



Main Folder

argos.cpp



build Folder



core Folder



camera Folder

camera.cpp
camera.hpp



log Folder

log.cpp
log.hpp



machine_learning Folder

machine_learning.cpp
machine_learning.hpp



network Folder

wifi.cpp
wifi.hpp



threads Folder

camera.cpp
camera.hpp
cloud.cpp
cloud.hpp
database.cpp
database.hpp
main.cpp
main.hpp
ml_inference.cpp
ml_inference.hpp
remote_client.cpp
remote_client.hpp
threads.cpp
threads.hpp



daemon Folder

shutdown.cpp
shutdown.hpp