

## Dynamic and adaptive body schema by learning to predict the sensory consequences of actions

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#### Overview

Systems-level approach to develop a body schema and agency:

- The **basal ganglia** will select an action based on the desired state (see Baladron and Hamker, 2020).
- The central pattern generator will be execute the action (see Nassour et al., 2020).
- The **cerebellum** will learn to predict the sensory consequences of the motor action in all modalities (vision, touch, proprioception) i.e. the body schema (see Schmid et al., 2019).
- The **prediction error** will be used to improve the prediction and to train action selection in the **basal ganglia**.

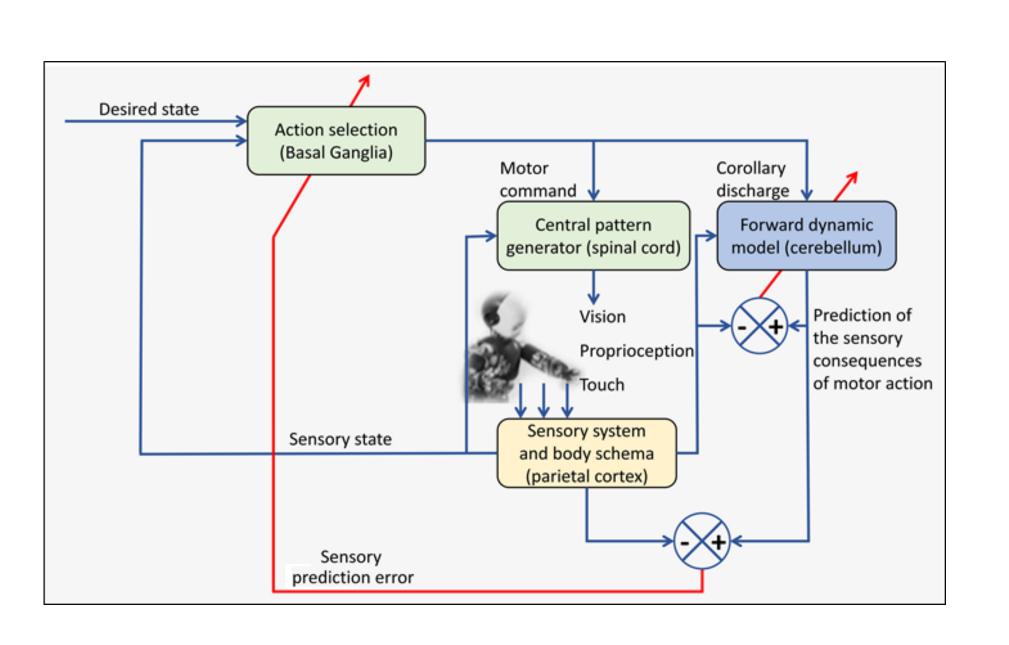


Figure 1: babbas

# Recurrent Basis Functions<sup>1</sup> Hier was zu dieser Veröffentlichung Pouget et al., 2002.

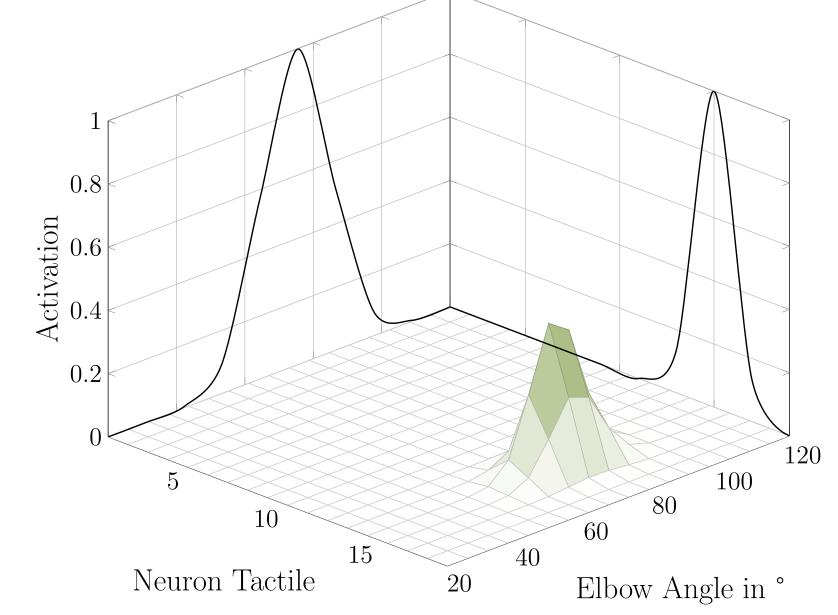


Figure 2: babbas

### Learning a Body Schema<sup>1</sup>

#### Basal Ganglia<sup>2</sup>

The 3-factor learning principles are primarily determined by presynaptic and post-synaptic neuron activity, as well as the dopamine signal.

