

Q1

(a) $T(v_1) = v_1 + 2v_2$ $T(v_2) = 3v_1 + 4v_2$ (2)

4 marks

$$\begin{aligned} \langle T(v_1), T(v_2) \rangle &= \langle v_1 + 2v_2, 3v_1 + 4v_2 \rangle \\ &= \underbrace{3\langle v_1, v_1 \rangle}_1 + \underbrace{4\langle v_1, v_2 \rangle}_0 + \underbrace{6\langle v_2, v_1 \rangle}_0 + \underbrace{8\langle v_2, v_2 \rangle}_1 \\ &= 3 + 8 = 11. \end{aligned}$$

(2)

(b) $[T^{-1}]_{\alpha}^{\alpha} = \frac{1}{4-6} \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} -2 & \frac{3}{2} \\ 1 & -\frac{1}{2} \end{bmatrix}$ (1.5)

3 marks

Since $T(v_1) = v_1 + 2v_2$ and T^{-1} exists, $T^{-1}(v_1 + 2v_2) = v_1$ (1.5)

(or) $T^{-1}(v_1 + 2v_2) = T^{-1}(v_1) + 2T^{-1}(v_2) = (-2v_1 + v_2) + 2(\frac{3}{2}v_1 - \frac{1}{2}v_2) = v_1$ (0.5)

(0.5) (0.5)

Q2

(a) $W^{\perp} = \{x \in \mathbb{R}^4 \mid \langle x, w \rangle = 0 \text{ for all } w \in W\}$

Sol 1. Since $\langle 0, w \rangle = 0$ for all $w \in W$, $0 \in W^{\perp} \Rightarrow$ non-empty

(3 marks) 2. $\forall x_1, x_2 \in W^{\perp}, \forall w \in W, \langle x_1 + x_2, w \rangle = \langle x_1, w \rangle + \langle x_2, w \rangle = 0 + 0 = 0$
so, $x_1 + x_2 \in W^{\perp}$ (1.5)

3. $\forall x \in W^{\perp}, k \in \mathbb{R}, \forall w \in W, \langle kx, w \rangle = k\langle x, w \rangle = k \cdot 0 = 0$
so $kx \in W^{\perp}$. (1.5)

(4 marks) (b) $W = \text{span}\{(1, 1, 2, 1), (1, 2, 1, 0)\}$. Find W^{\perp} .

Sol $W^{\perp} = \ker \left(\begin{bmatrix} 1 & 1 & 2 & 1 \\ -1 & 2 & 1 & 0 \end{bmatrix} \right)$ (2)

$$\begin{bmatrix} 1 & 1 & 2 & 1 \\ -1 & 2 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 2 & 1 \\ 0 & 3 & 3 & 1 \end{bmatrix}$$

$$x_1 + x_2 + 2x_3 + x_4 = 0$$

$$3x_2 + 3x_3 + x_4 = 0$$

Let $x_3 = t$ and $x_4 = s$. Then $x_2 = \frac{1}{3}(-3x_3 - x_4) = \frac{1}{3}(-3t - s) = -t - \frac{1}{3}s$

(2)

$$x_1 = -x_2 - 2x_3 - x_4 = +t + \frac{1}{3}s - 2t - s = -t - \frac{2}{3}s$$

$$(x_1, x_2, x_3, x_4) = t(-1, -1, 1, 0) + s(-\frac{2}{3}, -\frac{1}{3}, 0, 1)$$

$$W^\perp = \text{Span}\left\{(-1, -1, 1, 0), (-2, -1, 0, 3)\right\}$$

Q3

6 marks

$$(a) T(x \sin x) = (x \sin x)' = \sin x + x \cos x, [T(x \sin x)]_\alpha = (0, 1, 1, 0)$$

$$T(x \cos x) = (x \cos x)' = \cos x - x \sin x, [T(x \cos x)]_\alpha = (1, 0, 0, 1)$$

$$T(\sin x) = (\sin x)' = \cos x, [T(\sin x)]_\alpha = (0, 0, 0, 1)$$

$$T(\cos x) = (\cos x)' = -\sin x, [T(\cos x)]_\alpha = (0, 0, 1, 0)$$

$$[T]_\alpha^\alpha = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{rank 4}$$

$$\begin{cases} \text{ker}(T) = \{0\} \\ \text{Im}(T) = W \text{ or } \text{span}\left\{x \cos x + \sin x, -x \sin x + \cos x, \cos x, -\sin x\right\} \end{cases}$$

same

→ (b) Since $\text{ker}(T) = \{0\}$, T is injective.

