

DEEP LEARNING AND IMAGE RECONSTRUCTION

a. asensio ramos
@aasensior
github.com/aasensio



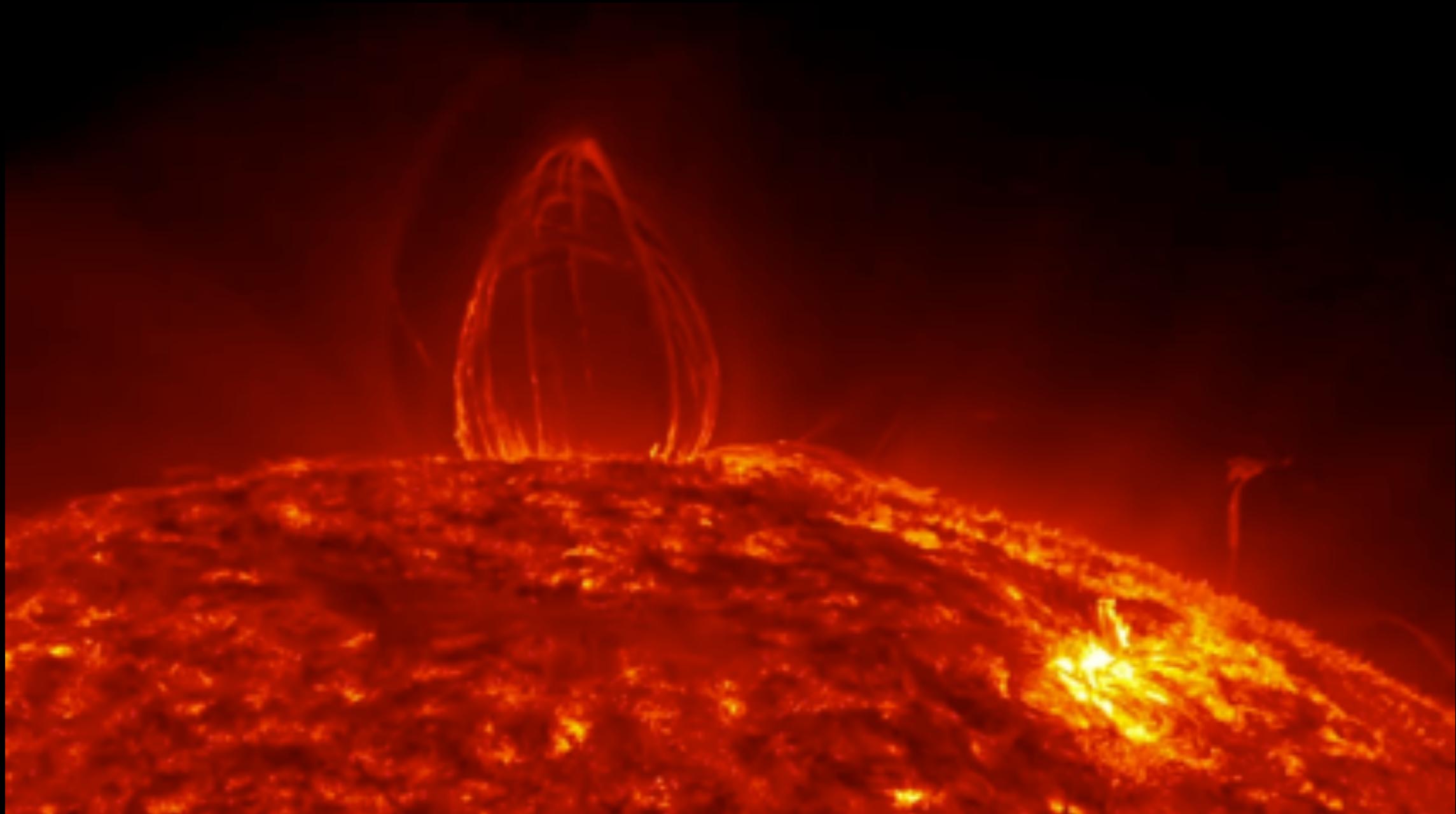
SUMMARY

- ▶ Motivation
- ▶ Image reconstruction: linear & non-linear
- ▶ Physics-based inference
- ▶ Conclusions

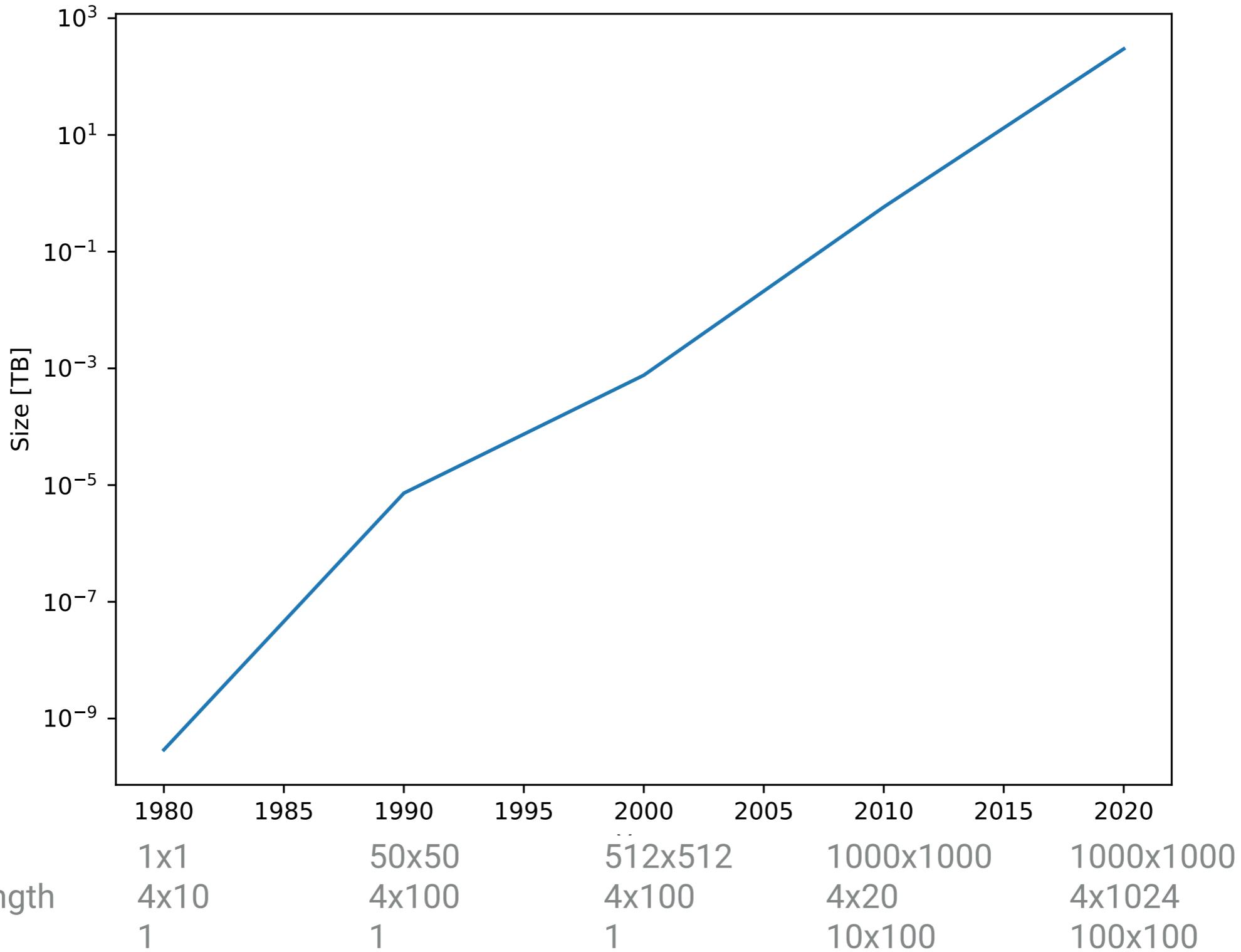
THANKS TO...

- ▶ C. Díaz Baso
- ▶ J. de la Cruz Rodríguez
- ▶ M. van Noort
- ▶ N. Olspert
- ▶ T. Felipe
- ▶ E. García Brook
- ▶ B. Tremblay

MY BACKGROUND



DATA IS INCREASING EXPONENTIALLY



OUR MODELS ARE OFTEN COMPLEX

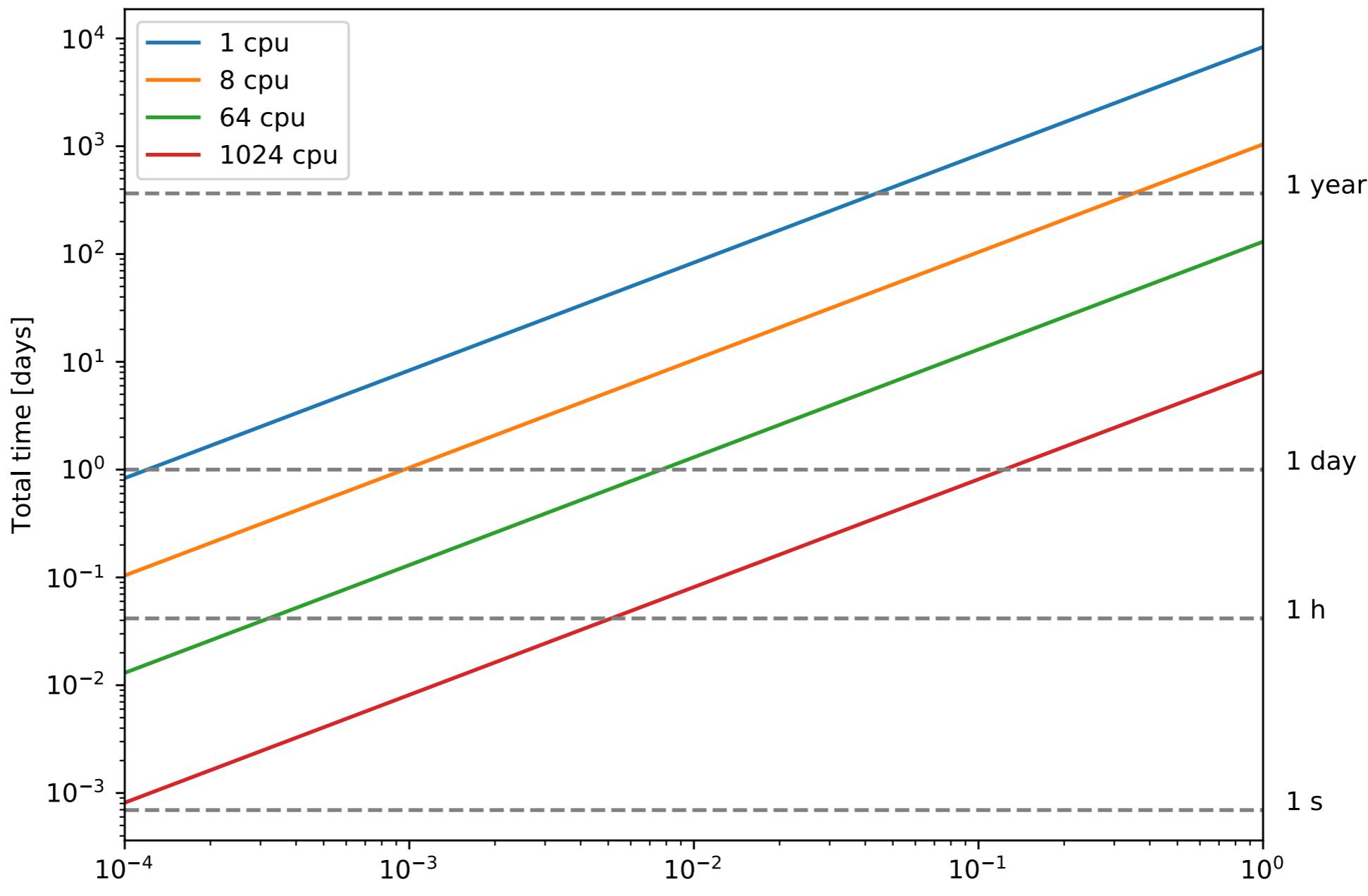
- ▶ 2000 x 2000 pixels
- ▶ 10 wavelength points 720 million spectral lines per day
- ▶ One observation per minute
- ▶ Observe during 3 hours

22.8 years to invert assuming 1 s per inversion

8.3 days to invert assuming 1 ms per inversion

SCALING WITH CPUS

3 hours @ 1 min cadence for FOV of 2000x2000



Magic number : 100 μ s per inversion

IMAGE RECONSTRUCTION

General problem

$$I = F(O) + n$$

$$\mathbf{I} = \mathbf{O} + \mathbf{n} \quad \xrightarrow{\hspace{2cm}} \text{Denoising}$$

$$\mathbf{I} = \mathbf{H}\mathbf{O} + \mathbf{n} \quad \xrightarrow{\hspace{2cm}} \text{Deconvolution}$$

$$\mathbf{I} = \mathbf{D}\mathbf{H}\mathbf{O} + \mathbf{n} \quad \xrightarrow{\hspace{2cm}} \text{Deconvolution+superresolution}$$

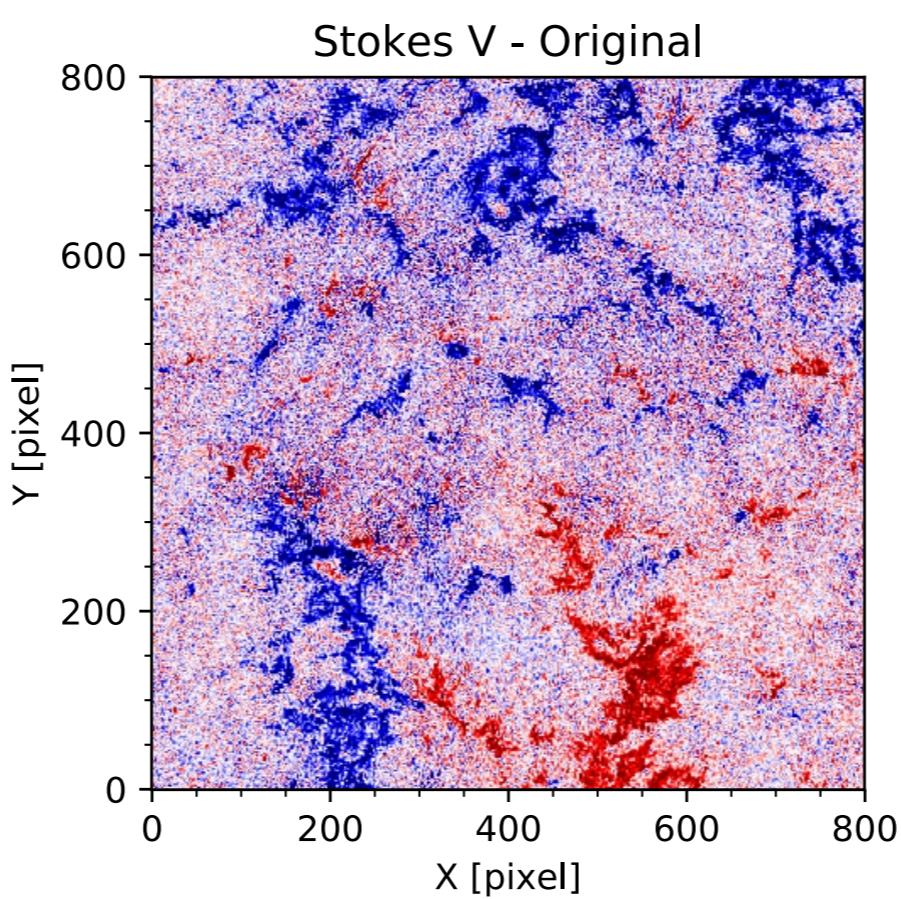
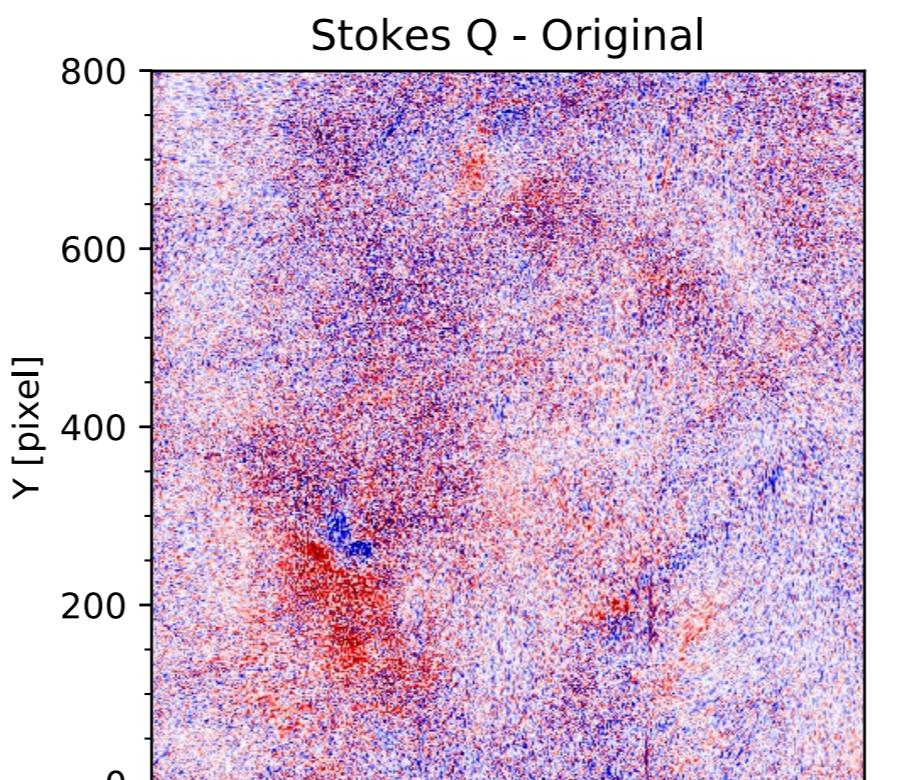
$$\mathbf{I} = RT(\mathbf{O}) + \mathbf{n} \quad \xrightarrow{\hspace{2cm}} \text{Reconstruction with nonlinear model}$$

image denoising

$$\mathbf{I} = \mathbf{O} + \mathbf{n}$$

NOISE FILTERING

$$\mathbf{I} = \mathbf{O} + \mathbf{n}$$



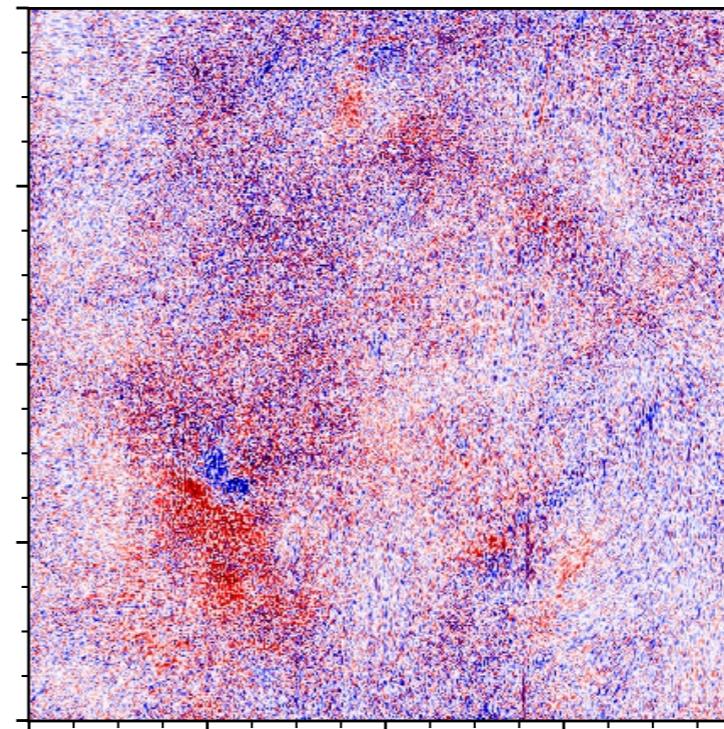
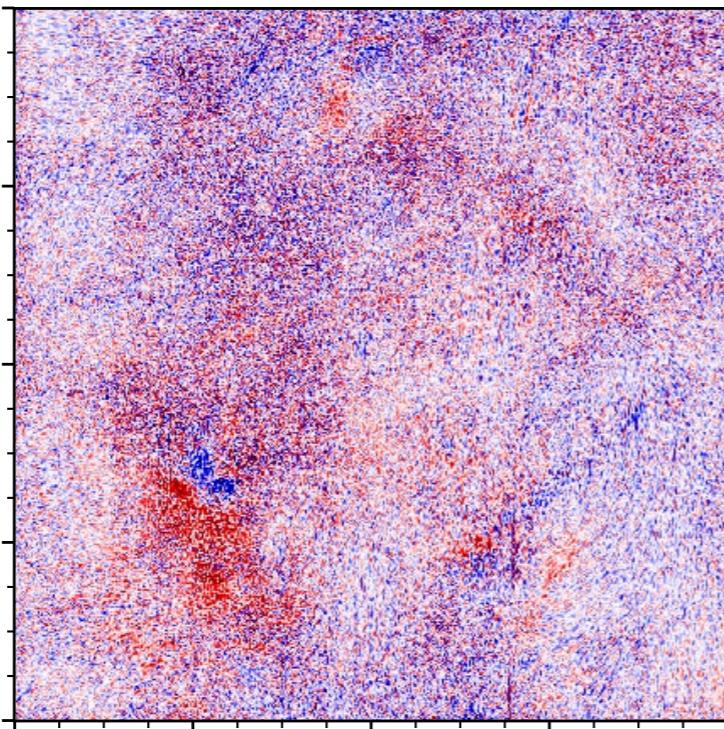
NOISE2NOISE: UNSUPERVISED TRAINING

