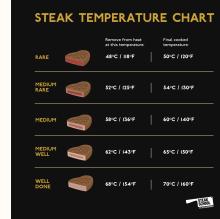


A

Power Management

02_Power.SchDoc



Product Specifications:
Battery Life: 2 hours

Temperature sensing range (max): 400°C (or roughly 350°C)

Module operating temperature range: roughly 60°C ambient on outside of module. With heat insulation in place, hopefully reduce ambient temperature to a max of 40°C (possibly lower)

Sensing accuracy (max): $\pm 1^\circ\text{C}$ (since meat has a 5°C range between doneness levels)

Interaction: rocker power switch, LEDs to indicate when grill needs to be turned, connect to mobile through WiFi and display GUI, run HTML web app with relevant information and selection of presets

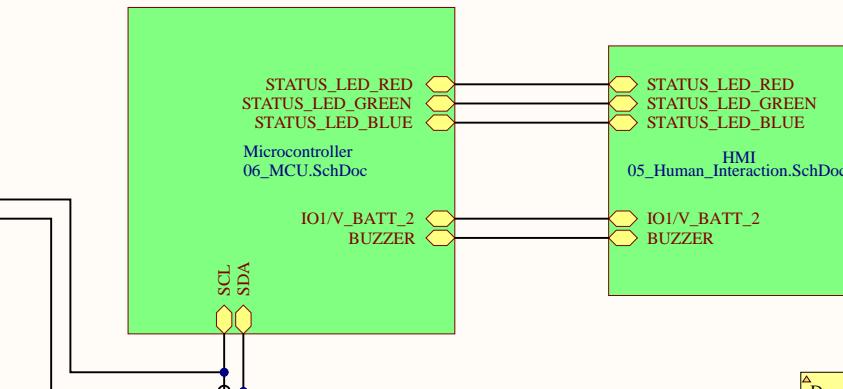
Accelerometer: to sense when the grid has been flipped

Storage: SD card

B

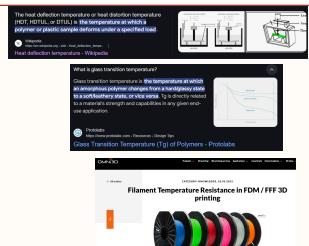
Temperature Sensor Interface

03_Temp_Sensor.SchDoc



Info Regarding 3D printed housing

Temperature reading at the handle of the grid measured to be $\pm 5^\circ\text{C}$, so the 3D printed housing should have a HDT (Heat Deflection Temperature) comfortably above that to ensure housing does not deform during use of product.
Also have to check the Glass Transition Temperature of the polymer.



C

Due to complexity of the board and size constraints, a 2-layer board will not be sufficient for this project (which is what is available if I make it at the university), so the PCB will need to be made elsewhere. JLCPCB is chosen as the PCB manufacturing company.

Consideration was taken to order a fully, or partially, populated board from JLCPCB to save time and insure correct soldering. But JLCPCB doesn't have some components, the main one being the ESP32-C6-MINI-H8, and the board will not be able to go in a reflow oven again as this will damage the components (being heated a second time). Another thing is that a minimum of 458 ESP32 IC's need to be bought for some reason. Also, through JLCPCB, you need to order extra components for "attrition quantity", which is basically extra's you need to get in case components get lost or are damaged in the Pick n Place procedure.

Instead, the PCB will still be ordered from JLCPCB, and all the components will be ordered from DigiKey.

