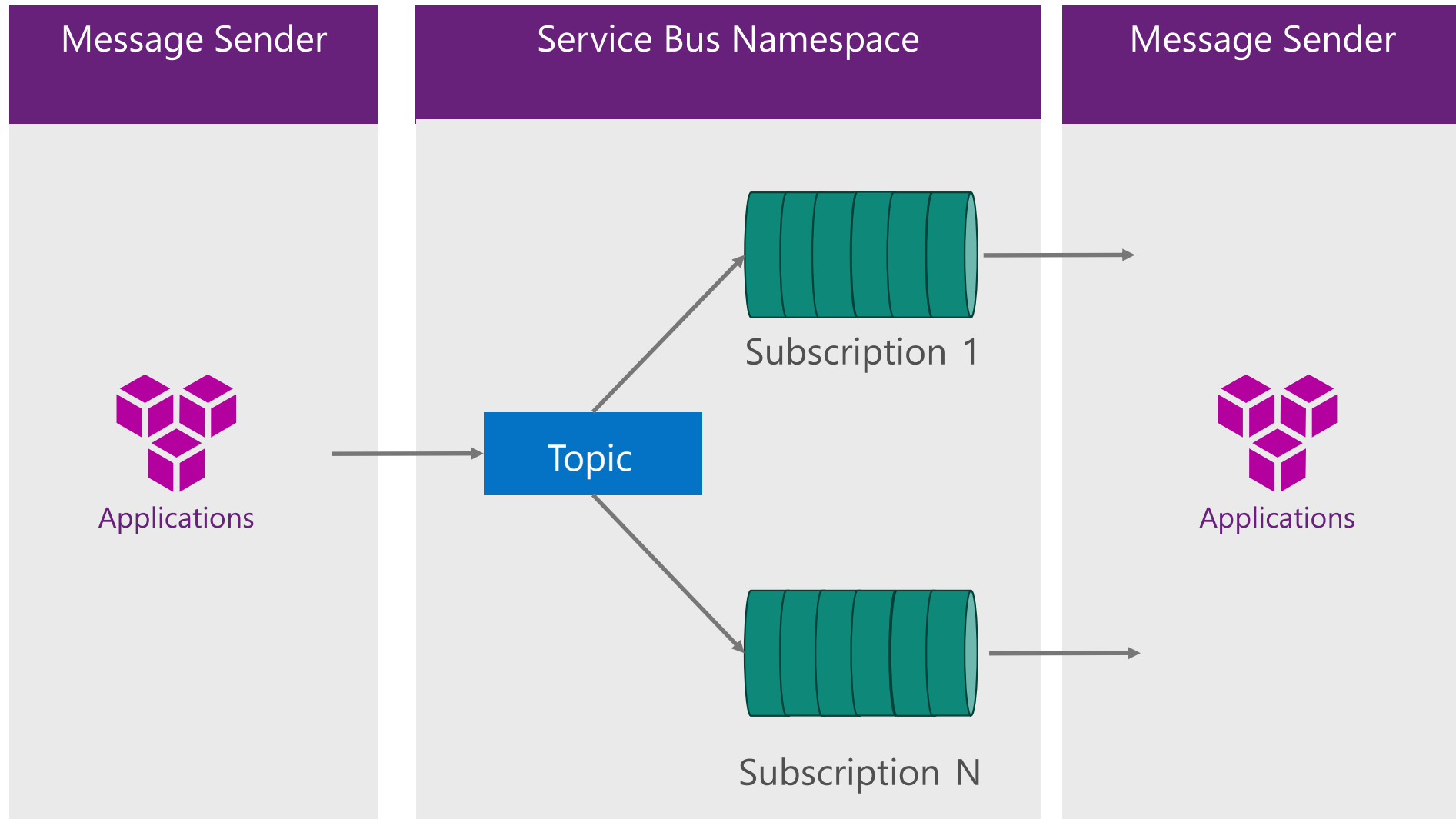


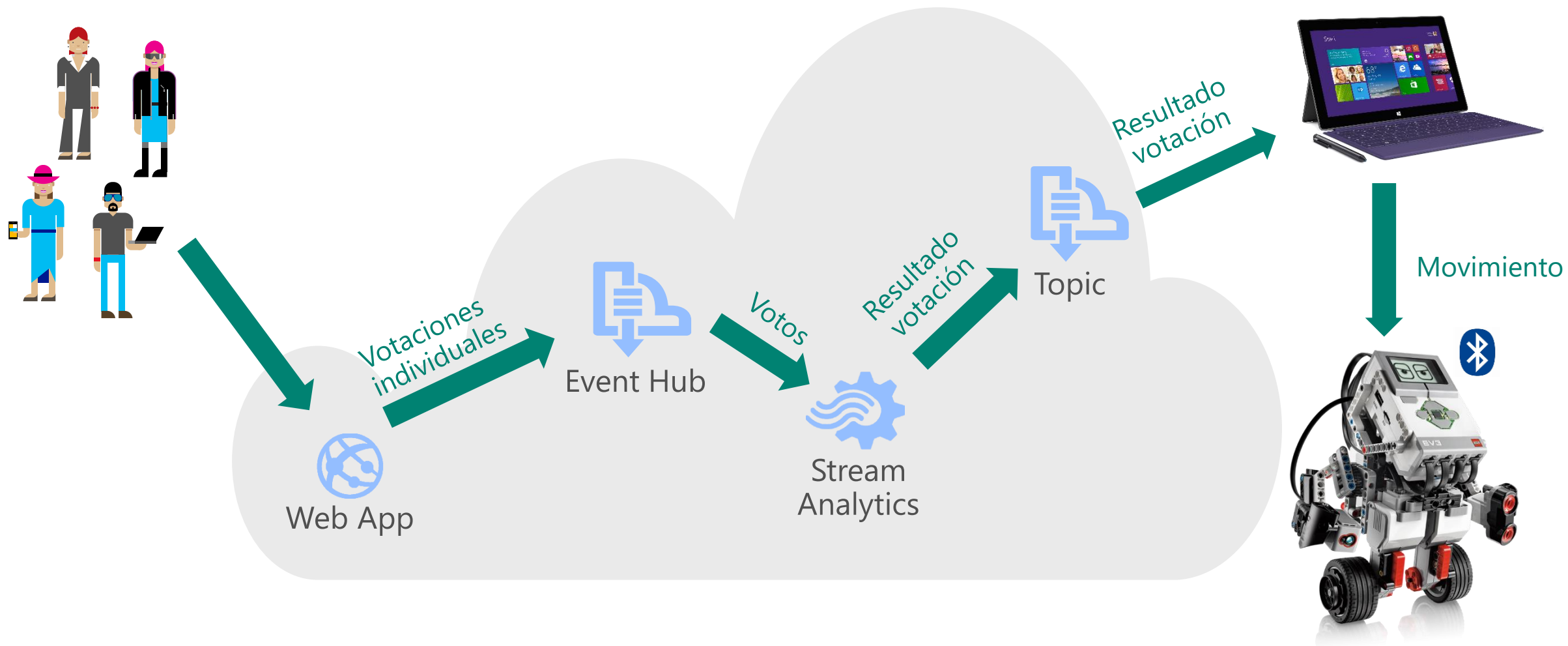




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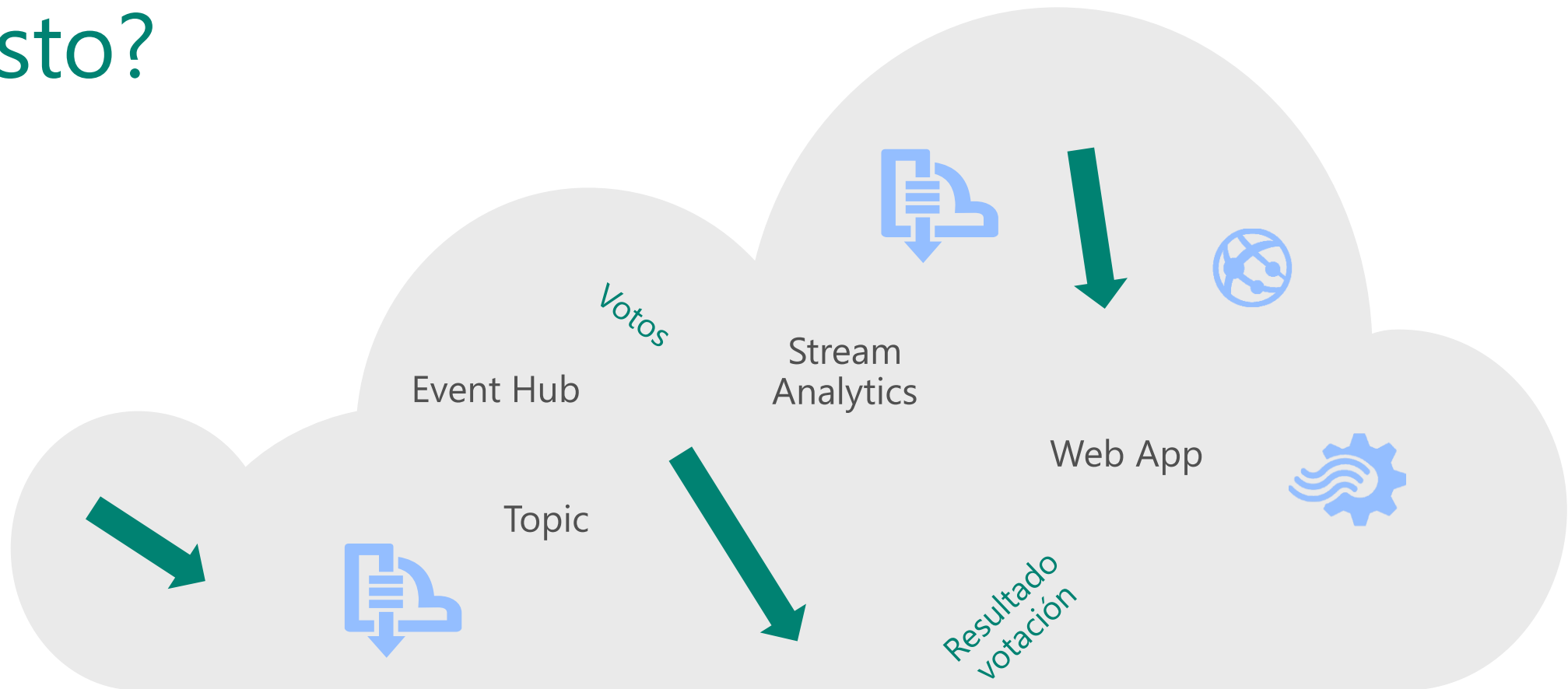
