Ornithopter

Peer Critique 1

What's an Ornithopter

- A mechanical bird!
- Generates thrust by flapping its wings.
- Subsystems:
 - Wings
 - Wing Flapping Mech.
 - Motor and Gearbox
 - Tail



Functional Requirements

- 1. Must be able to climb (this means thrust > drag)
- 2. Should be able to fly for at least 3 minutes on a charge.
- 3. Must generate its thrust by flapping its wings.
- 4. Should flap at a rate comparable to a similar size bird.
- 5. Must have wingspan ~1 meter or less.
- 6. Must be radio-controlled and maneuverable enough to be flown within the Olin soccer field.
- 7. Should be able to be re-assembled after a severe crash in 1 day or less.

Specifications

- 1. Wing is 1m span by 0.2 m chord
- 2. From testing: wing draws 20W
- 3. 200g weight budget
 - a. From design manual 100W/kg for climb

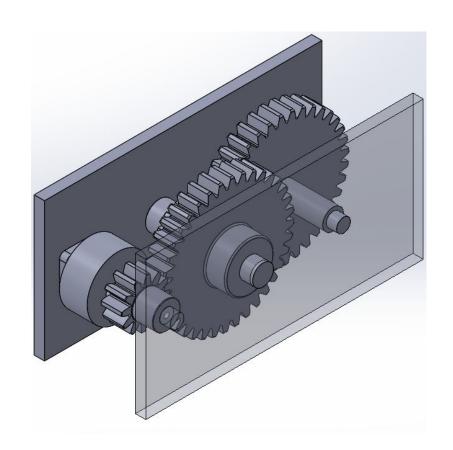
Gearbox

Requirements:

- Must output 20W at 3 flaps per second with wings attached.
- Must fit within 200g weight budget

Mechanics:

- Acts as fuselage, containing mounting points for other subsystems
- Uses a gear ratio of 9:1 determined from motor power and current calculations, in a 2x3:1 configuration to minimize weight.



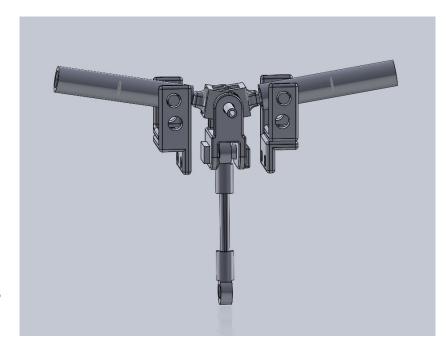
Flapping Mechanism

Requirements:

- Must output 20W at 3 flaps per second with wings attached.
- Must fit within 200g weight budget
- Must provide mostly symmetric flapping

Feedback Points:

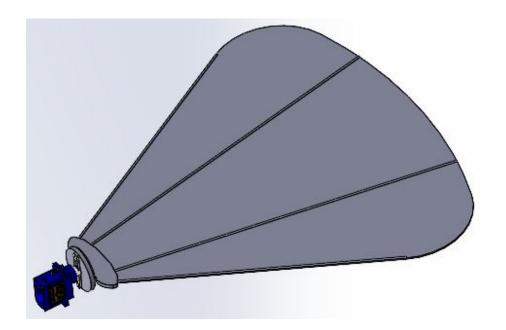
- Figuring out better materials (or whether current materials are sufficient)
- Whether heat will be an issue at high speeds
- Maintaining symmetry is extra support needed? How to implement?



Tail

Requirements

- Must fit within 200g weight budget
- Must be able to rotate to turn
- Must provide stability to flying



Weight Budget

Calculated using recommended power-weight ratio: 200g

Subsystem	Item	Quantity	Unit Mass (g)	Unit Cost	Total Mass	Total Cost	Notes		
Gear Box	Frame Plates	2			24	0	Based or	Based on 50x200mm piece of Lite Ply plywoo	
	Gears	1	21		21	0	Based or	Based on selecte 12 T, 1.07g 36 T, 6.73 g	
	Shafts	2	1		2	0	Based or	Based on 31 x 4mm aluminum shaft	
			Mappe						
	Motor	1	9		9	0			
				Subtotal	56				
Electronics	Receiver	1	1		1	0			
	ESC	1	13.5		13.5	0	GNB 1s	550	
	Battery Wires	1	13.5		13.5	0		20awg wire	
	vviies	-	1.3	Subtotal	15.5		1 1001 01	zoawy wile	
Flapping Mech				Jubiotal	13.3				
Topping week	Brackets (small)	2	0.7		0 1.4	0	Estimate	(not weighed)	
	Brackets (Large)	2			0 2.8	0			
	Spar Mount	2			0 4.2	0			
	Crank-Hinge Interface	1			0 2.5	0			
	Crank Attachments	2	0.4		0 0.8	0			
	Hinge	2			0 1.6	0			
	Nylon Spacer	2	0.5		0 1	0			
	Metal Dowel (Long)	4	1.5		0 6	0			
	Metal Dowel 4.6mm	1	1.7		0 1.7	0			
	Nail	2			0 1.6	0			
				Subtotal	23.6				
Wings	Spars	2	11		22	0			
	Fabric	2	3		6	0			
				Subtotal	28				
Tail	Servo	2	9		18	0	9g micro	servo (may be able to	use smaller)
				Subtotal	18				
				estimate	141.1				

Timeline

- We have not yet assembled most hardware (since benchmarking), have a few prototypes made
- We plan to begin assembly next week, aiming to complete it before Thanksgiving break.