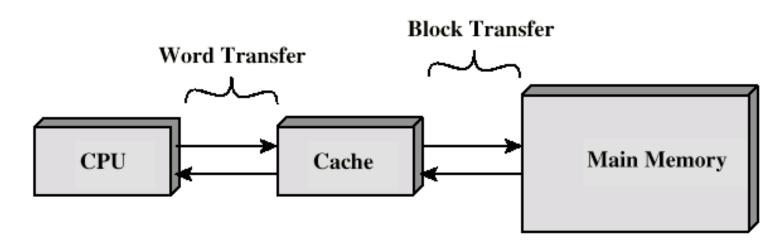
CACHE MEMORY

Cache Memory

- Small amount of fast memory, expensive memory
- Sits between normal main memory (slower) and CPU
- May be located on CPU chip or module
- It keeps a copy of the most frequently used data from the main memory.
- Reads and writes to the most frequently used addresses will be serviced by the cache.
- We only need to access the slower main memory for less frequently used data.



Principle of Locality

- In practice, most programs exhibit locality, which the cache can take advantage of.
- The principle of temporal locality says that if a program accesses one memory address, there is a good chance that it will access the same address again.
- The principle of spatial locality says that if a program accesses one memory address, there is a good chance that it will also access other nearby addresses.

Temporal Locality in Programs and Data

- Programs: Loops are excellent examples of temporal locality in programs.
 - The loop body will be executed many times.
 - The computer will need to access those same few locations of the instruction memory repeatedly.
- Data: Programs often access the same variables over and over, especially within loops.

Spatial Locality in Programs and Data Programs: Nearly every program exhibits spatial locality,

- Programs: Nearly every program exhibits spatial locality, because instructions are usually executed in sequence—if we execute an instruction at memory location *i, then we will probably also execute the next instruction, at* memory location *i+1.*
- Code fragments such as loops exhibit both temporal and spatial locality.
- **Data:** Programs often access data that is stored contiguously.
 - Arrays, like a in the code on the top, are stored in memory contiguously.
 - The individual fields of a record or object like employee are also kept contiguously in memory.

How caches take advantage of temporal locality

- The first time the processor reads from an address in main memory, a copy of that data is also stored in the cache.
 - The next time that same address is read, we can use the copy of the data in the cache *instead of* accessing the slower dynamic memory.
 - So the first read is a little slower than before since it goes through both main memory and the cache, but subsequent reads are much faster.

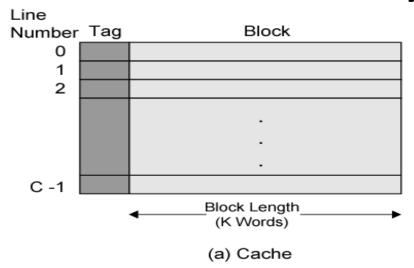
How caches take advantage of spatial locality

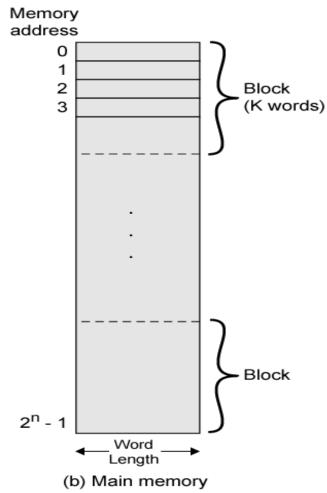
- When the CPU reads location i from main memory, a copy of that data is placed in the cache.
- But instead of just copying the contents of location *i*, we can copy several values into the cache at once, such as the four bytes from locations *i* through *i* + 3.
 - If the CPU later does need to read from locations i + 1, i + 2 or i + 3, it can access that data from the cache and not the slower main memory.
 - For example, instead of reading just one array element at a time, the cache might actually be loading four array elements at once.
- Again, the initial load incurs a performance penalty, but we're gambling on spatial locality and the chance that the CPU will need the extra data.

Hits and Misses

- A cache hit occurs if the cache contains the data that we're looking for.
 - cache can return the data much faster than main memory.
- A cache miss occurs if the cache does not contain the requested data.
 - CPU must then wait for the slower main memory.

