Excerpt from the *Item Description* of the *Download* tool:

Parameter	Explanation	Data Type
CLDMSK (Optional)	Dialog Reference License: "Customize" ➤ "Extensions" ➤ "☑ Spatial Analyst" Reduces the respective L2A cloud probability image to an own binary image (by means of a raster function chain) that highlights those areas where the specified cloud probability is reached/exceeded. Might be useful in assessing the effect of different mask thresholds (see threshold slider below, parameter CLDTHR). Tip 1: To change the mask color of an existing mask layer, expand the mask layer (within Table Of Contents, TOC), identify the color indicator (box symbol left to its value label), single-click on it (opens the Color Selector), and change the color to your liking. The Symbology tab from its Layer Properties dialog box doesn't help (for this kind of raster layer). Tip 2: To retroactively change the threshold value of an existing mask layer, edit the function chain as follows: 1. From the context menu (right-click) on the respective mask layer (within TOC), choose Properties 2. When prompted to "Build Raster Attribute Table", choose No (important: do not choose Yes). 3. From the Layer Properties dialog box, go to the Functions tab. 4. From the Function Chain, identify and double-click the Local Function (opens its Raster Function Properties dialog box). 5. From the Raster Function Properties dialog box, go to the Local tab, and select the second item from the Input Rasters list (the item that shows the current threshold value as a scalar item). 6. A single click on this selected scalar item makes it editable. Now change the scalar to your liking (value must be between 1 and 100).	Boolean
CLDFLT (Optional)	License: "Customize" ➤ "Extensions" ➤ "☑ Spatial Analyst" * From the list of available indices (see respective parameters below), each index whose name ends with an asterisk "*" is filterable. Filter rationale: Occasionally an index misleadingly indicates water at bright locations where no water is actually present (e.g. bright rooftops, or bright fields), and where the respective local L2A cloud probability coincidentally has a likewise misleading high value. This filter enables one to reduce the amount of false positives by masking out index pixels where the cloud probability reaches/exceeds the specified threshold (see threshold slider below, parameter CLDTHR). ☑ Note: The outlined filter functionality introduces additional raster functions into the function chain. In order to keep the computational load reasonable, use this filter option with care. ॐ Tip 1: To retroactively remove the entire filter from an existing index layer, modify the function chain as follows: 1. From the Layer Properties dialog box of the respective index layer, go to the Functions tab.	Boolean

	From the Function Chain, identify and right-click the topmost Local Function (opens its context menu).	
	From this Local Function's context menu, choose Remove (prompts to Resolve Dataset).	
	 From the Resolve Dataset dialog box, switch the Datasets input to <resample function.outputraster="">, and click OK.</resample> 	
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	 From the Layer Properties dialog box of the respective index layer, go to the Functions tab. 	
	 From the Function Chain, identify and double-click the Local Function closest to the "CLD" raster dataset (opens the Raster Function Properties dialog). 	
	 From the Raster Function Properties dialog box, go to the Local tab, and select the second item from the Input Rasters list (the item that shows the current threshold value as a scalar item). 	
	 A single click on this selected scalar item makes it editable. Now change the scalar to your liking (value must be between 1 and 100). 	
	There is no python reference for this parameter.	
CLDTHR (Optional)	Dialog Reference	Long
	Used for creating a Cloud mask, as well as for adding a Cloud filter to selected filterable* indices (see the previous two options).	
	There is no python reference for this parameter.	
SNWMSK (Optional)	Dialog Reference	Boolean
	Analogous to the CLDMSK parameter (see above), but with respect to the snow/ice probability image (instead of the cloud probability image).	
	There is no python reference for this parameter.	
SNWFLT (Optional)	Dialog Reference	Boolean
SNWFLT (Optional)	Dialog Reference Analogous to the CLDFLT parameter (see above), but with respect to the snow/ice probability image (instead of the cloud probability image).	Boolean
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	Analogous to the CLDFLT parameter (see above), but with respect to the snow/ice probability image (instead of the cloud probability image). There is no python reference for this parameter. Dialog Reference Used for creating a Snow/Ice mask, as well as for adding a Snow/Ice	
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(

 $(1-\theta)\cdot\rho_3 - (1+\theta)\cdot\rho_8 = 0$

(hyperplane that passes through the feature space origin)

General click path to change the threshold (or other coefficients of the index Expression):

- 1. From the Layer Properties dialog box of the respective index layer, go to the Functions tab.
- 2. From the Function Chain, identify and double-click the topmost Band Arithmetic Function (opens its Raster Function Properties dialog).
- From the Raster Function Properties dialog box, go to the Band Arithmetic tab, and modify the Expression to your liking.

