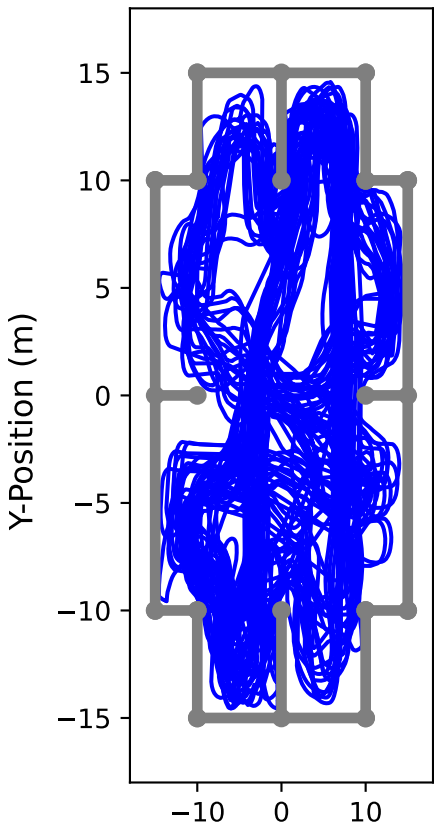
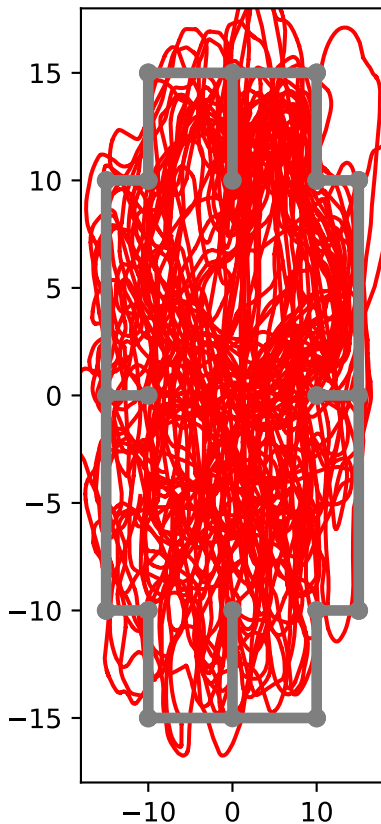


Ground Truth



Noisy Odometry



Optimized Estimate