$$\operatorname{argmin}_{\theta} \sum_i L(f_{\theta}(\hat{x}_i), \hat{y}_i)$$

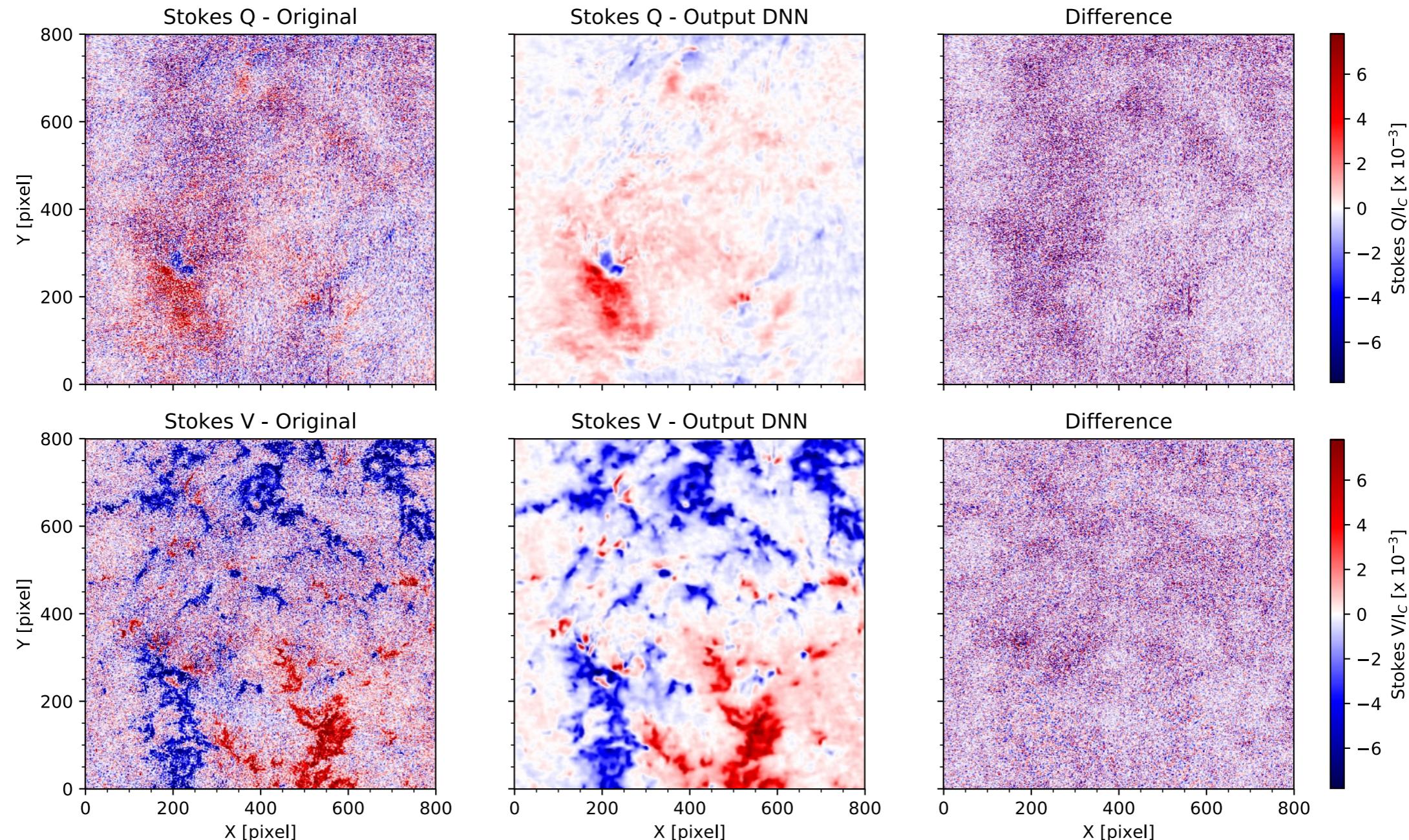
$\hat{y}_i \sim$ noisy distribution with same expectation

Lehtinen et al. (2018)

Two different realisations of noise

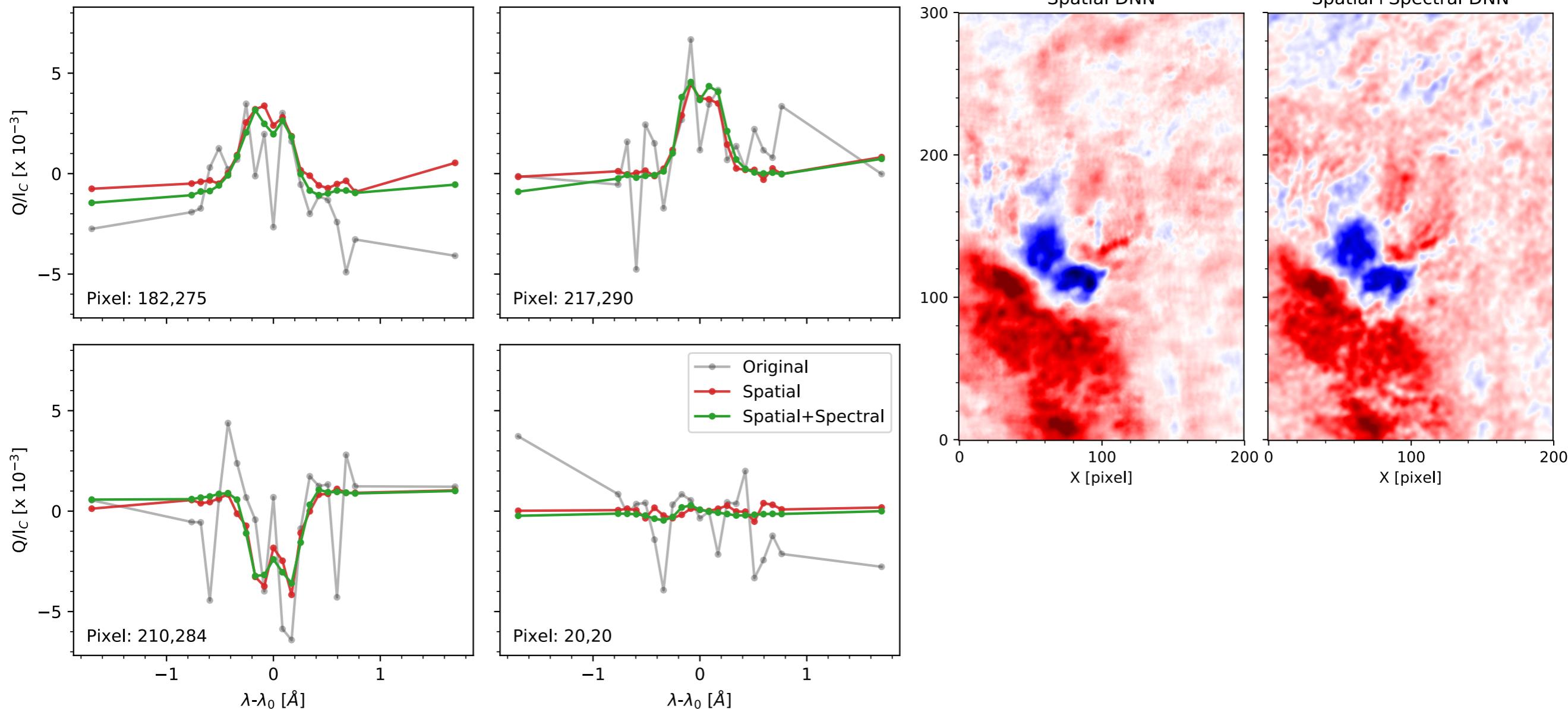


NOISE FILTERING : SST DATA



Díaz Baso et al. (2019)

NOISE FILTERING : PROFILES

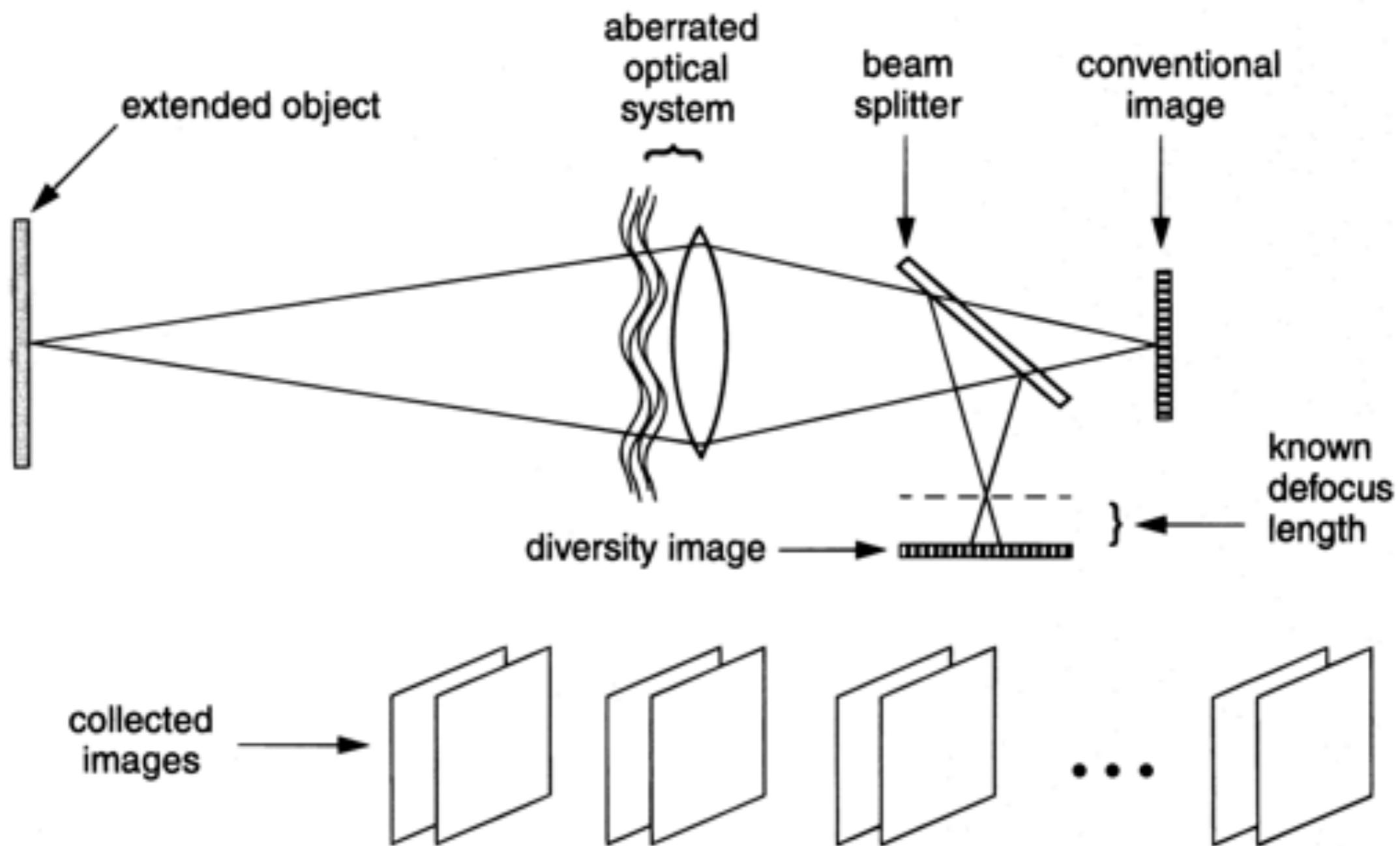


Díaz Baso et al. (2019)

image deconvolution

$$\mathbf{I} = \mathbf{H}\mathbf{O} + \mathbf{n}$$

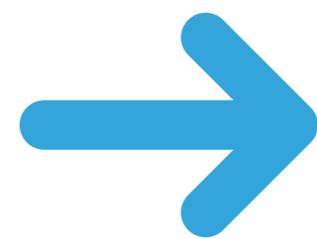
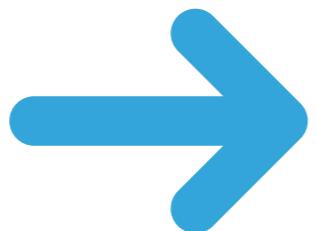
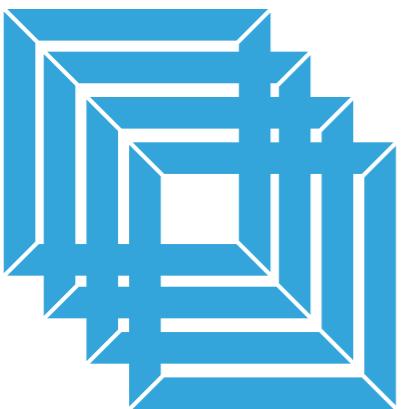
MULTIFRAME BLIND DECONVOLUTION



Paxman et al. (1996)

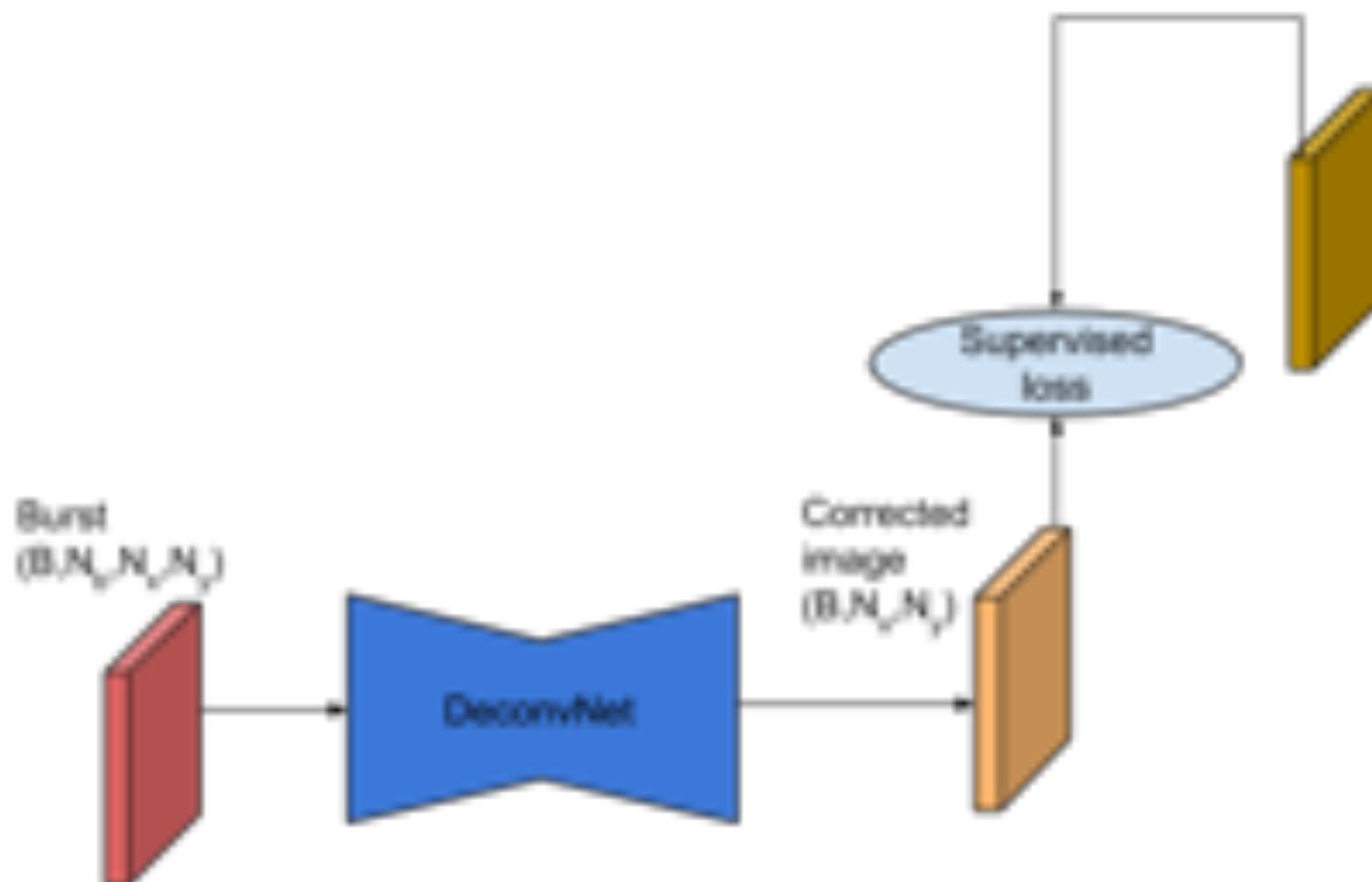
MFBD: SUPERVISED TRAINING

Burst of
perturbed images



Corrected
image

MFBD: SUPERVISED TRAINING

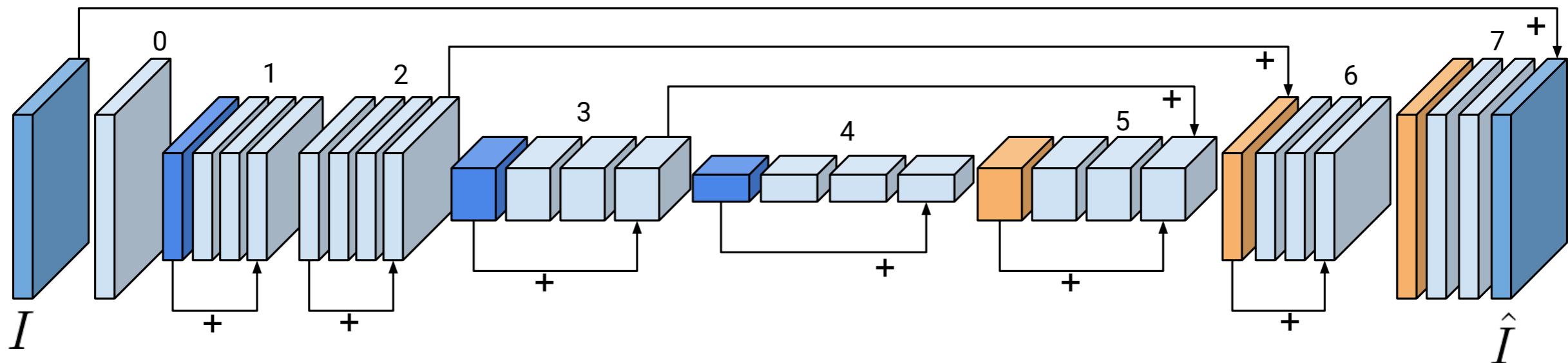


Asensio Ramos et al. (2019)

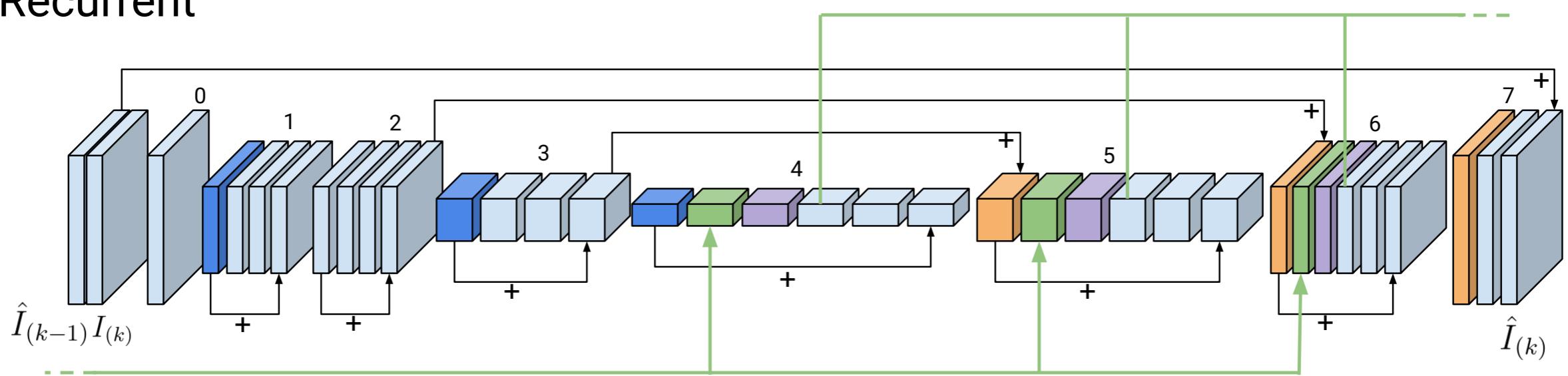
- ▶ 1k x 1k images at ~100 Hz
- ▶ https://github.com/aasensio/learned_mfbd

