

# 1 Parsing-as-deduction rules for noisy channel

## 1.1 Item format

Each item has the following entries:

1. frame index (usually denoted  $i, j, \dots$ )
2. HMM state type ( $\in \{start, mid, end\}$ )
3. PLU bottom type (typically denoted  $A, B, \dots$ )
4. PLU bottom index (typically denoted  $a, b, \dots$ )
5. edit operation type ( $\in \{IB, IT, SUB\}$ )
6. PLU top type (typically denoted  $M, N, \dots$ )
7. PLU top index (denoted  $m, n, \dots$ )
8. the probability of the item (usually  $P$  or  $P'$ )

## 1.2 Moves in Levenshtein matrix

### 1.2.1 Insert Bottom

$$\frac{[i, end, A, a, , N, n, P]}{[i + 1, start, B, a + 1, , N, n, P' = P \cdot p(end \rightarrow start) \cdot p(op = IB) \cdot p(IB(B)) \cdot p(f_{i+1}|B, start)]}$$

### 1.2.2 Insert Top

$$\frac{[i, end, A, a, , M, m, P]}{[i, end, A, a, , N, m + 1, P' = P \cdot p(op = IT) \cdot p(f_i|A, end)]}$$

### 1.2.3 Substitute

$$\frac{[i, end, A, a, , M, m, P]}{[i + 1, start, B, a + 1, , N, m + 1, P' = P \cdot p(end \rightarrow start) \cdot p(op = SUB) \cdot p(SUB(B|N)) \cdot p(f_{i+1}|B, start)]}$$

## 1.3 Moves in trellis