

Insurance Supervision under Climate Change: A Pioneer Detection Method

Eric Vansteenberghe ^a

^aBanque de France

Disclaimer

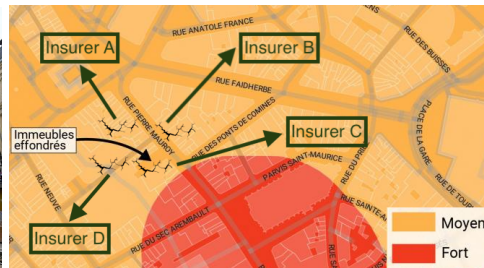
*A storm is threatening
My very life today
If I don't get some shelter
I'm going to fade away*

Michael Phillip Jagger and Keith Richards

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Motivation 1/2

- ▶ November 12, 2022, two buildings collapsed in Lille city center
- ▶ Did insurers receive claims? (cracks as early warnings) illustration^b
- ▶ Investigation to determine if collapse due to CC (will be public information)



^b”La Voix du Nord” 30.11.2022 C. Canivez and J. Depelchin

Motivation 2/2

What are the optimal regulation and supervision actions?

1. Build own beliefs:
 - ▶ On-site ad-hoc inspections;
 - ▶ Stress tests;
 - ▶ Modeling;
 - ▶ Opinion pooling.
2. Information sharing in the form of:
 - ▶ Disclosures;
 - ▶ Announcements;
 - ▶ Regulatory constraints.

Contributions to the literature

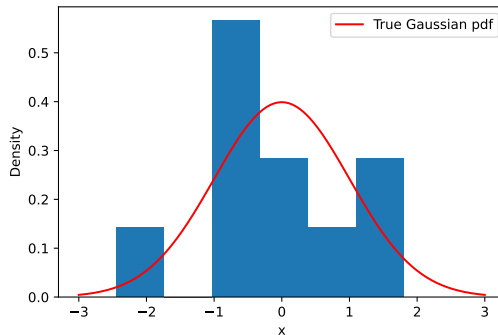
- ▶ **Opinion pooling, combination forecast:** [Stone \[1961\]](#), [Genest and Zidek \[1986\]](#), [Clemen \[1989\]](#), [Timmermann \[2006\]](#), and [Wang et al. \[2022\]](#).
 - ▶ Gaussian context:
 - ▶ difficult to beat a mean excluding outliers.
 - ▶ Extreme Value context:
 - ▶ extremes do occur but rarely \implies hard to guess the tail;
 - ▶ \implies new Pioneer's Detection Method.
- ▶ **Insurability and supervisor mandate:**
 - ▶ [Berliner \[1985\]](#), [Charpentier \[2008\]](#);
 - ▶ this is the first paper to suggest using insurance on-site inspection to gather and then pool expertise wrt climate change.

Pioneer Detection Method: illustration 1/3

- ▶ Risk-averse insurance buyer exposed to aggregated losses:
 - ▶ $x(\alpha^t)$;
 - ▶ x rv \sim **Pareto** with unknown tail parameter α^t :
 - ▶ [Kleiber \[2003\]](#) Pareto, a parsimonious model effective for capturing the right-tail behavior of loss distributions.
- ▶ Climate change impacts the tail parameter over time t ;
- ▶ The realization of α^t is never observable.

Pioneer Detection Method: illustration 2/3

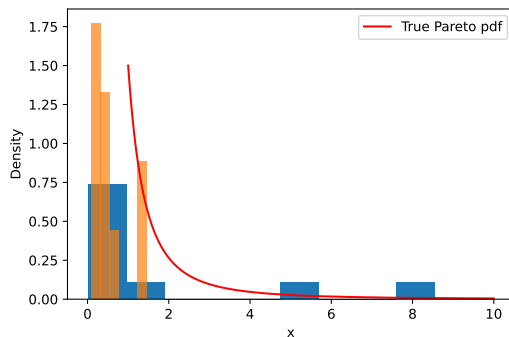
- ▶ In a Gaussian world, standard normal law, sample of 10 losses



- ▶ $\bar{x} \simeq 0$
- ▶ $Var(x) \simeq 1$

Pioneer Detection Method: illustration 3/3

- ▶ In an EVT, Pareto law ($\alpha = \mathbf{1.5}$), sample of 10 losses
- ▶ blue and orange fragmented information

