## Clustered Covariate Regression

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Oct. 11, 2019

### Introduction

- Identification is necessary for consistency
- A crucial aspect to identification in single-index models is the non-singularity of the Gram matrix  $E(\mathbf{x}'\mathbf{x})$ 
  - Singularity of  $E(\mathbf{x}'\mathbf{x}) \Longrightarrow$  non-identification in e.g. linear and probit regressions
- Singularity of the Gram matrix caused by
  - High dimensionality many/more covariates relative to observations
  - Multicollinearity
  - Both

### Motivation

- ▶ Singularities of  $E(\mathbf{x}'\mathbf{x})$  in the limit theory engenders
  - inconsistency
  - differing rates of convergence

(Phillips 2016)

 Estimation impossible without adjustments when non-singularity holds in finite samples

## Contribution

A novel approach to identification, inference, and estimation, namely, Clustered Covariate Regression (CCR)

- ▶ in the presence of rank deficiency, weak identification due to
  - high-dimensionality
  - multicollinearity
  - both

## How does the CCR work?

- ▶ Project an  $n \times p$  rank-deficient **x** using a  $p \times k$  projection matrix m such that m'x'xm is non-singular.
- $\triangleright$  p > k, n >> k

## Outline

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Related Literature

The CCR

Estimation

Asymptotic Theory

Monte Carlo Experiments

**Empirical Model** 

Conclusion

## Strands of related literature

- Variable selection, e.g.,
  - ▶ the Lasso (Belloni, Chernozhukov, and Hansen (2014b))
  - sequential hypothesis tests (Chudik, Kapetanios, and Pesaran (2018))
- ▶ Dimension reduction (using pre-constructed projection matrices) e.g., Wold, Esbensen, and Geladi, 1987
  - principal component regression (PCR)
  - partial least squares (PLS)

## What is gained by the CCR?

- ▶ The CCR spans the class of single-index models, e.g., linear, logit, and quantile regressions
- CCR obviates sparsity assumption in the high-dimensional parameter  $\beta$ 
  - but assumes (approximate) reducibility of a high-dimensional  $\beta \in \mathbb{R}^p$  vector to a smaller identifiable  $\delta \in \mathbb{R}^k$ , p > k
- CCR obviates the choice of tuning parameter and penalty function
  - but requires a criterion (e.g., BIC) for model selection
- ▶ The CCR projection matrix **m** is model, outcome, covariate dependent; it is not pre-constructed
- ► Immune to multicollinearity via projection

### The conditional functional

Suppose a conditional functional (e.g., conditional expectation, conditional quantile)

$$\nu(y_i|\mathbf{x}_i) = g(\mathbf{x}_i\boldsymbol{\beta}) = g(\mathbf{x}_i\boldsymbol{m}\boldsymbol{\delta})$$

- $ightharpoonup eta = m\delta$  (or approximately)
- unknown parameters  $\beta$  is  $p \times 1$ ,  $\delta$  is  $k \times 1$
- **m** is an unknown  $p \times k$  (clustering) projection matrix

## The projection matrix I

### Characteristics of the projection matrix **m**:

- ▶ **m** belongs to a set  $\mathcal{M}$  of  $p \times k$  matrices
- ▶ has exactly p non-zero elements
- the columns of m correspond to clusters
- each row comprises only one non-zero element
- ▶ the vector of non-zero elements in m are researcher-specified, e.g. standard deviations or a vector of ones
- Cluster assignments unknown a priori

# The projection matrix II

#### An example

▶ 
$$\delta = [\delta_1, \delta_2]'$$
,  $\mathbf{x} = [x_1, x_2, x_3, x_4]$ , and  $\mathbf{m}' = \begin{bmatrix} \eta_1 & 0 & 0 & \eta_4 \\ 0 & \eta_2 & \eta_3 & 0 \end{bmatrix}$ 

- ► The linear predictor function  $\mathbf{x} \boldsymbol{m} \boldsymbol{\delta} = x_1 \eta_1 \delta_1 + x_2 \eta_2 \delta_2 + x_3 \eta_3 \delta_2 + x_4 \eta_4 \delta_1 = x_1 \beta_1 + x_2 \beta_2 + x_3 \beta_3 + x_4 \beta_4 = \mathbf{x} \boldsymbol{\beta}$
- factorises eta into  $m\delta$
- if scaling,  $\eta_j$  specified by researcher else  $\eta_j=1$  for all  $j=1,\ldots,p$