MULTIFRAME BLIND DECONVOLUTION

Encoder-decoder

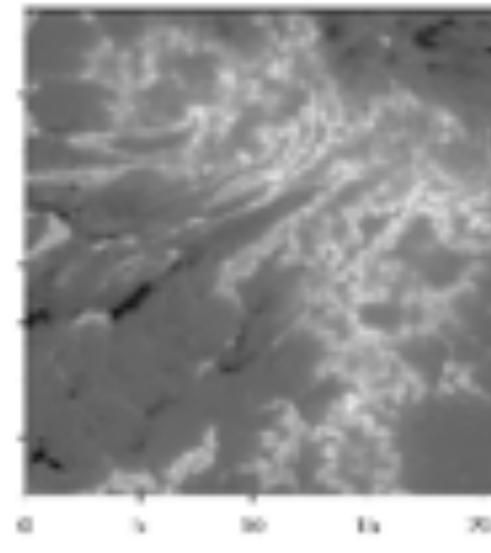
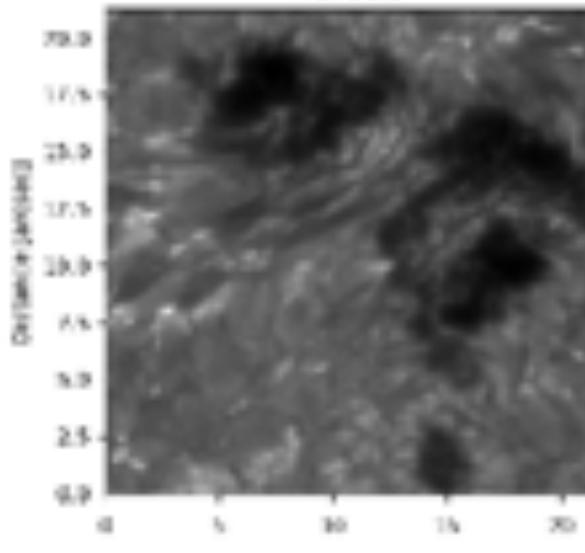


Recurrent

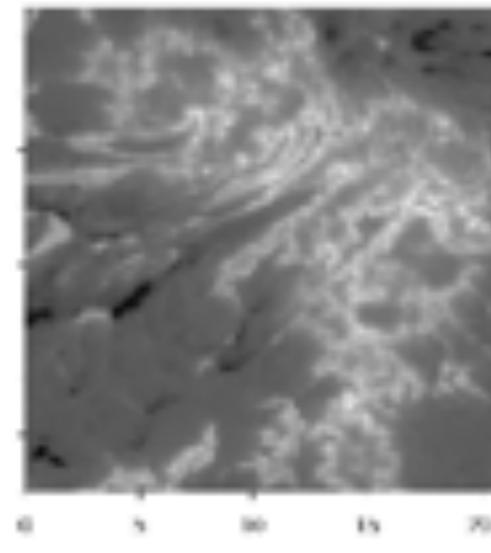
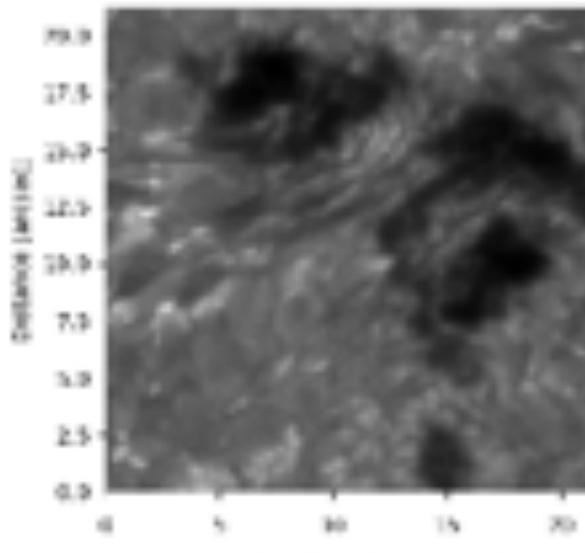


POLARIMETRY

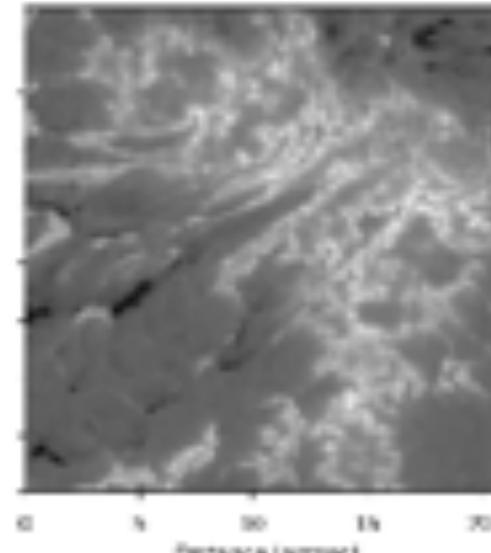
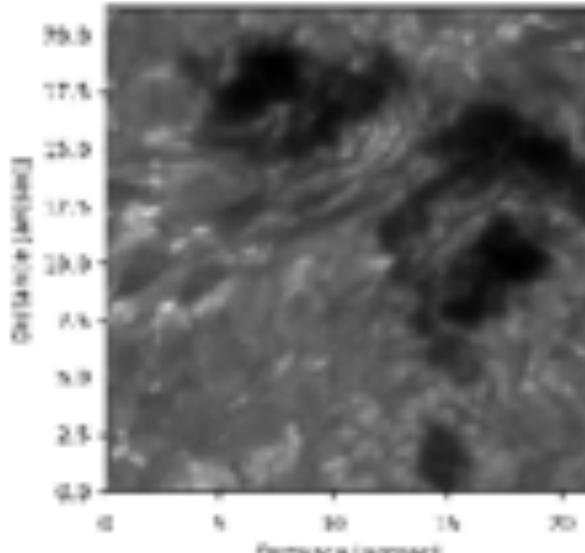
MOMFIT



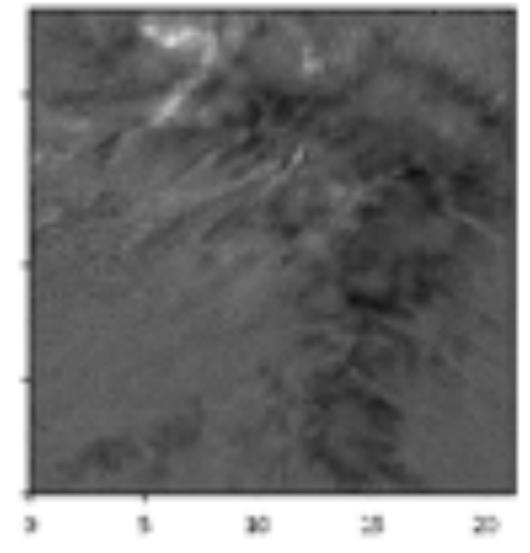
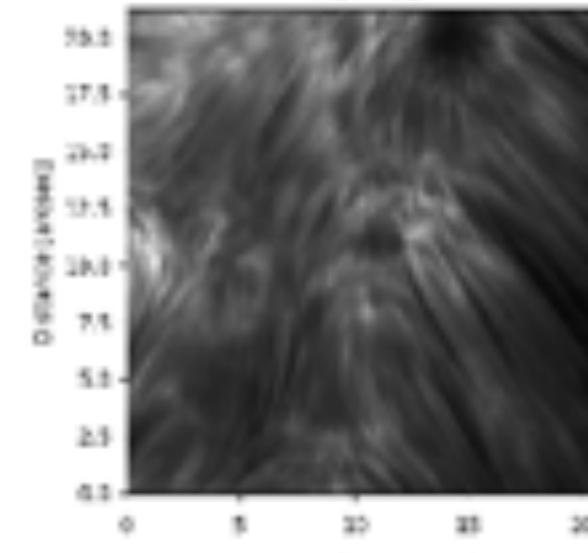
Recursive network



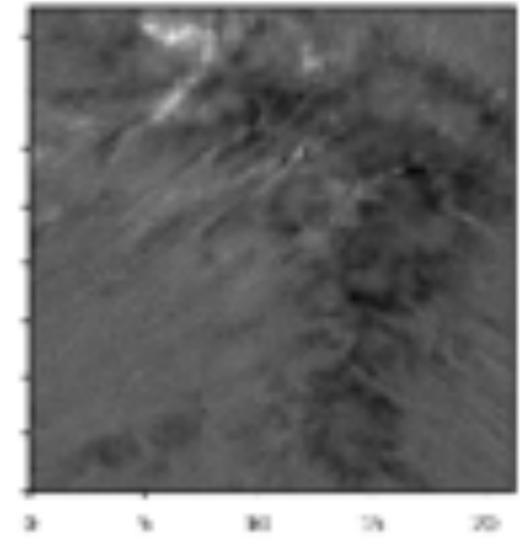
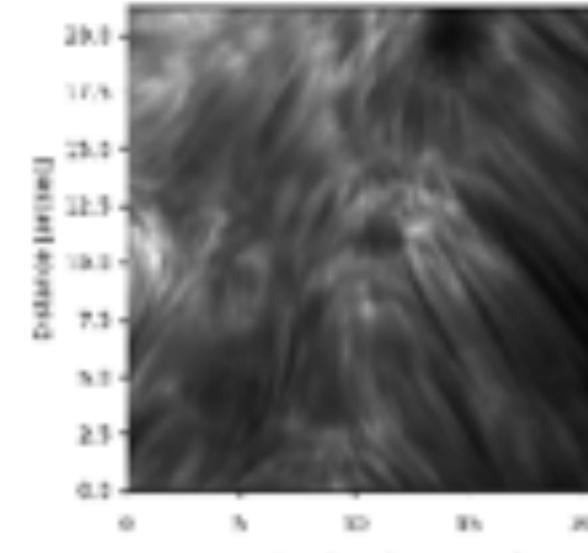
Encoder-decoder network



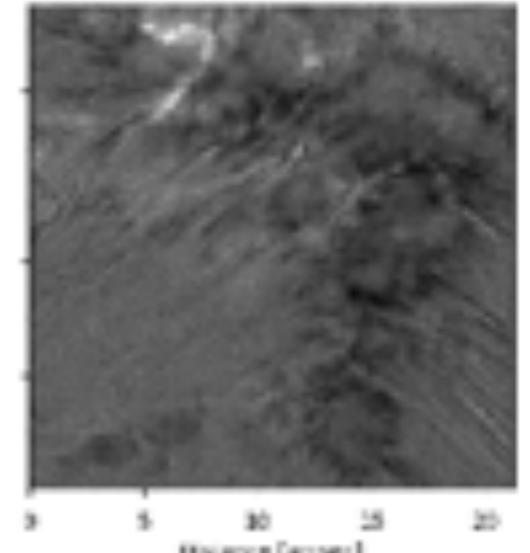
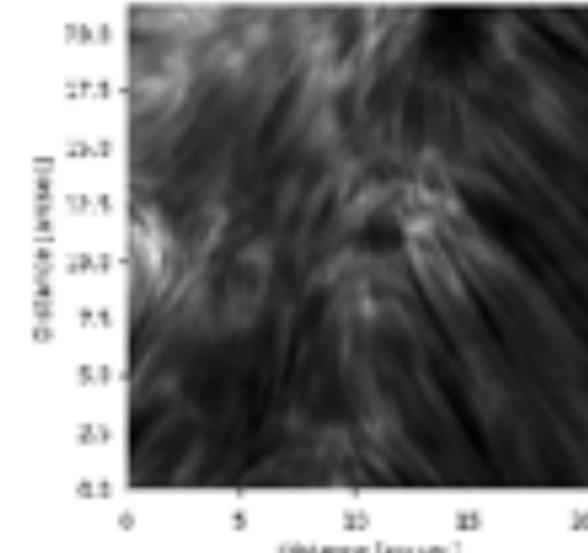
MOMFIT



Recursive network



Encoder-decoder network



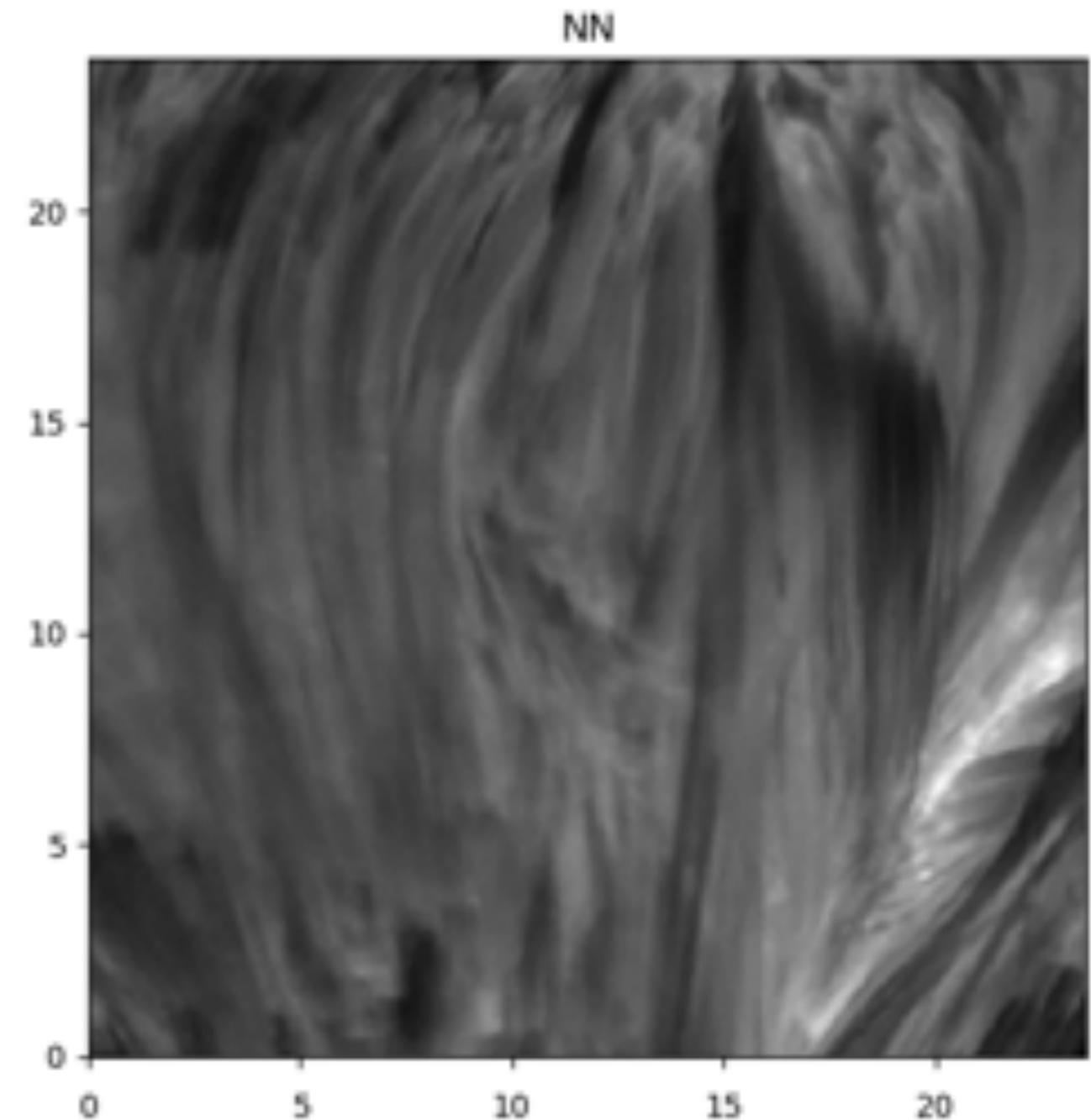
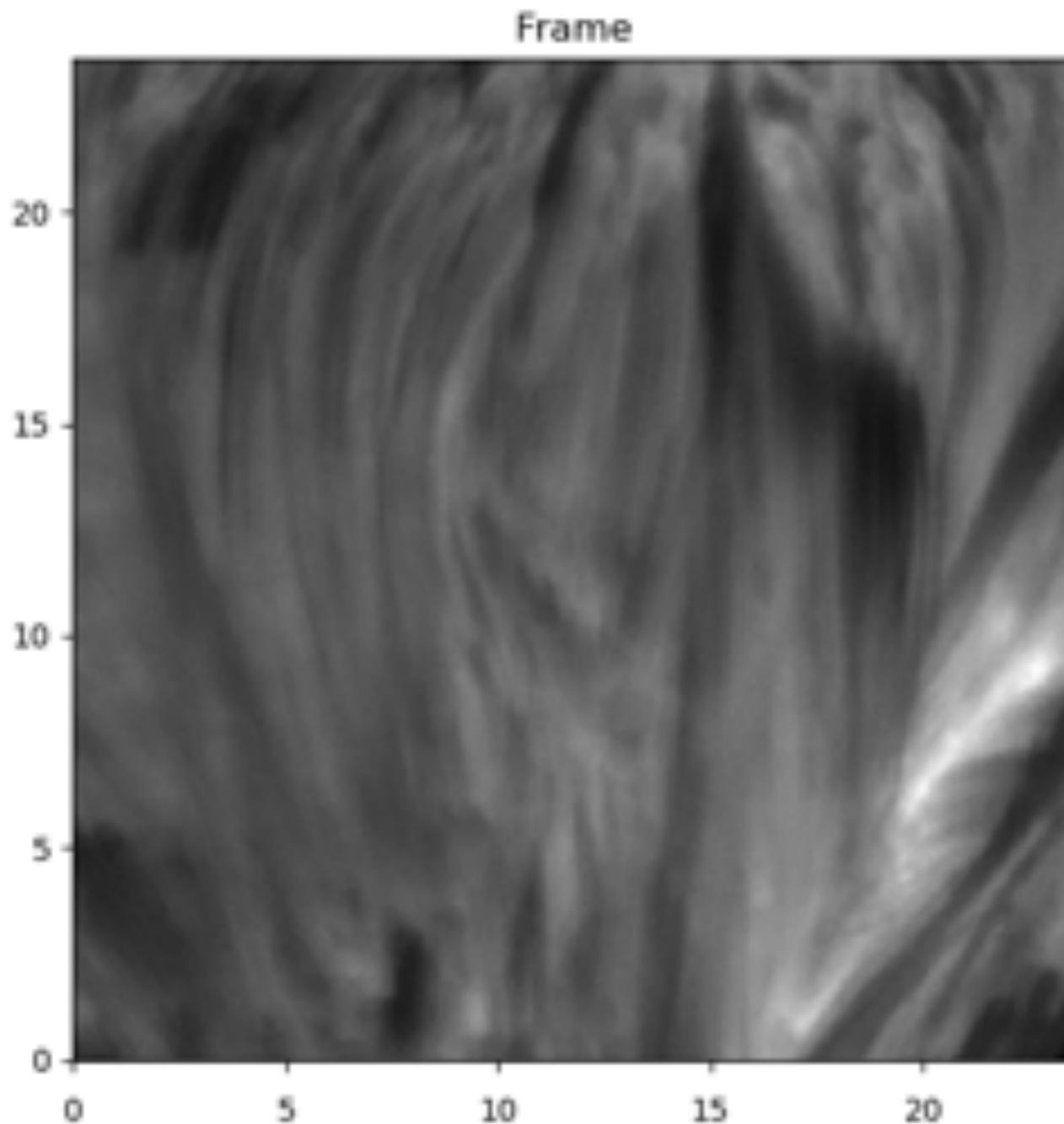
Distance [arcsec]

Distance [arcsec]

Distance [arcsec]

Distance [arcsec]

