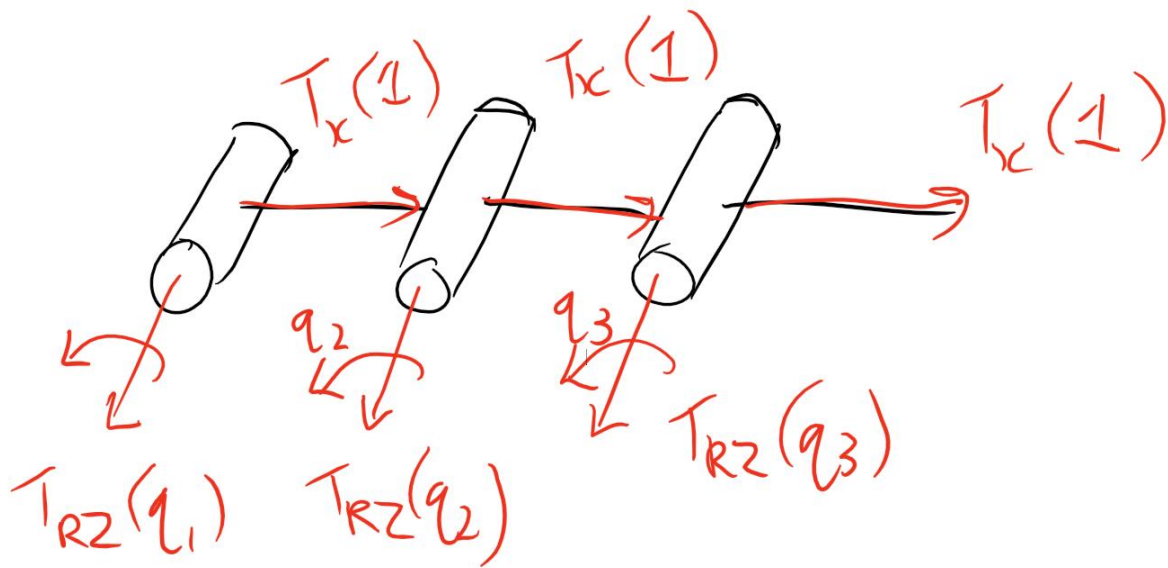


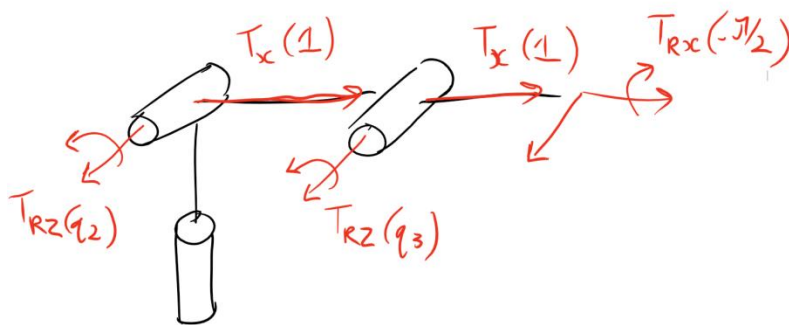
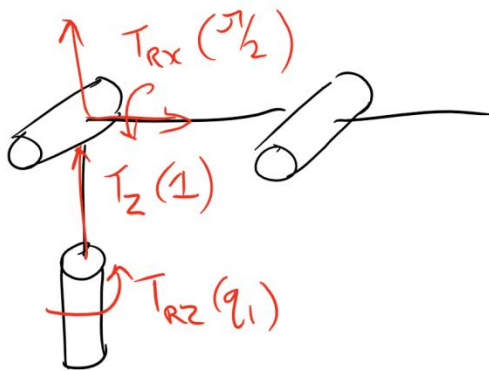
**3-Link Planar Robot**

	$\theta_j$	$d_j$	$a_j$	$\alpha_j$
Link 1	$q_1$	0	1	0
Link 2	$q_2$	0	1	0
Link 3	$q_3$	0	1	0



