## CS 480/680 Introduction to Machine Learning

Lecture 4 Non-Parametric Methods: KDE, k-NN, and k-Means

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# The algorithms we have encountered so far involved assuming a hypothesis class and parametrization

Perceptron: Separating Hyperplane

$$\mathcal{H}_{+} = \{x : w^{T}x > -b\}$$
  
 $\mathcal{H}_{-} = \{x : w^{T}x < -b\}$ 

Linear Regression:

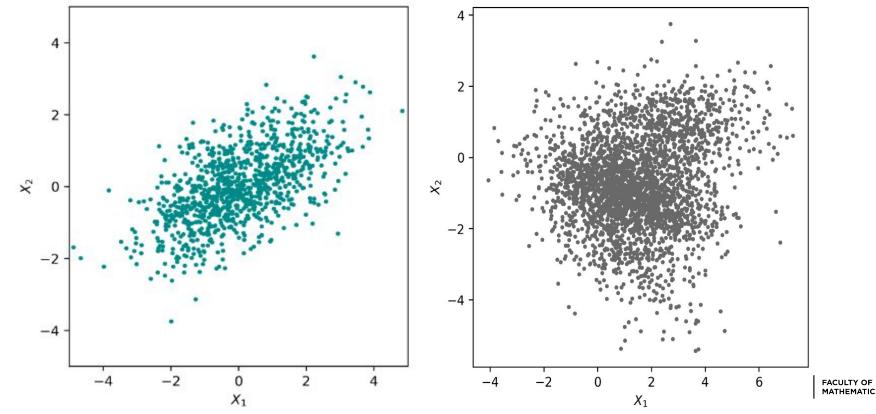
$$y(x) = w^T x + b$$

Gaussian distribution learning

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}$$



Strong assumptions limit the class of functions you can approximate well



Learning a distribution without a hypothesis class Kernel (Parzen) Density Estimation

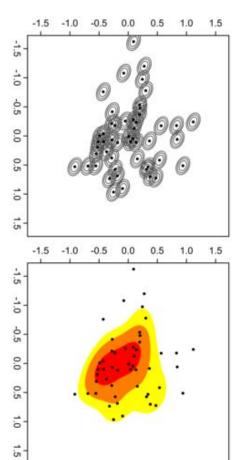
Given a set of observations  $\{x_1, x_2, \dots x_n\}, x_i \in \mathbb{R}^d$ , the Parzen estimate for the probability density at some arbitrary point  $x_o$  is calculated as

$$\hat{p}_X(x_o) = \frac{1}{n\lambda} \sum_{i=1}^n K_\lambda(x_0, x_i)$$

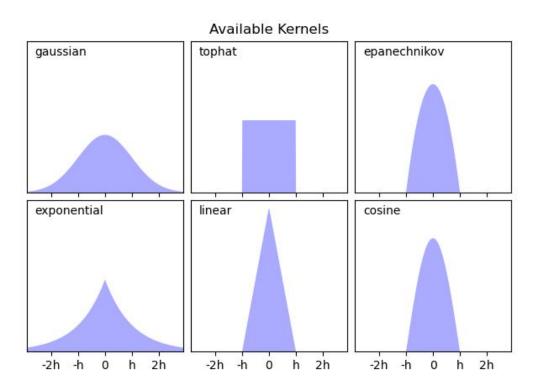
Where:  $K_{\lambda} : \mathbb{R}^{d} \times \mathbb{R}^{d} \to \mathbb{R}_{+}$  is a non-negative kernel function, and  $\lambda$  is the length scale parameter. For KDE, we often desire  $K_{\lambda}$  to be symmetric and shift-invariant. That is:

$$K_{\lambda}(x_0, x_i) = K(x_0/\lambda - x_i\lambda)$$

Figure: Wikipedia Elements of Statistical Learning, Section 6.6



#### Many admissible kernels for density estimation

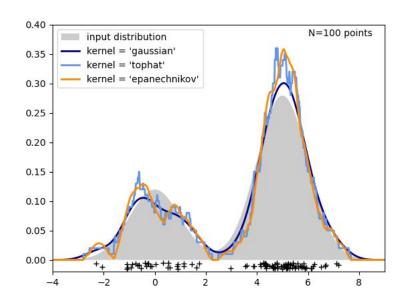




Source: Sci-Kit Learn

## Using KDE to approximate the reference in KL divergence

$$D_{\mathrm{KL}}(P || Q) = \int_{-\infty}^{\infty} p(x) \log \frac{p(x)}{q(x)} dx$$
 (Continuous Random Variable)





#### Today we'll look at examples of non-parametric algorithms

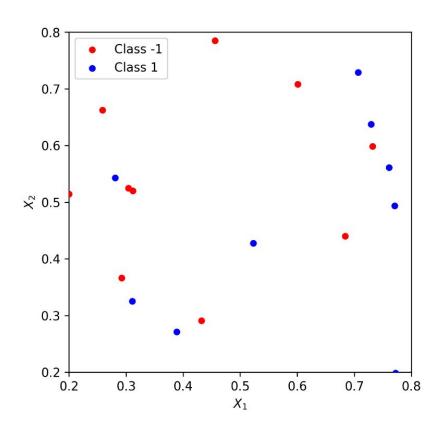
- I. Classification (k-Nearest Neighbors)
- II. Clustering (k-Means)



## Non-Parametric Supervised Learning

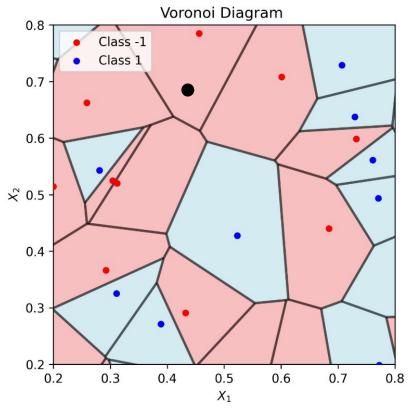
K-Nearest Neighbors (k-NN)

#### Classification with non-linearly separable data





# Approach: assume that points that are near to one another are likely to have the same label





### k-Nearest Neighbors (k-NN) Classification

#### Algorithm 1 k Nearest Neighbors

(binary classification)

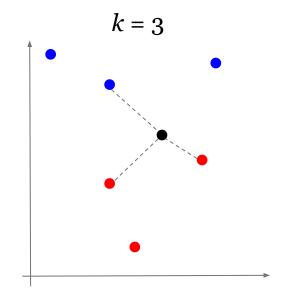
#### Input:

- 1: Dataset  $\{(x_1, y_1), \dots, (x_n, y_n)\}, x_i \in \mathbb{R}^d, y_i \in \{\pm 1\}$
- 2: Number of neighbors k
- 3: New instance  $x \in \mathbb{R}^d$
- 4: for  $i = \{1, 2, ... n\}$  do  $d_i = \text{dist}(x, x_i)$
- 5: end for
- 6: Find smallest k indices of d
- 7: return Majority vote of  $\{y_i, \dots y_k\}$

KNN requires a distance function

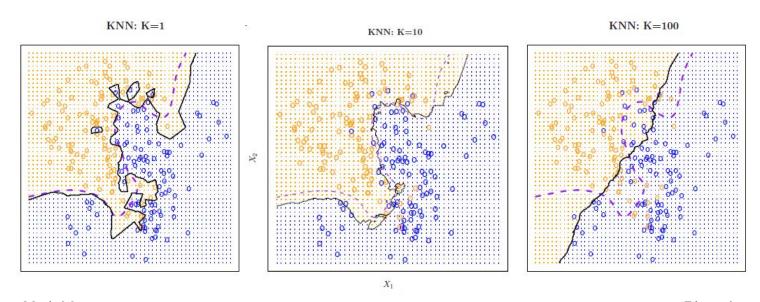
$$d: \rm I\!R^d \times \rm I\!R^d \rightarrow \rm I\!R$$

