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Sec 4.6
    3pt5 #4 (c)
                      Suppose P and Q are orthogonal Motrices
                        (PO)t = Otpt = OTPT = (PO)T => PO is orthogonal
                (d) Suppose () is orthogonal.
                          #5 (a) \forall x, y \in \mathbb{R}^n, \langle Q_x, Q_y \rangle = \langle x, Q^{\dagger}(Q_y) \rangle for any matrix Q
                (\Rightarrow) Suppose Q is orthogonal. \langle Qx,Qy\rangle = \langle x, (Q^{\dagger}Q)y\rangle = \langle x,y\rangle
                                                                                            1 OtO=I because a 15 orthogral
3 pts
                 (€) Suppose <Qx, 0y>= <x, y> for all x, y ∈ 12.
                                        < *, (0+0)>> = < 0*, 0>> = <*.>> =>
                                                                                                  O_f O = I
                                                         > Q is orthogonal by ascumption
  3 pts \rightarrow (b) Suppose Q is orthogonal. \|Q \times \|_{2}^{2} < 0 \times, 0 \times > \frac{1}{2} < \infty, \times > = \| \times \|^{2}
                                                                             From (a)
                                          ⇒ Sme 10×1170 and 11×170, 10×1=11×11 (1)
   3pk \Rightarrow (c) Let A be on nxn motrix. Suppose |A \times I| = | \times I| for all \times \in \mathbb{R}^n.
                      \langle A \times, A \rangle \rangle = \frac{1}{4} \left( \|A \times + A \gamma \|^2 - \|A \times - A \gamma \|^2 \right)^2 by Polarization identity (1)
                                      = \frac{1}{4} \left( \| A(x+y) \|^2 - \| (A(x-y) \|^2) \right)
= \frac{1}{4} \left( \| x+y \|^2 - \| x-y \|^2 \right) by the ossumption
                                          = < x, >> by polarization identity.
                                     > A is orthogonal from #5(a)
                 Suppose A is symmetric. That is, A=At
    IPIS → (1) A is Orthogonal → (11) A = I
                     proof A is orthograph => AA+=I => AA=I => A^=I
                                                                                            because A=At
     3pts \rightarrow 00 A^2 = I \Rightarrow (00) All exponenties of A are 1 or -1
                                          A \times = X \times \text{ for } \times \in \mathbb{R}.

A(A \times) = A(A \times) \Rightarrow A^{2k_1} = A^{2k_2} = A^{2k_3} = A^{2k_4} = A^{2k_4}
                                Let x be an eigenvalue of A. Then
                                      (I) A(B \times B \times B) \Rightarrow A^2(A) = \lambda(B \times B) \Rightarrow A = \lambda^2 \times B
                                            => 12=1 => 1===1
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proof Lot \lambda be an eigenvalue of A.
                                                                                                              Then
                                                                                                                                                       Ax= 1x for Vx & Ex
                                                                                                  ter ^{*}x \in t_{\lambda}

A^{\dagger}Ax = A^{\dagger}(\lambda x) = A(\lambda x) = \lambda A(x) = \lambda^{2}x
A^{\dagger}Ax = A^{\dagger}(\lambda x) = A(\lambda x) = \lambda A(x) = \lambda^{2}x
A^{\dagger}Ax = A^{\dagger}(\lambda x) = A^{\dagger}A(x) = x
A^{\dagger}Ax = A^{\dagger}(\lambda x) = A^{\dagger}A(x) = x
                                                               (1) Y & Br y= + xit... + tnxn where {x1...xn} is a basis
                                                                                                     Therefore, A^{t}A(Y) = \sum_{i=1}^{n} t_{i}(A^{t}A)(x_{i}) = \sum_{i=1}^{n} t_{i} x_{i} = y consisting at eigenvectors.
                                                                                                                                     At A=I >> A is orthogonal
                       Sect. 1 #6 (5Pts)
1 pts => (a) Let == 22+2=0. Z=+± \1-2 = -1±1
 \text{(b)} \quad \text{Let } \vec{z}^3 - \vec{z}^2 + 2\vec{z} - 2 = 0 \quad 0 = \vec{z}^2 \vec{z}^2 + 2\vec{z} - 2 = \vec{z}^2 (\vec{z} - 1) + 2(\vec{z} - 1) = (\vec{z}^2 + 2)(\vec{z} - 1)
Since -i = Cos(\frac{3\pi}{2} + 2\pi k) + isin(\frac{3\pi}{2} + 2\pi k),
                                                                                                         Z= Cos(3T+T/k)+ isin(3T+T/k), k=0,1 (流流)
                                                                when 4 = 0, Z = \cos(\frac{3\pi}{4}) + i \sin(\frac{3\pi}{4}) = -i + i + i = i
                                                                 When k=1, z=\cos(\frac{3\pi}{4}+\pi)+\cos(\frac{3\pi}{4}+\pi)=\sqrt{2}
       \frac{1}{5} \frac{1}{1} \frac{1}
                                                                                                                                                                      \lambda^2 = 2\lambda + 1 - 1 = 0 \implies \lambda^2 = 2\lambda = 0
                                                                                                                                                             \Rightarrow \Lambda(\lambda-2)=0
\Rightarrow \lambda=0 \text{ or }\lambda=2 \text{ } \leftarrow \text{ eigenvalues}
                                       For \lambda=0,