# Service Bus Topic





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La teoría está muy bien  
pero....¿Cómo monto  
todo esto?



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# DEMO

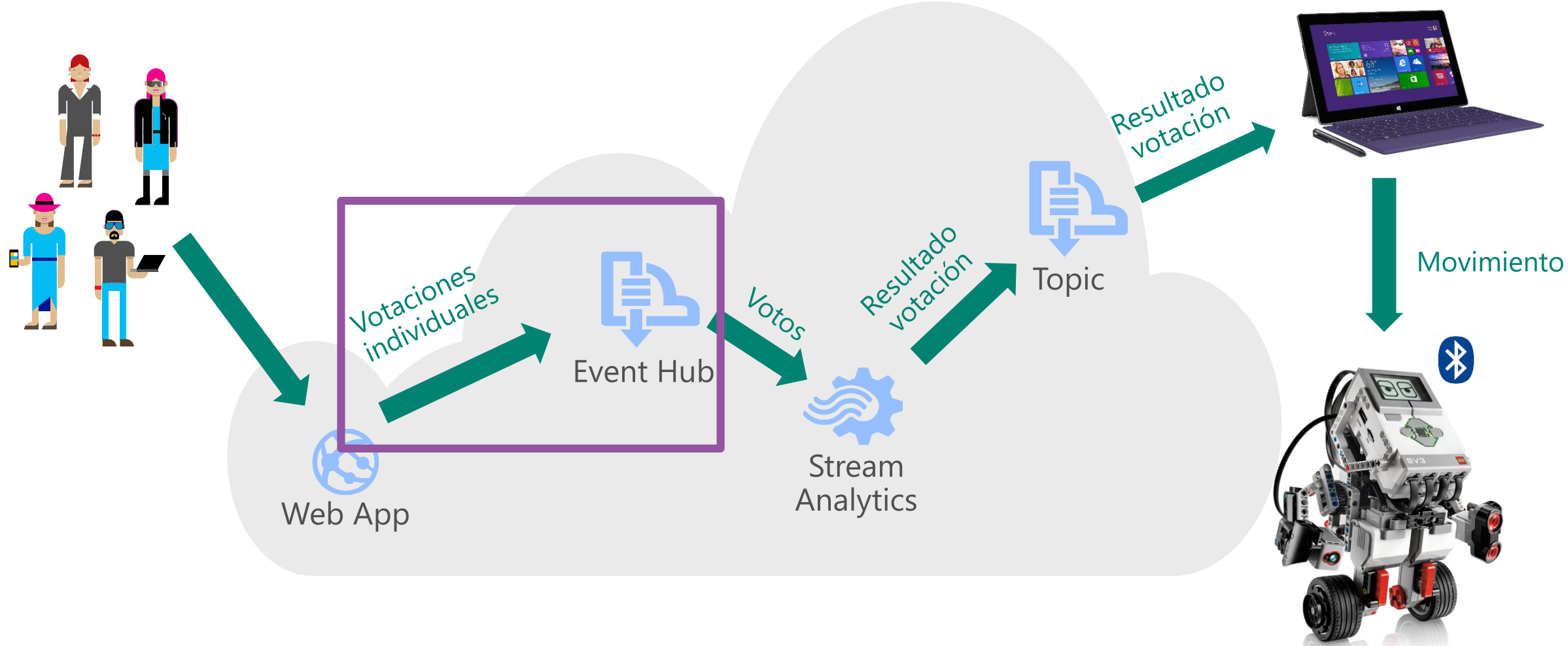
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Ya tenemos  
nuestra  
arquitectura  
¿Y ahora?