- Euclidean:  $d(x, x') = \sqrt{\sum_{m=1}^{d} (x_m x'_m)^2}$
- Manhattan:  $d(x, x') = \sum_{m=1}^{d} ||x_m x'_m||_1$





#### The bias-variance tradeoff and the role of hyperparameter *k*



**Variable:**Predictions depend strongly on training dataset

**Biased:** systematic error due to simplified model



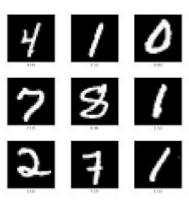
### Computational complexity of KNN

	Time		Space	
Train	0		O(nd)	
Test	Computing distances: Fast sorting: O(nd+ nlogk) ≈ O(nd) for	O(nd) O(n log k) small k	O(nd)	



### KNN on handwritten digit recognition (MNIST)

PREPROCESSING	TEST ERROR RATE (%)
Linear Classifier	rs
none	12.0
deskewing	8.4
deskewing	7.6
K-Nearest Neighb	ors
none	5.0
none	3.09
none	2.83
deskewing	2.4
Convolutional ne	ets
subsampling to 16x16 pixels	1.7
none	1.1
none	1.1
none	1.1
none	0.95
none	0.85
none	3.0
none	0.7
none	0.83
none	0.56
	Linear Classifier  none  deskewing  K-Nearest Neighb  none  none  none  deskewing   Convolutional n  subsampling to 16x16 pixels  none  none



#### An upper bound on KNN error rate (Cover and Hart, 1967)

The Bayes optimal classifier outputs the most likely class under a known distribution P:

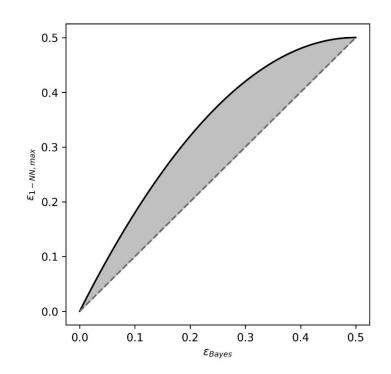
$$\hat{y}(x) = \operatorname{argmax}_{c} \Pr[y = c | x, P]$$

- Given a point x, look at the distribution of labels given that feature vector
- Pick whichever label is most likely to be generated
- Error rate  $\epsilon : E[1 \max_{c} Pr[y = c | x, P]]$

Suppose KNN(x) is a Nearest Neighbor binary classifier with k=1, then its error rate  $\epsilon_h$ 

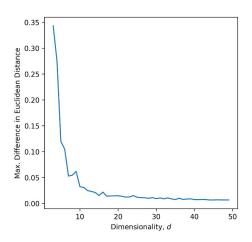
$$\lim_{n\to\infty} \epsilon_{KNN} < 2\epsilon_{Bayes} (1 - \epsilon_{Bayes})$$

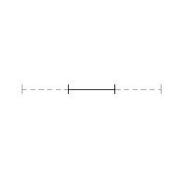
Where  $\epsilon_{Bayes}$  is the error rate of the Bayes optimal classifier, and n is the number of samples.

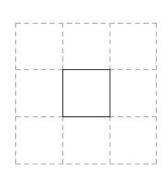


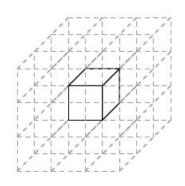


# Caveat of the Cover-Hart Theorem The "curse of dimensionality" (Bellman, 1961)









The number of samples needed to train the KNN classifier to reach the lower bound on the error rate grows exponentially with the number of features.