General Notes (also apply to other indices):

- If you need a decimal within the Expression, you can express it by an integer fraction (for example, use "12/100" instead of "0.12" or "0,12"). This way, the expression becomes independent of the locale. Otherwise, you would have to use your locale's specific decimal separator character.
- Availability of indices requires ArcGIS version ≥10.5, since the Expression parser of the Band Arithmetic Function is too error prone (notably regarding a constant term) in lower ArcGIS versions.

There is no python reference for this parameter.

MNDWI (Optional)

Dialog Reference

Boolean

Modified Normalised Difference Water Index

Xu H.Q. (2005)

Separatrix manifold:

$$(\rho_3 - \rho_{11}) / (\rho_3 + \rho_{11}) = \theta$$

(typically $\theta=0$)

 \Leftrightarrow

$$(1-\theta)\cdot\rho_3$$
 - $(1+\theta)\cdot\rho_{11}$ = 0

(hyperplane that passes through the feature space origin)

There is no python reference for this parameter.

nNDVI (Optional)

Dialog Reference

Boolean

(negative) Normalized Difference Vegetation Index

Rouse J.W., Haas R.H., Schell J.A., Deering, D.W. (1973)

Separatrix manifold:

$$(\rho_4 - \rho_8) / (\rho_4 + \rho_8) = \theta$$

	(typically A=0)	
	(typically $\theta=0$)	
	\Leftrightarrow	
	$(1-\theta)\cdot\rho_4 - (1+\theta)\cdot\rho_8 = 0$	
	(hyperplane that passes through the feature space origin)	
	There is no python reference for this parameter.	
nNDVI_GREEN (Optional)	Dialog Reference	Boolean
	(negative) Normalized Difference Vegetation Index - Green	
	Separatrix manifold:	
	$\rho_3 \cdot (\rho_4 - \rho_8) / (\rho_4 + \rho_8) = \theta$	
	(typically θ =0)	
	\Leftrightarrow	
	$(\rho_3-\theta)\cdot\rho_4-(\rho_3+\theta)\cdot\rho_8=0$	
	(non-planar hypersurface that passes through the feature space origin)	
	There is no python reference for this parameter.	
SWI (Optional)	Dialog Reference	Boolean
	Superfine Water Index	
	Sharma R.C., Tateishi R., Hara K., Nguyen L.V. (2015)	
	Separatrix manifold:	
	$(S - 7 \cdot \rho_8) / (S + 7 \cdot \rho_8) = \theta$	
	(typically θ =0)	
	where S is the saturation component of the HSV representation (as converted from RGB composite)	
	There is no python reference for this parameter.	
WRI (Optional)	Dialog Reference	Boolean
	Water Ratio Index	
	Shen L., Li C.C. (2010)	
	Separatrix manifold:	
	$(\rho_3 + \rho_4) / (\rho_8 + \rho_{11}) = \theta$	
	(typically $\theta=1$)	
	⇔	
	$\rho_3 + \rho_4 - \theta \cdot (\rho_8 + \rho_{11}) = 0$	
	(hyperplane that passes through the feature space origin)	
	There is no python reference for this parameter.	
NWIgreen (Optional)	Dialog Reference	Boolean
	New Water Index	