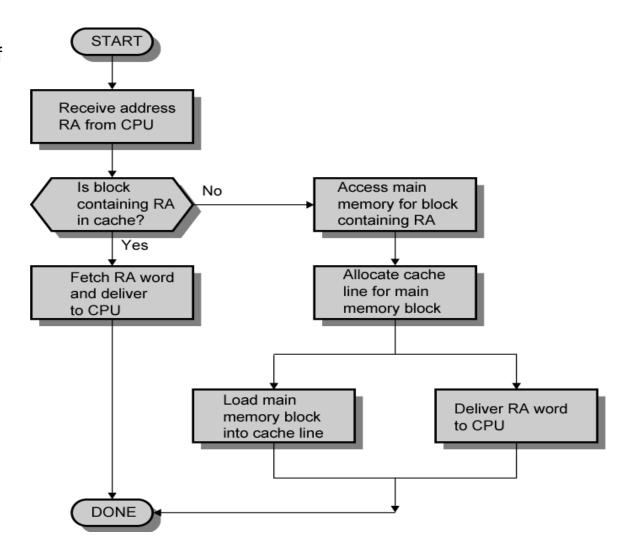
Cache/Main Memory Structure





Cache read operation

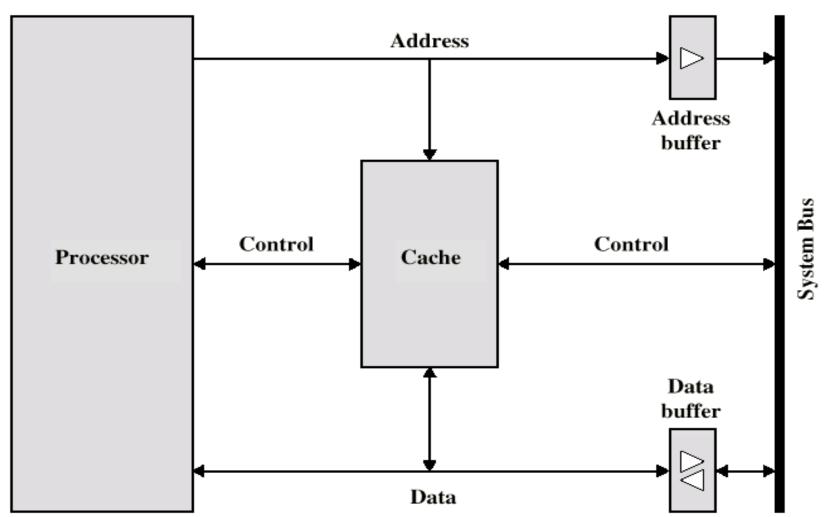
- CPU requests contents of memory location
- Check cache for this data
- If present, get from cache (fast)
- If not present, read required block from main memory to cache
- Then deliver from cache to CPU
- Cache includes tags to identify which block of main memory is in each cache slot



Size of Cache Design

- Cost
 - More cache is expensive
- Speed
 - More cache is faster (up to a point)
 - Checking cache for data takes time

Typical Cache Organization



Comparison of Cache Sizes

Processor	Туре	Year of Introduction	L1 cachea	L2 cache	L3 cache
IBM 360/85	Mainframe	1968	16 to 32 KB	_	_
PDP-11/70	Minicomputer	1975	1 KB	_	_
VAX 11/780	Minicomputer	1978	16 KB	_	
IBM 3033	Mainframe	1978	64 KB	_	_
IBM 3090	Mainframe	1985	128 to 256 KB	_	_
Intel 80486	PC	1989	8 KB	_	_
Pentium	PC	1993	8 KB/8 KB	256 to 512 KB	_
PowerPC 601	PC	1993	32 KB	_	_
PowerPC 620	PC	1996	32 KB/32 KB	_	_
PowerPC G4	PC/server	1999	32 KB/32 KB	256 KB to 1 MB	2 MB
IBM S/390 G4	Mainframe	1997	32 KB	256 KB	2 MB
IBM S/390 G6	Mainframe	1999	256 KB	8 MB	_
Pentium 4	PC/server	2000	8 KB/8 KB	256 KB	
IBM SP	High-end server/ supercomputer	2000	64 KB/32 KB	8 MB	_
CRAY MTAb	Supercomputer	2000	8 KB	2 MB	
Itanium	PC/server	2001	16 KB/16 KB	96 KB	4 MB
SGI Origin 2001	High-end server	2001	32 KB/32 KB	4 MB	_
Itanium 2	PC/server	2002	32 KB	256 KB	6 MB
IBM POWER5	High-end server	2003	64 KB	1.9 MB	36 MB
CRAY XD-1	Supercomputer	2004	64 KB/64 KB	1MB	_

Direct Mapping

- Each block of main memory maps to only one cache line
 - i.e. if a block is in cache, it must be in one specific place
- Address is in two parts