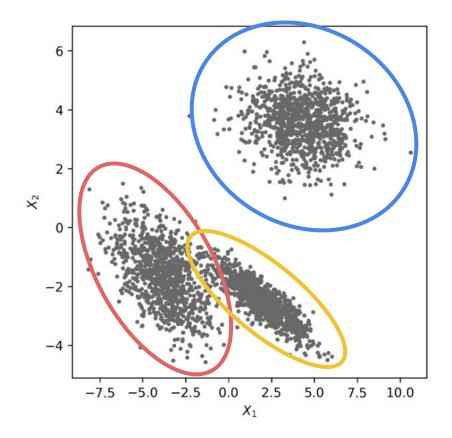
Right: Michael Betancourt, 2018
Discussion: Elements of Statistical Learning, Section 2.5,
Proof: Understanding Machine Learning, Section 19.2.2



## **K-Means Clustering**

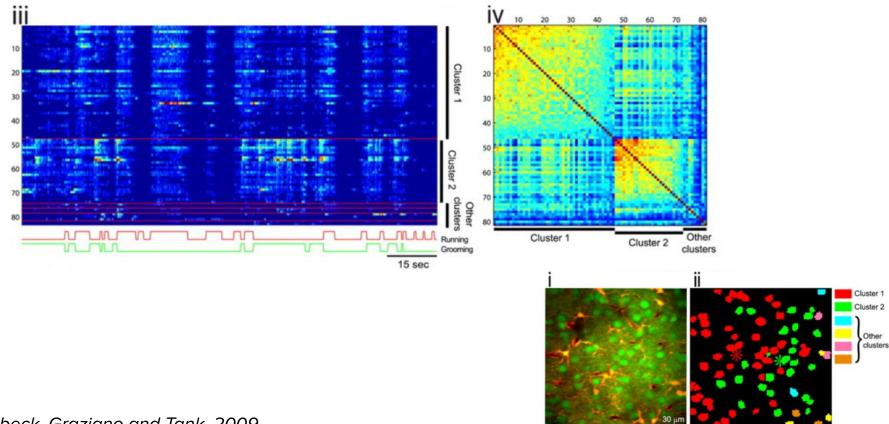
Non-Parametric Clustering

### The clustering task concerns grouping unlabelled data





#### Example: Clustering applied to neural data in motor cortex



Dombeck, Graziano and Tank, 2009

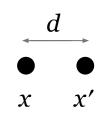
### A common clustering problem

Given: A dataset of n observations,  $D = \{x_1, x_2, \dots, x_n\}$ ,  $x_i \in \mathbb{R}^d$ , and function  $f : \mathbb{R}^d \to \mathbb{R}_+$ 

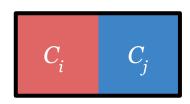
- f is symmetric:  $f(x, x') = f(x', x) \ \forall x, x'$
- If f is a distance function,  $f(x,x) = 0 \ \forall x$ , and  $f(x,z) \leq f(x,y) + f(y,z)$
- If f is a similarity measure,  $f: \mathbb{R}^d \to [0,1]$ ,  $f(x,x) = 1 \ \forall x$

Goal: A partition of the set into a set of subsets  $C = \{C_1, C_2, \dots C_k\}.$ 

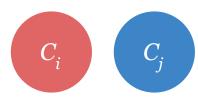
- Each observation belongs to a subset:  $\bigcup_{i=1}^{k} C_i = D$
- Each observation belongs to only one subset:  $C_i \cap C_j = 0, \forall i \neq j$