GENERALIZATION TO UNSEEN DATA



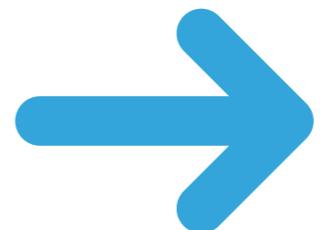
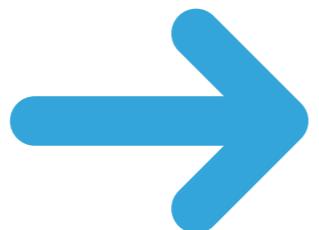
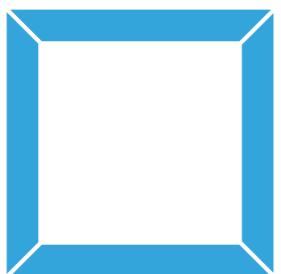
100 images/s

image
deconvolution+superresolution

$$I = DHO + n$$

SINGLE IMAGE SUPERRESOLUTION

Perturbed
image

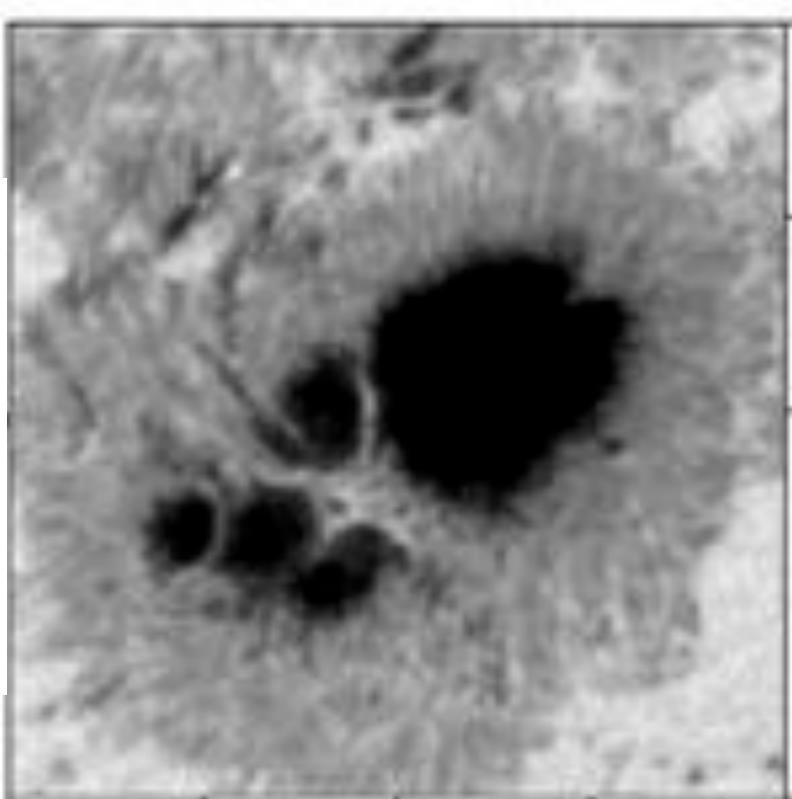


Corrected
image

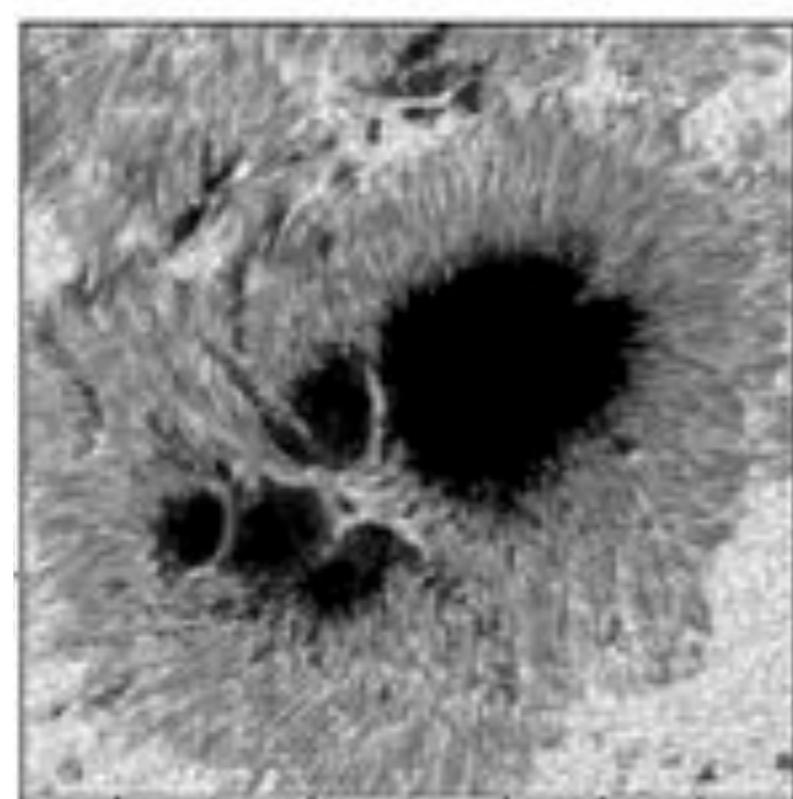


ENHANCE: SINGLE IMAGE SUPERRESOLUTION

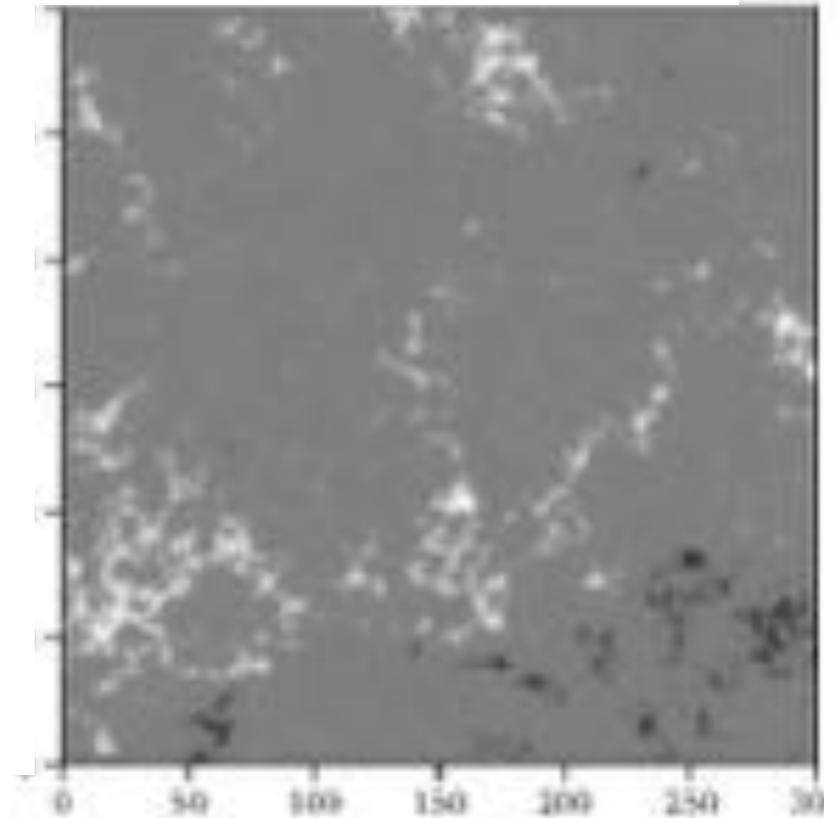
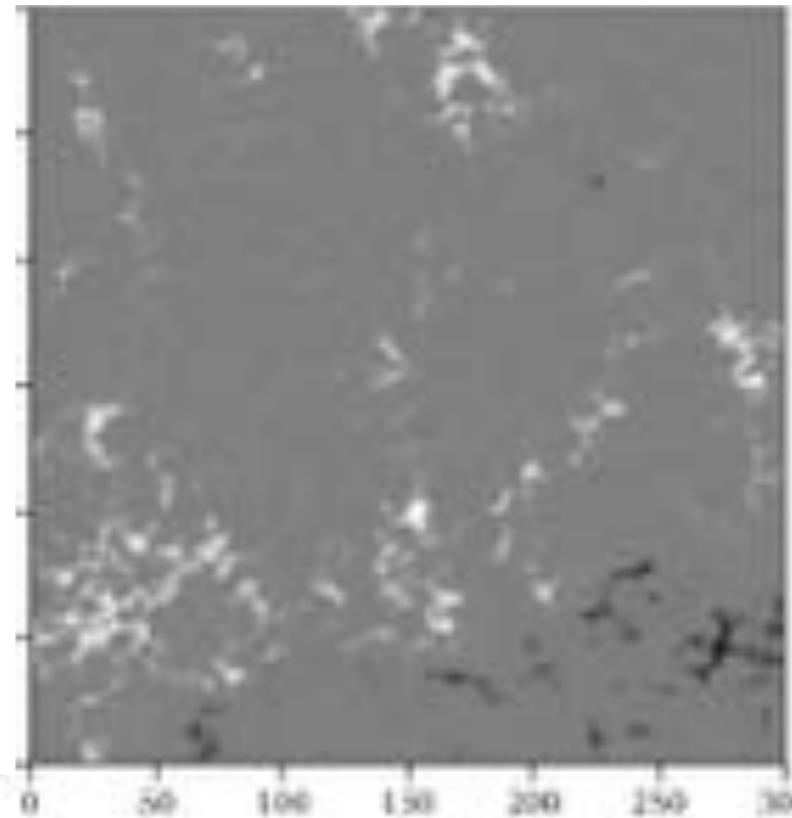
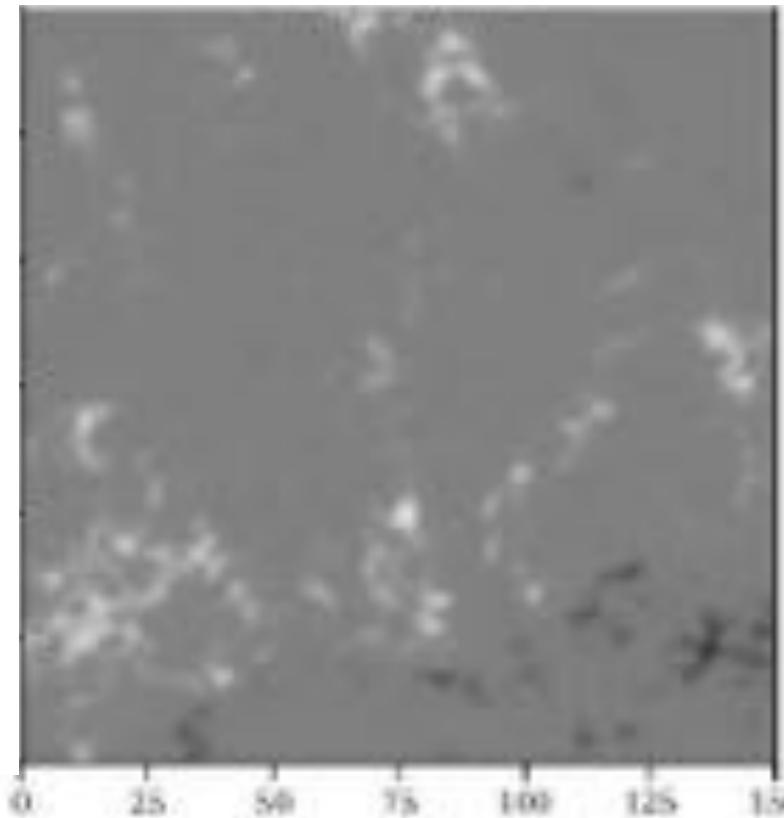
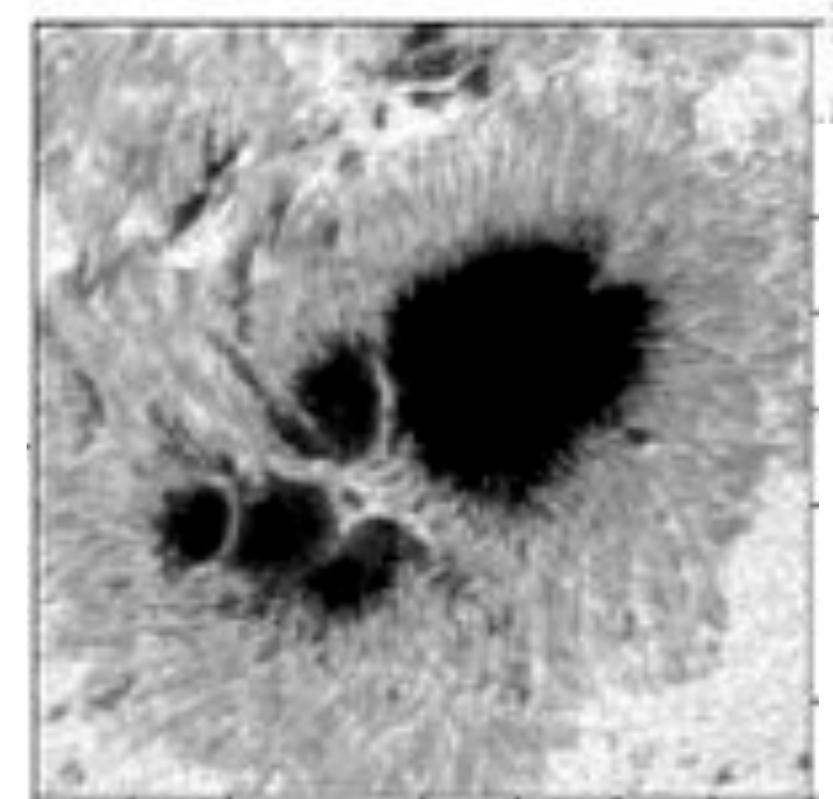
HMI



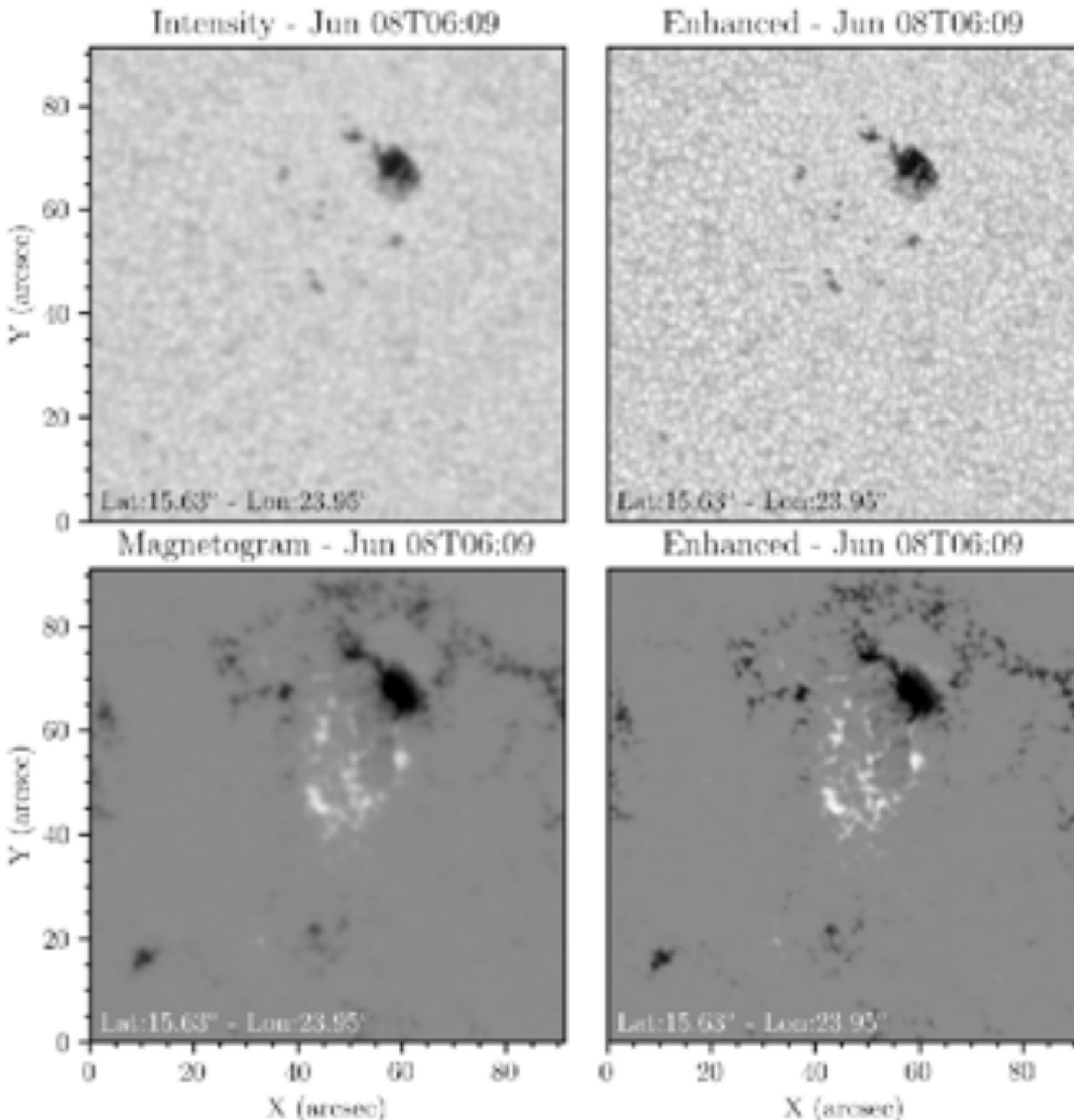
Neural network



Hinode



ENHANCE <https://github.com/cdiazbas/enhance>



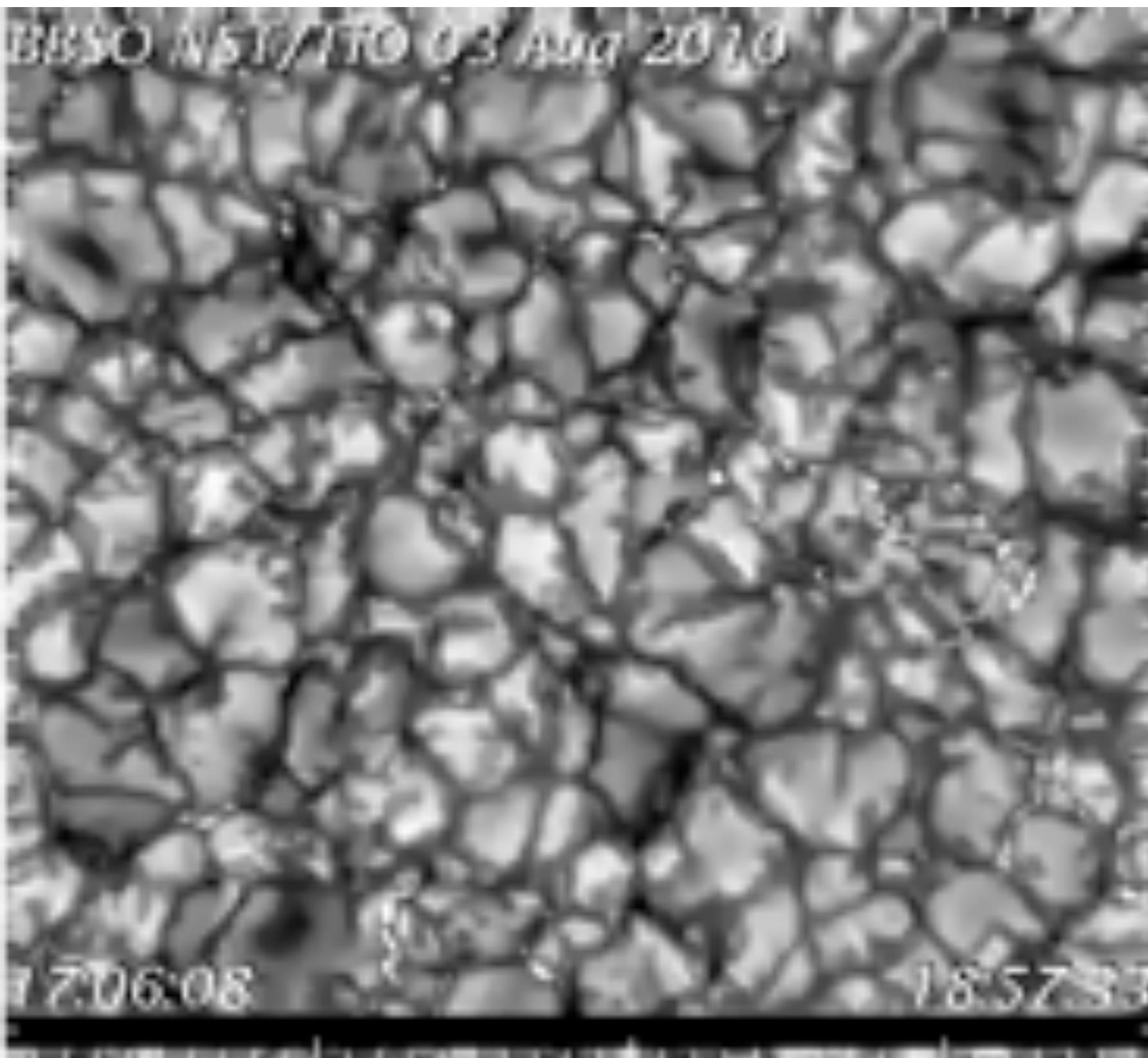
courtesy of S. Castellanos Durán

image nonlinear inversion

$$\mathbf{I} = f(\mathbf{O}) + \mathbf{n}$$

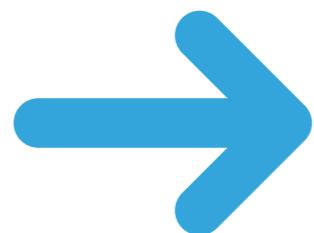
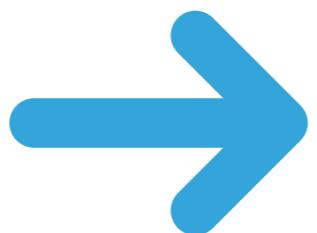
optical flow estimation