¡A programar!



# Enviando eventos a Event Hub



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# Enviando eventos a Event Hub

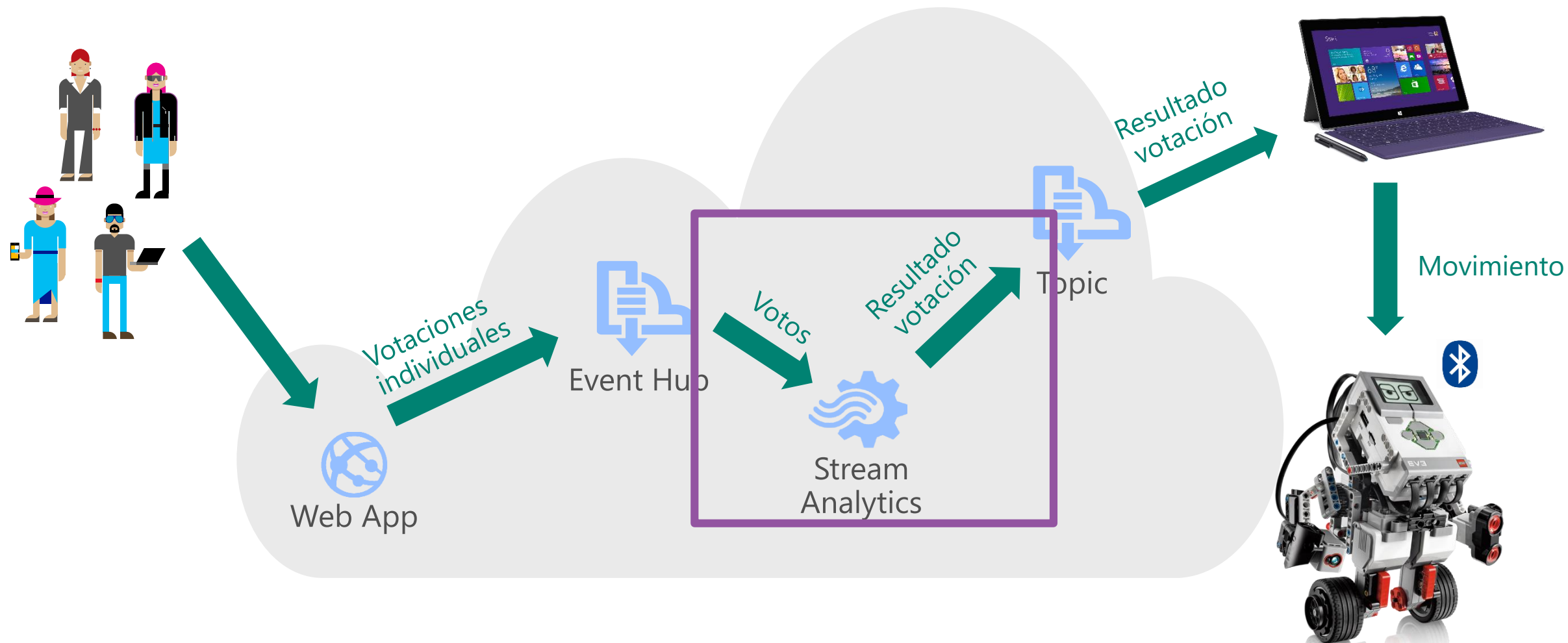
```
EventHubData ehd = new EventHubData() { Movement = movement, EntryTime= DateTime.UtcNow};

var serializedString = JsonConvert.SerializeObject(ehd);
EventData data = new EventData(Encoding.UTF8.GetBytes(serializedString))
{
    PartitionKey = "0"
};

EventHubClient client = EventHubClient.CreateFromConnectionString(ConfigurationManager.AppSettings["ConnectionString"],
    "legodemoeventhub");

await client.SendAsync(data);
```