Main Memory address Line / Slot Tag Line/Slot **Memory Content** Tag 000 001 010 Cache address Cache content

Example 1: Direct Mapping

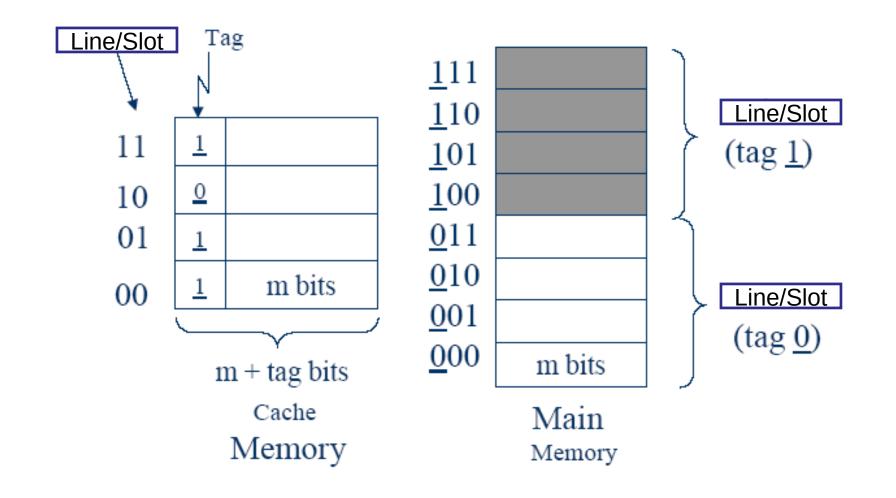
A main memory contains 8 words while the cache has only 4 words. Using direct address mapping, identify the fields of the main memory address for the cache mapping.

Solution:

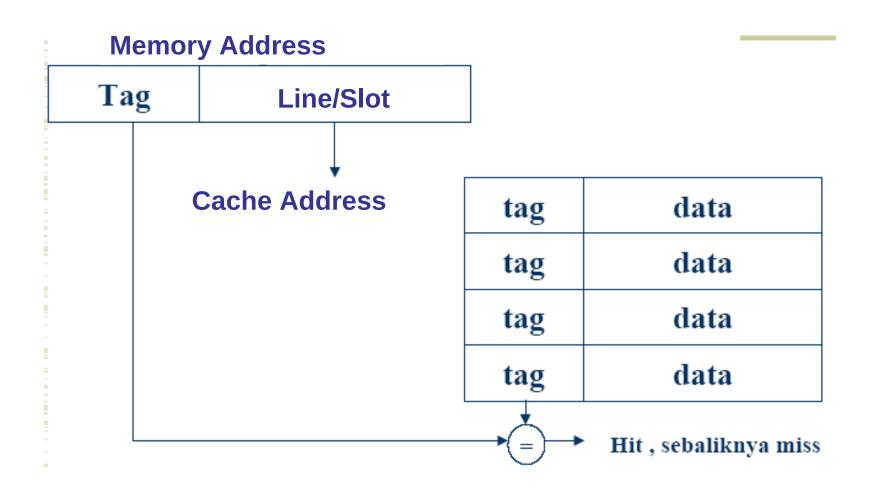
Total memory words = $8 = 2^3 \rightarrow \text{Require 3 bit for main memory address.}$

Total cache words = $4 = 2^2 \rightarrow \text{Require 2 bit for cache address} \rightarrow \text{line / slot}$ Main memory address = 3 bits

