

ERICA TEVERE

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EDUCATION

Johns Hopkins University | M.S.E. Robotics – Faculty Scholarship (GPA: 3.5 / 4.0) May 2021
University of Michigan - Ann Arbor | B.S.E. Mechanical Engineering – Magna Cum Laude (GPA: 3.6 / 4.0) May 2019

WORK EXPERIENCE

National Institute of Standards and Technology (NIST) August 2020 – Present
Robotics Intern – Grasping, Manipulation, and Safety of Robotic Systems Group Gaithersburg, MD

- Researching and developing standard for grasp efficiency, testing methods to detect object slip during manipulation tasks
- Investigating and establishing environments for grasp efficiency testing in simulation using Gazebo, PyBullet, and Klampt

FANUC America Corporation May 2019 – August 2019
Robotics Intern – Motion Planning Group Rochester Hills, MI

- Developed and implemented prototype system to perform dynamic path planning using Intel RealSense D435 sensor
- Performed regression testing for 8 motion options on upcoming software release to verify function and performance

NASA Jet Propulsion Laboratory May 2017 – December 2017
Mechanical Engineering Intern – Planetary Sample Acquisition and Handling Group Pasadena, CA

- Designed custom parallel manipulator to simulate expected rate of compliance of a robotic arm during sample collection
- Created Python tool to automatically generate movement sequences for testbed robotic arm resulting in decrease in individual test duration by 20%, a reduced required training level of operators, and lower frequency of human error faults during testing
- Calculated machining tolerances and re-designed tool to manually actuate ball locking features on sample acquisition hardware
- Upgraded Mars 2020 testbed to characterize sample acquisition and handling hardware during routine loading interactions and magnify anomalies in flight-like conditions before manufacturing of flight model hardware

Fiat Chrysler Automobiles June 2016 – September 2016
Supply Chain Intern – Powertrain Production Planning Group Auburn Hills, MI

- Identified issues in supplier release system and spearheaded a task force consisting of 4 departments within FCA to develop and implement proposed solutions - executed inexpensive solutions resulting in a 2 month reduction in the project timeline

RESEARCH AND PROJECT EXPERIENCE

Johns Hopkins University Autonomous Systems, Control, and Optimization (ASCO) Lab March 2020 – Present
Graduate Researcher Assistant – Rough-terrain Ground Vehicle Control Project Baltimore, MD

- Integrating depth sensing onto an unmanned ground vehicle for real-world testing of reinforcement learning control algorithm
- Investigating different deep learning methods to identify and isolate drivable surfaces for off-road/unstructured environments
- Creating pipeline to use vehicle odometry and RGBD camera data to learn and predict unfavorable driving conditions

University of Michigan Autonomous Robotic Manipulation (ARM) Lab May 2018 – December 2018
Undergraduate Researcher Assistant – Manipulation of Deformable Objects Project Ann Arbor, MI

- Evaluated limitations of Robotiq 3-finger gripper during grasping to produce functional requirements of replacement gripper
- Designed a parallel gripper with 7 inches less of obstacle interference and 1 inch more of travel in grasping direction
- Incorporated force sensing into gripper fingertips to improve motor control when grasping deformable objects in testing
- Performed lifecycle testing on entire gripper assembly to validate failure point of system

SAE Michigan Baja Racing September 2015 – August 2019
Team Captain ('18-'19), Testing Colead ('17-'18), Composite Subsystem Lead ('16-'17) Ann Arbor, MI

- Managed final design decisions, system integration, and vehicle timeline resulting in record breaking 1st place season finish
- Oversaw \$100,00 budget, sponsor relations, recruitment, and community outreach of 40+ person team
- Orchestrated 6 week on-car testing period to quantify performance of vehicle and tune critical subsystems
- Reengineered front suspension component to decrease weight by 50% and increase strength in application by 60%
- Managed design and manufacturing of 10+ carbon fiber vehicle panels and rule-compliant component guards
- Created design of experiment (DOE) to quantify aluminum/carbon fiber bond characteristics, properties, and strength

PUBLICATIONS

Yahnker, C., Shiraishi, L.R., ... **Tevere, E.L.** "Introduction to Tools and Techniques for Surface Sampling on Europa." *16th Biennial ASCE Aerospace Division International Conference on Engineering, Science, Construction, and Operations in Challenging Environments*, Cleveland, Ohio, April 9-12, 2018.

SKILLS

Programming: ROS, C++, Python, MATLAB/Simulink, familiar with Orocos, familiar with OpenCV, familiar with LabVIEW
Embedded Systems/Sensors: Arduino, stereo cameras, IMU, strain gages, linear potentiometers, infrared sensors, Hall effect sensors
Software: CAD (NX, CATIA, SolidWorks), Siemens Teamcenter, FEA/Optimization (Altair HyperWorks), JMP
Manufacturing: manual and CNC mill and lathe, 3D printing, carbon fiber layups, familiar with TIG welding, familiar with GD&T