The labels high and low indicate whether the pre- and post-activity is more than or less than a given threshold (for example, mean population activity).

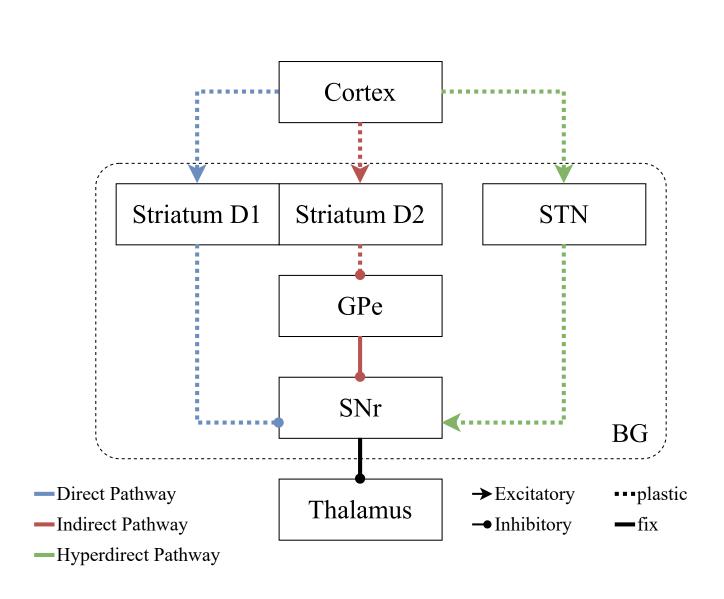


Figure 3: Modeling of segregated basal ganglia pathways

DA+ and DA- labels indicate if SNc activity is above or below a given threshold. A sign specifies the weight changes in the relevant projections for each combination of these criteria (+,, no sign). Table S8 contains the real mathematical explanation of plasticity, in addition to the general description offered.

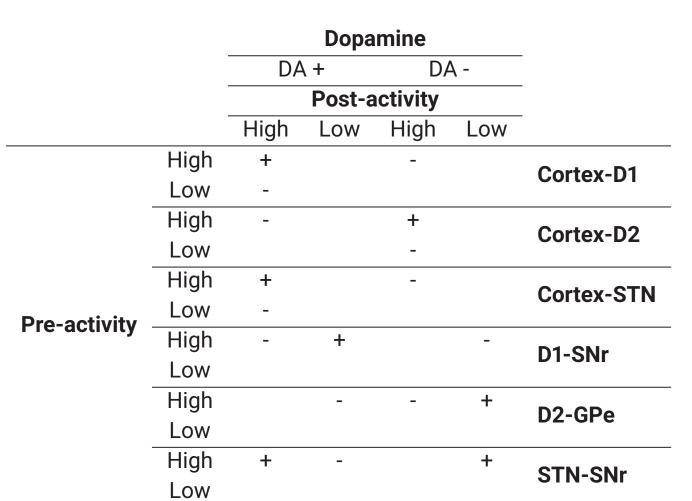


Table 1: +: LTP; -: LTD; no sign: no weight change

#### Motor Learning with the Basal Ganglia<sup>2</sup> Direct: Indirect: Hyperdirect: Movement Plan: Trial 5 SNr GPe SNr in [cm] Trial 20 >20SNr GPe SNr Trial 50 20 x in [cm] SNr GPe SNr Figure 4: Right: Development Trial 100 of motor learning in the different pathways. SNrGPe SNr

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#### References

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