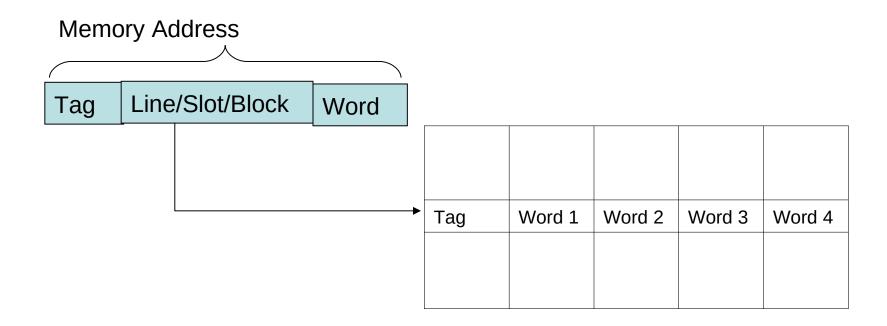
Example 1: Direct Mapping



Direct Mapping: Hit or Miss



Block Direct Mapping

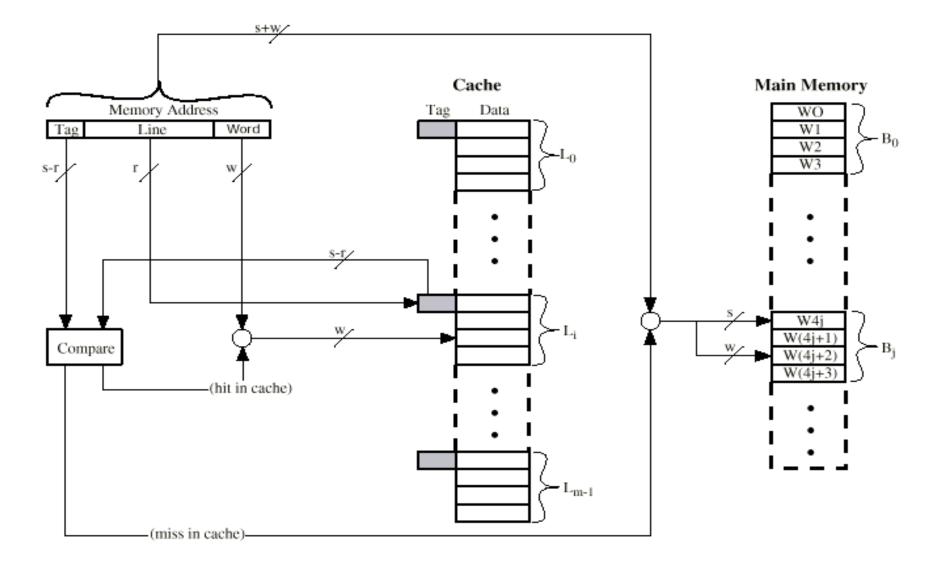


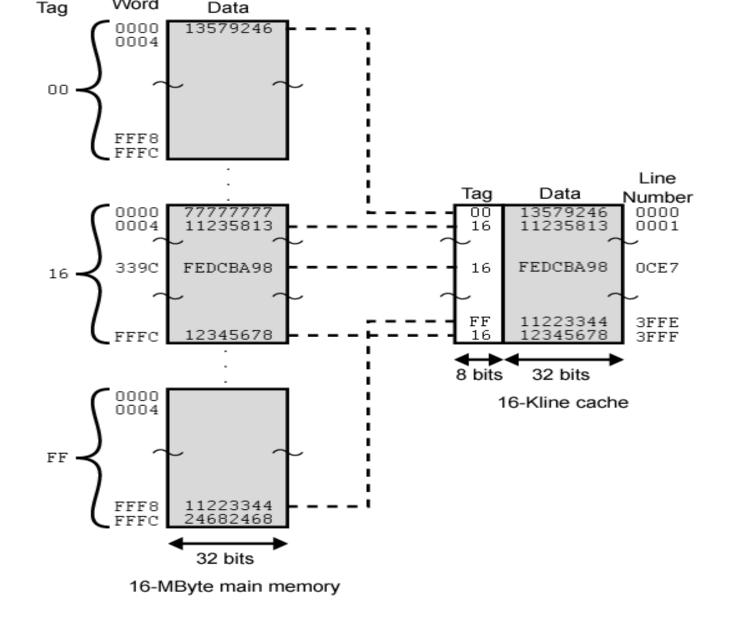
Example: Derive Index(Block) and Offset (Word bits). Given

```
Memory size = 256KB = 2^{18}
Block size = 32Bytes = 2^{5}
```

Number of blocks in cache = Cache size/Block size = $64KB/32B = 2^{16}/2^{5}$ = 2^{11}