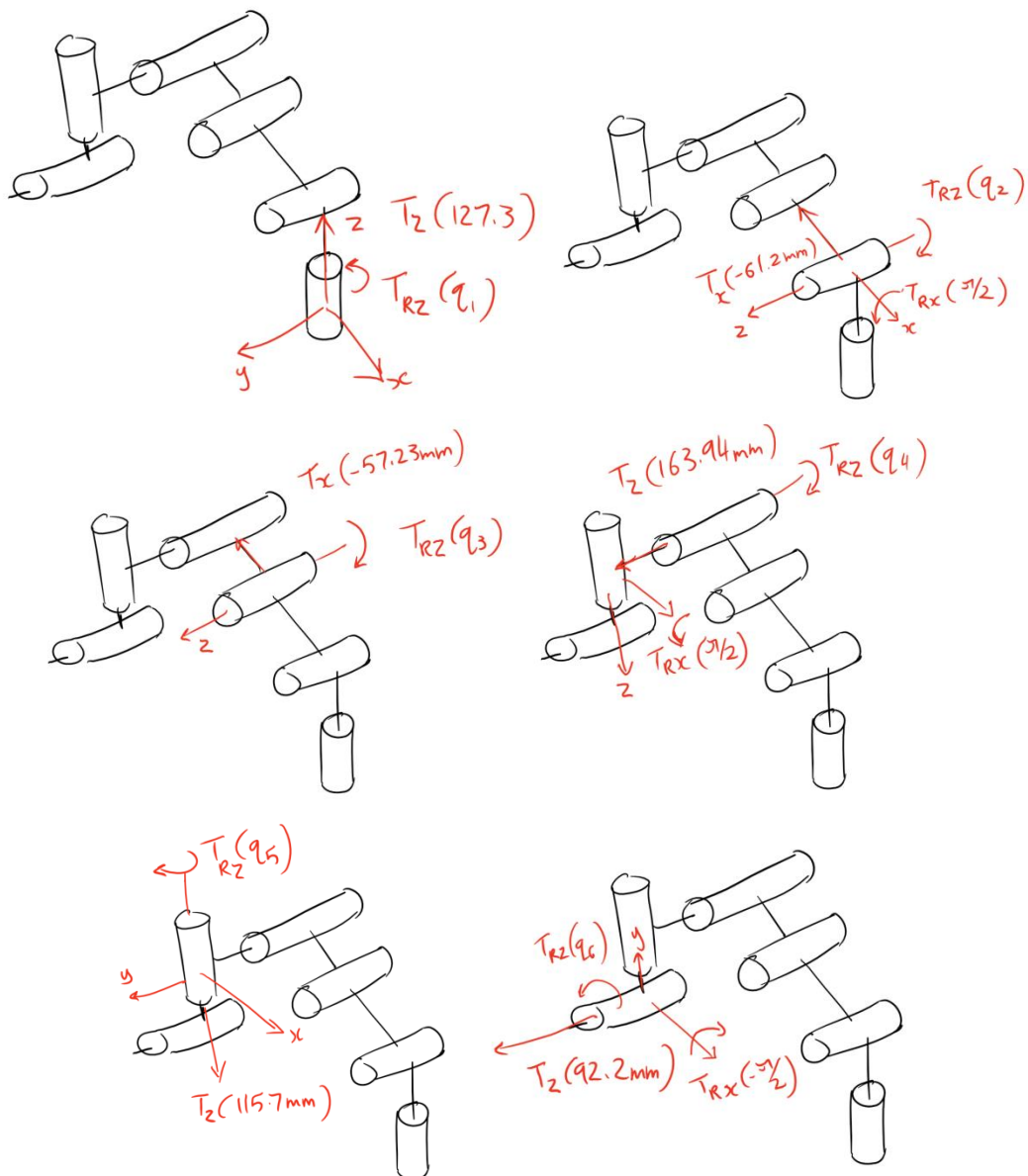
**3-Link 3D Robot**

	$\theta_j$	$d_j$	$a_j$	$\alpha_j$
Link 1	$q_1$	1	0	$\pi/2$
Link 2	$q_2$	0	1	0
Link 3	$q_3$	0	1	$-\pi/2$