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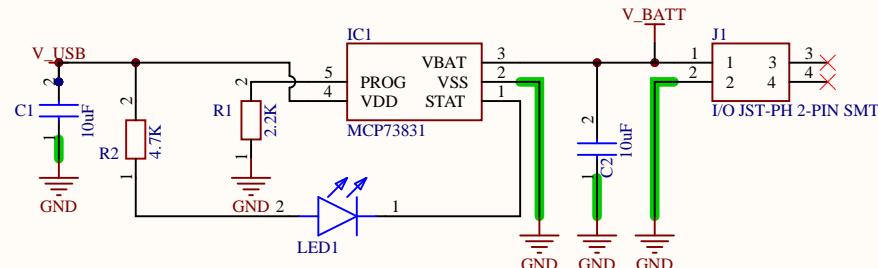
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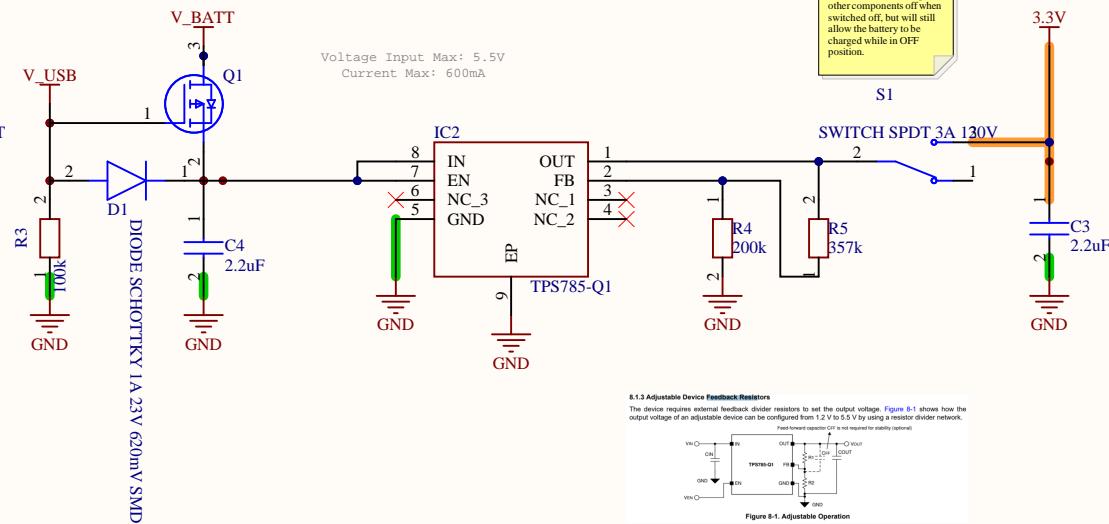
A

Battery Charger

$$I_{CHG} = 1000 / R_{PROG}$$

Δ $I_{CHG} = 400mA$
 $R_{prog} = 1000/400mA$
 $= 2.5k\Omega$
 $\approx 2.2k\Omega (454.54mA)$

For 1200mAh battery the max charge time will be $\pm 2h30m$.

3V3 Regulator

Δ SPDT switch will keep all other components off when switched off, but will still allow the battery to be charged while in OFF position.

Voltage Input Max: 5.5V
Current Max: 600mA

8.1.3 Adjustable Device Feedback Resistors
The device needs external feedback resistors to set the output voltage. Figure 8-1 shows how the output voltage of an adjustable device can be configured from 1.2V to 3.5V by using a resistor divider network.



Figure 8-1. Adjustable Operation

$$V_{OUT} = V_{FB} \times (1 + R_1 / R_2) + I_{FB} \times R_1 \quad (2)$$

V_{FB}	Feedback voltage	Adjustable output only	1.182	1.2	1.218	V
I_{FB}	Feedback pin current	Adjustable output only	-0.05	0.01	0.05	μA

To disregard the effect of the FB pin current error term in **Equation 2** and to achieve best accuracy, choose R_2 to be equal to or smaller than $550 k\Omega$ so that the current flowing through R_1 and R_2 is at least 100 times larger than the I_{FB} current listed in the **Electrical Characteristics** table. Lowering the value of R_2 increases the immunity against noise injection. Increasing the value of R_2 reduces the quiescent current for achieving higher efficiency at low load currents. **Equation 3** calculates the setting that provides the maximum feedback divider series resistance.

$$(R_1 + R_2) \leq V_{OUT} / (I_{FB} \times 100) \quad (3)$$

Δ $V_{out} = 3.3V$
 $R_2 = 200k$
 $R_1 = 350k \rightarrow R_1 = 357k$
 $V_{out_new} = 3.342V$



Δ Battery has about 300 cycles. Include easy replaceable battery slot in final design for if customers battery dies then it can be replaced.
Aim to have max power consumption of entire system to be 500mA so that product can last 2 hours of use.

