

In [8]: `import numpy as np`

In [41]: `#QUESTION 1`
`U=np.array([[10**(-1),1],[7/12,0],[-0.7,0], [np.cos(100),0.2]])`
`print(U)`

```
[[ 0.1      1.      ]
 [ 0.5833333 0.      ]
 [-0.7      0.      ]
 [ 0.86231887 0.2     ]]
```

In [42]: `#QUESTION 2`
`A=5*np.identity(4)+U.dot(U.T)`
`print(A)`

```
[[ 6.01      0.05833333 -0.07      0.28623189]
 [ 0.05833333 5.34027778 -0.40833333 0.50301934]
 [-0.07      -0.40833333 5.49      -0.60362321]
 [ 0.28623189 0.50301934 -0.60362321 5.78359384]]
```

In [43]: `#QUESTION 3`
`b= [1,0,-2,-1]`
`x=np.linalg.inv(A).dot(b)`
`print(x)`

```
[ 0.17250495 -0.01068021 -0.38718375 -0.22092097]
```

In [44]: `#QUESTION 4`
`D=np.diagflat(np.diag(A))`
`J=np.linalg.inv(D).dot(D-A)`
`print(J)`
`C=np.linalg.inv(D).dot(b)`
`print(C)`

```
[[ 0.      -0.00970605  0.01164725 -0.04762594]
 [-0.01092328 0.      0.07646294 -0.09419348]
 [ 0.01275046 0.07437766 0.      0.10994958]
 [-0.04949032 -0.08697349 0.10436819 0.      ]]
 [ 0.16638935 0.      -0.36429872 -0.17290287]
```

In [45]: `#QUESTION 5`
`det=np.linalg.det(J)`
`if det!=0:`
 `print("J est inversible puisque det(J)=",det)`

J est inversible puisque det(J)= -2.748813242563203e-06

```
In [56]: #QUESTION 6
x0=[0,0,0,0]
for i in np.arange(20):
    x0=J.dot(x0)+C
    if(i==15 or i==20):
        print(x0)
```

```
[ 0.17250495 -0.01068021 -0.38718375 -0.22092097]
```

```
In [ ]:
```