A-\lambda I = A = \begin{bmatrix} 1 & i \\ -i & i \end{bmatrix} \sim \begin{bmatrix} 1 & i \\ 0 & 0 \end{bmatrix} \Rightarrow 1 \times_1 + i \times_2 = 0

Cos \times_2 = 1.
                                                        \begin{pmatrix} x_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} -it \\ t \end{pmatrix} = t \begin{pmatrix} -i \\ 1 \end{pmatrix}, So E_{\Lambda=0} = \text{span} \left\{ (-i, 1) \right\}
                             For \lambda=2
A-2I = \begin{bmatrix} -1 & i \\ -i & -1 \end{bmatrix} \sim \begin{bmatrix} -1 & i \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} -x_1+i x_2=0 \\ tet & x_2=t \end{bmatrix}
\begin{bmatrix} x_1 \\ y_2 = \begin{pmatrix} it \\ 1 \end{pmatrix} = t \begin{bmatrix} i \\ i \end{pmatrix}, So \ E_{\lambda=2} = Span \left\{ (\hat{i}, 1) \right\}
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7pts > (iii) All enformations of A are 1 or -1 >> A re orthogonal

(spts) Sec 5.2 # 12 (50ts) (a) [coso -sino] WA. (b) \[ \begin{aligned} \cdot  $\det (A-\lambda I) = 0 \Rightarrow (-\lambda)^{2} + \alpha^{2} = 0$   $\Rightarrow \lambda^{2} = -\alpha^{2} \Rightarrow \lambda = \pm \alpha \lambda$ deHA-XI)= 0 0 = 05m2+5(K-040) <= For  $\lambda = \alpha i$ ,  $A - (\alpha i)I = \begin{bmatrix} -\alpha i - \alpha \\ \alpha - \alpha i \end{bmatrix}$   $\begin{array}{ccc} \alpha i & \alpha \\ 0 & 0 \end{array}$   $\begin{array}{cccc} \alpha i & \alpha \\ \alpha i & \alpha_1 + \alpha_2 = 0 \end{array}$  $\Rightarrow$   $\lambda^2 = 2 \cos \theta \lambda + \omega^2 \theta + \cos^2 \theta = 0$  $\Rightarrow V_5 = 3 \cos 0 y + 1 = 0$  $\Rightarrow A = \cos\theta \pm \sqrt{(\alpha_0^2 - 1)} = (\cos\theta \pm \sqrt{-\sin^2\theta})$   $= \cos\theta \pm \sin\theta$ Let  $Y_r=t$ . Then  $X_1=-\frac{1}{L}t$ = itFor 1=casotsinoi, A-(rosotsinoi)I En=ai = span { (i,1) } = [(-sno); -sno] sno (-sno); tor λ=-ai, A+(ai) [= [ai -a]
a ai] - [ai -a] aix, -ax=0  $(\sin \theta) i \times = -\cos \theta \times x$ Let  $x_1 = -i \times x$ Exercis = span { (i, 1) } cino + Z For 1 = cosp - smoi, A - (cosp - smoi) I

= [ smbi - smo ]

smoi - smo ]

smoi x - smo x = 0 Let xz=t, then x = +xz = -it (assumy smo+o) Ex=co20-suo: = Span ((-i,1)) Sec 5.3 #3 (a) (5pts) W = (i,-1, i) and Wz= (1,1,0) Led (WI= IV,  $|W_2| = |V_2 - P(W_1) = |V_2 - \langle \underline{V_2}, |W_1 \rangle = |W_1|$  $\langle w_2, w_1 \rangle = \langle w_2, w_1 \rangle = (1)(-i) + (1)(-i) + (0)(-i) = -1 - i$  $\| w_i \|^2 = \langle w_i, w_i \rangle = i(-i) + (-1)(-1) + (i)(-i) = 1 + 1 + 1 = 3$  $W_{a} = (1,1,0) - (\frac{-1-i}{3})(i,-1,i) = (1,1,0) + \frac{1+i}{3}(i,-1,i)$  $= \left(\frac{2}{3} + \frac{1}{3}i, \frac{2}{3} - \frac{1}{3}i, -\frac{1}{3} + \frac{1}{3}i\right)$ 

 $\left\{ \left(i, -1, i\right), \left(\frac{2}{3} + \frac{1}{3}i, \frac{2}{3} - \frac{1}{3}i, -\frac{1}{3} + \frac{1}{3}i\right) \right\}$  orthogonal