MEASURING VELOCITIES

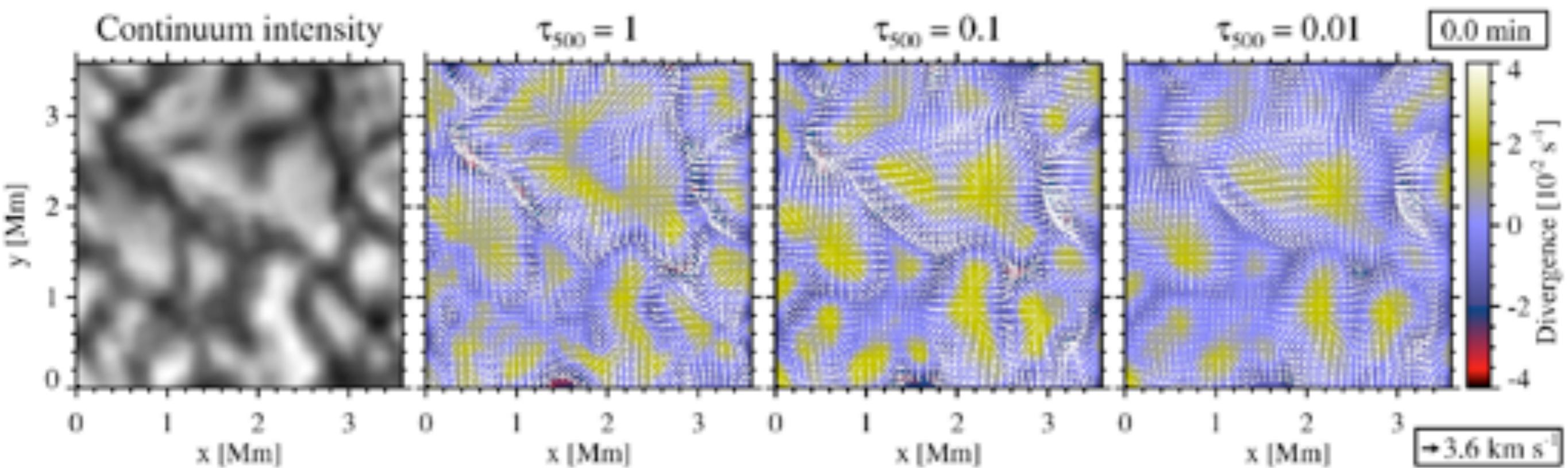


MEASURING VELOCITIES

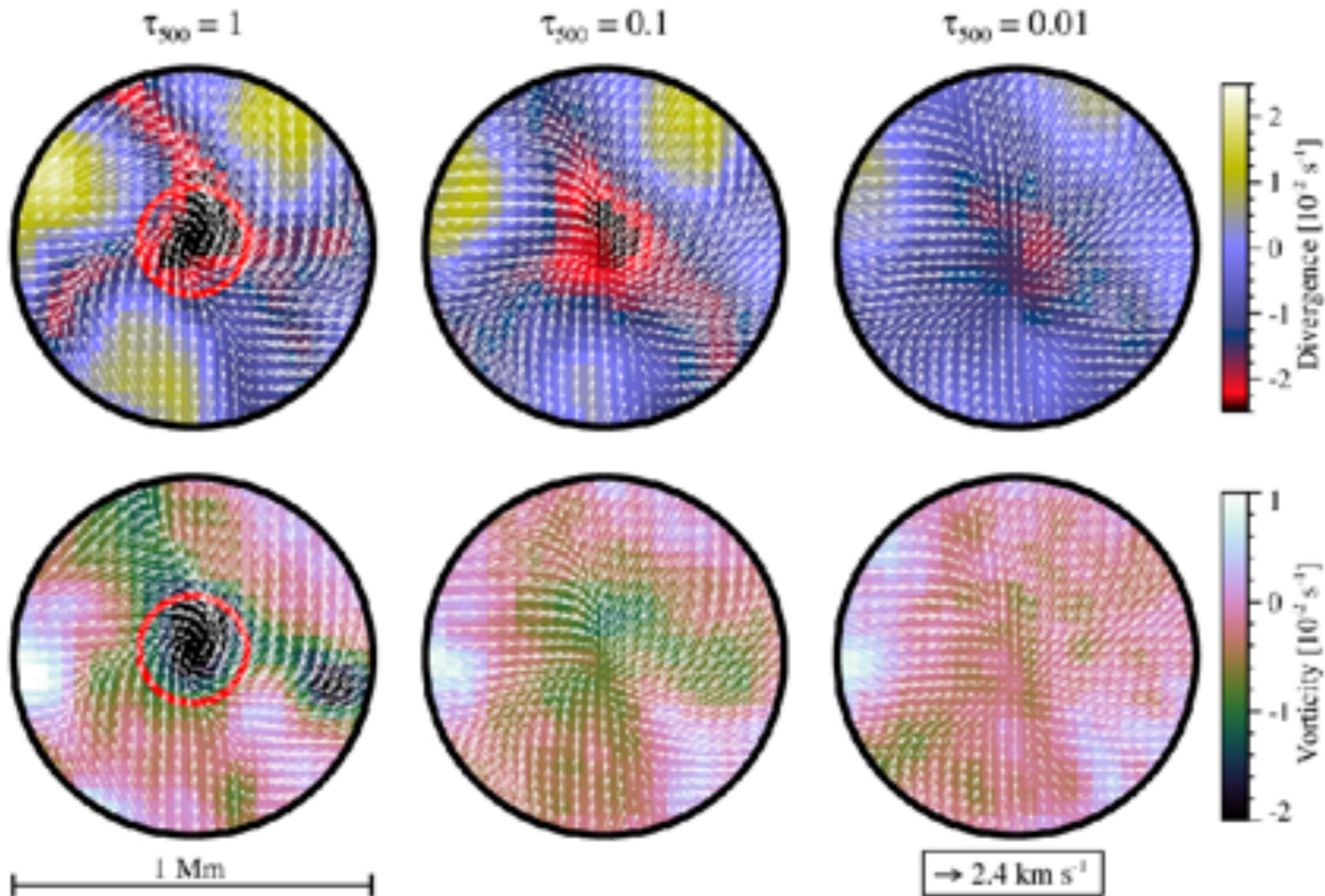
Consecutive
frames



v_x, v_y

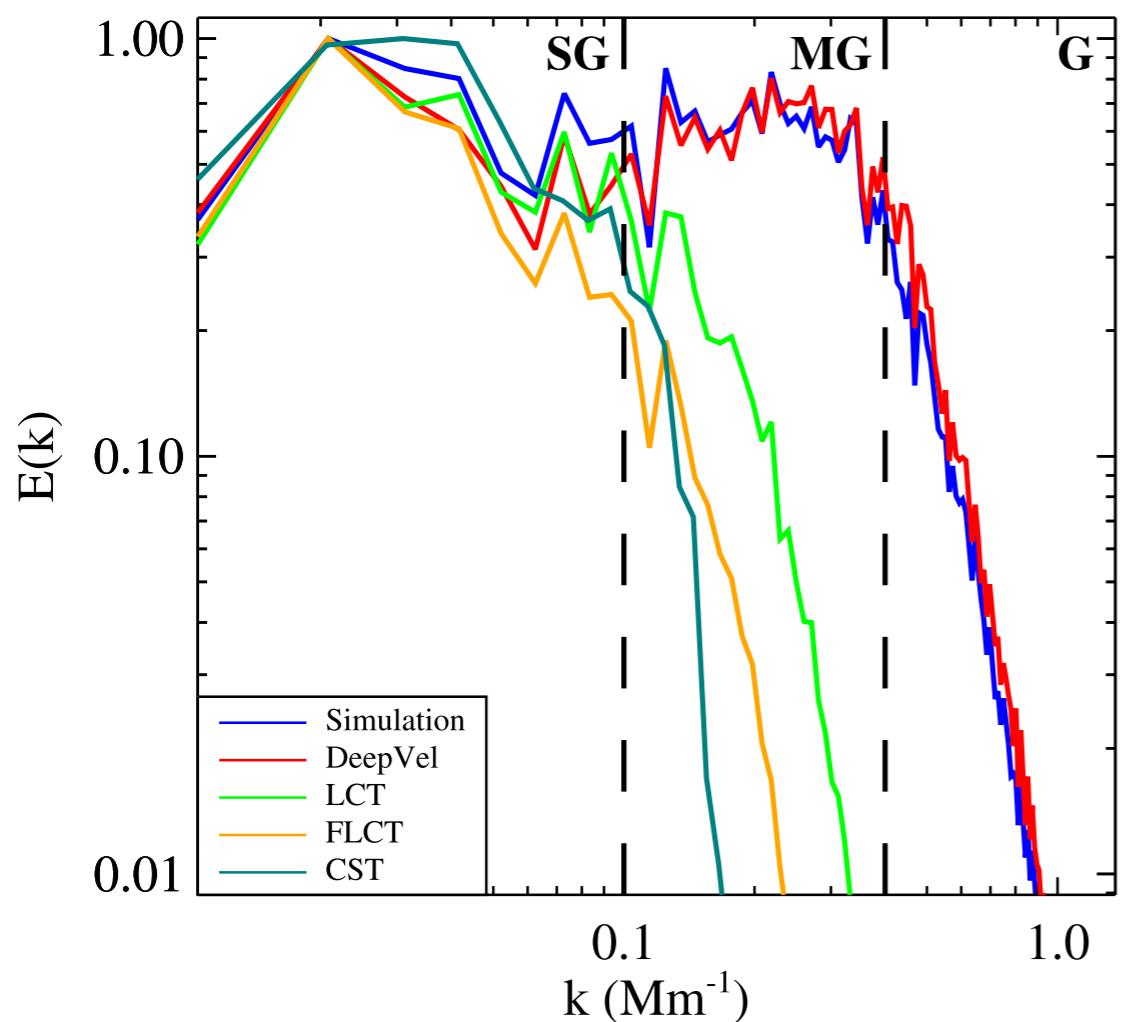


SMALL SCALE VORTEX FLOWS

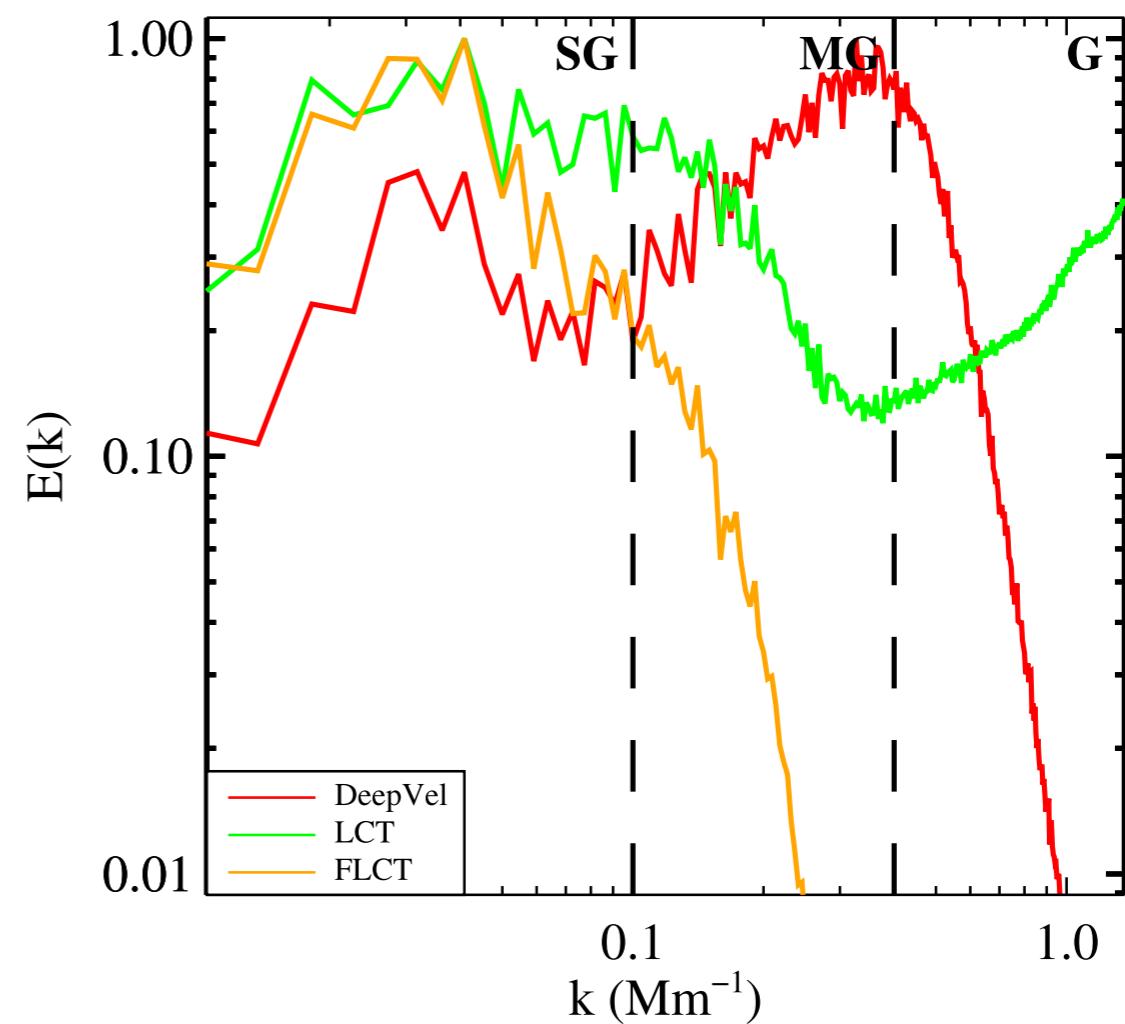


KINETIC ENERGY SPECTRUM

Simulations



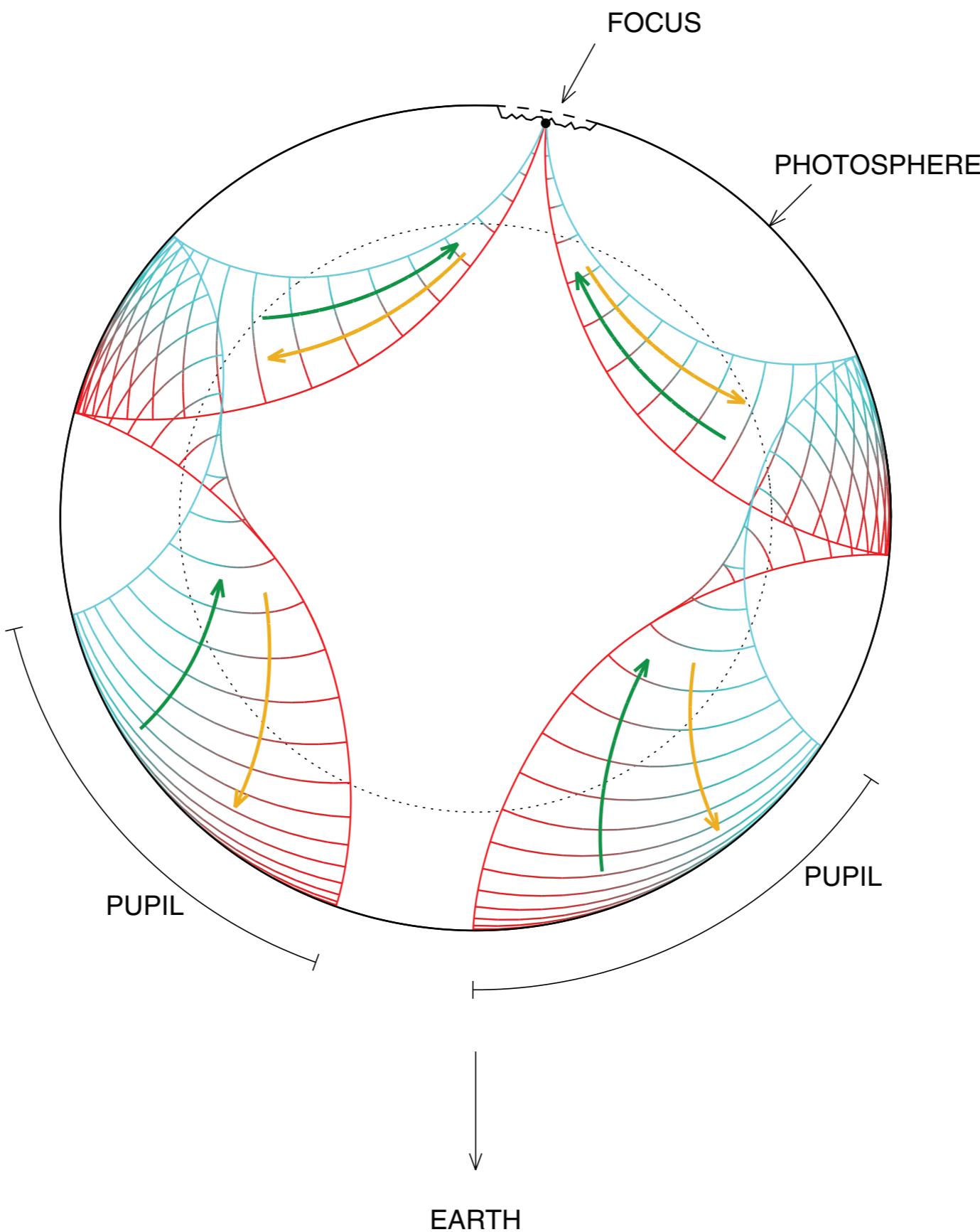
SDO/HMI



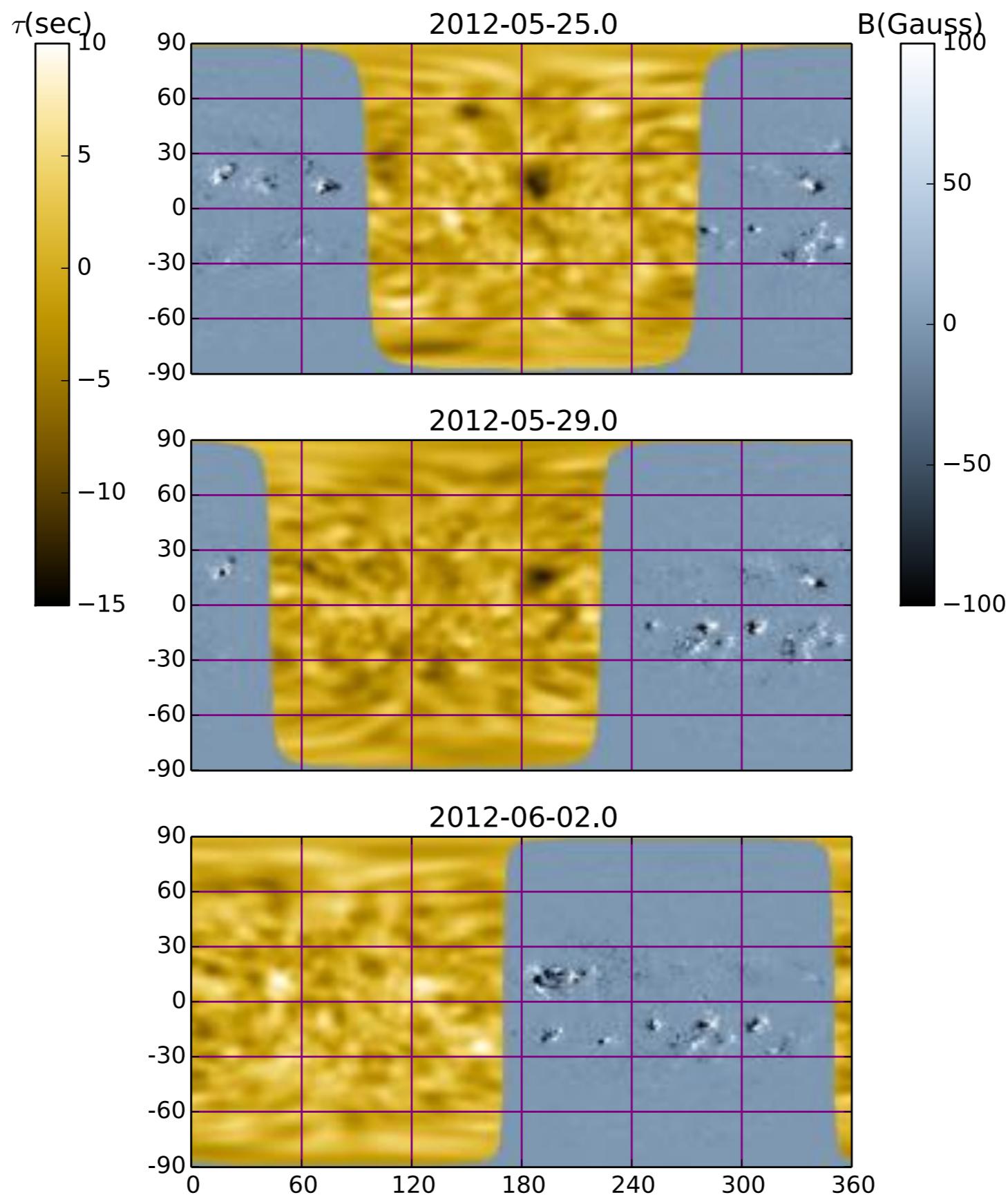
Tremblay et al. (2018)