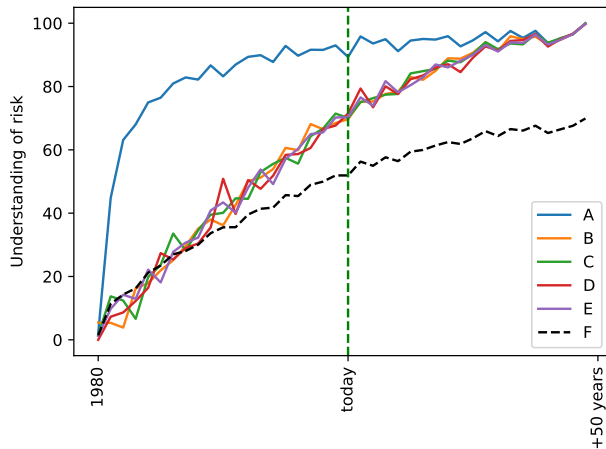


- ▶ $\hat{\alpha}_{\text{orange}} \simeq 5.5$
- ▶ $\hat{\alpha}_{\text{blue}} \simeq 1.2$
 - ▶ Granular information: $\hat{\alpha}_{\text{granular}} \simeq \mathbf{1.6}$, simple estimate average: $\hat{\alpha}_{\text{average}} \simeq 3.4$

Pioneer Detection Method

- ▶ can't observe α^t ;
- ▶ extreme events have low probability of occurrence but do happen:
 - ▶ heterogeneous learning rate depending on (random) exposure.
- ▶ **Pioneers** are experts who deviate from the majority opinion but towards which other experts' opinions converge over time although experts do not cooperate nor observe other estimates.
- ▶ PDM: implicit inter-temporal voting among experts to identify pioneers.
- ▶ A convergence in direction is enough to identify a Pioneer.

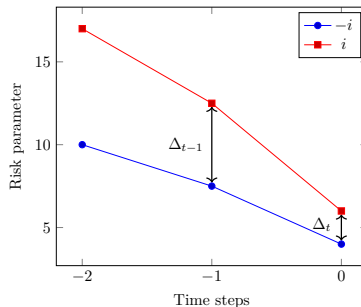
Pioneer Detection Method - time series



How to identify today that expert **A** is a pioneer?

Pioneer Detection Method - step 1 / 3

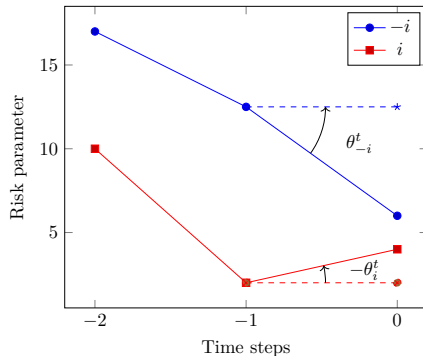
- **First step:** distance reduction dummy, $\delta_{\text{distance}}^t = \mathbb{1}_{\Delta_t < \Delta_{t-1}}$



- i represents the expert of interest
- $-i$ the average estimate of his competitors (i excluded).

Pioneer Detection Method - step 2/3

Second step: orientation change for convergence, $\delta_{\text{orientation}}^t = \mathbb{1}_{\theta_{-i}^t > \theta_i^t}$.

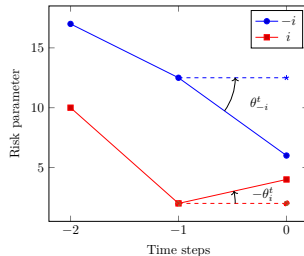


- ▶ i represents the expert of interest
- ▶ $-i$ the average estimate of his competitors (i excluded).

Pioneer Detection Method - step 3 / 3

Third step: proportion of the convergence attributed to each potential pioneer i :

$$w_i^t = \delta_{\text{distance}}^t \times \delta_{\text{orientation}}^t \times \frac{|\theta_{-i}^t|}{|\theta_{-i}^t| + |\theta_i^t|} \quad (1)$$



S subjective estimate:

$$\hat{\alpha}_S^t = \sum_i w_i^t \hat{\alpha}_i^t \quad (2)$$

New tool: alternatives competitors

1. Granger Causality (**GC**),
[Granger, 1969] and [Toda and Yamamoto, 1995].
2. (lagged) **Correlation** [Pearson, 1895],
as in Sakurai et al. [2005] and Forbes and Rigobon [2002].
3. Information transfer [Schreiber, 2000],
similar to GC if the r.v. are Gaussian [Barnett et al., 2009].
4. Bayesian Model Averaging
(BMA, Draper [1995]) but three challenges [Wang et al., 2022].

Comparison with Combination Forecast literature - Hog price

	prices	Econometric	ARIMA	Expert
date				
1976-03	47.90	48.55	48.54	47.00
1976-06	49.15	46.64	49.05	48.50
1976-09	43.53	47.76	46.81	45.00
1976-12	34.16	43.71	39.12	35.00
1977-03	38.96	45.32	35.27	35.00
...
1978-09	48.59	46.78	47.18	51.00
1978-12	50.03	52.08	47.28	45.00
1979-03	51.79	49.69	51.72	51.00
1979-06	43.07	51.01	50.05	48.00

- ▶ The data set is taken from [Bessler and Brandt \[1981\]](#).