# The CCR estimation problem

- An objective, e.g. linear regression  $Q_n(\mathbf{x}\boldsymbol{m}\boldsymbol{\delta}) \equiv n^{-1} \sum_{i=1}^n q(\mathbf{x}_i \boldsymbol{m}\boldsymbol{\delta}), \ q(\mathbf{x}_i \boldsymbol{m}\boldsymbol{\delta}) = (y_i \mathbf{x}_i \boldsymbol{m}\boldsymbol{\delta})^2$
- $Q_n(\boldsymbol{\delta}) \equiv \frac{1}{|\mathcal{A}_n|} \int_{\mathcal{M}} Q_n(\mathbf{x} \boldsymbol{m} \boldsymbol{\delta}) \mathbf{1}_{\mathcal{A}_n}(\boldsymbol{m}) d\mu(\boldsymbol{m}) = \frac{1}{|\mathcal{A}_n|} \sum_{\boldsymbol{m} \in \mathcal{A}_n} Q_n(\mathbf{x} \boldsymbol{m} \boldsymbol{\delta})$
- $ightharpoonup \mu$  is the counting measure
- ▶ set  $A_n \equiv \{ \boldsymbol{m} \in \mathcal{M} : Q_n(\mathbf{x}\boldsymbol{m}\delta) \leq Q_n(\mathbf{x}\boldsymbol{s}\delta) \ \forall \boldsymbol{s} \in \mathcal{M} \setminus \boldsymbol{m} \}$
- ▶  $\mathbf{1}_{\mathcal{A}_n}(\mathbf{m}) \equiv \mathbf{1}\{\mathbf{m} \in \mathcal{A}_n\}$  indicator for  $\mathbf{m} \in \mathcal{A}_n$
- $ightharpoonup |\mathcal{A}_n| \equiv \mu(\mathcal{A}_n)$  denotes the cardinality of  $\mathcal{A}_n$

### The Estimation Problem

#### Minimisation

$$\hat{\delta} = \operatorname{arg\,min}_{\delta \in \mathbf{\Delta}} \, Q_n(\delta)$$

- ▶ If an  $m \in A_n$  is known,  $\delta$  can be estimated
- ▶ But,  $\mathbf{m} \in \mathcal{A}_n$  is unknown,  $\implies \delta$  is unknown
- lacktriangle Approach: use a sequential scheme to estimate  $m{m} \in \mathcal{A}_n$  and  $m{\delta}$

# The Sequential CCR Algorithm

fix k (number of clusters)

- 1. Initialise counter l=0, parameter vector  $\boldsymbol{\beta}^{(l)}=\boldsymbol{m}^{(l)}\boldsymbol{\delta}^{(l)}$
- 2. Update  $l \leftarrow l+1$ , for each  $j=1,\ldots,p$ ,
  - update  $\hat{\beta}_j^{(I)} = \operatorname{arg\,min}_{\beta_j} Q_n(\mathbf{x}_{-j}\boldsymbol{\beta}_{-j}^{(I)} + x_j\beta_j)$
  - assign  $\hat{\beta}_i^{(l)}$  to a cluster and update  $m^{(l)}$
  - update  $\delta^{(I)} = \operatorname{arg\,min}_{\delta \in \Delta} Q_n(\mathbf{x} \boldsymbol{m}^{(I)} \boldsymbol{\delta})$
  - update  $oldsymbol{eta}^{(I)} \leftarrow oldsymbol{m}^{(I)} oldsymbol{\delta}^{(ar{I})}$
- 3. Check convergence for  $Q_n(\mathbf{x} \mathbf{m}^{(l-1)} \delta^{(l-1)}) Q_n(\mathbf{x} \mathbf{m}^{(l)} \delta^{(l)}) < \epsilon$  else return to step 2

Without clustering, the algorithm is similar to the (block)-coordinate descent algorithm (used for e.g. Lasso)

Optimal k is determined using a model selection criterion, e.g., BIC

### Assumptions

- 1.  $\mu(\mathcal{A}_n) \to 1$  as  $n \to \infty$ , i.e.,  $\mathcal{A}_n \to \{\boldsymbol{m}_o\}$  as  $n \to \infty$
- 2.  $\sqrt{p/n} \to 0$  as  $p, n \to \infty$

## Theorem - Consistency

- $\hat{\delta}_n \stackrel{p}{\to} \delta_o$  under standard assumptions
- $lacksymbol{\hat{eta}}_n\stackrel{p}{ o}eta_o$  where  $\hat{eta}_n\equiv m{m}_n\hat{m{\delta}}_n$  and  $m{eta}_o\equivm{m}_om{\delta}_o$