Collectively Exhaustive

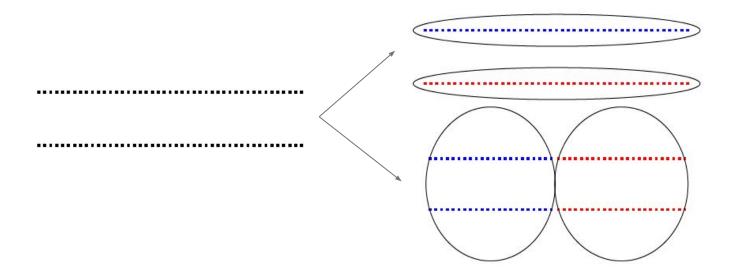


Disjoint or mutually exclusive



Understanding Machine Learning, Chapter 22

#### Clustering output depends on what we mean by similarity



### The k-Means clustering objective

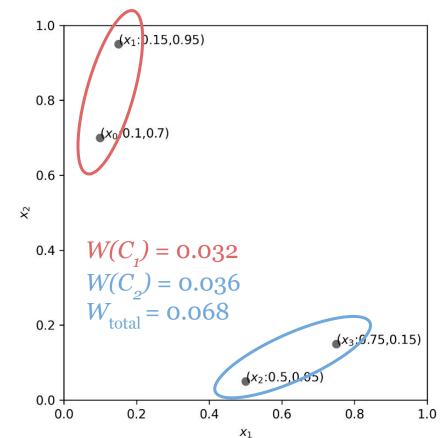
Objective:

Cost of 
$$C_j$$
,  $W(C_j)$ 

$$\min_{C_1, \dots, C_k} \sum_{j=1}^k \frac{1}{|C_j|} \sum_{x_i, x_i' \in C_j} \|x_i - x_i'\|_2^2,$$

Where:

 $|C_j|$  is the number of points in cluster j



### The k-Means clustering objective

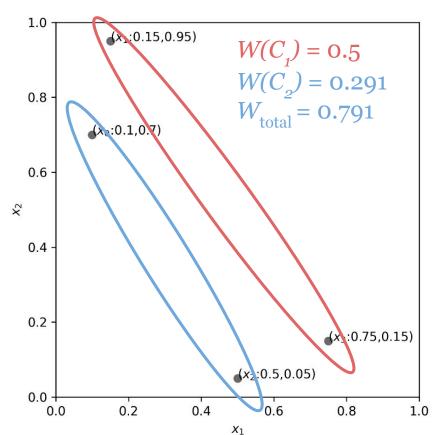
Objective:

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Where:

 $|C_j|$  is the number of points in cluster j



### Reformulating the *k*-Means objective

The  $j^{\text{th}}$  cluster has a centroid  $\mu_j \in \mathbb{R}^d$ :

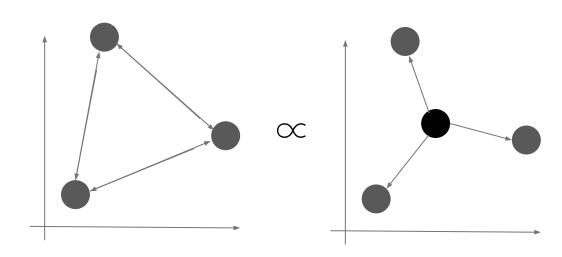
$$\mu_j = \frac{1}{|C_j|} \sum_{x_i \in C_j} x_i$$

It can be shown that

$$\sum_{x_i, x_i' \in C_i} \|x_i - x_i'\|_2^2 \propto \sum_{x_i \in C_j} \|x_i - \mu_j\|_2^2,$$

therefore, the objective can be rewritten as:

$$\min_{C_1, \dots, C_k} \sum_{j=1}^k \frac{1}{|C_j|} \sum_{x_i \in C_i} ||x_i - \mu_j||_2^2.$$





#### How to minimize the objective function?

- If you do brute-force search, you'll have a bad time
  - $\circ$  There are  $K^n$  possible clusters (an NP-hard problem)
  - $\circ$  Would only work for small k and n
- Partial derivative won't be as helpful here
  - Hard-membership means the gradient is non-smooth
  - Multiple local minima