	T. T (0000)	
	Ding F. (2009)	
	Separatrix manifold:	
	$(\rho_3 - (\rho_8 + \rho_{11} + \rho_{12})) / (\rho_3 + (\rho_8 + \rho_{11} + \rho_{12})) = \theta$	
	(typically θ =0)	
	\Leftrightarrow	
	$(1-\theta)\cdot\rho_3 - (1+\theta)\cdot(\rho_8+\rho_{11}+\rho_{12}) = 0$	
	(hyperplane that passes through the feature space origin)	
	There is no python reference for this parameter.	
NWIblue (Optional)	Dialog Reference	Boolean
	New Water Index	
	Yang H.B., Wang Z.M., Zhao H.L., Guo Y. (2011)	
	Separatrix manifold:	
	$(\rho_2 - (\rho_8 + \rho_{11} + \rho_{12})) / (\rho_2 + (\rho_8 + \rho_{11} + \rho_{12})) = \theta$	
	(typically θ =0)	
	\Leftrightarrow	
	$(1-\theta)\cdot\rho_2 - (1+\theta)\cdot(\rho_8+\rho_{11}+\rho_{12}) = 0$	
	(hyperplane that passes through the feature space origin)	
	There is no python reference for this parameter.	
MBWI (Optional)	Dialog Reference	Boolean
MBWI (Optional)	Dialog Reference Multi-Band Water Index	Boolean
MBWI (Optional)		Boolean
MBWI (Optional)	Multi-Band Water Index	Boolean
MBWI (Optional)	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018)	Boolean
MBWI (Optional)	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold:	Boolean
MBWI (Optional)	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: $2 \cdot \rho_3 - \rho_4 - \rho_8 - \rho_{11} - \rho_{12} = \theta$ (typically $\theta = 0$; hyperplane, with distance to the feature space origin if	Boolean
MBWI (Optional)	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: $2 \cdot \rho_3 - \rho_4 - \rho_8 - \rho_{11} - \rho_{12} = \theta$ (typically $\theta = 0$; hyperplane, with distance to the feature space origin if $\theta \neq 0$) Φ Tip: Adjust the threshold according to the shadow length. For example, in the case of a winter scene with significant shadow, a value around $\theta = -5/100$ might be reasonable to limit the amount of false positives. In the case of a summer scene with minor shadow, the threshold can be set to a lower value around $\theta = -15/100$. This minimizes the loss of details, i.e. minimizes the amount of false	Boolean
MBWI (Optional) WI2015 (Optional)	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: $2\cdot\rho_3-\rho_4-\rho_8-\rho_{11}-\rho_{12}=\theta$ (typically θ =0; hyperplane, with distance to the feature space origin if θ \neq 0) \oplus Tip: Adjust the threshold according to the shadow length. For example, in the case of a winter scene with significant shadow, a value around θ =-5/100 might be reasonable to limit the amount of false positives. In the case of a summer scene with minor shadow, the threshold can be set to a lower value around θ =-15/100. This minimizes the loss of details, i.e. minimizes the amount of false negatives.	Boolean
	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: $2 \cdot \rho_3 - \rho_4 - \rho_8 - \rho_{11} - \rho_{12} = \theta$ (typically $\theta = 0$; hyperplane, with distance to the feature space origin if $\theta \neq 0$) Tip: Adjust the threshold according to the shadow length. For example, in the case of a winter scene with significant shadow, a value around $\theta = -5/100$ might be reasonable to limit the amount of false positives. In the case of a summer scene with minor shadow, the threshold can be set to a lower value around $\theta = -15/100$. This minimizes the loss of details, i.e. minimizes the amount of false negatives. There is no python reference for this parameter.	
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	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: 2·ρ₃ - ρ₄ - ρ₃ - ρ₁₁ - ρ₁₂ = θ (typically θ=0; hyperplane, with distance to the feature space origin if θ≠0) ☼ Tip: Adjust the threshold according to the shadow length. For example, in the case of a winter scene with significant shadow, a value around θ=-5/100 might be reasonable to limit the amount of false positives. In the case of a summer scene with minor shadow, the threshold can be set to a lower value around θ=-15/100. This minimizes the loss of details, i.e. minimizes the amount of false negatives. There is no python reference for this parameter. Dialog Reference Water Index 2015 Fisher A., Flood N., Danaher T. (2016)	
	Multi-Band Water Index Wang X.B., Xie S.P., Du J.K. (2018) Separatrix manifold: 2·ρ₃ - ρ₄ - ρଃ - ρ₁₁ - ρ₁₂ = θ (typically θ=0; hyperplane, with distance to the feature space origin if θ≠0) ☼ Tip: Adjust the threshold according to the shadow length. For example, in the case of a winter scene with significant shadow, a value around θ=-5/100 might be reasonable to limit the amount of false positives. In the case of a summer scene with minor shadow, the threshold can be set to a lower value around θ=-15/100. This minimizes the loss of details, i.e. minimizes the amount of false negatives. There is no python reference for this parameter. Dialog Reference Water Index 2015 Fisher A., Flood N., Danaher T. (2016) Separatrix manifold:	