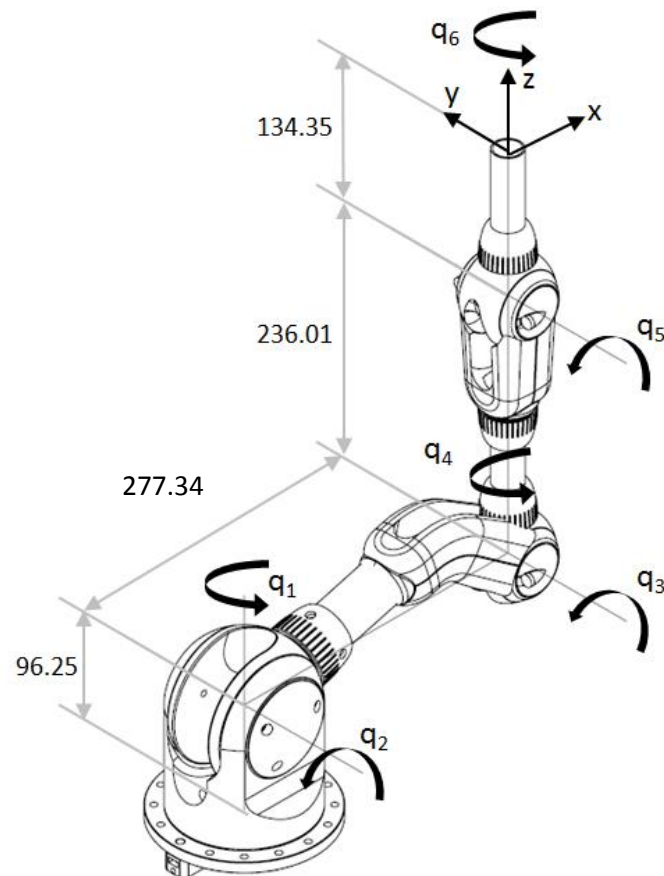
**AAN-BOT (UR10)**

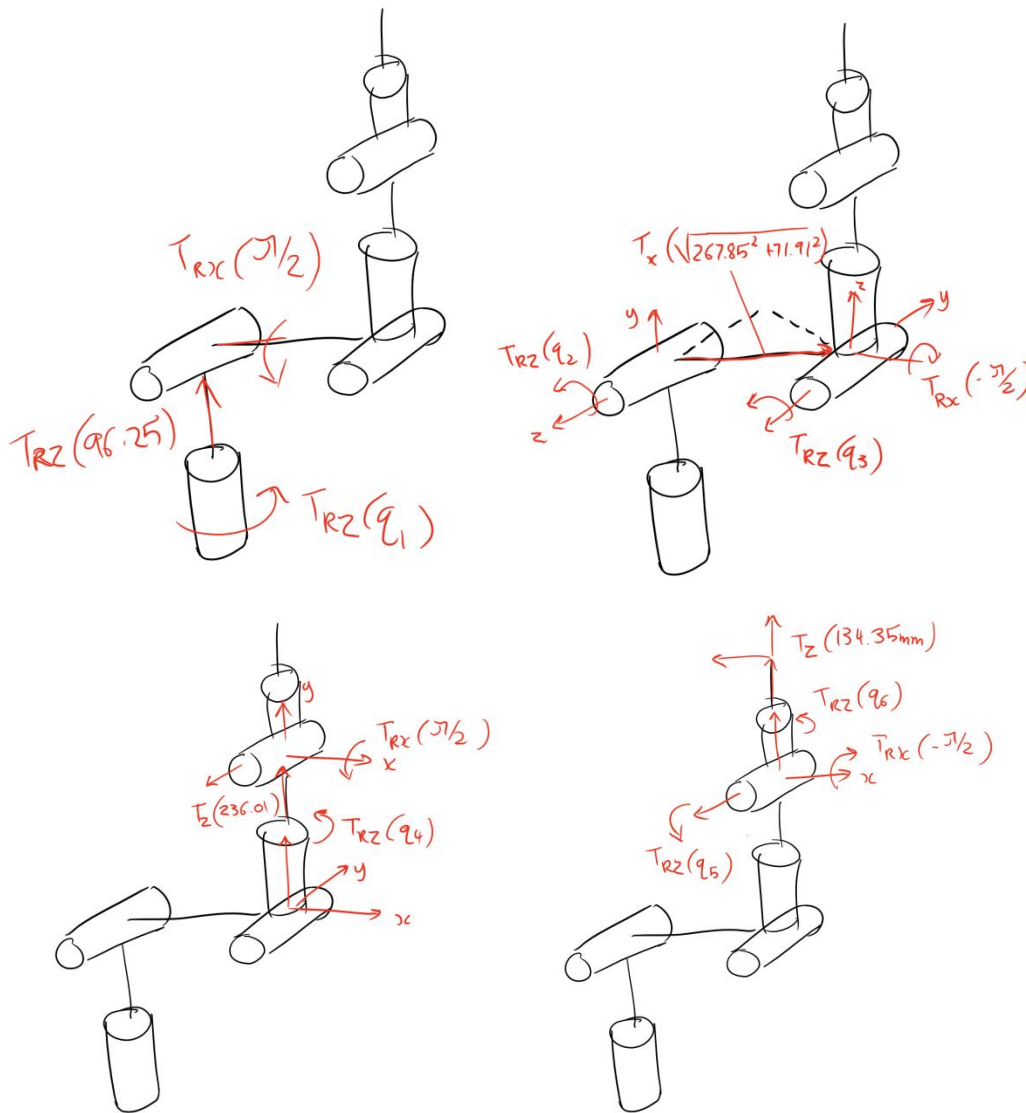
	$\theta_j$	$d_j$	$a_j$	$\alpha_j$
Link 1	$q_1$	0.1273	0	$\pi/2$
Link 2	$q_2$	0	-0.612	0
Link 3	$q_3$	0	-0.5723	0
Link 4	$q_4$	0.163941	0	$\pi/2$
Link 5	$q_5$	0.1157	0	$-\pi/2$
Link 6	$q_6$	0.0922	0	0



**Submerged Pile Inspection Robot (SPIR)**

	$\theta_j$	$d_j$	$a_j$	$\alpha_j$
Link 1	$q_1$	96.25mm	0	$\pi/2$
Link 2	$q_2$	0	277.34mm	0
Link 3	$q_3$	0	0	$-\pi/2$
Link 4	$q_4$	236.01mm	0	$\pi/2$
Link 5	$q_5$	0	0	$-\pi/2$
Link 6	$q_6$	134.35mm	0	0





**Sawyer**

	$\theta_j$	$d_j$	$a_j$	$\alpha_j$
Link 1	$q_1$			
Link 2	$q_2$			
Link 3	$q_3$			
Link 4	$q_4$			
Link 5	$q_5$			
Link 6	$q_6$			
Link 7	$q_7$			