Q4

3 marks

$$\text{Let } T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R}) \text{ be defined by } T(p(x)) = p(x) + p'(x)$$

$$\begin{aligned} (a) \quad \forall p_1(x), p_2(x) \in P_2(\mathbb{R}), \quad T(p_1(x) + p_2(x)) &= p_1(x) + p_2(x) + p_1'(x) + p_2'(x) \\ &= (p_1(x) + p_1'(x)) + (p_2(x) + p_2'(x)) \\ &= T(p_1(x)) + T(p_2(x)) \end{aligned}$$

$$\forall p(x) \in P_2(\mathbb{R}), \quad \forall k \in \mathbb{R}, \quad T(kp(x)) = kp(x) + kp'(x) = k(p(x) + p'(x)) = kT(p(x))$$

So T is linear

4 marks (b)

Let $S = \{1, x, x^2\}$. $T(1) = 1$, $T(x) = x+1$, $T(x^2) = x^2 + 2x$

$$[T]_S^S = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}. \quad \lambda = 1 \text{ is the only eigenvalue of } T$$

$$[T]_S^S - I = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \quad x_1 = t, \quad x_2 = 0 \text{ and } x_3 = 0$$

$$\Rightarrow \text{Null}([T]_S^S - I) = \text{span}(\{(1, 0, 0)\}) \quad (1)$$

$$\Rightarrow E_{\lambda=1} = \text{span}(\{1\}) \quad (1)$$

1 marks

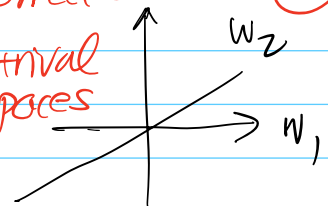
(c) Since $\dim(E_{\lambda=1}) = 1$ and the algebraic multiplicity of $\lambda = 1$ is 3, T is not diagonalizable.

Q5

4 marks

(a) $W_1 = \text{span}\{(1, 0)\}$ and $W_2 = \text{span}\{(1, 1)\}$

$$\langle (1, 0), (1, 1) \rangle = 1 \neq 0 \Rightarrow W_1 \neq W_2^\perp$$



But since $\dim(W_1) = \dim(W_2) = 1$ and $W_1 \cap W_2 \neq \{(0, 0)\}$,
 $W_1 \oplus W_2 = \mathbb{R}^2$

(b) $S_1 = \{(1, 0, 0), (0, 1, 0)\} \subset \text{span}(\{(1, 0, 0), (0, 1, 0)\})$

$S_2 = \{(0, 2, 0)\} \subset \text{span}(\{(0, 1, 0), (0, 0, 1)\})$

S_1 and S_2 are linearly independent because $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ has rank 2.

$S_1 \cup S_2 = \{(1, 0, 0), (0, 1, 0), (0, 2, 0)\}$ is linearly dependent because $(0, 2, 0) = 0(1, 0, 0) + 2(0, 1, 0)$.

Remark: There are many different correct examples.

Q6

$$W = \text{span} \{ \underbrace{(2, 1, 2, 0), (0, -1, 2, 1)}_{\text{not orthogonal}} \}$$

(a) Let $v_1 = (2, 1, 2, 0)$ and $W = \text{span} \{ (2, 1, 2, 0) \}$
 (3 marks) $w_2 = (0, -1, 2, 1) - \text{Proj}_W (0, -1, 2, 1) = (0, -1, 2, 1) - \frac{\langle (0, -1, 2, 1), (2, 1, 2, 0) \rangle}{\| (2, 1, 2, 0) \|^2} (2, 1, 2, 0)$
 $= (0, -1, 2, 1) - \frac{3}{9} (2, 1, 2, 0) = (0, -1, 2, 1) - \frac{1}{3} (2, 1, 2, 0)$
 $= \frac{1}{3} (0, -3, 6, 3) - (2, 1, 2, 0) = \frac{1}{3} (-2, -4, 4, 3)$
 $\{ (2, 1, 2, 0), (-2, -4, 4, 3) \}$ is an orthogonal basis for W .
 for computing

(b) $P_W (1, 0, 0, 1) = \frac{\langle (1, 0, 0, 1), (2, 1, 2, 0) \rangle}{\| (2, 1, 2, 0) \|^2} (2, 1, 2, 0) + \frac{\langle (1, 0, 0, 1), (-2, -4, 4, 3) \rangle}{\| (-2, -4, 4, 3) \|^2} (-2, -4, 4, 3)$
 $= \frac{2}{9} (2, 1, 2, 0) + \frac{1}{45} (-2, -4, 4, 3)$
 $= \frac{1}{45} (22, 6, 24, 3)$
 computing

Q7

(a) $T(x) = \lambda x, x \neq 0$. Then $T^2(x) = T(T(x)) = T(\lambda x) = \lambda T(x) = \lambda(\lambda x) = \lambda^2 x$
 (3 marks) $\Rightarrow \lambda^2$ is an eigenvalue of T^2 .

(b) Let $t_1 x + t_2 T(x) = 0$ where $t_1, t_2 \in \mathbb{R}$.
 (4 marks)

$T(t_1 x + t_2 T(x)) = T(0)$
 $\Rightarrow t_1 T(x) + t_2 T^2(x) = 0 \Rightarrow t_1 T(x) + t_2 0 = 0 \Rightarrow t_1 T(x) = 0$
 $\Rightarrow t_1 = 0$ because $T(x) \neq 0$.

Then $0x + t_2 T(x) = 0 \Rightarrow t_2 = 0$ too, so $\{x, T(x)\}$ is linearly independent because $T(x) \neq 0$.