## Theorem - Asymptotic Normality

$$\sqrt{n}(\hat{\delta}_n - \delta_o) \stackrel{d}{\to} \mathcal{N}(\mathbf{0}, \mathbf{V}_o)$$
 where  $\mathbf{V}_o = \mathbf{A}_o^{-1} \mathbf{B}_o \mathbf{A}_o^{-1}$ ,  $\mathbf{A}_o \equiv E[\mathbf{H}(\mathbf{x}_i \mathbf{m}_o \delta_o)]$ , and  $\mathbf{B}_o \equiv E[\mathbf{s}(\mathbf{x}_i \mathbf{m}_o \delta_o)\mathbf{s}(\mathbf{x}_i \mathbf{m}_o \delta_o)']$ 

# CCR in a baseline specification

Table: Baseline model:  $\mathbf{x}_i \stackrel{iid}{\sim} \mathcal{N}(0, \mathbf{I}_p), \ \delta = [-2, -1, 0, 1, 2, 3]'$ 

n	р	CCR	OLS	LASSO	PCR	PLS
30	12	0.201(0.086)	0.199(0.054)	<b>0.197</b> (0.055)	0.395(0.215)	0.325(0.112)
	24	<b>0.365</b> (0.136)	0.375(0.145)	0.372(0.140)	0.515(0.173)	0.400( <b>0.119</b> )
	36	0.821(0.181)	-	1.400(6.244)	0.769(0.144)	0.766(0.133)
90	12	<b>0.069</b> (0.023)	0.091( <b>0.021</b> )	0.091(0.022)	0.357(0.231)	0.188(0.055)
	24	<b>0.060</b> (0.023)	0.010( <b>0.018</b> )	0.099(0.018)	1.061(0.158)	0.353(0.078)
	36	<b>0.065</b> (0.027)	0.110( <b>0.018</b> )	0.109(0.018)	1.225(0.117)	0.490(0.083)

Note: (1) Results: average  $d_{\beta} = \|\hat{\beta} - \beta_o\|_1/p$ . (2) 1000 simulations each (3)  $\sigma(d_{\beta})$  in parentheses. (4) Optimal k - BIC. (5) Two-step Lasso, PCR, and PLS - 10-fold CV (6)  $k^* = 6$ .

# CCR under Multicollinearity

Table: Multicollinearity:  $\mathbf{x}_i \stackrel{iid}{\sim} \mathcal{N}(0, \mathbf{\Sigma})$ ,  $\mathbf{\Sigma}_{jj'} = 0.5^{|j-j'|}$ 

n	р	CCR	OLS	LASSO	PCR	PLS
30	12	0.283(0.106)	0.250( <b>0.075</b> )	<b>0.246</b> (0.076)	0.336(0.143)	0.554(0.126)
	24	0.468(0.168)	0.481(0.194)	<b>0.448</b> (0.164)	0.479(0.137)	0.533( <b>0.118</b> )
	36	1.118(0.241)	-	1.197(2.346)	<b>0.714</b> (0.132)	0.757( <b>0.118</b> )
90	12	<b>0.094</b> (0.041)	0.116(0.030)	0.114(0.031)	0.250(0.127)	0.389(0.067)
	24	<b>0.076</b> (0.036)	0.128( <b>0.026</b> )	0.126(0.026)	0.300(0.118)	0.285(0.061)
	36	<b>0.083</b> (0.043)	0.142( <b>0.026</b> )	0.140(0.026)	0.327(0.111)	0.389(0.065)

Note: (1) Results: average  $d_{\beta} = \|\hat{\beta} - \beta_o\|_1/p$ . (2) 1000 simulations each (3)  $\sigma(d_{\beta})$  in parentheses. (4) Optimal k - BIC. (5) Two-step Lasso, PCR, and PLS - 10-fold CV (6)  $k^* = 6$ .

# The empirical model

Estimating private and spillover effects of R&D on productivity

$$E[y_{it}|\mathbf{w}_{it},\mathbf{x}_{t}] = \alpha_{0} + \mathbf{w}_{it}\mathbf{\theta} + x_{it}\gamma_{ii} + \sum_{j \neq i} x_{jt}\gamma_{ij} + \alpha_{t} + \delta_{i}$$

- $ightharpoonup k_w + T + N + N^2$  parameters, NT observations
- e.g. T = 27, N = 50, p = 2577 parameters, n = NT = 1350 firm-year observations
- ▶ *p* > *n*

### Conclusion

In a nutshell, we propose Clustered Covariate Regression. It is a novel approach to

- handling rank-deficiency in single-index models
  - multicollinearity, high-dimensionality, or both
- ightharpoonup offers advantages: e.g. obviates sparsity in  $oldsymbol{eta}$  and increases precision
- interesting extensions (left for future work)
  - ▶ high-dimensional causal inference
  - multicollinearity in non-linear models
  - estimating latent network structures from panel data