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U_04.1_Temp_Sensor_Info
04.1_Temp_Sensor_Info.SchDoc

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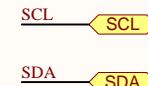
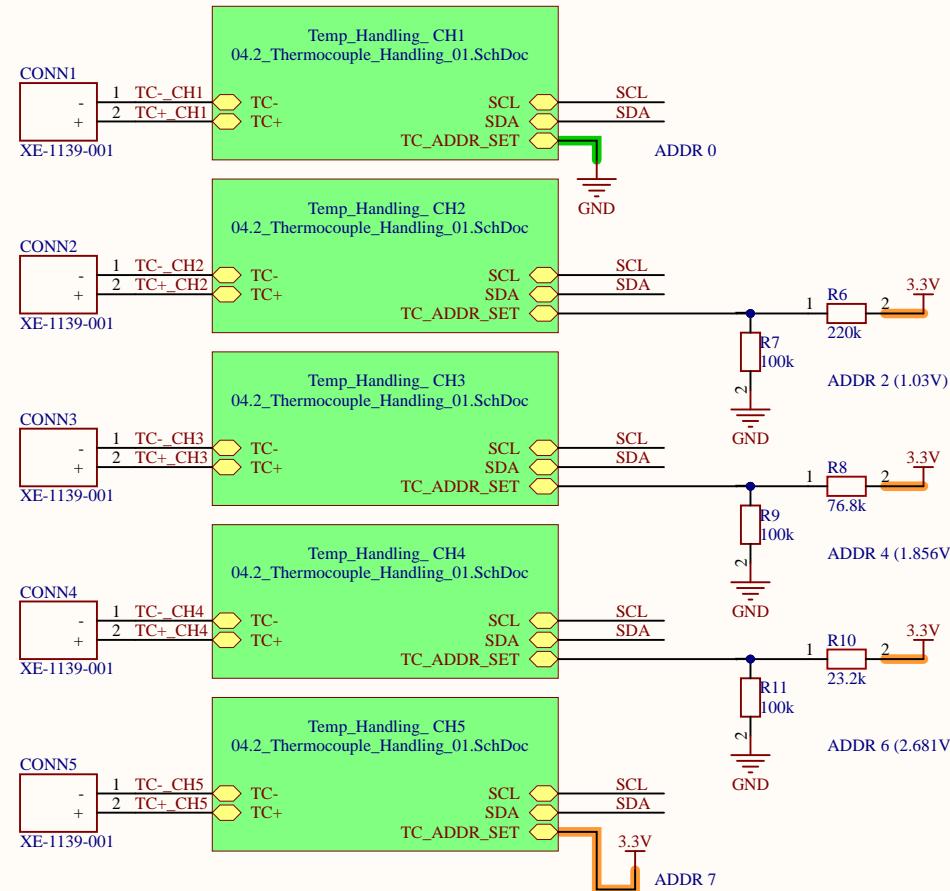
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ADDR uses an internal ADC to check the voltage on the pin to determine the last three bits of the 7-bit I²C address (1:1:0:0:A2:A1:A0).

Setting ADDR to GND = 1:1:0:0:0:0:0
Setting ADDR to VIN = 1:1:0:0:1:1:1

For other values and resistor divider setup, see the DS for details.

