

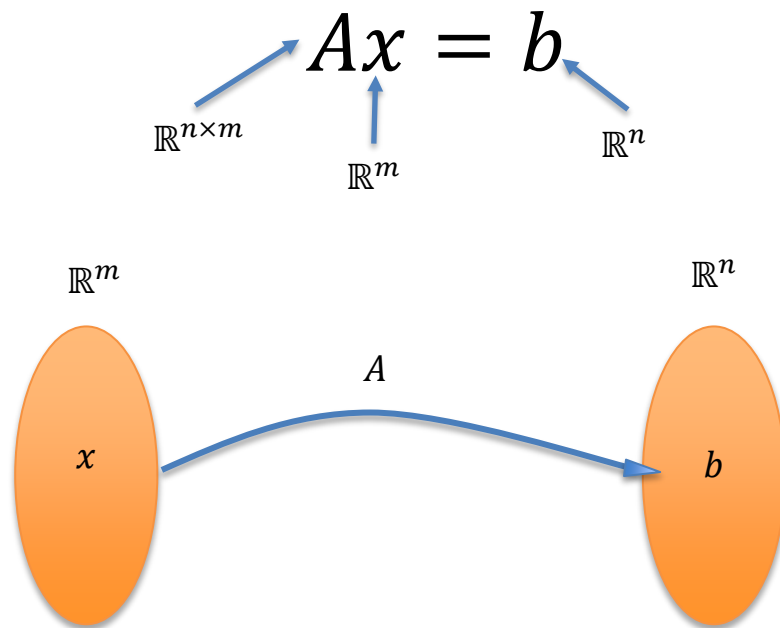
MATLAB Tutorial 08

ENME 303 Computational Methods for Engineers

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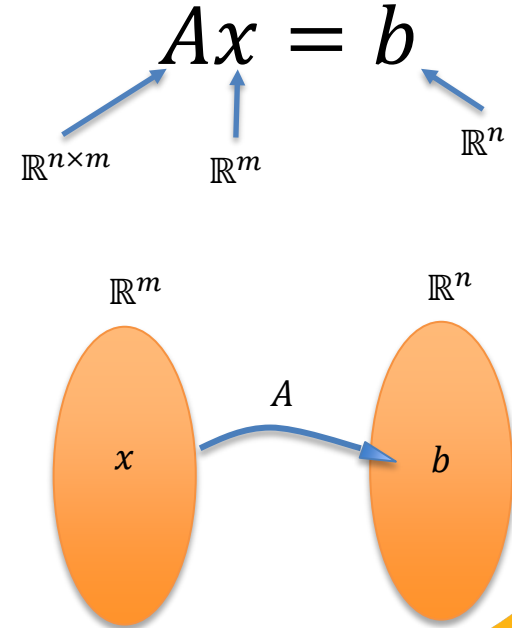
Adapted from Parham Oveissi (2023)

When Does a Solution Exist?!

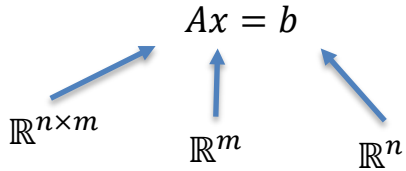


When Does a Solution Exist?!


- If b is not in $\mathcal{R}(A)$, then there is **no solution**.
- If $\mathcal{N}(A) \neq \{0\}$, then you can't have a unique solution (there are **infinite solutions**).
 1. $x_n \in \mathcal{N}(A)$, then $Ax_n = 0$
 2. Suppose there is a solution x_s s.t. $Ax_s = b$
 3. Then $A(x_s + x_n) = b$ is also a solution!
 4. Since there are infinite elements in $\mathcal{N}(A)$, there are infinite solutions!
- If $\mathcal{N}(A) = \{0\}$, then there exists a **unique solution**.



Existence and Uniqueness of a Solution



For $m = n$
(Square Matrices)


	$b \in \mathcal{R}(A)$	$b \notin \mathcal{R}(A)$
$\mathcal{N}(A) = \{0\}$	$x = A^{-1}b$ 	Can't happen $\mathcal{R}(A) = \mathbb{R}^n$
$\mathcal{N}(A) \neq \{0\}$	Infinitely many solutions	No solution exists

Existence and Uniqueness of a Solution

$$\begin{array}{ccc}
 & Ax = b & \\
 \nearrow & \uparrow & \nwarrow \\
 \mathbb{R}^{n \times m} & \mathbb{R}^m & \mathbb{R}^n
 \end{array}$$

For $m < n$
(Tall Matrices)

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} & \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} & = & \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \\
 \uparrow & \uparrow & & \uparrow \\
 \mathbb{R}^{3 \times 2} & \mathbb{R}^2 & & \mathbb{R}^3
 \end{array}$$

	$b \in \mathcal{R}(A)$	$b \notin \mathcal{R}(A)$
$\mathcal{N}(A) = \{0\}$	$x = (A^T A)^{-1} A^T b$ 	No solution exists
$\mathcal{N}(A) \neq \{0\}$	Infinitely many solutions	No solution exists

Existence and Uniqueness of a Solution

$$\begin{array}{ccc}
 & Ax = b & \\
 \nearrow & \uparrow & \nwarrow \\
 \mathbb{R}^{n \times m} & \mathbb{R}^m & \mathbb{R}^n
 \end{array}$$