farside enhancement
image segmentation

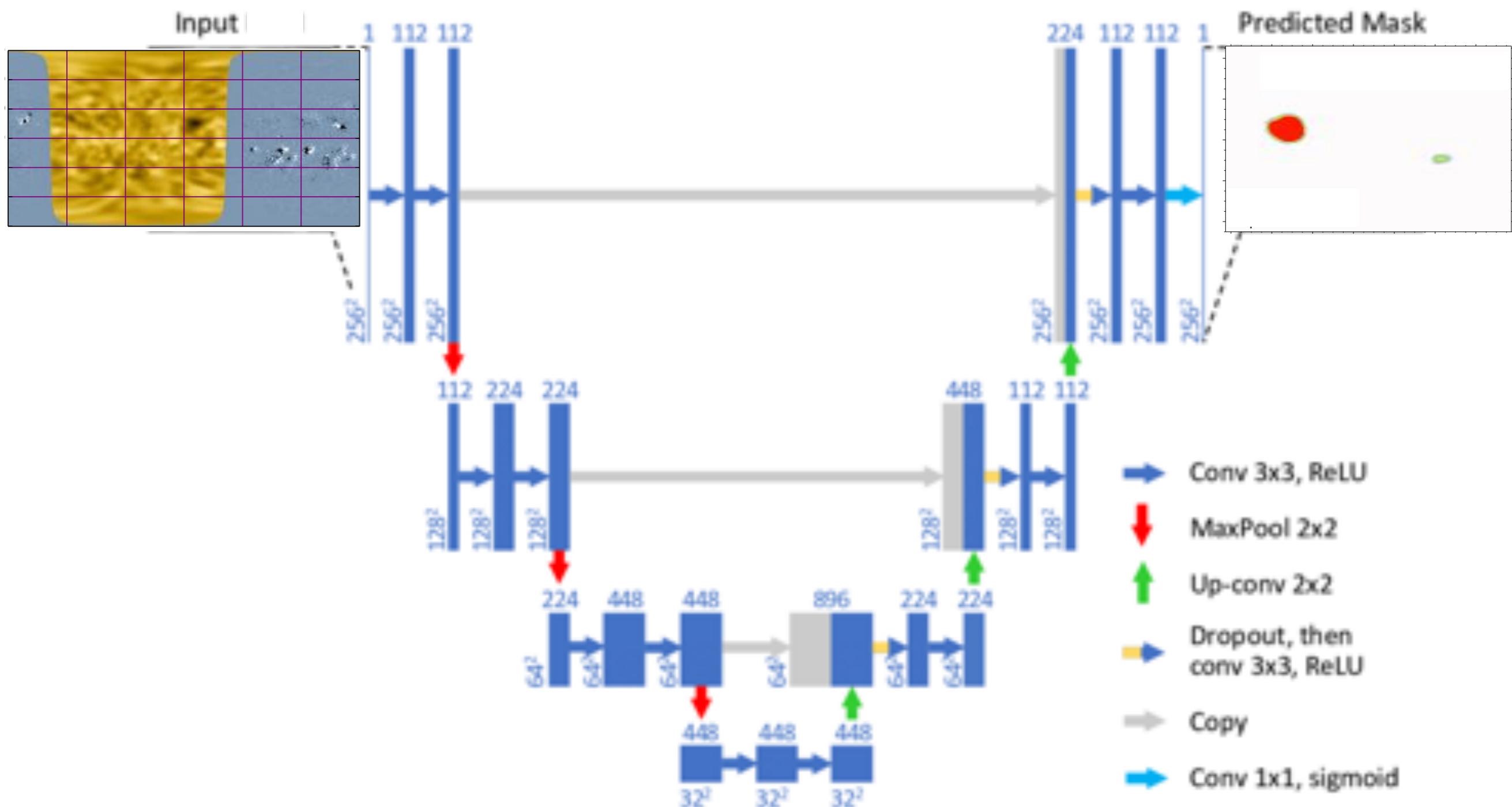
FARSIDE PROBLEM



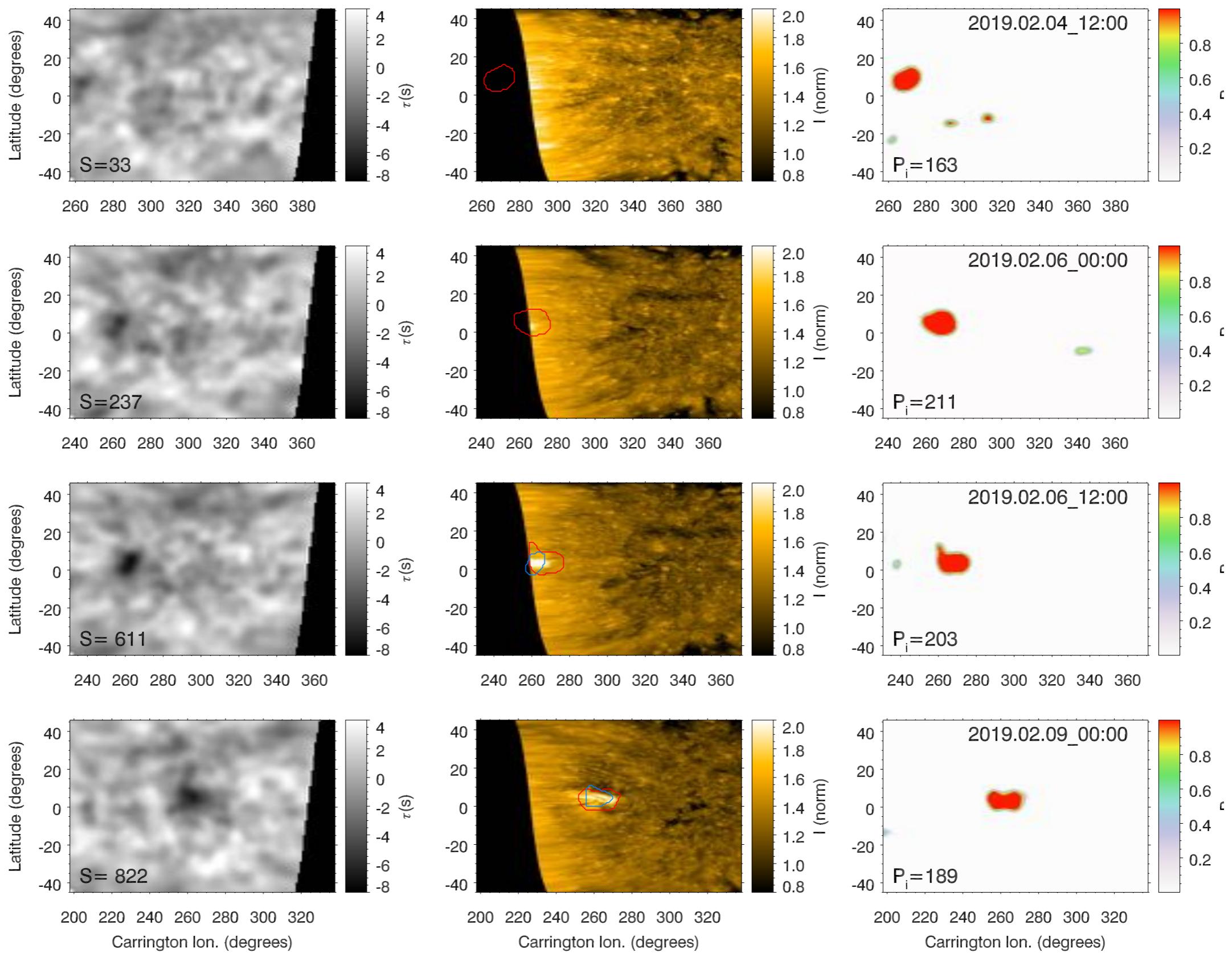
CURRENT FAR SIDE PREDICTIONS



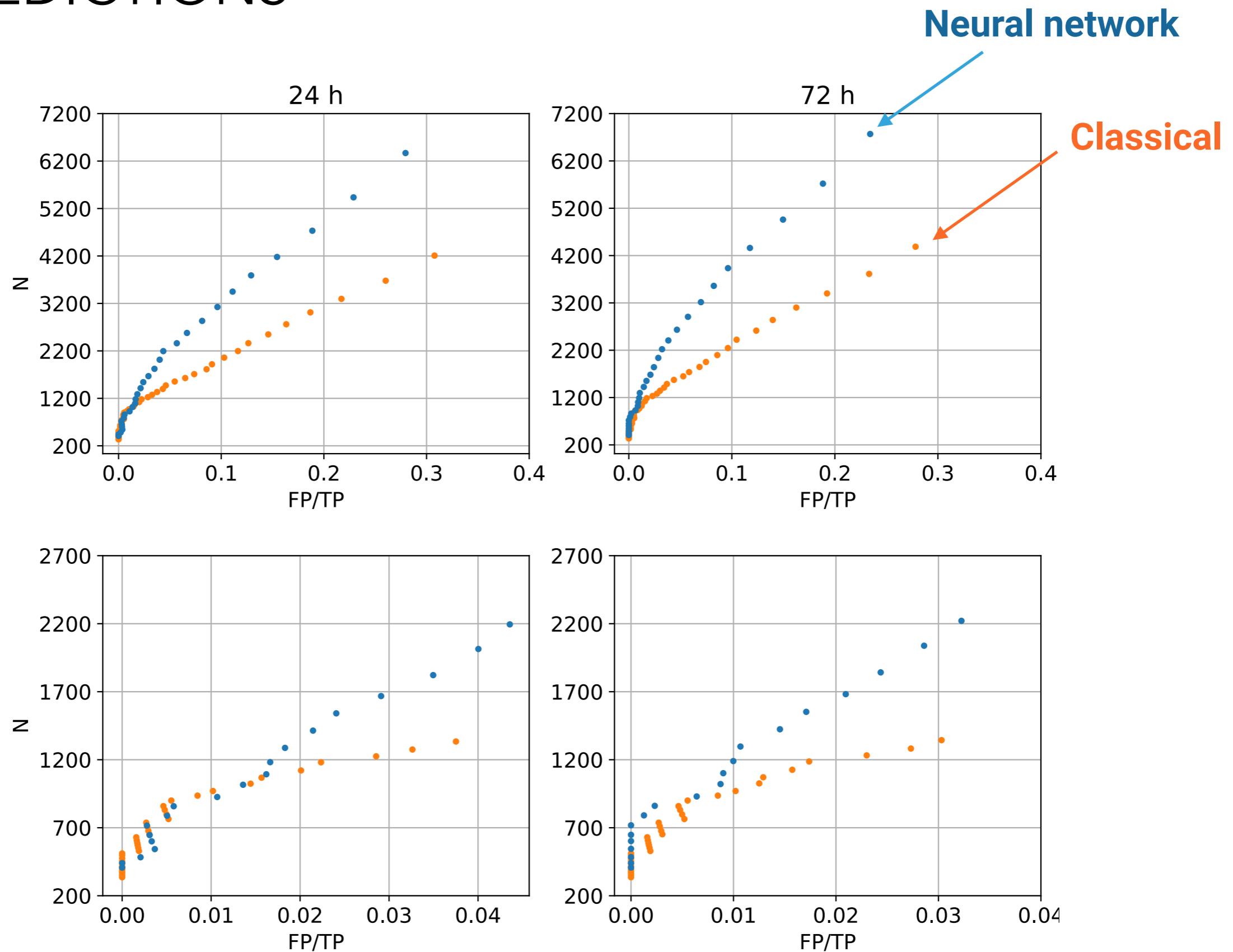
U-NET ARCHITECTURE



OUR PREDICTIONS

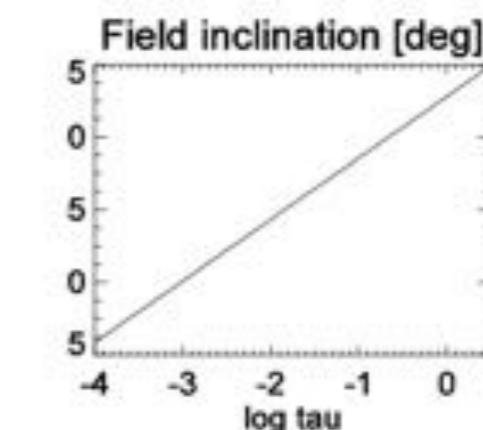
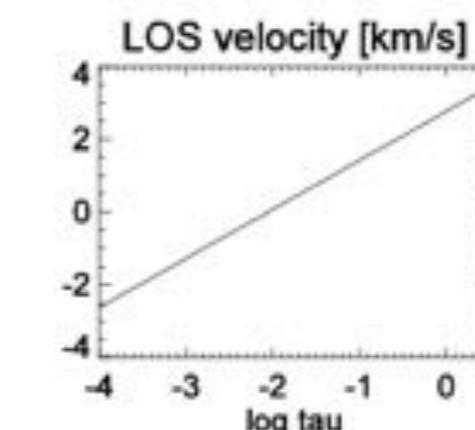
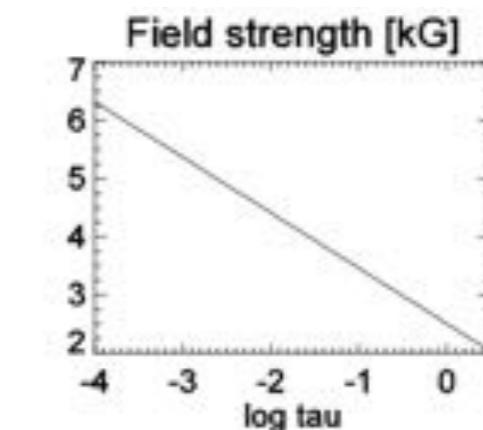
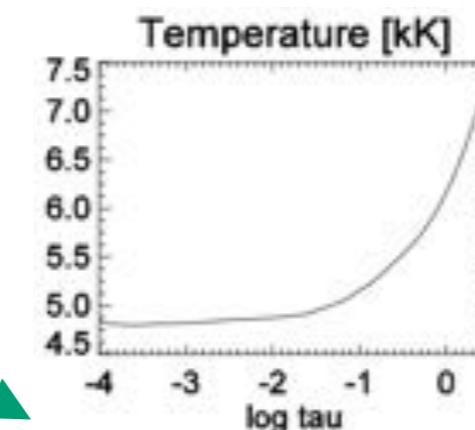
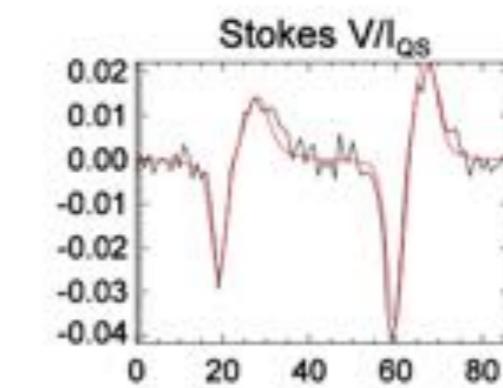
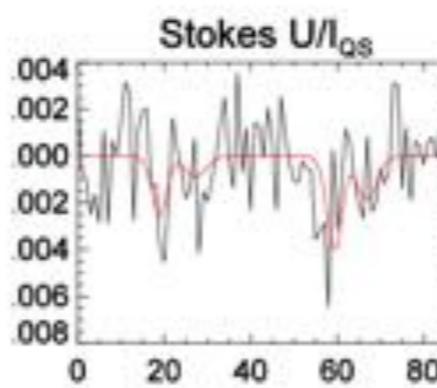
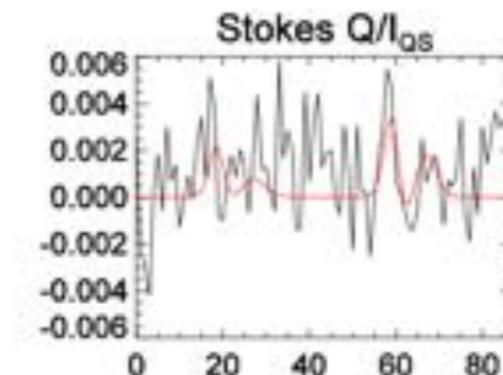
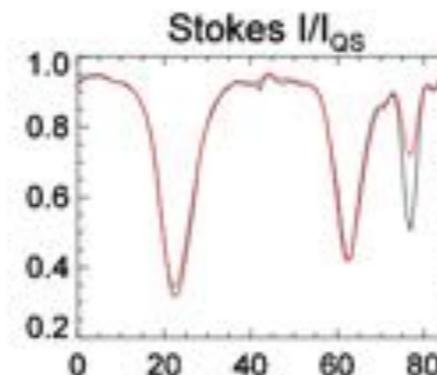
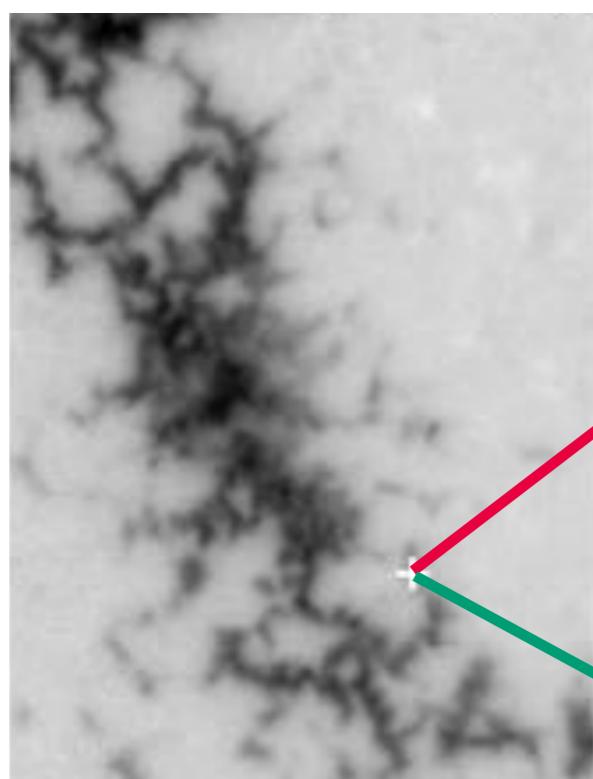


OUR PREDICTIONS



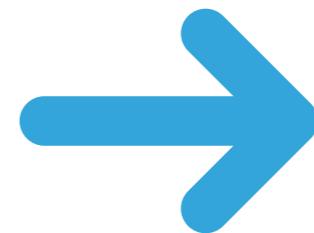
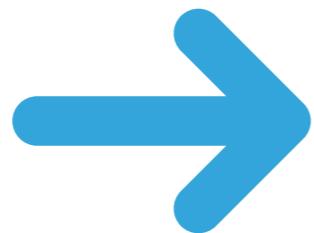
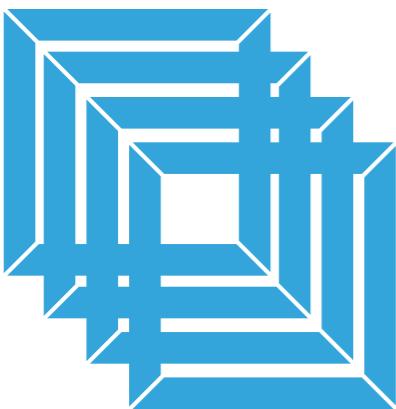
spectropolarimetric inversions

SPECTROPOLARIMETRIC INVERSIONS



SPECTROPOLARIMETRIC INVERSIONS

Stokes profiles

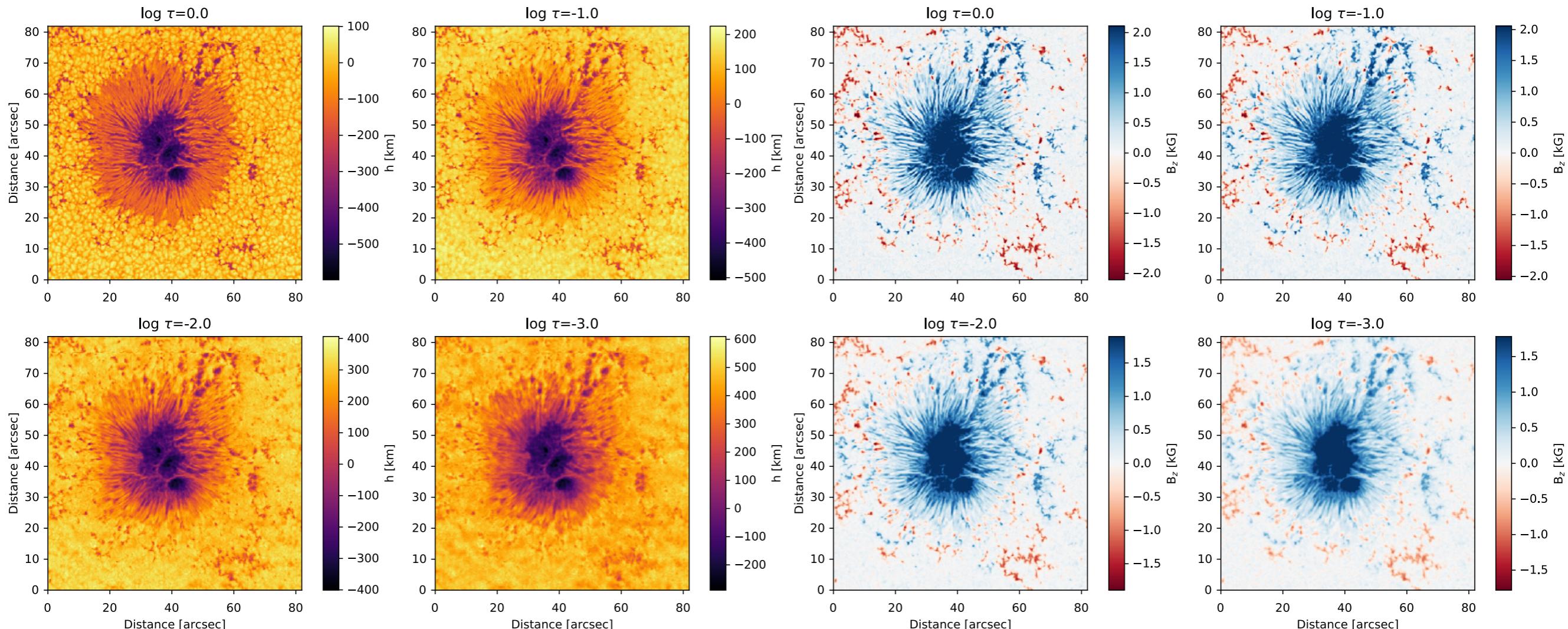


T, v, B, ...