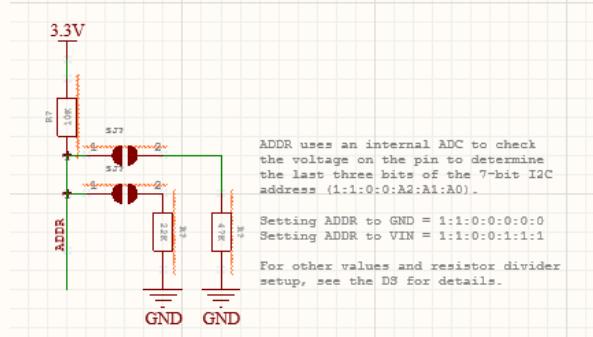
I ² C Address Selection Levels (Note 1)						
Command Byte [1:100 000x]	V _{ADDR}	GND	—	—	V	Address = 0
Command Byte [1:100 001x]	V _{ADDR_L}	V _{ADDR_TYP}	—	V _{ADDR_H}	(Note 2)	Address = 1
Command Byte [1:100 010x]	—	(Note 2)	(Note 2)	—	(Note 2)	Address = 2
Command Byte [1:100 011x]	—	—	—	—	—	Address = 3
Command Byte [1:100 100x]	—	—	—	—	—	Address = 4
Command Byte [1:100 101x]	—	—	—	—	—	Address = 5
Command Byte [1:100 110x]	—	—	—	—	—	Address = 6
Command Byte [1:100 111x]	—	—	—	—	V _{DD}	Address = 7

Note 1 The ADDR pin can be tied to V_{DD} or V_{SS}. For additional addresses, a resistive divider network can be used to set voltage levels that are rationed to V_{DD}. The device supports up to eight levels (see Section 6.3.1 “I²C Addressing” for recommended resistor values).

2 V_{ADDR_TYP} = Address * V_{DD}/8 + V_{DD}/16,
V_{ADDR_L} = V_{ADDR_TYP} - V_{DD}/32 and
V_{ADDR_H} = V_{ADDR_TYP} + V_{DD}/32 (where: Address = 1, 2, 3, 4, 5, 6).

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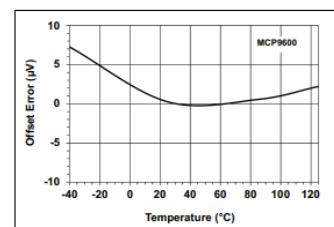
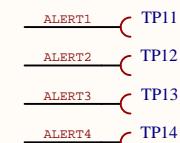
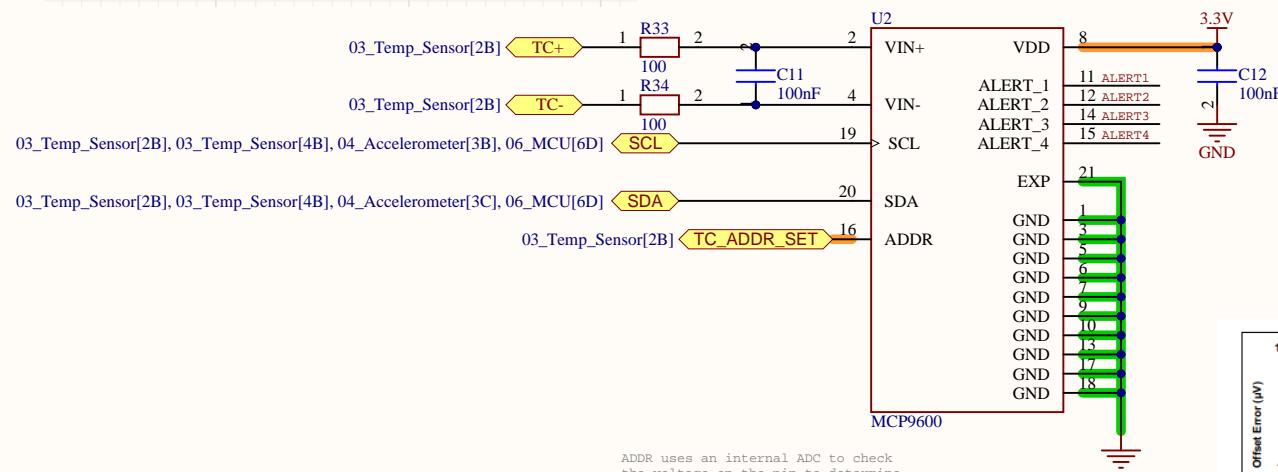


