

YIJUN(ESTHER) GU

Robotics, Imperial College, London, UK

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RESEARCH OVERVIEW

My research lies at the intersection of human-robot interaction, machine learning, multi-modal perception, tactile sensing, physics simulation, and ergonomics. I develop interfaces and algorithms that enable robots to interact with human safely and efficiently, while adapting to individual preferences. Beyond physical interaction, I am also interested in understanding human cognition, ensuring that the developed technologies align with users' mental models and well-being. My work is particularly focused on advancing assistive technologies in personal and healthcare applications.

EDUCATION

Ph.D., Electrical and Electronic Engineering

Feb 2022 – present

Imperial College London, UK

Advisor: Yiannis Demiris

*Funded by EEE PhD Scholarship

M.S., Computer Science

May 2021

Specialization in Computational Perception and Robotics

Georgia Institute of Technology, USA

Thesis: Virtual Reality as a Stepping Stone to Real-World Robotic Caregiving

Advisor: Charles C Kemp & Zackory Erickson

B.S.E., Computer Science, Data Science (double major)

May 2019

University of Michigan, USA

PAPERS IN SUBMISSION

Reducing caregiver burden with robotics: Limb manipulation assistance for caregivers in bed bathing

Yijun Gu*, Ertug Ovur*, Yiannis Demiris (* Equal contribution.)
ACM Transactions on Human-Robot Interaction (THRI), 2025

Title omitted for blind review

Yijun Gu*, Ertug Ovur*, Yiannis Demiris (* Equal contribution.)
IEEE Transactions on Robotics (T-RO), 2025

JOURNAL ARTICLES

Vttb: A visuo-tactile learning approach for robot-assisted bed bathing.

Yijun Gu, Yiannis Demiris
IEEE Robotics and Automation Letters (RAL), 2024

Revolutionizing clean energy labs: Robotic imitation learning for efficient fabrication AI-powered electrical units assembly platform.

Yijun Gu*, Xi Xu*, Tianyi Zhang, Jiwen Yu, Stephen Skinner (* Equal contribution.)
Energy and AI, 2025

CONFERENCE PROCEEDINGS

Learning Bimanual Manipulation Policies for Bathing Bed-bound People.

Yijun Gu, Yiannis Demiris

IEEE International Conference on Intelligent Robots and Systems (IROS), 2024

* Oral Presentation

Assistive VR Gym: Using Interactions with Real People to Improve Virtual Assistive Robots.

Yijun Gu*, Zackory Erickson*, Charles C Kemp (* Equal contribution.)

IEEE International Conference on Robot & Human Interactive Communication (RO-MAN), 2020

RESEARCH EXPERIENCE

Personal Robotics Lab, Imperial College London

Feb 2022 - Jan 2026 (exp.)

PhD Student, Principal Investigator: Prof. Yiannis Demiris

- Developed a transformer-based imitation learning framework that enables robot to accurately sense the human body through multimodal sensing and perform safe interaction during assistive bed bathing.
- Proposed the first robot-assisted bed bathing application that performs autonomous bathing around the human body using bimanual robot arms.
- Investigated algorithmic advancements in comfort modeling, establishing the ergonomic foundations for predicting and adapting to human physical states.
- Collaborated on the development of a ergonomic limb-repositioning system aimed at minimizing caregiver physical load during bathing scenarios.
- Collaborated on the development of a system that optimizes human ergonomics for bimanual handover locations and enables safe human–robot co-manipulation.

Healthcare Robotics Lab, Georgia Institute of Technology

Aug 2020 – May 2022

Graduate Research Assistant, Principal Investigator: Prof. Charles C. Kemp, Prof. Greg Turk, Prof. Karen Liu, and Dr. Zackory Erickson

- Developed algorithmic advancements to safely transfer robot controllers from physics simulation to real robots for robotic assistance.
- Benchmarked how much observation noise standard robot control policies can handle when transferred to real robots.
- Investigated algorithmic advancements to improve robot control policy robustness to noise.
- Presented a framework that integrates human biomechanical models and utilizes virtual reality to evaluate and improve simulation-trained assistive robots with real users.

CROMA Lab, University of Michigan

July 2018 – Apr 2019

Undergraduate Research Assistant, Principal Investigator: Dr. Sai R. Gouravajhala

- Developed a mix-initiative system that leverages real-time crowd workers to annotate subcomponents of objects and generate point cloud objects with new configurations.

Laboratory for Progress, University of Michigan

Sep 2017 – Apr 2018

Undergraduate Research Assistant, Principal Investigator: Prof. Chad Jenkins and Dr. Zhiqiang Sui

- Worked as part of the "Never Mind the Bounding Boxes, Here's the SAND Filters" project.

- Explored Point Pair Features (PPF), an occlusion-robust 6D pose estimation algorithm that couples oriented point pair features with a Hough-like voting scheme to match models to scenes.

TEACHING EXPERIENCE

ELEC70015 Human Centered Robotics , Imperial College London Graduate Teaching Assistant, Prof. Yiannis Demiris	Spring 2022 - present
ELEC60009/70061 Deep Learning , Imperial College London Graduate Teaching Assistant, Prof. Krystian Mikolajczyk	Spring 2025
ELEC60019/70059 Applied Machine Learning , Imperial College London Graduate Teaching Assistant, Prof. Abd Al Rahman Abu Ebayyeh	Fall 2024
ELEC60019/70059 Applied Machine Learning , Imperial College London Graduate Teaching Assistant, Prof. Abd Al Rahman Abu Ebayyeh	Fall 2023
ELEC60019/70059 Applied Machine Learning , Imperial College London Graduate Teaching Assistant, Prof. Krystian Mikolajczyk	Fall 2022
CS6476 Computer Vision , Georgia Institute of Technology Graduate Teaching Assistant, Prof. Frank Dallert	Spring 2021
CS6601 Artificial Intelligence , Georgia Institute of Technology Graduate Teaching Assistant, Prof. Thomas Ploetz	Fall 2020
EECS280 Programming and Intro Data Structures , University of Michigan Fall 2018 Teaching Assistant, Prof. James Juett	Spring 2017 –

RESEARCH MENTORSHIP

Anqi Qiu , M.S., IC, EEE PhD Student at UCL	2022 - 2023
Xinyun Chi , M.S., IC, EEE PhD Student at UoM	2023 - 2024
Rapin Adchariyaporn , M.S., IC, EEE	2025 -

ACADEMIC SERVICE

Journal Reviewer	IEEE Transactions on Human-Machine Systems(THMS), IEEE Robotics and Automation Letter(RA-L), IEEE Internet of Things Journal(IoT), Scifiniti Publishing
Conference Reviewer	IEEE ICRA, IEEE IROS, IEEE RO-MAN

SKILLS

Programming Libraries and Tools	Python, C++, ROS, Matlab, Latex, Git, HTML, Docker, IOS (Swift), Scikit-learn, Pytorch, Tensorflow, Numpy, pandas, matplotlib, OPENCV, OpenNI, Bullet, MUJOCO, IssacGym, PCL, Virtual Reality, BLENDER
Robots Sensors	Franka, Kinova, Spot, Baxter, AgileX, Allengo Hand, Kinect, RealSense, Zed, RGBD cameras, Gelsight, Digit, tactile sensors, Delsys EMG system, LiDAR, HTC VIVE, Vision Pro, OptiTrack
Operating Systems Languages	Linux, IOS, Raspberry Pi Chinese (Native), English (Proficient), Japanese (Conversational)