AR10933 : INFERENCE

τ surfaces

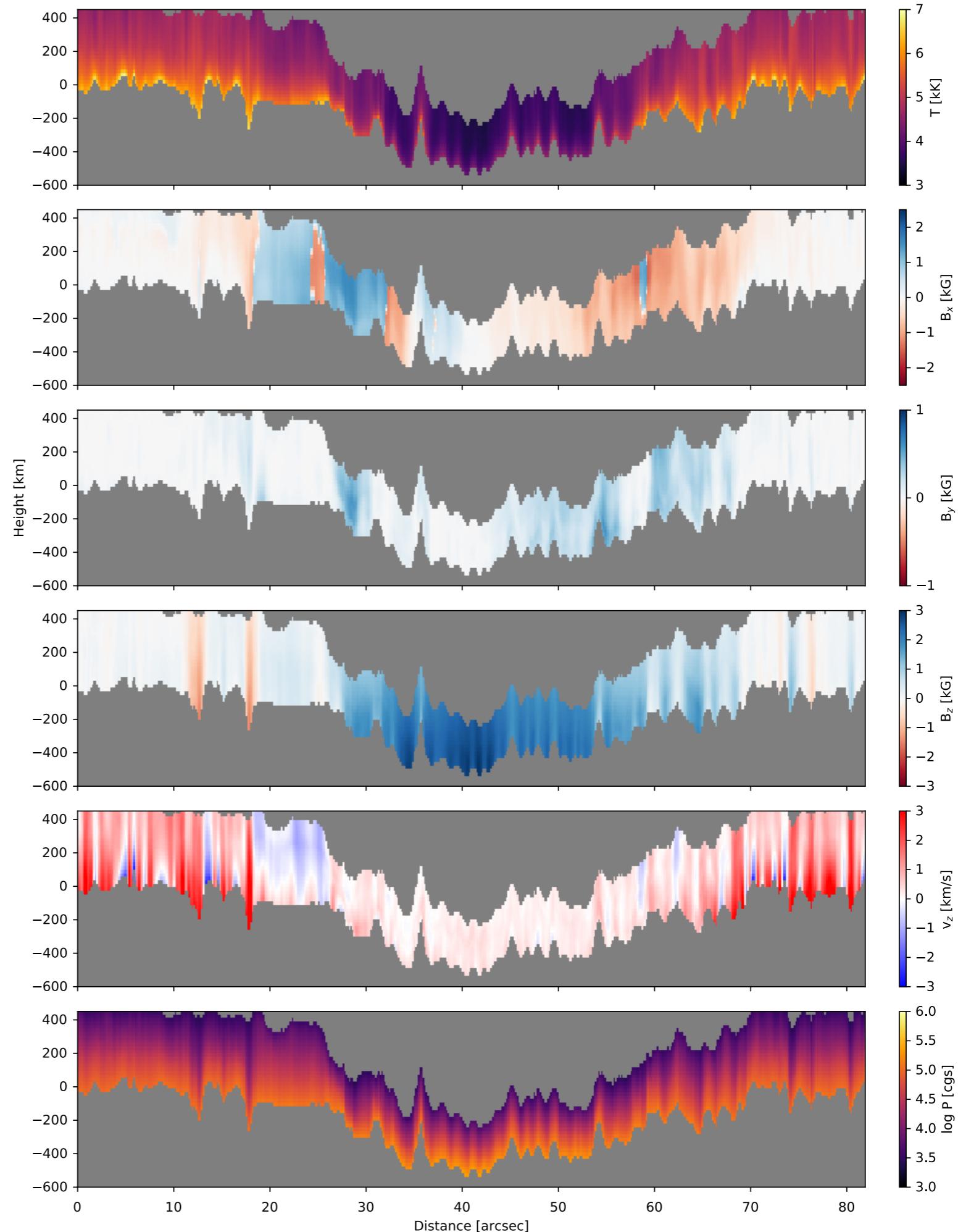
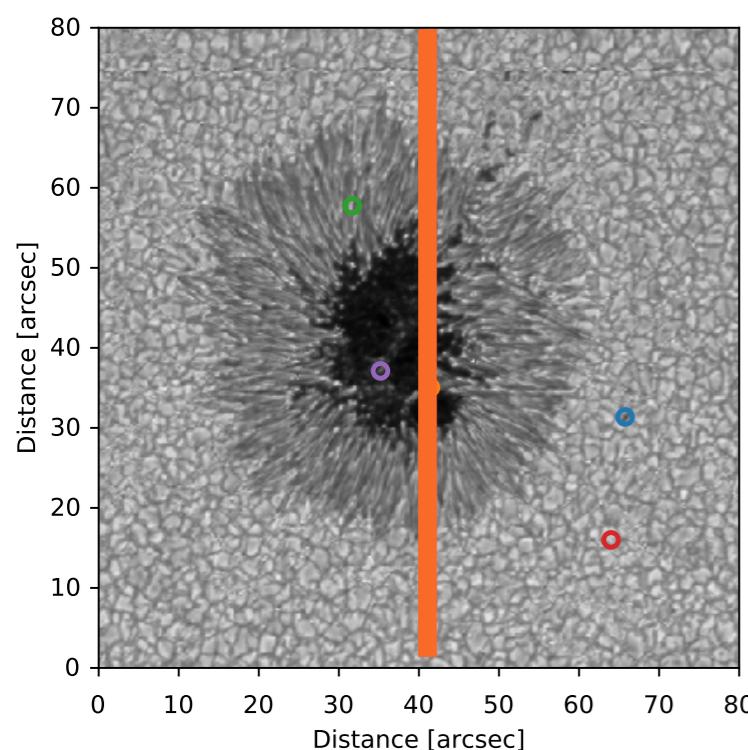


180 ms for 512x512

700 ns per pixel

30 minutes for all Hinode observations

LIGHT BRIDGE



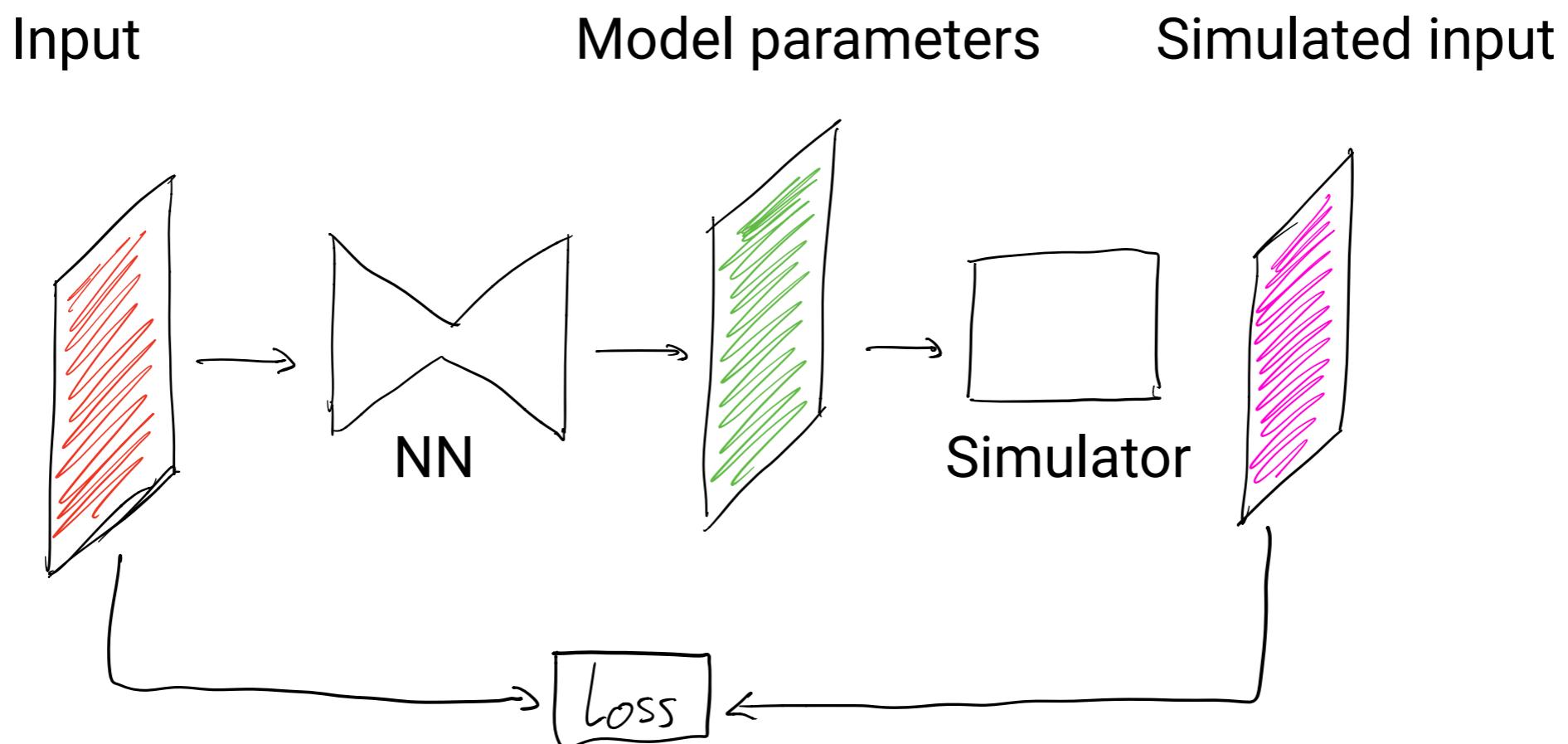
physics-based losses

&

surrogate models

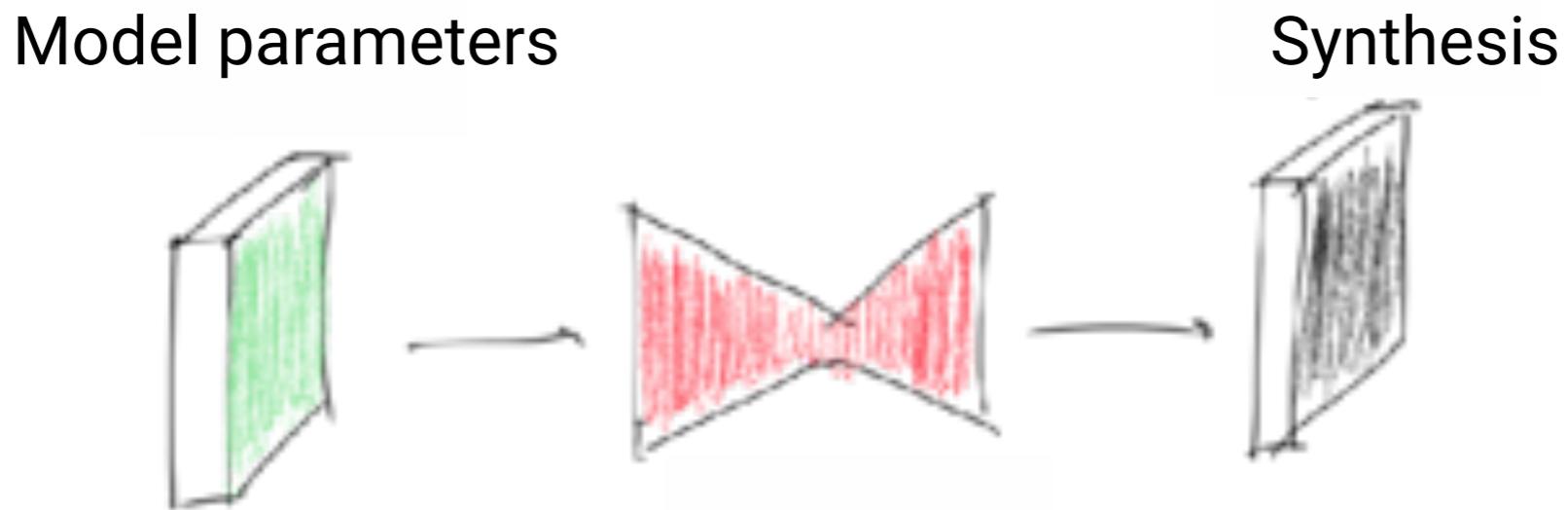
PHYSICS-BASED LOSSES

- ▶ Use our knowledge of physics
- ▶ Make use of differentiable simulators
- ▶ Train unsupervisedly



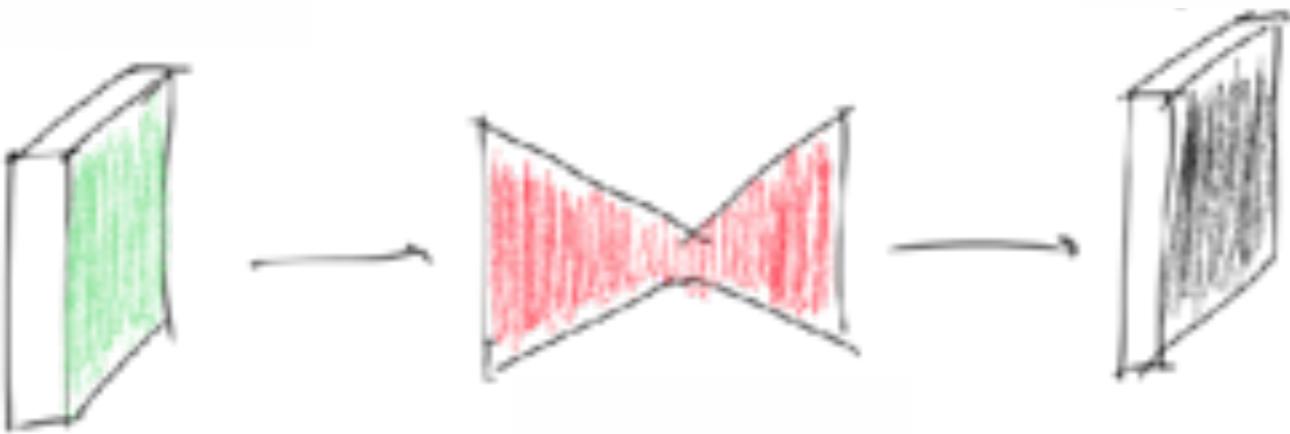
SURROGATE MODELS

If **model → output** synthesis is complex and time consuming



and train this well-defined mapping on observations/simulations

SURROGATE MODELS



- ▶ Fast Bayesian inference (Hamiltonian Montecarlo)
- ▶ Fast classical inversions
- ▶ Fast classical inversions via emulators+loop unrolling

$$\theta_{i+1} = \theta_i + [\mathbf{J}^T \mathbf{J} + \lambda \text{diag}(\mathbf{J}^T \mathbf{J})]^{-1} \mathbf{J}^T [\mathbf{y} - \mathbf{f}(\boldsymbol{\beta})]$$

$$\theta_{i+1} = \theta_i + g[\mathbf{J}, \mathbf{y}, \mathbf{f}(\boldsymbol{\beta})]$$

UNSUPERVISED MULTIFRAME BLIND DECONVOLUTION

Can training be done unsupervisedly?

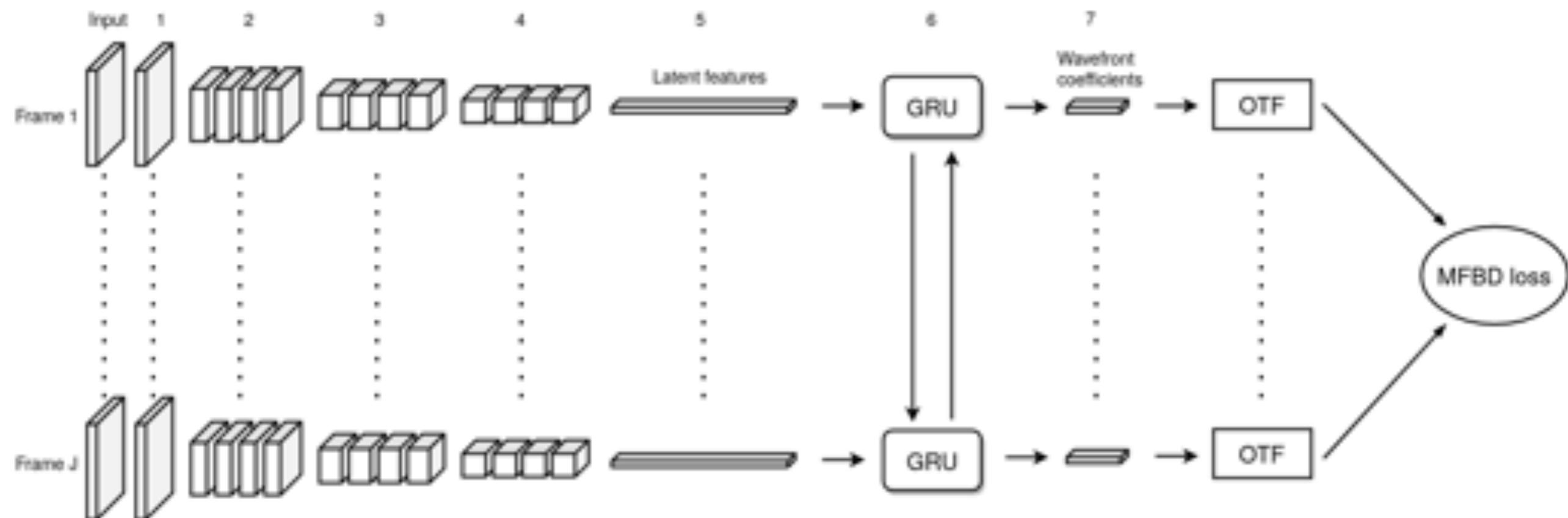
$$L_i(\alpha_i) = \sum_u \left[\sum_j^J |D_{ij}|^2 - \frac{\left| \sum_j^J D_{ij}^* \hat{S}_{ij} \right|^2}{\sum_j^J |\hat{S}_{ij}|^2 + \gamma_i} \right]$$