	There is no python reference for this parameter.	
AWEInsh (Optional)	Dialog Reference	Boolean
/WEIISH (Optional)	Automated Water Extraction Index (non-shadow scene)	
	Feyisa G.L., Meilby H., Fensholt R., Proud S.R. (2014)	
	Separatrix manifold:	
	$4 \cdot (\rho_3 - \rho_{11}) - (0.25 \cdot \rho_8 + 2.75 \cdot \rho_{12}) = 0$	
	(hyperplane that passes through the feature space origin)	
AWEIch (Ontional)	There is no python reference for this parameter. Dialog Reference	Boolean
AWEIsh (Optional)	Automated Water Extraction Index (scene with shadow)	boolean
	Feyisa G.L., Meilby H., Fensholt R., Proud S.R. (2014)	
	Separatrix manifold:	
	$\rho_2 + 2.5 \cdot \rho_3 - 1.5 \cdot (\rho_8 + \rho_{11}) - 0.25 \cdot \rho_{12} = 0$	
	(hyperplane that passes through the feature space origin)	
	There is no python reference for this parameter.	
SBM2m3_6p2m8p6m11p6m12p2 (Optional)	Dialog Reference	Boolean
	Simple Band Multiplication (variant's working title herein: Pine)	
	(Experimental index by the author, 2018)	
	General notation: SBM(···) = $C \cdot \Pi \rho_i \uparrow x_i$ (C=const)	
	Notation convention of "" (that identifies the respective variant):	
	 The letter "p" of each band's reflectance identifier is left out, i.e. only the respective band number is noted (e.g. "p₃" is abbreviated to "8"). 	
	• Factors that carry a negative exponent are grouped to the right side of the fraction line symbol "—", whereupon the respective negative exponent sign becomes inverted (cp. $\rho^{-2}/1 = 1/\rho^2$).	
	Separatrix manifold:	
	SBM(···) - 1 = 0	
	(non-planar hypersurface that passes through the feature space origin)	
	☼ Tip: Adjust the constant C according to the shadow length. The aim is to balance the multiplier in such a way that a reasonable trade-off between minimizing the amount of false positives (at higher C values) and minimizing the amount of false negatives (at lower C values) is reached:	
	 From the Layer Properties dialog box of the respective index layer, go to the Functions tab. 	
	From the Function Chain, identify and double-click the topmost Band Arithmetic Function (opens its Raster Function Properties dialog box).	
	From the Raster Function Properties dialog box, go to the Band Arithmetic tab, and vary the multiplier (placed at the	

beginning of the Expression), typically by powers of ten. For example, if the initial value reads 50000, try 5000 or 500 (or even less) in the case of a winter scene (with significant shadow), whereas higher values like 500000 or 5000000 (or even higher) might fit better in the case of a summer scene (with minor shadow).

Additional tips:

- Incorporating a 10m band (e.g. p₈) as multiplier of a resampled 20m band should improve sharpness (cp. multiplicative sharpening).
- A higher exponent might emphasize the respective band's significance (note: a change of any exponent value requires the constant C to be readjusted accordingly).

There is no python reference for this parameter.

SCL (Optional)

Dialog Reference

Boolean

Unique pixel values (stored as 8-bit integers), along with their respective display color and label (in compliance with L2A Product Definition Document S2-PDGS-MPC-L2A-PDD-V14.2, Issue: 4.6, Date: 2017-06-23):

- 1. Saturated or defective pixel (red).
- 2. Dark features / Shadows (very dark grey).
- 3. Cloud shadows (dark brown).
- 4. Vegetation (green).
- 5. Not-vegetated (dark yellow).
- 6. Water (dark and bright) (blue).
- 7. Unclassified (dark grey).
- 8. Cloud medium probability (grey).
- 9. Cloud high probability (white).
- Thin cirrus (very bright blue).
- 11. Snow or ice (very bright pink).

- From the expanded SCL layer (within Table Of Contents), single-click on the color indicator of the respective class (opens the Color Selector).
- 2. From the Color Selector dialog box, go to the Properties tab.
- 3. Within the Properties tab, from the Other Options section, tick "☑ Color is Null".

There is no python reference for this parameter.