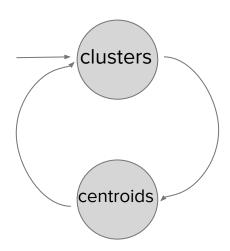


### Lloyd's algorithm for K-Means clustering

#### **Algorithm 1** Lloyd's k-Clustering method

```
Input:
 1: Dataset D = \{x_1, x_2, \dots, x_n\} x_i \in \mathbb{R}^d
 2: Number of clusters k
Output: Partition C = \{C_1, C_2, \dots C_k\}
 3: Randomly initialize partition C^0 = \{C_1, C_2, \dots C_k\}
 4: while \exists i C_i^{(t)} \neq C_i^{(t-1)} do
         for C^t = \{C_1^t, C_2^t, \dots C_k^t\} do \mu_j = \frac{1}{|C_j^t|} \sum_{x_i \in C_j^t} x_i

    Compute centroid of cluster j
    ✓
          end for
          for \{x_1, x_2, ..., x_n\} do
           j = \operatorname{argmin}_{i} \|x_{i} - \mu_{j}\|_{2}^{2}
           C_i^{t+1} \cup \{x_i\} \triangleright Reassign sample i to cluster j
 9:
         end for
10: end while
11: return Partition C^{(t)} = \{C_1, C_2, \dots C_k\}
```





### Lloyd's algorithm in action

#### **Algorithm 1** Lloyd's k-Clustering method

#### Input:

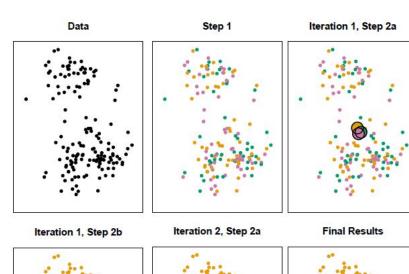
- 1: Dataset  $D = \{x_1, x_2, \dots, x_n\}$   $x_i \in \mathbb{R}^d$
- 2: Number of clusters k

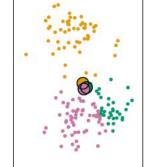
Output: Partition  $C = \{C_1, C_2, \dots C_k\}$ 

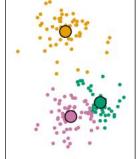
- 3: Randomly initialize partition  $C^0 = \{C_1, C_2, \dots C_k\}$
- 4: while  $\exists i C_i^{(t)} \neq C_i^{(t-1)}$  do

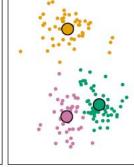
5: for 
$$C^t = \{C_1^t, C_2^t, \dots C_k^t\}$$
 do  $\mu_j = \frac{1}{|C_j^t|} \sum_{x_i \in C_j^t} x_i$ 

- 6: 7: 8: ▶ Compute centroid of cluster j
- end for
- for  $\{x_1, x_2, ..., x_n\}$  do  $j = \operatorname{argmin}_{i} \|x_{i} - \mu_{j}\|_{2}^{2}$ 
  - $C_i^{t+1} \cup \{x_i\}$   $\triangleright$  Reassign sample i to cluster j
- 9: end for
- 10: end while
- 11: **return** Partition  $C^{(t)} = \{C_1, C_2, \dots C_k\}$