# Analizando los datos con Stream Analytics

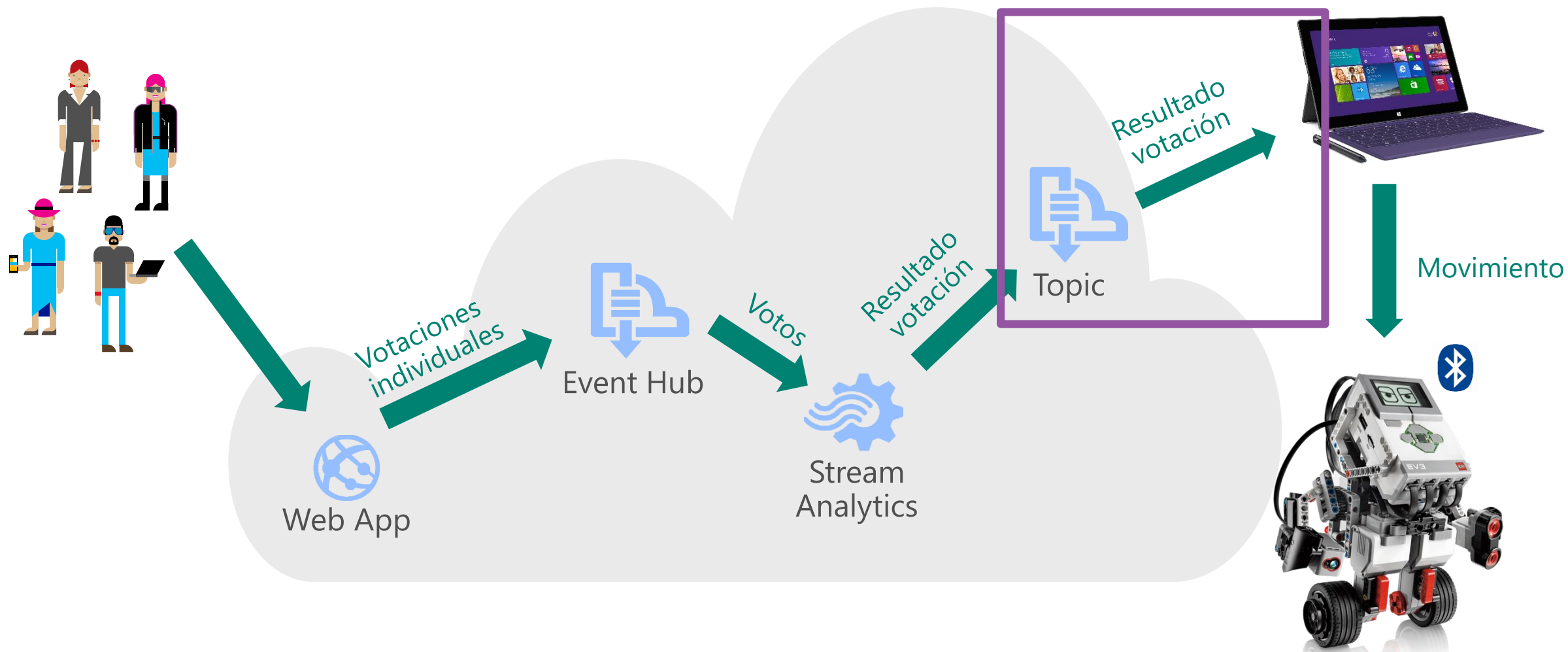


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# Analizando los datos con Stream Analytics

```
1 with cnt as (  
2     SELECT  
3         Movement, Count(*) as votes  
4  
5     FROM  
6         Input TIMESTAMP BY EntryTime  
7  
8         GROUP BY Movement, TumblingWindow(second,3)  
9 ),  
10 cnt2 as (  
11     select max(votes) as votes from cnt group by TumblingWindow(second,3))  
12  
13 select SYSTEM.TIMESTAMP as time ,cnt.movement, cnt.votes  
14 from cnt  
15 join cnt2 on cnt.votes=cnt2.votes and DateDiff(ss,cnt,cnt2) between 0 and 3  
16
```

# Recibiendo eventos del Topic



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# Recibiendo eventos del Topic