Number of bits in Tag =





 Tag
 Line
 Word

 Main memory address =
 8
 14
 2

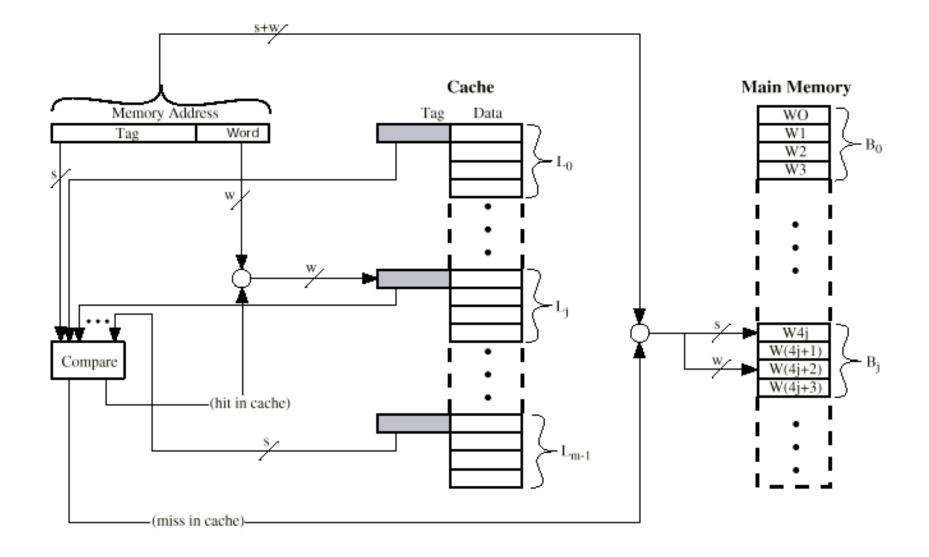
Direct Mapping pros & cons

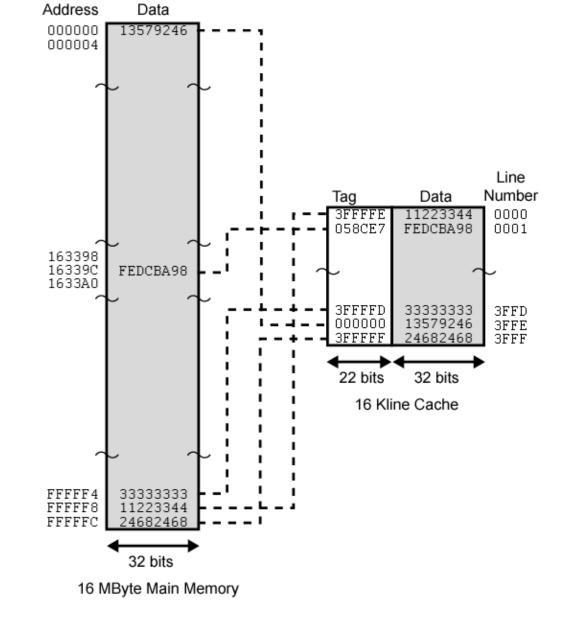
- Simple
- Inexpensive
- Fixed location for given block
 - If a program accesses 2 blocks that map to the same line repeatedly, cache misses are very high

Associative Mapping

- A main memory block can load into any line of cache
- Memory address is interpreted as tag and word
- Tag uniquely identifies block of memory
- Every line's tag is examined for a match
- Cache searching gets expensive

Main memory address				
Tag	Word			





Example: Given M.M= 16MB, Cache has 16K Lines, Block Size=4words, Devise Memory address format

(a). Main memory capacity = 16MByte =

Therefore the number of bits for the main memory address = 24 bits

- (b) Given a cache memory of the size 16 Kline = 2¹⁴ locations (line number) not important...! (Since the any word can be loaded into any cache location)
- (c) Each line stores a block of words.

Block size =

Therefore 2 bits for block of words

(d) Memory address format consists of tag and word field.

