

Lecture 2

Decision Theory

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Agenda

- > Introduction to Decision Making
- > Decision Making Without Probabilities
- > Decision Making With Probabilities
- > Expected Value of Perfect Information
- > Next Class

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Decision Analysis

- > Techniques used to make decisions among a set of discrete alternatives in the face of uncertain future events
 - investments
 - new products
 - facility expansion
 - choice of professors/courses

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Key Characteristics

- > Important problem
- > Unique
- > Non-instantaneous decision required
- > Complex
- > Uncertainty

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Terminology

- > Decision Alternatives
 - controllable; our choice
- > Outcomes (States of nature)
 - future events, uncontrollable
 - define all (mutually exclusive, collectively exhaustive)
- > Payoffs
 - $V(D, S) \leftarrow$ Value of A Decision in a certain State
- > Criteria, for evaluation of alternatives

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Structuring Decision Problems

- > Payoff Table
 - matrix/table of actions vs outcomes, payoffs
- > Decision Trees
 - chronological representation of problem
 - nodes and branches
 - 2 types of nodes: square = decision, round = outcome
 - payoffs at end of branches

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Payoff Tables

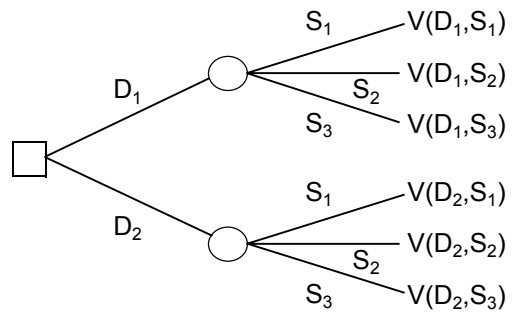
		States of Nature		
		S_1	S_2	S_3
Decision	D_1	$V(D_1, S_1)$	$V(D_1, S_2)$	$V(D_1, S_3)$
	D_2	$V(D_2, S_1)$	$V(D_2, S_2)$	$V(D_2, S_3)$
	D_3	$V(D_3, S_1)$	$V(D_3, S_2)$	$V(D_3, S_3)$

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Decision Trees



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Types of Problems

- > CERTAINTY - know which outcome (state of nature) will occur; hence select best alternative
- > UNCERTAINTY - no probability information available
- > RISK - probabilities of outcomes (states of nature) are available

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Decisions Under Uncertainty

- > When decision maker doesn't know which outcome will occur & has no probability estimates
- > Four commonly used criteria :
 - equally likely (LAPLACE)
 - the optimistic approach (MAXIMAX)
 - the conservative approach (MAXIMIN)
 - the MINIMAX REGRET approach

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Decisions Under Uncertainty

Payoff Table		States of Nature		
		S_1	S_2	S_3
Decision	D_1	10,000	6,500	-4,000
	D_2	8,000	6,000	1,000
	D_3	5,000	5,000	5,000

- > What decision would you choose?
- > Why?

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Laplace Criterion

- > Assume all states are equally likely

Payoff Table		States of Nature			Average Payoff
		S_1	S_2	S_3	
Decision	D_1	10,000	6,500	-4,000	4,167
	D_2	8,000	6,000	1,000	5,000
	D_3	5,000	5,000	5,000	5,000

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Optimistic Approach

- > Used by optimistic (aggressive?) decision maker
- > Decision with the largest possible payoff is chosen
- > Any concerns about this approach?

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Maximax (Optimistic)

- > Maximize the maximum payoff

Payoff Table		States of Nature			Maximum Payoff
		S ₁	S ₂	S ₃	
Decision	D ₁	10,000	6,500	-4,000	10,000
	D ₂	8,000	6,000	1,000	8,000
	D ₃	5,000	5,000	5,000	5,000

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Conservative/Pessimistic Approach

- > For conservatives or pessimists
- > For each decision identify the minimum payoff; select the maximum of these minimum payoffs
- > Any concerns about this approach?

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Maximin (Pessimistic)

- > Maximize the minimum payoff

Payoff Table		States of Nature			Minimum Payoff
		S ₁	S ₂	S ₃	
Decision	D ₁	10,000	6,500	-4,000	-4,000
	D ₂	8,000	6,000	1,000	1,000
	D ₃	5,000	5,000	5,000	5,000

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Minimax Regret Approach

- > Construct a regret (opportunity loss) table
- > For each state of nature calculate the difference between each payoff and the largest payoff for that state of nature.
- > Using regret table, the maximum regret for each possible decision is listed
- > Chose decision which minimizes the maximum regrets

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Minimax Regret

- > Minimize the maximum regret

Payoff Table		States of Nature		
		S ₁	S ₂	S ₃
Decision	D ₁	10,000	6,500	-4,000
	D ₂	8,000	6,000	1,000
	D ₃	5,000	5,000	5,000