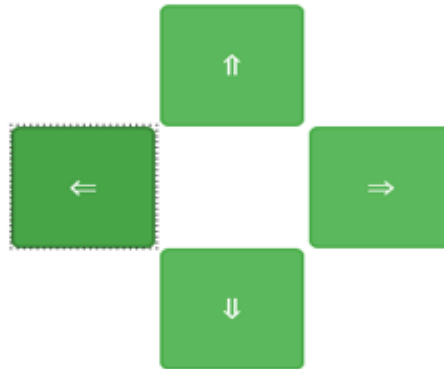
```
var subscriptionClient = SubscriptionClient.CreateFromConnectionString(connectionString, topicPath, subscriptionName);  
  
var brokeredMessage = await subscriptionClient.ReceiveAsync(TimeSpan.FromSeconds(1));  
  
var message = brokeredMessage.GetBody<string>();  
  
var movement = JsonConvert.DeserializeObject<EventHubVotes>(message);
```

# ¿Jugamos?

<http://legoev3web.azurewebsites.net/>

# ¡¡Controla nuestro Robot LEGO!!

Vota la dirección hacia la que quieres dirigir el robot

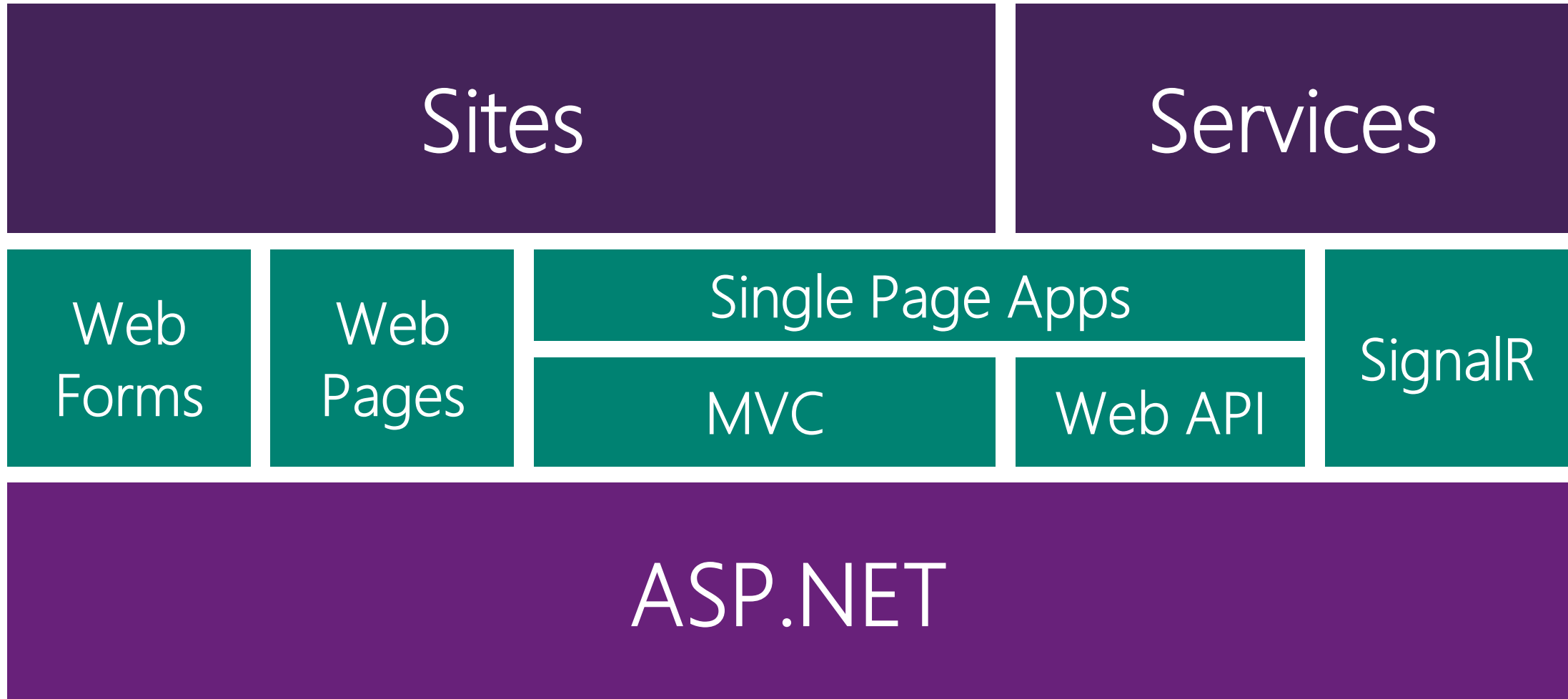


## Votaciones

Izquierda	Adelante	Derecha	Atrás
14	24	37	21



# Funcionamiento ASP.NET



# ¿Qué es SignalR?

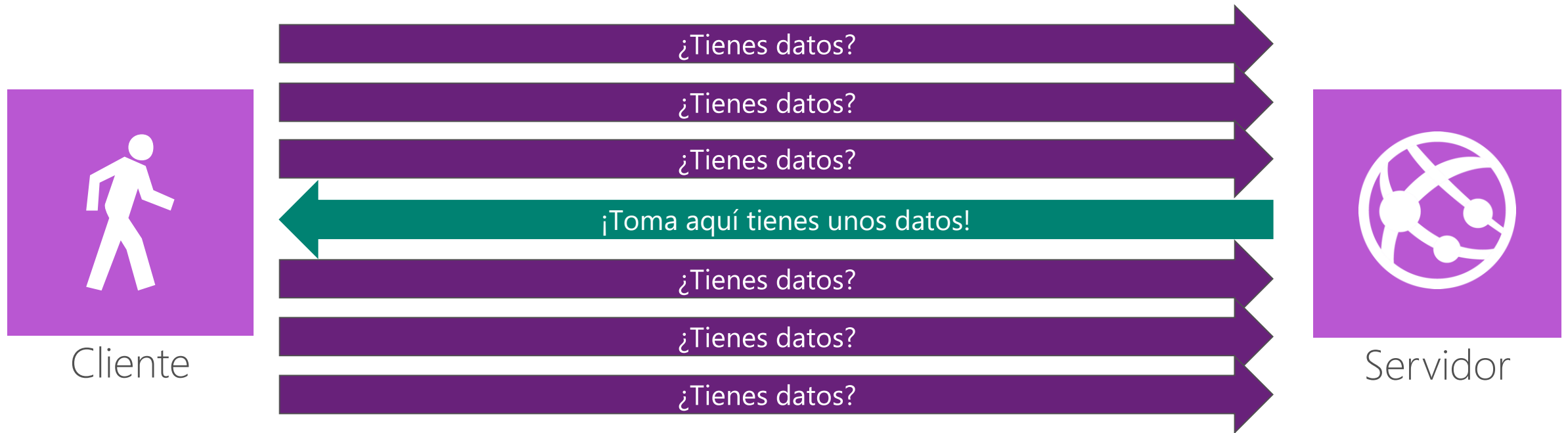
SignalR es una serie de abstracciones alrededor de varios métodos para proporcionar conexiones HTTP persistentes, distribuidos como código open-source.

[¿Y esto en castellano?]

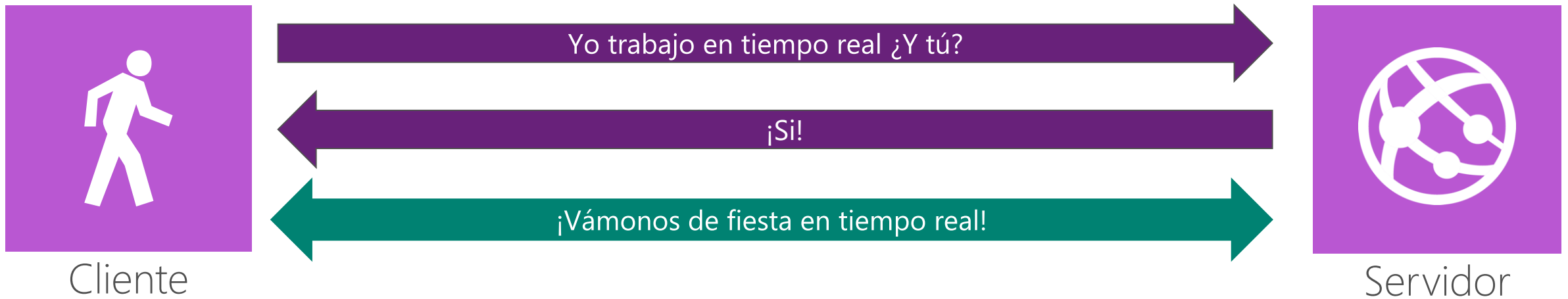
SignalR hace las conexiones HTTP en tiempo real tan fáciles que parece magia.