Tag bits + words bits = 24 bits

Tag bits + 2 = 24 bits

Therefore tag bits = 24 - 2 = 22 bits

Draw the format of main memory address

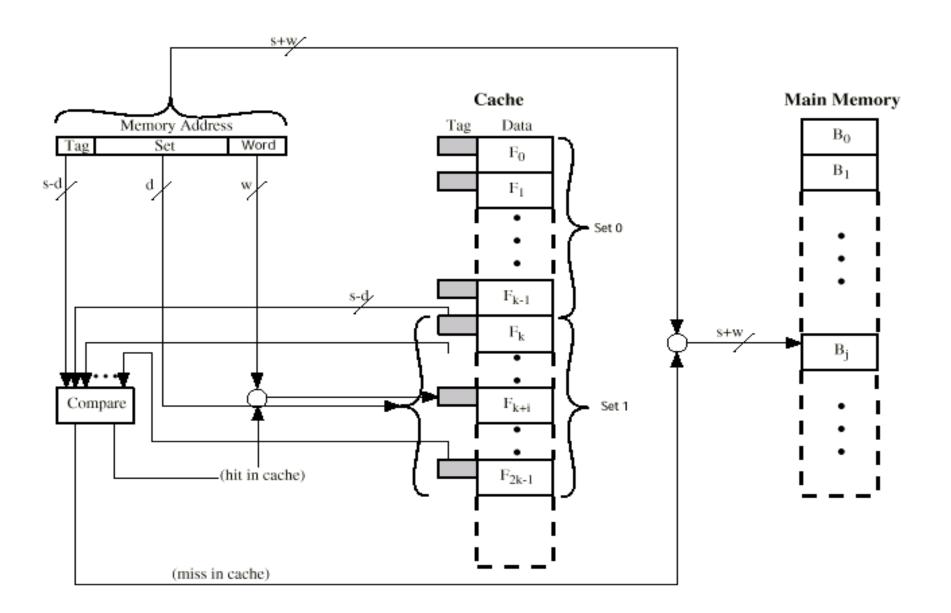
TAG=22bits

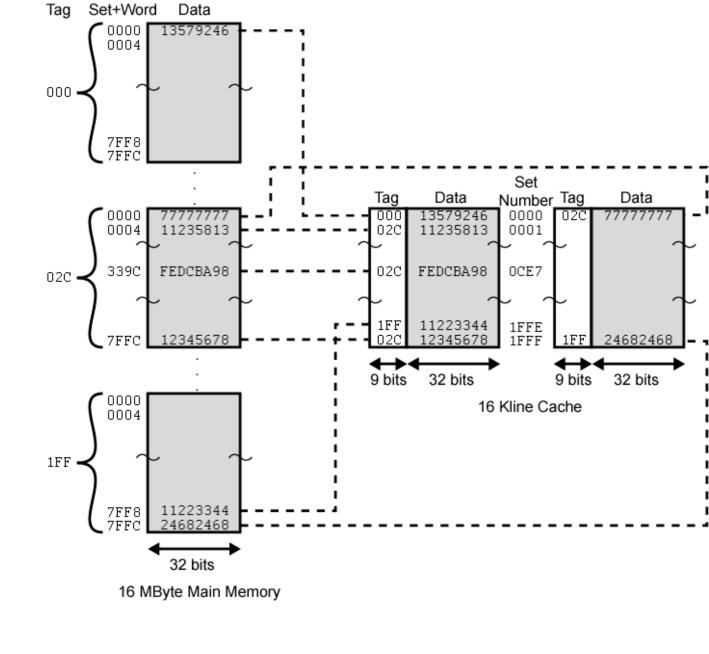
Word=2bits

Set Associative Mapping

- Cache is divided into a number of sets
- Each set contains a number of lines
- A given block maps to any line in a given set
 - e.g. Block B can be in any line of set i
- e.g. 2 lines per set
 - 2 way set associative mapping
 - A given block can be in one of 2 lines in only one set

Main memory address						
Tag	Set/Index	Word				





 Tag
 Set
 Word

 Main Memory Address =
 9
 13
 2

Set Associative Mapping Example 1

Given memory size of 256KB, Cache size of 64KB, and memory block size of 2 Bytes, find the address format using 4-Way Set Associate Mapping?

Solution:

```
Memory Size=256KB= 218
```

To find:

Number of Sets in Cache(Index) = $2^{16}/(4*2)=2^{13}$

Number of bits in Tag = Total - Index-Offset = 18-13-1=4

Tag: 4 bits Index: 13 bits Offest: 1 bit

Set Associative Mapping Example 2

 Given memory size of 256KB, Cache size of 64KB, and memory block size of 2 Bytes, find the address format using 8-Way Set Associate Mapping?

Solution:

```
Memory Size=256KB= 218
```

Block Size(Offset) =
$$2 \text{ Bytes} = 2^{1}$$

Cache Size =
$$64KB=2^{16}$$

To find:

```
Number of Sets in Cache(Index) = 2^{16}/(8*2)=2^{12}
```

Number of bits in Tag = Total – Index-Offset = 18-12-1 = 5

Tag: 5 bits Index: 12 bits Offest: 1 bit

Replacement Algorithms (1) Direct mapping

- No choice
- Each line/slot or block only maps to one line/slot or block
- Replace that line/slot or block

Replacement Algorithms (2) Associative & Set Associative

- Hardware implemented algorithm (speed)
- Least Recently used (LRU)
- First in first out (FIFO)
 - replace block that has been in cache longest
- Least frequently used (LFU)
 - replace block which has had fewest hits
- Random

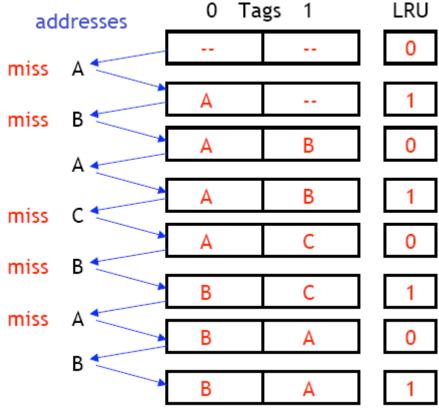
LRU Example

 Assume a associative cache with two blocks, which of the following memory references miss in the cache

assume distinct addresses go to distinct blocks

On a miss, we replace the LRU.

