MECH-6024, MECH-5124

Computational Methods in Additive Manufacturing I

Assignment 1 (100 points)

To be worked on individually. Do not consult with others.

Due on February 6th, 2020 - Thursday (In Class)

Note: Show all detailed calculations and workings.

1. Find the equation of a plane passing through point A = (2, 3, 4) and having a normal vector N = (1, 1, 3). Find the distance of this plane from a point on the origin P = (0, 0, 0) and also find the closest point on this plane to the origin. (10pts)

2. Given two skew lines:

Points on line 1: A = (1, 2, 3) and B = (2, 1, 2)

Points on line 2: C = (1, 3, 4) and D = (4, 4, 1)

Find the shortest distance between lines 1 and 2. (15pts)

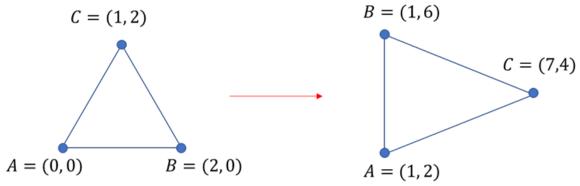
- 3. Determine whether or not a line defined by equation $Q = (2, 3, 4) + \lambda (1, 2, 2)$ intersects with a triangle formed by three points F = (0, 0, 0), G = (-2, -1, 1), and H = (1, -3, -2) (20pts)
- 4. Calculate the area **A** of a triangle formed by three points:

$$B = (1, 0, -1), C = (-4, -2, 1), and D = (-2, 5, 3)$$

Then calculate the perpendicular distance \mathbf{H} of point $\mathbf{P} = (3, -2, 5)$ from the plane on which this triangle lies.

Finally, calculate the volume **V** of the tetrahedron (i.e. pyramid) formed with base **BCD** and tip **P**. Notice how this series of calculations is the same as a scalar triple product divided by 6. (20pts)

5. Describe a series of transformations which can be applied to result in the figure on the right shown below (not drawn to scale.) Using the same types of transformations but in a different order, create a new series of transformations which results in the figure on the right side. Make sure that A and B are not swapped. (15pts)



6. Determine the 4x4 transformation matrix for revolving +30 degrees about the line defined by $Q = (2, 3, 4) + \lambda (1, 2, 2)$

Assume that positive rotation follows right hand rule with the thumb along the increasing λ direction of this line.

Then apply this transformation to three points A = (1, 2, 3), B = (2, 1, 2), and C = (1, 3, 4) using a single matrix multiplication operation. (20pts)