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# SignalR en Servidores y Clientes Antiguos

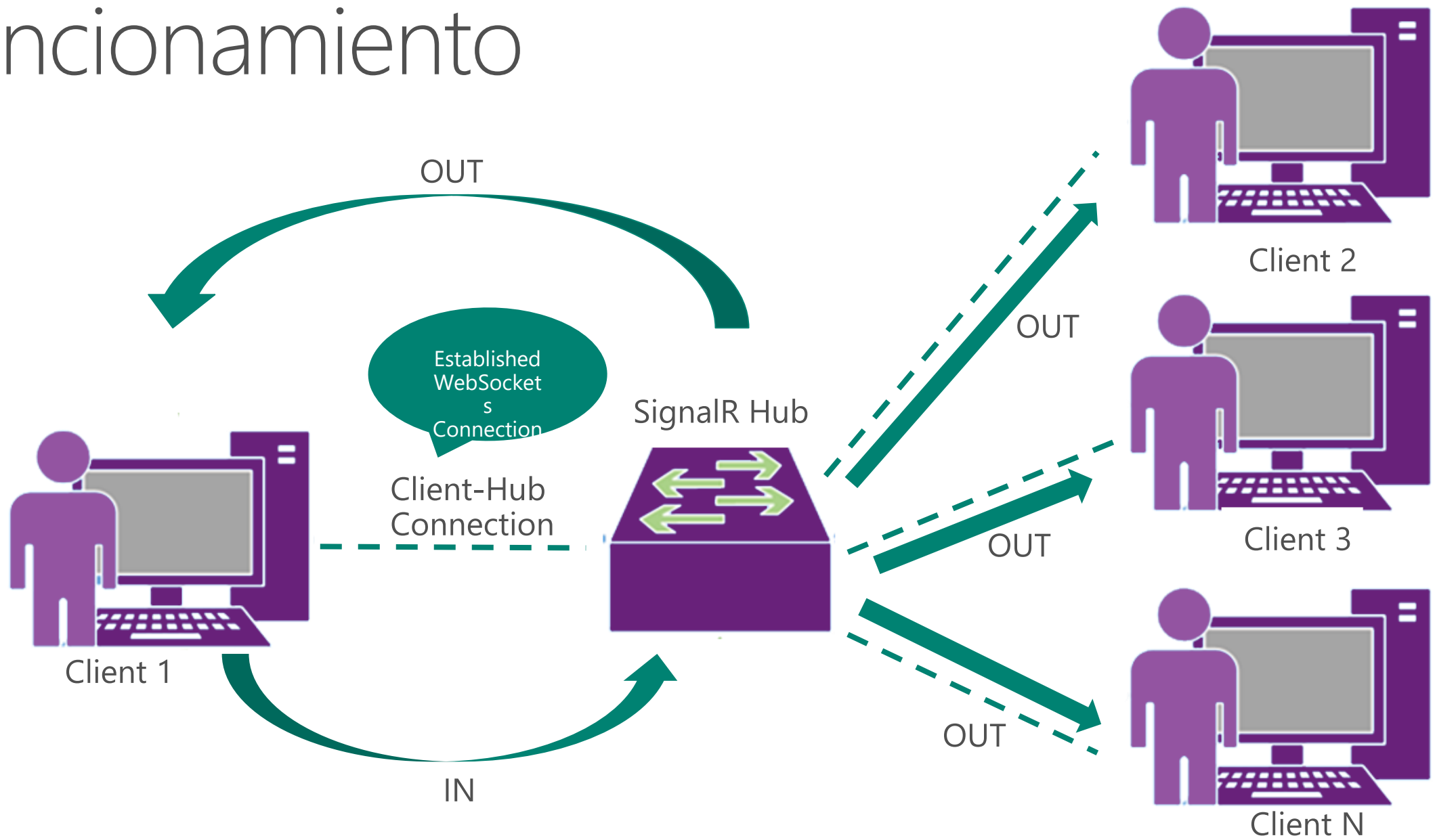


# SignalR en Servidores y Clientes Modernos



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# Funcionamiento



Puedes encontrar todo el código de las demos en:

<http://github.com/isabelcabezasm>

# Conclusiones

-  Lego no es solo para niños
-  Jugar todos significa escalar
-  Cuando tengas un problema,  
tu solución está en Azure
-  Signal R es "magia"

# Q&A



<http://aka.ms/DOTNETT8S1>

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# ¡Gracias!

Isabel Cabezas  
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Beatriz García  
@BeRoces



<http://aka.ms/DOTNETT8S1>



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