FIGURE 2-15: Input Offset Error Voltage
(V_{IN+}, V_{IN-})

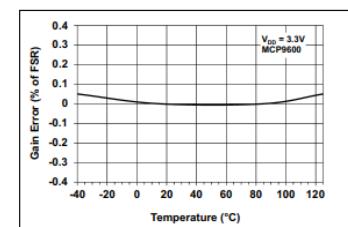


FIGURE 2-18: Full-Scale Gain Error.
V_{D2} = 3.3V

- Measurement Resolution:
 - Hot and cold-junctions: +0.0625°C (typical)
- Four Programmable Temperature Alert Outputs:
 - Monitor hot or cold-junction temperatures
 - Detect rising or falling temperatures
 - Up to 255°C of programmable hysteresis

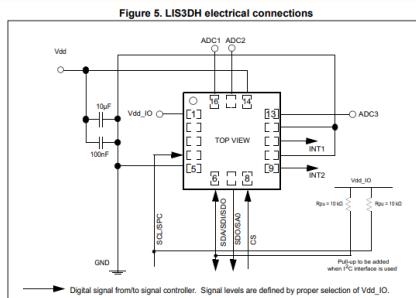
Resolution of 0.0625°C.

Look into setting temperature alerts when desired preset temperatures are reached.

Input offset voltage and full-scale gain error are both at their minimum at a temperature of 30°C.
Aim to have ambient temperature inside module to be 30°C.

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The device core is supplied through the Vdd line while the I/O pads are supplied through the Vdd_IO line. Power supply decoupling capacitors (100 nF ceramic, 10 μ F aluminum) should be placed as near as possible to pin 14 of the device (common design practice).

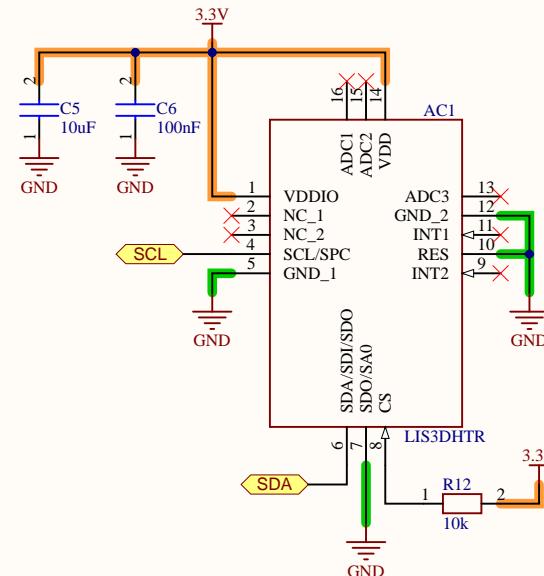
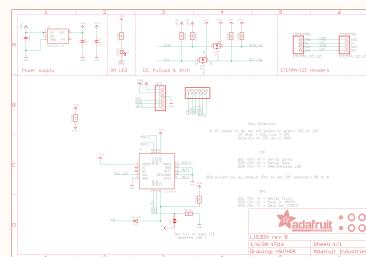
All the voltage and ground supplies must be present at the same time to have proper behavior of the IC (refer to Figure 5). It is possible to remove Vdd maintaining Vdd_IO without blocking the communication bus, in this condition the measurement chain is powered off.

The functionality of the device and the measured acceleration data is selectable and accessible through the I²C or SPI interfaces. When using the I²C, CS must be tied high. ADC1, ADC2 & ADC3 if not used can be left floating or connected to Vdd or GND.

The functions, the threshold and the timing of the two interrupt pins (INT1 and INT2) can be completely programmed by the user through the I²C/SPI interface.

