Deliverable	Date	Responsible	Title	Status
D5.1	3	Caen	Definition of internal architecture and interface between software modules	Delivred 05/2015
D5.2	3	Caen	Definition of the use cases for the demonstrations	Delivered 12/2014
D5.3	12	Sapienza	Technical specification of the robot set-up and of the communication infrastructure	
D5.4	15	Caen	Description of the first demonstration	
D0.1	18	Caen	Document describing the mid-term assessment	
D1.1	18	Sapienza	Knowledge-based environment modelling	Draft
D1.2	18	Sapienza	Software component for environment modelling	
D2.1	18	VUB	Description and specification of the proposed solutions for the sensor processing	
D2.2	18	VUB	A software of sensor, image and video processing	
D1.3	21	Sabanci	Methods for integrating spatial reasoning with common sense reasoning and non-monotonic reasoning	
D1.4	21	Sabanci	Software component for knowledge base reasoning	
D2.3	21	VUB	Description and specification of the proposed solutions for the scene analysis	
D2.4	21	VUB	A software of scene analysis	
D4.1	24	Sapienza	Document of specification of localisation and navigation methods	
D4.2	24	Sapienza	A software of navigation module to integrate in the whole architecture	

D3.1.1	27	Sapienza	Multi-modal human-robot interaction	
D3.1.2	27	Caen	Human needs estimation	
D3.2.1	27	Sapienza	Developed software for multi-modal human-robot interaction	
D3.2.2	27	Caen	Developed software for human needs estimation	
D4.3	30	Caen	Document of specification of multi-robot planning using DEC-POMDP	Draft
D4.4	30	Caen	A software of decision module to integrate in the whole architecture	
D5.5	33	Caen	Description of the final demonstration	
D0.2	36	Caen	Document describing the final assessment	
D5.6	36	Sapienza	Performance evaluation in the uses cases of the final demonstration	