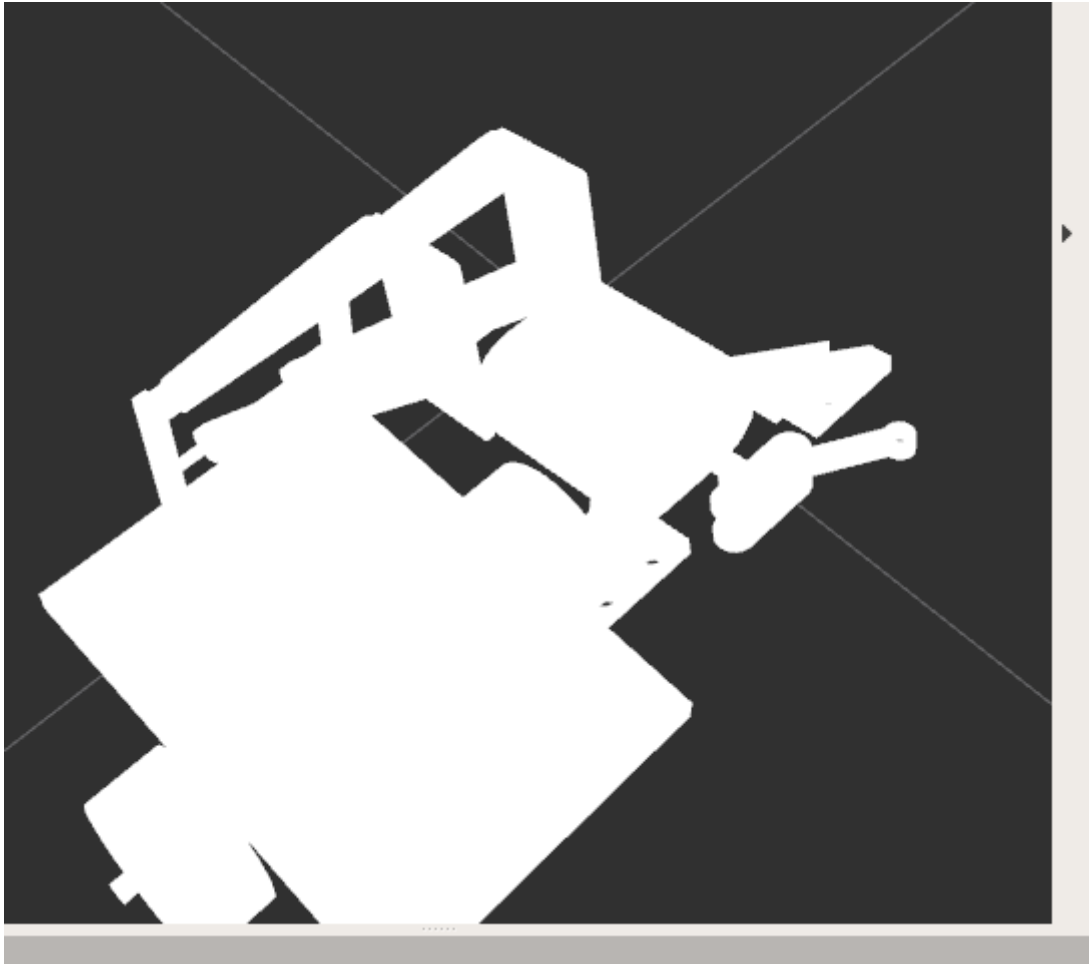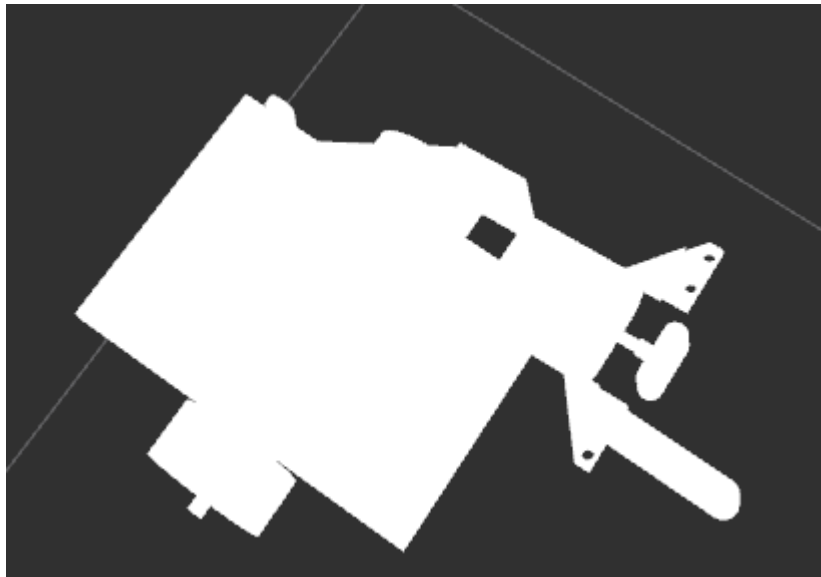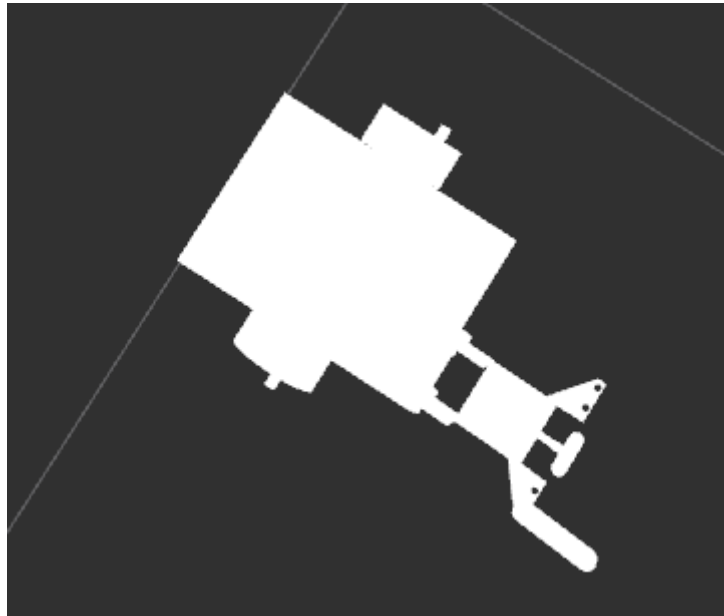URDF :
- links : intertia
- joints : limits

INT1 :

Ext1 :

Ext2 :

Ext 3

MoveIt Setup Assistant :
- collisison matrix generation (MAY CAUSE ISSUES… BUT THE MODEL IS CLEAN SO IT SHOULD BE ALL RIGHT)
- solver choice : KDL