* Upon Power on rPI
  + Run main.cpp
    - Read IR
      * While (4th bit = 1)
        + Wait
      * While (4th bit = 0)
        + Read 3 route bits into variable(s)
        + Convert binary route to digit
        + Display digit on to 7 segment display
    - Begin route - Drive DC motors
      * While (running route)
        + Verify location using ultrasonic
      * To location A
        + While (3rd bit = 0) North
        + While (3rd bit = 1) South
      * To location B
        + While (2nd bit = 0) North
        + While (2nd bit = 1) South
      * To Treasure Chest
        + West until edge of board
        + At edge of board spin Ship Wheel

Turn X number of turns

* + - * West back to start
      * To location C
        + While (1st bit = 0) North
        + While (1st bit = 1) South
  + End