On a hit, we just update the LRU.

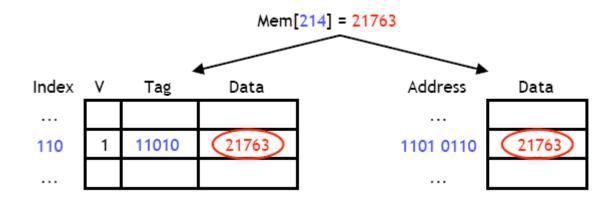


Write Policy

- Must not overwrite a cache block unless main memory is up to date
- Multiple CPUs may have individual caches
- I/O may address main memory directly

Write through

- A write-through cache write updates both the cache and the main memory
- Multiple CPUs can monitor main memory traffic to keep local (to CPU) cache up to date
- Lots of traffic
- Slows down writes



Write back

- Updates initially made in cache only
- Update bit for cache slot is set when update occurs
- If block is to be replaced, write to main memory only if update bit is set
- Other caches get out of sync
- I/O must access main memory through cache

Cache Coherence

- Assuming a system with multiple processors and multiple caches.
- If a word in one cache is altered, then that word needs to be altered in :
 - Main memory as well as other cache
- Even with write-through policy other caches may contain invalid data.
- Thus the problem is to maintain Cache Coherence.

Approaches for Cache Coherence

Bus watching with write through

- Each cache controller monitors the address lines to detect write operations to memory.
- If shared locations in memory are overwritten by another controller(master).
- Other cache controllers invalidate their corresponding cache entries.

Approaches for Cache Coherence (Cont'd)

Hardware Transparency

- All updates to main memory via cache are reflected in all caches.
- If one of the cache is updated :
 - It is automatically written main memory as well as updating other caches.

Noncacheable Memory

- Chunks of main memory are designed as non-cacheable.
- Shared memory is noncacheable.
- All the access to the shared memory is cache misses.

Line Size

- The relationship between block size and hit ratio is complex.
- As block size increases the hit ratio will increase at first.
 - Locality of reference comes into play
- But very large block size will also decrease performance:
 - Probability of newly fetched information becomes less.
 - Blocks need to be replaced shortly after being brought in!

Line Size (Cont'd)

- Optimal block size is a characteristic of the program.
- Line size of 8 to 64 is optimal for normal usage.
- For HPC systems, line size is 64- to 128 bytes.

Multilevel Caches

- On-chip Cache L1
- Off-chip Cache L2
 - Static RAM, faster then system bus
 - Separate data path, reduce burden on system bus
 - A number of CPU have incorporated L2 on the CPU itself.
- Off-chip Cache L3
 - L2 moves into CPU, L3 becomes external.
 - Most recently, L3 also incorporated on the CPU.

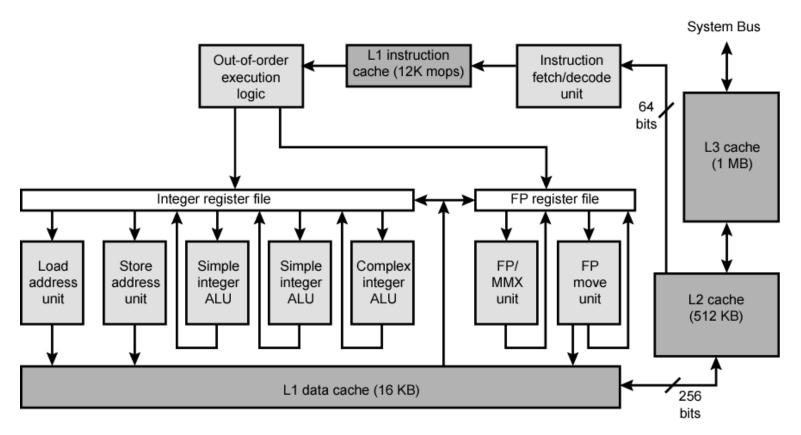
Pentium 4 Cache

- 80386 no on chip cache
- 80486 8k using 16 byte lines and four way set associative organization
- Pentium (all versions) two on chip L1 caches
 - Data & instructions
- Pentium III L3 cache added off chip
- Pentium 4
 - L1 caches
 - 8k bytes
 - 64 byte lines
 - four way set associative
 - L2 cache
 - Feeding both L1 caches
 - 256k
 - 128 byte lines
 - 8 way set associative
 - L3 cache on chip