For $m > n$
(Wide Matrices)

$$\begin{array}{ccc}
 \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} & \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} & = & \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \\
 \uparrow & \uparrow & & \uparrow \\
 \mathbb{R}^{2 \times 3} & \mathbb{R}^3 & & \mathbb{R}^2
 \end{array}$$

	$b \in \mathcal{R}(A)$	$b \notin \mathcal{R}(A)$
$\mathcal{N}(A) = \{0\}$	Can't happen	Can't happen
$\mathcal{N}(A) \neq \{0\}$	Infinitely many solutions	No solution exists

Least Squares Solution

- Let $Ax = y$ be a system equations where $A \in \mathbb{R}^{m \times n}$ and $m > n$ (tall/skinny). A least squares solution of $Ax = y$ is a solution \hat{x} in \mathbb{R}^n such that:

$$\min_{\hat{x}} \|A\hat{x} - b\|_2^2$$

- One can find the least square solution by: ([Proof](#))

$$x = (A^T A)^{-1} A^T b$$

- The term $(A^T A)^{-1} A^T$ is a left inverse (pseudo-inverse) of A .

Least/Minimum Norm Solution

- Let $Ax = y$ be a system equations where $A \in \mathbb{R}^{m \times n}$ and $m < n$ (wide/fat). A least/minimum solution of $Ax = y$ is a solution x in \mathbb{R}^m which minimizes $\|x\|$ among all the solutions (infinite number of solutions).
- One can find the least/minimum solution by: ([Proof](#))
$$x = A^T (AA^T)^{-1} b$$
- The term $A^T (AA^T)^{-1}$ is a right inverse (pseudo-inverse) of A .

Practice 01

- Consider the following system of linear equations.

$$\begin{cases} 2x + 3y = 5 \\ 2x + 4y = 6 \end{cases}$$

1. Write this system of equations in the $Ax = b$ form. Provide A and b .
2. Find the reduced row Echelon form of A using [rref](#) function.
3. Find the rank of A using [rank](#) function.
4. Find a basis for $\mathcal{R}(A)$ using [orth](#) function. What's the dimension of $\mathcal{R}(A)$?
5. Find a basis for $\mathcal{N}(A)$ using [null](#) function. What's the dimension of $\mathcal{N}(A)$?
6. Plot each column of A and b using MATLAB's [quiver](#) function.
7. Does a solution to the equation $Ax = b$ exist? If so, is it unique?
8. the solution is unique find the unique solution and if not find a solution to the given system of equations.

Practice 02

- Consider the following system of linear equations.

$$\begin{cases} 9x + 5y + 8z = 3 \\ 7x + 8y + 5z = 8 \\ 9x + 4y + 0z = 4 \end{cases}$$

- Write this system of equations in the $Ax = b$ form. Provide A and b .
- Find the reduced row Echelon form of A using [rref](#) function.
- Find the rank of A using [rank](#) function.
- Find a basis for $\mathcal{R}(A)$ using [orth](#) function. What's the dimension of $\mathcal{R}(A)$?
- Find a basis for $\mathcal{N}(A)$ using [null](#) function. What's the dimension of $\mathcal{N}(A)$?
- Plot each column of A and b using MATLAB's [quiver](#) function.
- Does a solution to the equation $Ax = b$ exist? If so, is it unique?
- the solution is unique find the unique solution and if not find a solution to the given system of equations.

Practice 03

- Consider the following system of linear equations.

$$\begin{cases} 9x + 5y + 24z = 3 \\ 7x + 8y + 31z = 8 \\ 9x + 4y + 21z = 4 \end{cases}$$

- Write this system of equations in the $Ax = b$ form. Provide A and b .
- Find the reduced row Echelon form of A using [rref](#) function.
- Find the rank of A using [rank](#) function.
- Find a basis for $\mathcal{R}(A)$ using [orth](#) function. What's the dimension of $\mathcal{R}(A)$?
- Find a basis for $\mathcal{N}(A)$ using [null](#) function. What's the dimension of $\mathcal{N}(A)$?
- Plot each column of A and b using MATLAB's [quiver](#) function.
- Does a solution to the equation $Ax = b$ exist? If so, is it unique?
- the solution is unique find the unique solution and if not find a solution to the given system of equations.

Practice 04

- Consider the following system of linear equations.

$$\begin{cases} 9x + 5y + 24z = 21.0 \\ 7x + 8y + 31z = 26.2 \\ 9x + 4y + 21z = 18.6 \end{cases}$$

- Write this system of equations in the $Ax = b$ form. Provide A and b .
- Find the reduced row Echelon form of A using [rref](#) function.
- Find the rank of A using [rank](#) function.
- Find a basis for $\mathcal{R}(A)$ using [orth](#) function. What's the dimension of $\mathcal{R}(A)$?
- Find a basis for $\mathcal{N}(A)$ using [null](#) function. What's the dimension of $\mathcal{N}(A)$?
- Plot each column of A and b using MATLAB's [quiver](#) function.
- Does a solution to the equation $Ax = b$ exist? If so, is it unique?
- the solution is unique find the unique solution and if not find a solution to the given system of equations.

Thanks!