Pin#	Name	Function	Pin status
1	Vdd_IO	Power supply for I/O pins	
2	NC	Not connected	
3	NC	Not connected	
4	SCL	I ² C serial clock (SCL) SPI serial port clock (SPC)	Default: input high impedance
5	GND	0 V supply	
6	SDA	I ² C serial data (SDA) SPI serial data input (SDI)	Default: (SDA) input high impedance
7	SDO	3-wire interface serial data output (SDO)	
8	SAO	SPI serial data output (SDO) I ² C less significant bit of the device address (SA0)	Default: input with internal pull-up ⁽¹⁾
9	CS	SPI enable I ² C/SPI mode selection: 1: SPI idle mode / I ² C communication enabled 0: SPI communication mode / I ² C disabled	Default: input high impedance
10	RES	Connect to GND	
11	INT1	Interrupt interrupt 1	Default: push-pull output forced to GND
12	GND	0 V supply	
13	ADC3	Analog-to-digital converter input 3	Default: input high impedance
14	Vdd	Power supply	
15	ADC2	Analog-to-digital converter input 2	Default: input high impedance
16	ADC1	Analog-to-digital converter input 1	Default: input high impedance

1. In order to disable the internal pull-up on the SDO/SAO pin, write 90h in CTRL_REG0 (7Eh).



$\gamma^{(1)}$	SDO	SDO serial data output (SDO) I ² C less significant bit of the device address (SA0)
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1. SDO/SAO pin is internally pulled up. Refer to Table 3 for the internal pull-up values (typ.).



Vdd_IO	Resistor value for SDO/SA0 pin
	Typ. (k Ω)
1.7 V	54.4
1.8 V	49.2
2.5 V	30.4
3.6 V	20.4

Δ I²C address LSB will not need to change so tie pin 7 (CS) low.

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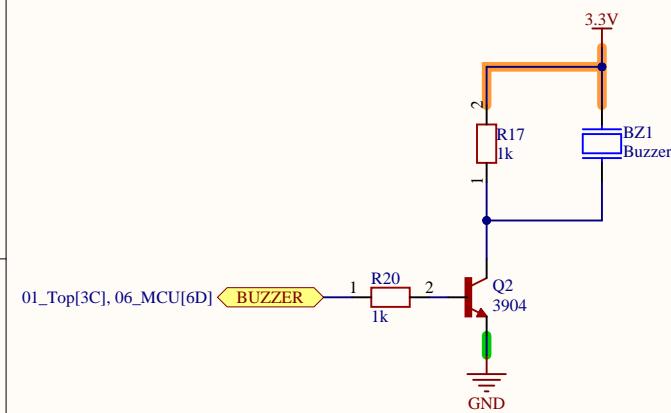
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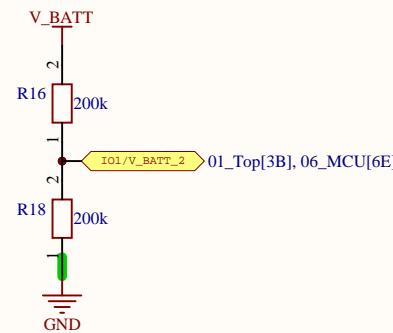
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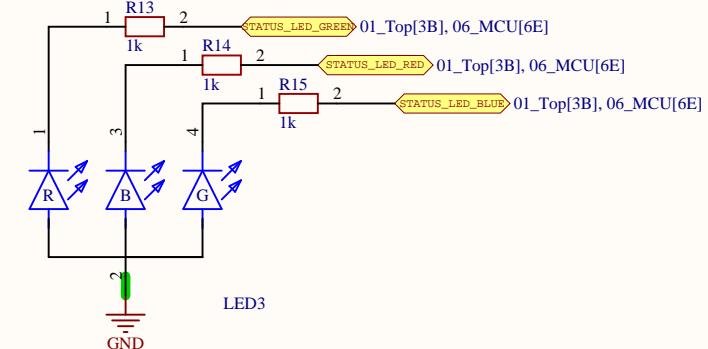
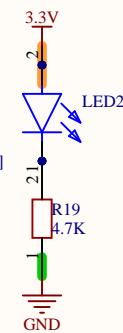
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Battery Voltage



LEDs



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