Intel Cache Evolution (Extra Notes-Skip)

Problem	Solution	Processor on which feature first appears
External memory slower than the system bus.	Add external cache using faster memory technology.	386
Increased processor speed results in external bus becoming a bottleneck for cache access.	Move external cache on-chip, operating at the same speed as the processor.	486
Internal cache is rather small, due to limited space on chip	Add external L2 cache using faster technology than main memory	486
Contention occurs when both the Instruction Prefetcher and the Execution Unit simultaneously require access to the cache. In that case, the Prefetcher is stalled while the Execution Unit's data access takes place.	Create separate data and instruction caches.	Pentium
Increased processor speed results in external bus becoming a bottleneck for L2 cache access.	Create separate back-side bus that runs at higher speed than the main (front-side) external bus. The BSB is dedicated to the L2 cache.	Pentium Pro
	Move L2 cache on to the processor chip.	Pentium II
Some applications deal with massive databases and must have rapid access to large amounts of data. The on-chip caches are too small.	Add external L3 cache.	Pentium III
	Move L3 cache on-chip.	Pentium 4

Pentium 4 Block Diagram (Extra Notes)



Pentium 4 Core Processor (Extra Notes)

- Fetch/Decode Unit
 - Fetches instructions from L2 cache
 - Decode into micro-ops
 - Store micro-ops in L1 cache
- Out of order execution logic
 - Schedules micro-ops
 - Based on data dependence and resources
 - May speculatively execute
- Execution units
 - Execute micro-ops
 - Data from L1 cache
 - Results in registers
- Memory subsystem
 - L2 cache and systems bus

PowerPC Cache Organization

- 601 single 32kb 8 way set associative
- 603 16kb (2 x 8kb) two way set associative
- 604 32kb
- 620 64kb
- G3 & G4
 - 64kb L1 cache
 - 8 way set associative
 - 256k, 512k or 1M L2 cache
 - two way set associative
- **G**5
 - 32kB instruction cache
 - 64kB data cache

PowerPC G5 Block Diagram L2 cache On-chip caches L1 instruction cache L1 data cache Instruction fetch Instruction fetch Branch and decode logic and decode unit Instruction dispatch group Instruction queues Velocity engine Load/ storett Load/ store Execution Condition register Branch execution Floating point Floating point Integer Floating Integer Complex Simple units Instruction 2 3 5 completion group

Internet Sources

- Manufacturer sites
 - Intel
 - IBM/Motorola
- Search on cache

Memory System Performance

- The <u>hit time</u> is how long it takes data to be sent from the cache to the processor. This is usually fast, on the order of 1-3 clock cycles
- The miss penalty is the time to copy data from main memory to the cache. This often requires dozens of clock cycles (at least)
- The miss rate is the percentage of misses

Average Memory Access Time

The average memory access time, or AMAT, can then be computed

AMAT = Hit time + (Miss rate x Miss penalty)

- This is just averaging the amount of time for cache hits and the amount of time for cache misses
- Obviously, a lower AMAT is better
- Miss penalties are usually much greater than hit times, so the best way to lower AMAT is to reduce the miss penalty or the miss rate

Performance Example 1

Assume that 33% of the instructions in a program are data accesses. The cache hit ratio is 97% and the hit time is one cycle, but the miss penalty is 20 cycles.

```
AMAT = Hit time + (Miss rate x Miss penalty)
= 1 cycle + (3% x 20 cycles)
= 1.6 cycles
```

■ If the cache was perfect and never missed, the AMAT would be one cycle. But even with just a 3% miss rate, the AMAT here increases 1.6 times!

Peformance Example 2

A CPU has access to 2 levels of memory. Level 1 contains 1000 words and has access time 0.01 μ s; level 2 contains 100,000 words and has access time 0.1 μ s. Assume that if a word to be accessed is in level 1, then, the CPU accesses it directly. If it is in level 2, then the word is first transferred to level 1 and then accessed by the CPU. For simplicity, we ignored the time required for the CPU to determine whether the word is in level 1 or level 2.

Suppose 95% of the memory access are found in the cache. Then, the average access to a word can be expressed as:

Peformance Example 3

$$(0.95)(0.01 \,\mu\text{s}) + (0.05)(0.01 \,\mu\text{s} + 0.1 \,\mu\text{s})$$

- = 0.0095 + 0.0055
- $= 0.015 \mu s.$