Regret Table		States of Nature			Maximum Regret
		S ₁	S ₂	S ₃	
Decision	D ₁	0	0	9,000	9,000
	D ₂	2,000	500	4,000	4,000
	D ₃	5,000	1,500	0	5,000

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Minimization Problems

- > These problems have been maximization problems - seeking the best payoff
- > What if these had been minimization problems - seeking the best/lowest cost



Minimization Problems

- > Minimin (Optimistic)
 - choose the global lowest cost option
- > Minimax (Pessimistic)
 - identify maximum costs for each decision, then select the minimum of these
- > Minimax regret
 - minimal of the maximum regrets



Minimization Objective

Payoff Table		States of Nature			Minimum Cost	Maximum Cost
		S ₁	S ₂	S ₃		
Decision	D ₁	10,000	6,500	-4,000	-4,000	10,000
	D ₂	8,000	6,000	1,000	1,000	8,000
	D ₃	5,000	5,000	5,000	5,000	5,000

Minimin Minimax

Regret Table		States of Nature			Maximum Regret
		S ₁	S ₂	S ₃	
Decision	D ₁	5,000	1,500	0	5,000
	D ₂	3,000	1,000	5,000	5,000
	D ₃	0	0	9,000	9,000

Minimax Regret



Decisions Under Risk

- > Probabilities known for Outcomes (States of Nature)
- > Use Expected Value Approach
- > The decision yielding the best expected return is chosen



Expected Value

- > Expected value of a decision alternative is the sum of weighted payoffs for that alternative



Expected Value

- > Expected value (EV) of decision alternative D_i is defined as:

$$EV(D_i) = \sum_{j=1}^N P(S_j) V(D_i, S_j)$$

- > N = the number of states of nature
- > P(S_j) = the probability of state of nature s_j
- > V(D_i, S_j) = the payoff corresponding to decision alternative d_i and state of nature s_j



Expected Value

- > That last slide will keep the Mathematicians and Statisticians happy
- > A more practical approach, or view, of EV:

State	S ₁	S ₂	S ₃	
P(S)	0.6	0.2	0.2	
Payoff	10,000	6,500	-4,000	EV
EV(Payoff)	6,000	1,300	-800	6,500

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Sumproduct Function (Excel)

- > The sumproduct function can speed up making up our spreadsheet, and add to its general applicability
- > in cell e3: =sumproduct(b2..d2,b3..d3)

State	S ₁	S ₂	S ₃	
P(S)	0.6	0.2	0.2	EV
Payoff	10,000	6,500	-4,000	6,500
EV(Payoff)	6,000	1,300	-800	6,500

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Decisions Under Risk

- > Expected value approach

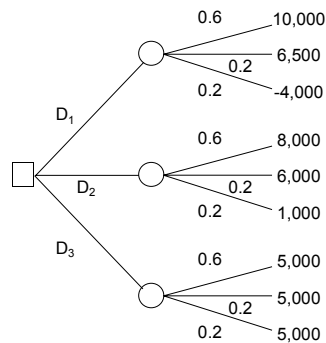
Payoff Table		States of Nature			EV(D _i)
		S ₁	S ₂	S ₃	
P(S)		0.6	0.2	0.2	
Decision	D ₁	10,000	6,500	-4,000	6,500
	D ₂	8,000	6,000	1,000	6,200
	D ₃	5,000	5,000	5,000	5,000

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Decision Tree Approach



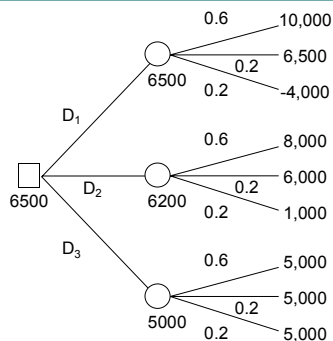
Roll back to a decision

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Decision Tree Approach



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Expected Value of Perfect Information

- > Frequently information is available which can improve the probability estimates for the possible outcomes (states of nature)
- > Expected value of perfect information (EVPI) is the increase in the expected profit that would result if one knew with certainty which state of nature would occur
- > EVPI provides an upper bound on the expected value of any sample or survey information

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EVPI Calculation

- > Difference between the expected payoff under perfect information and the expected payoff of the optimal decision without perfect information



EVPI Calculation - I

Payoff Table		States of Nature			EV(D _i)
		S ₁	S ₂	S ₃	
P(S)		0.6	0.2	0.2	
Decision	D ₁	10,000	6,500	-4,000	6,500
	D ₂	8,000	6,000	1,000	6,200
	D ₃	5,000	5,000	5,000	5,000
Best		10,000	6,500	5,000	8,300
					-6,500
					EVPI 1,800



EVPI Calculation - II

- > The EVPI can also be calculated as the expected regret under the optimal decision under uncertainty
- > D₁ was the optimal decision under uncertainty

P(S)	0.6	0.2	0.2	E(Regret)
D ₁	0	0	9000	1,800



Next Class

- > Practice Problems for
 - Linear Programming
 - Decision Theory