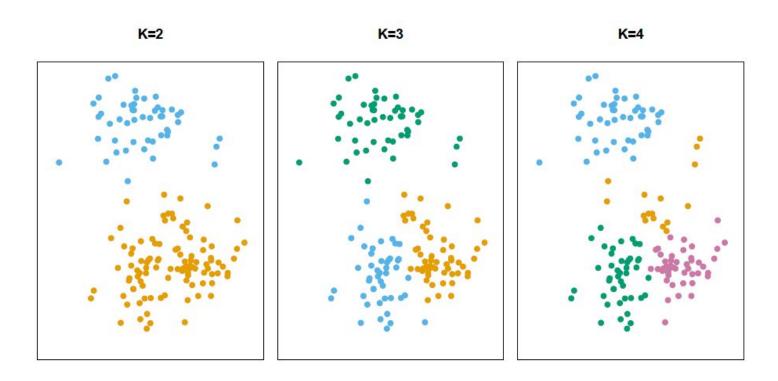






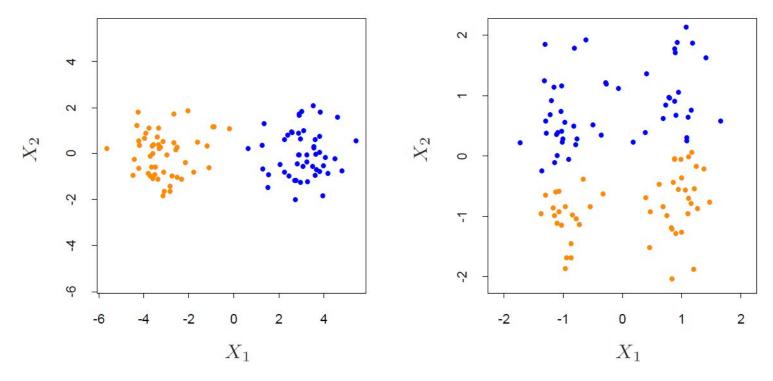


#### Limitations of *k*-Means



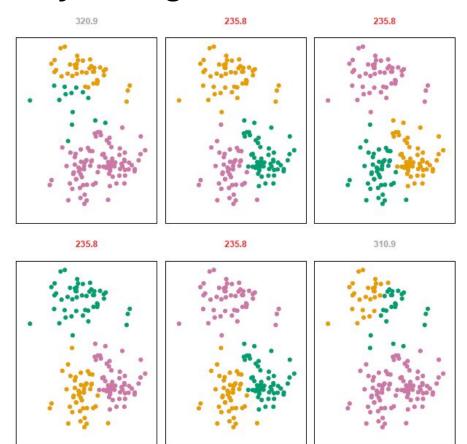


#### Limitations of *k*-Means





### **Limitations of Lloyd's Algorithm**



Introduction to Statistical Learning, Section 12.4



# Summary

# Now that we're at the end of the lecture, you should be able to...

- ★ Differentiate **parametric and non-parametric algorithms**, and give examples of algorithms in unsupervised and supervised settings.
- $\star$  Defend k-NN on both empirical and theoretical grounds, with reference to the **Bayes optimal classifier**.
- ★ State the Cover-Hart theorem and anticipate its implications on real datasets, with reference to the curse of dimensionality.
- ★ Characterize ML algorithms by their compromise of the bias-variance tradeoff.
- ★ Use kernel density estimation (KDE) to fit an empirical distribution.
- ★ Apply KDE to assess a learned parametric model with KL divergence.
- \* State the clustering problem and differentiate it from classification.
- ★ Implement Lloyd's algorithm for K-Means clustering.
- $\star$  Implement k-NN classification with O(ndk) at test.
- $\star$  Design k-NN algorithms and justify choices against alternatives.
- ★ Recommend k-NN in appropriate supervised learning settings.

#### Errata

- On the slide titled "Reformulating the k-Means objective", there appeared a reference to  $u'_j$ . This has been corrected to  $\mu_j$ , denoting the centroid of cluster j.
- On the slides titled "LLoyd's algorithm for K-Means clustering" and "Lloyd's algorithm in action", the algorithm should have returned the partition at iteration t, which is now captured on line 11 of the algorithm pseudocode.

#### Added Context

- On the slide titled "An upper bound on KNN error rate (Cover and Hart, 1967) there was a figure depicting how the KNN error rate is bounded by twice the error of the Bayes optimal classifier. The plot explored the case where the Bayes optimal classifier has an error rate greater than 50%, but this is non-sensical. The figure now restricts the exploration to the case where the Bayes rate is at most 50%, and also emphasizes that the actual KNN error rate can be anywhere from the Bayes error rate up to twie the Bayes error rate adjusted by a factor involving that rate.
- On the slide titled "Learning a distribution without a hypothesis class", details covered during
  the recitation about the mapping of the kernel function and the effect of lambda have now been
  spelled out in the text of the slide.
- On the slide titled "Computational complexity of KNN" nuance has been added to the complexity
  of the algorithm at test time.