$$P_{ij} = A_{ij} \exp \{i\phi_{ij}\}$$

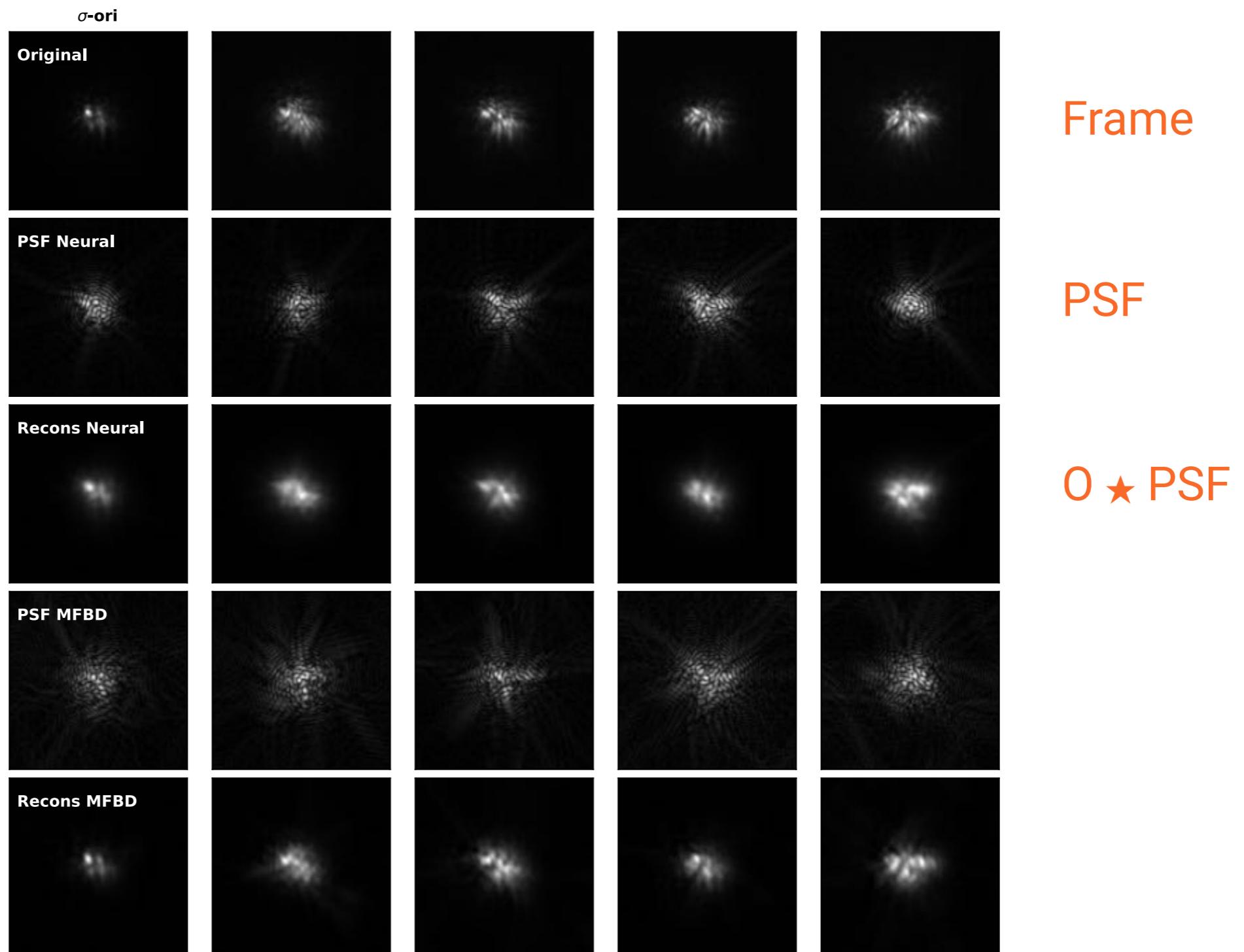
$$\phi_{ij} = \sum_k \alpha_k Z_k(r, \theta)$$

$$S_{ij} = P_{ij} \otimes P_{ij}$$

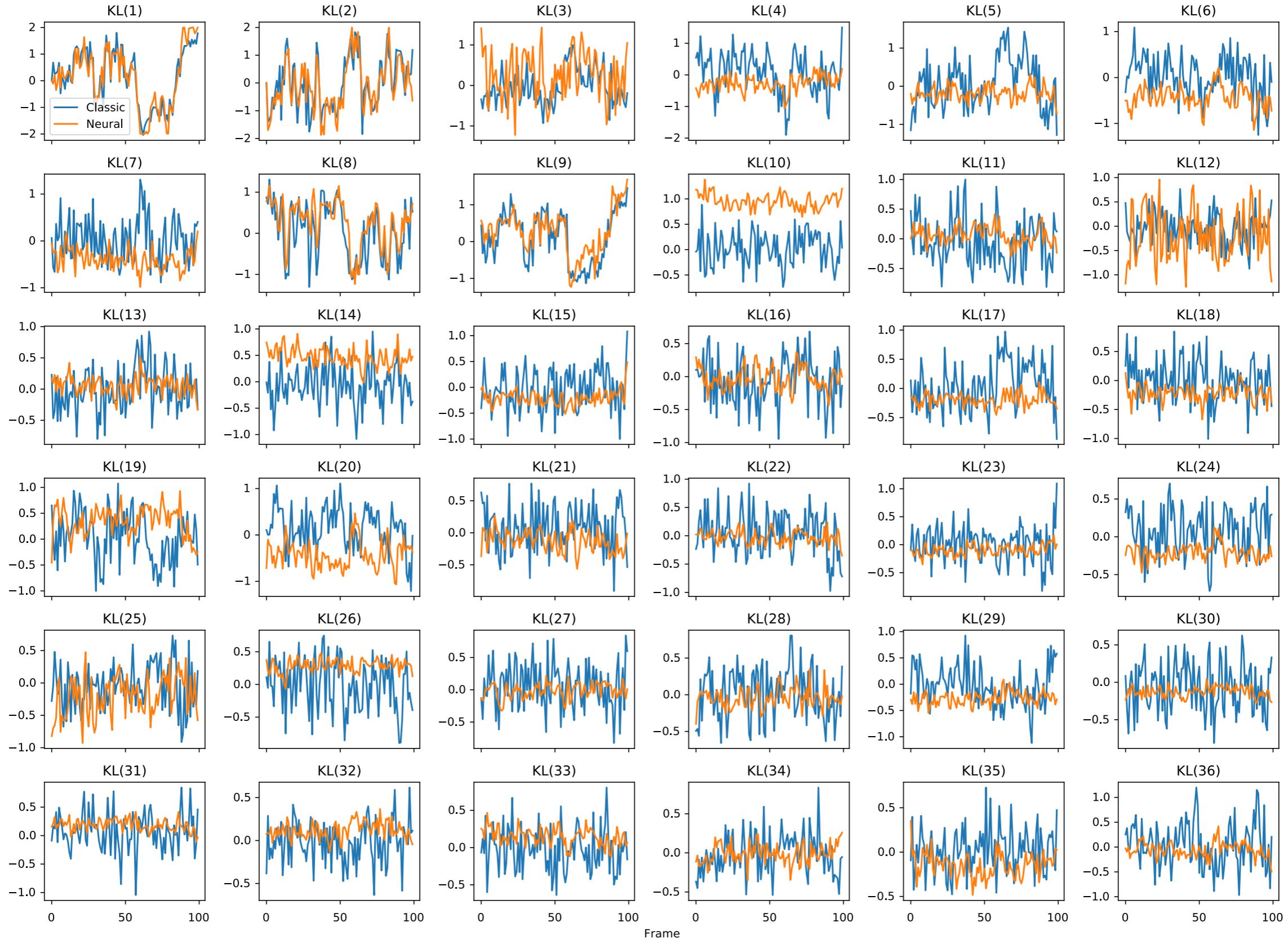
NEURAL MULTIFRAME BLIND DECONVOLUTION



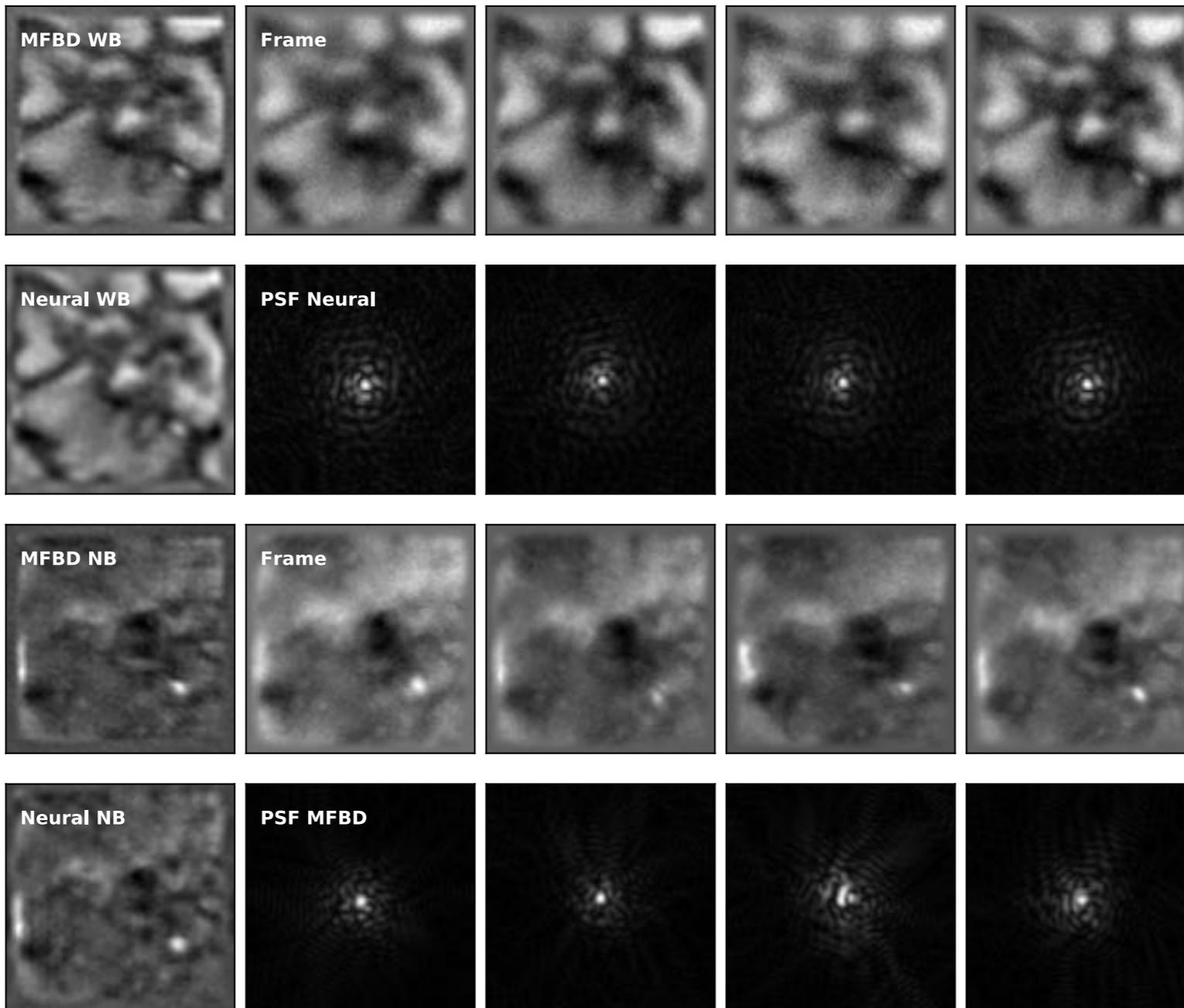
MULTIFRAME RECONSTRUCTION OF STARS



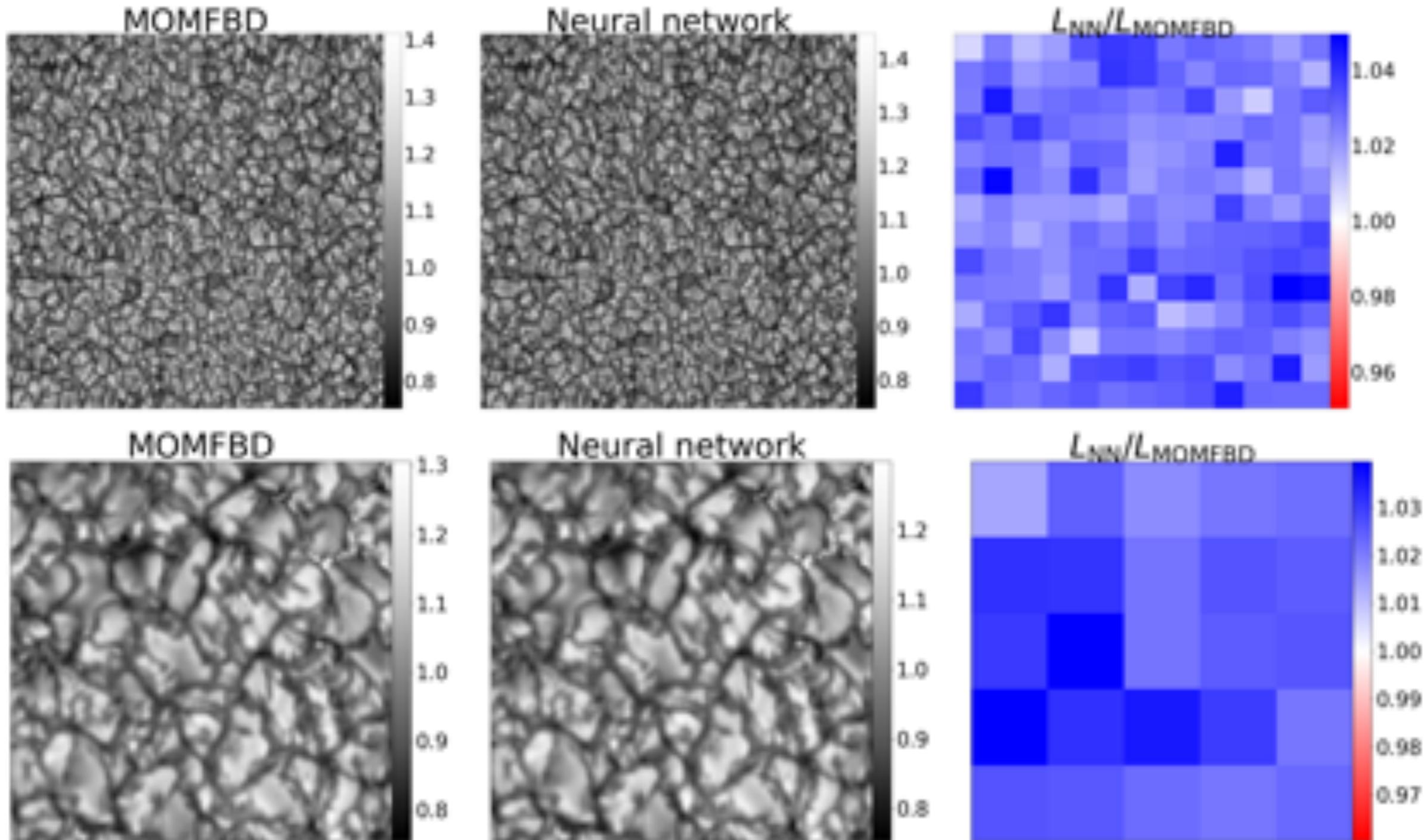
KARHUNEN-LOÈVE MODES



EXTENDED OBJECTS



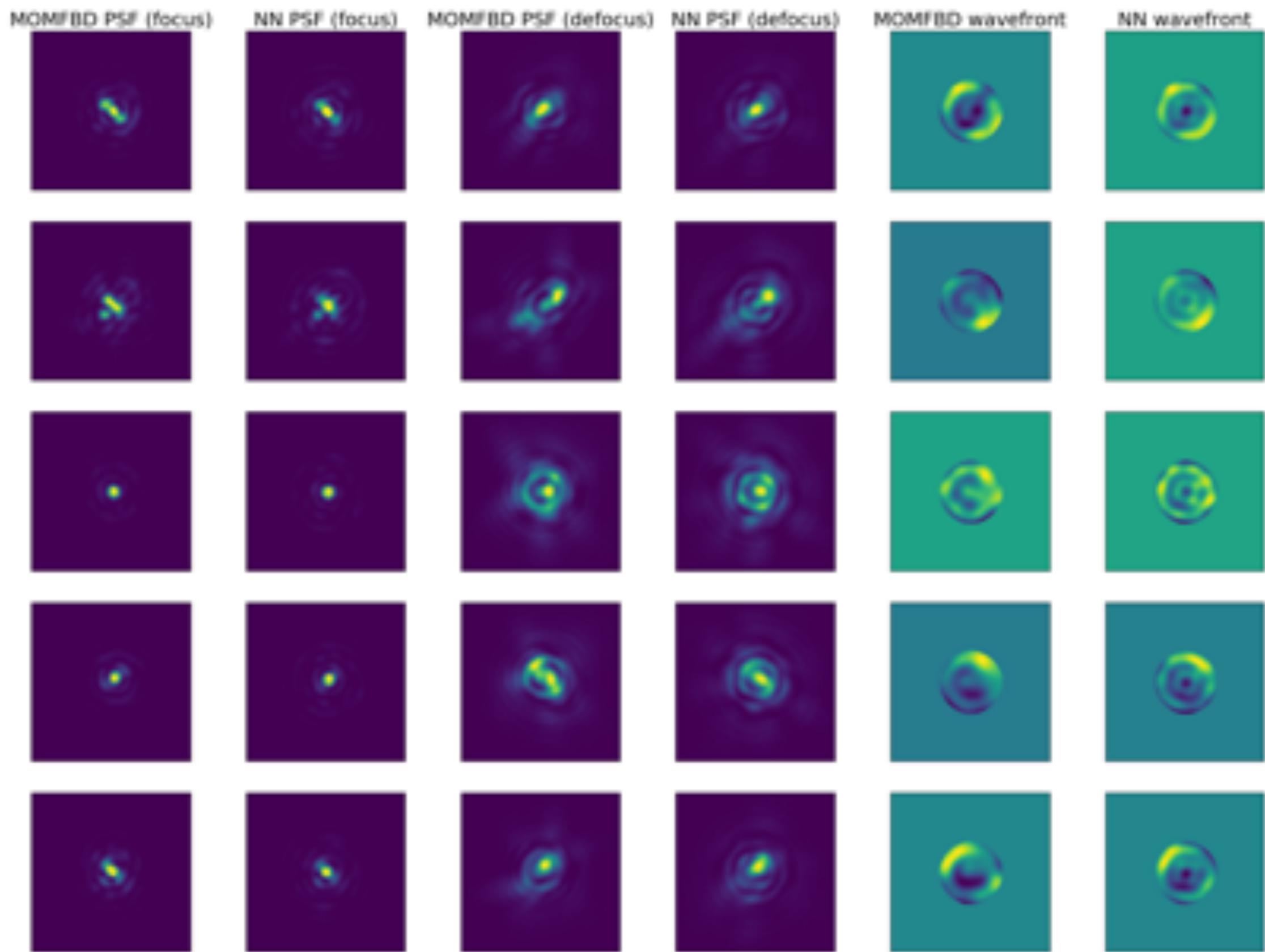
EXTENDED OBJECTS



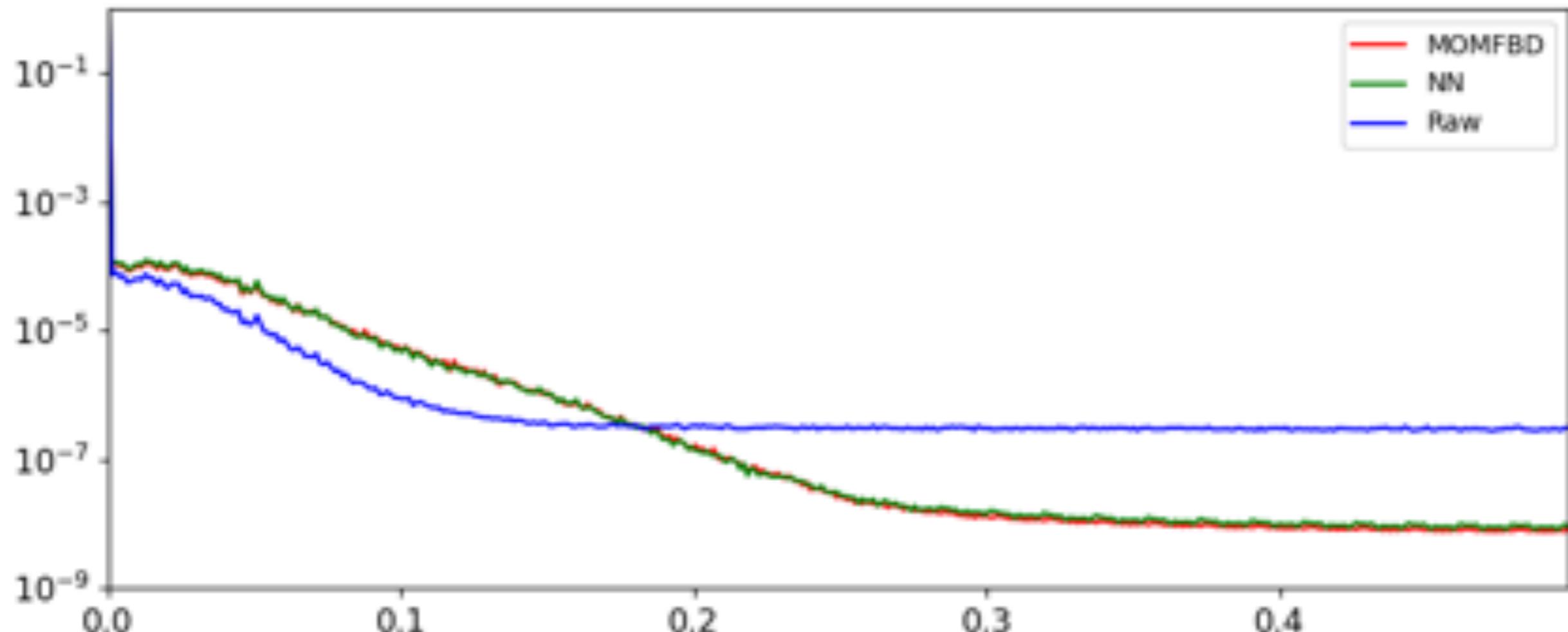
KL COEFFICIENTS



POINT SPREAD FUNCTIONS



POWER SPECTRUM



CONCLUSIONS

- ▶ ML can produce inferences for images/tensors at very fast rates
- ▶ Linear & nonlinear forward problems
- ▶ Tend towards physics-based losses
 - ▶ Inform algorithms
 - ▶ Train unsupervisedly with physics
 - ▶ Bayesian inference
 - ▶ Bypass some parts of the calculations with ML
- ▶ My examples were in Solar Physics but I hope they are motivating for applying them to your field