Comparison with Combination Forecast literature - Hog price

	Expert	Econometric	AR	ARIMA	Median	L.Corr.	GC	Mean	Min. Var.	Pioneers
RMSE	1.35	1.22	1.00	0.64	0.64	0.56	0.55	0.52	0.48	0.42

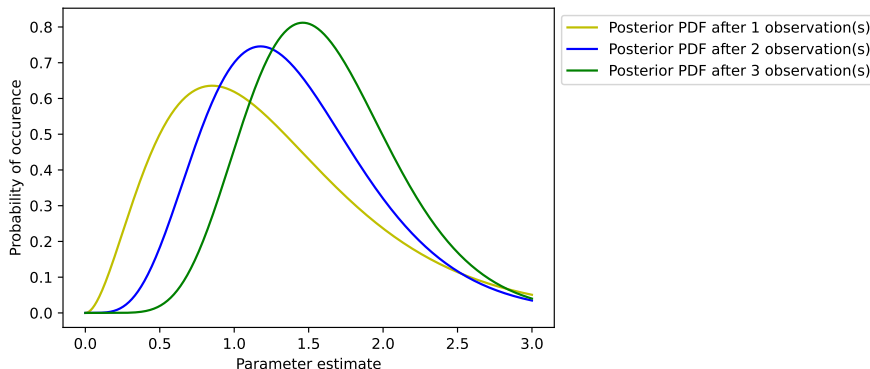
- ▶ Reported weights are the average when they are varying over time for the method:

Component	L.Corr.	GC	Mean	Min. Var.	Pioneers
Econometric	0.30	0.50	0.33	0.53	0.70
ARIMA	0.35	0.50	0.33	0.25	0.17
Expert	0.36	0.00	0.33	0.22	0.12

PDM validation - i.i. Bayesian experts

- ▶ Tipping point: stable α^- (unexpectedly) jumps to $\alpha = 1.5$ (then stable)
- ▶ [Arnold and Press \[1989\]](#) natural conjugate prior family for α is $\text{Gamma}(s_i^t, r_i^t)$
- ▶ start with vague prior $s_i^0 = r_i^0 = 10^{-3}$.

Bayesian expert posterior update with sample size



PDM validation - i.i. Bayesian experts

Time	Pioneers	Linear	Median	L.Corr.	GC
2	1.00	4.05	1.67	13.61	4.63
3	1.00	3.80	1.46	104.72	4.01
4	1.00	2.09	1.30	39.53	2.39
5	1.00	1.75	1.26	20.17	2.02
6	1.00	1.61	1.24	3.66	1.92
7	1.00	1.53	1.23	11.60	1.86
8	1.00	1.48	1.23	2.84	1.82
9	1.00	1.44	1.23	2.47	1.79

- ▶ Pareto type one distribution with $\alpha = 1.5$;
- ▶ 10^5 Monte Carlo simulations;
- ▶ $m=5$ non-cooperative Bayesian experts;
- ▶ robust to ranges of α and $m < \infty$.

S policy recommendation: welfare benefit

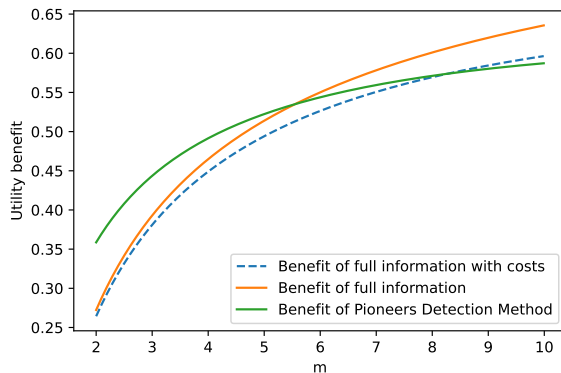
- ▶ Reminder: Pareto optimal contracts are solution of

$$\begin{cases} \max_{I(x^t), \Pi} \mathbb{E}_{\hat{\alpha}_b^t} [U(w - x^t + I(x^t) - \Pi)] \\ \text{subject to } \Pi(x^t) = \mathbb{E}_{\hat{\alpha}^t} [I(x^t)] \end{cases} \quad (3)$$

- ▶ Welfare gain substituting Π based on $\hat{\alpha}_i^t$ with $\hat{\alpha}_S^t = \sum_i w_i^t \hat{\alpha}_i^t$?
- ▶ Logarithm utility as in Mossin [1968]:

$$\mathbb{E}_{\hat{\alpha}_S^t} [\log(\text{constant} - \Pi)] \quad (4)$$

S policy recommendation: benefit, no data collection cost



- ▶ Even if claim collection would be costless, always more beneficial for S to use the PDM with less than five ICs.

Conclusion

- ▶ What can I advise an insurance supervisor to do if a tipping point introduces heterogeneous beliefs detrimental to welfare?
- ▶ Insurance market model to determine the form of indemnity:
 - ▶ Pareto type I where the tail parameter is never observable.
- ▶ I study optimal supervision actions and compare
 1. on-site inspections for information gathering;
 2. new Pioneers Detection Method for opinion pooling.
- ▶ My policy recommendation is to use the Pioneers Detection Method if small count of IC for an asset class.
- ▶ This conclusion in favor of the PDM is stronger when information collection and modeling costs are included.

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