~~3~~ 2 goals :

- ~~Enable real time update of the IHM indicators from Matlab when asked by the latter~~

THERE WONT BE ANY REAL TIME FLOW FROM .m TO .mapp

INSTEAD, THE REAL TIME PLOT WILL BE DONE IN ANOTHER FIGURE LAUNCHED FROM AND UPDATED BY the .m

- Transfer map_matrix to OccupancyGrid
- Global planner

https://youtu.be/yZx9SQ-bfk0