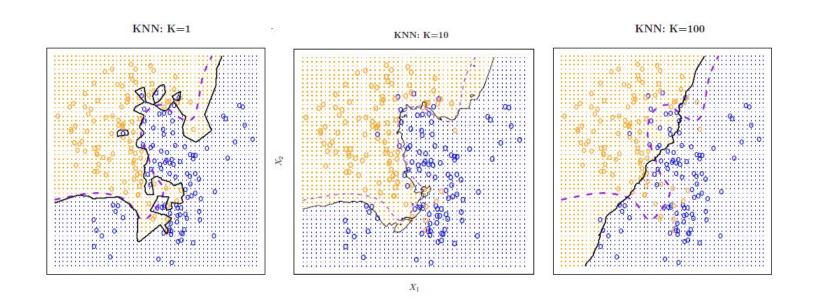
CS 480/680 Introduction to Machine Learning

Lecture 11 Ensemble Methods

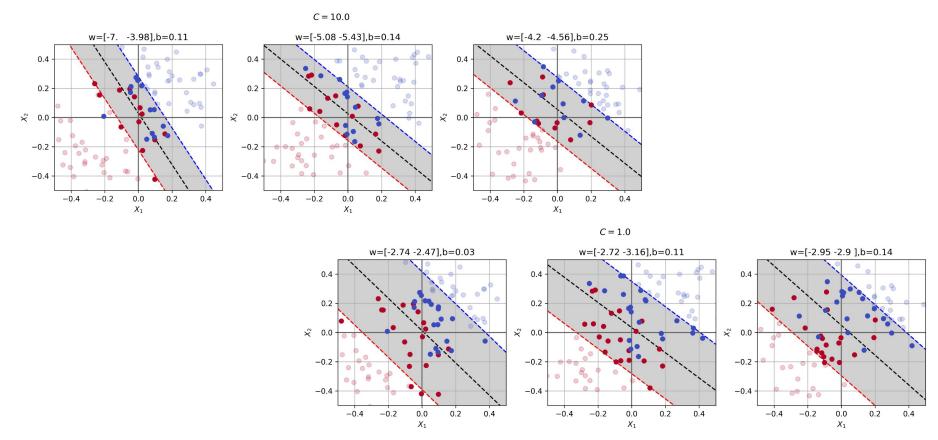
Kathryn Simone 22 October 2024



The bias-variance tradeoff in KNN

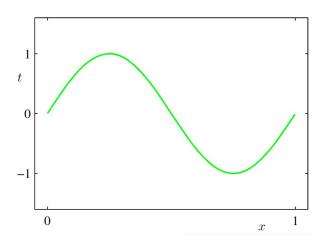


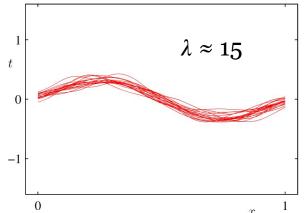
The bias-variance tradeoff in SVMs

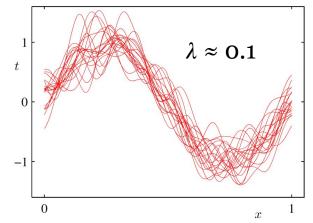


The bias-variance tradeoff in linear regression

True function









Suppose we are tasked with predicting random variable $Y \in \mathbb{R}$ which is a function of $X \in \mathbb{R}^d$ corrupted by Gaussian noise ϵ :

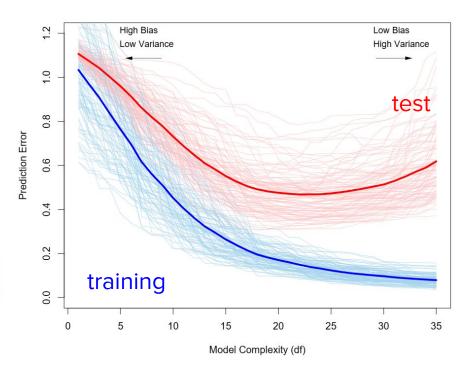
$$Y = f(X) + \epsilon$$
$$\epsilon \sim \mathcal{N}(\mu = 0, \sigma_{\epsilon}^{2})$$
$$f: \mathbb{R}^{d} \to \mathbb{R}$$

Expectation of the squared error for some new test input x_t is:

$$\begin{aligned} \operatorname{Err}(x_t) &= \mathbb{E}\left[(Y - \hat{f}(x_t))^2 \mid X = x_t \right] \\ &= \sigma_{\epsilon}^2 + \left[\mathbb{E}[\hat{f}(x_t)] - f(x_t) \right]^2 + \mathbb{E}\left[\left(\hat{f}(x_t) - \mathbb{E}[\hat{f}(x_t)] \right)^2 \right] \\ &= \overline{\operatorname{Bias}^2} \end{aligned}$$

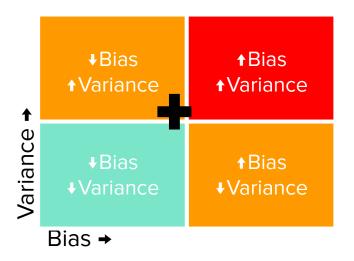
 $\hat{f}(x_t)$: Prediction for one approximated function

 $\mathbb{E}[\hat{f}(x_t)]$: Average over predictions





Strategy so far: Select a *single* model to optimize BV tradeoff



Is this really the best we can do?

This strategy is at odds with our everyday decision-making





My cats absolutely love it, it has even positively affected their behavior bring out their "inner kitten", it actually surprised me with how happy both my cats where once they actually got comfortable using it, they even spend more time with myself and my fiancée, they're extremely grateful.



My cat is about 14 lbs. He has trouble climbing up and down because there is no room. He can't use anything except the top bed. So this is not for "large" cats. As we've propped it up against the window he uses the window sill as extra space to get up and down. We didn't have the heart to return it because once he got to the top he loved the view. But of course once the return period (1 month) passed the bed on top started to rip.. so he may not have this bed for much longer..

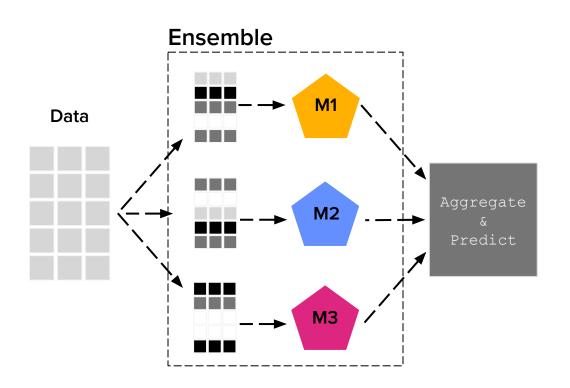
Helpful Report

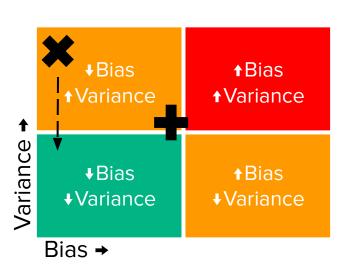
This strategy is at odds with our everyday decision-making



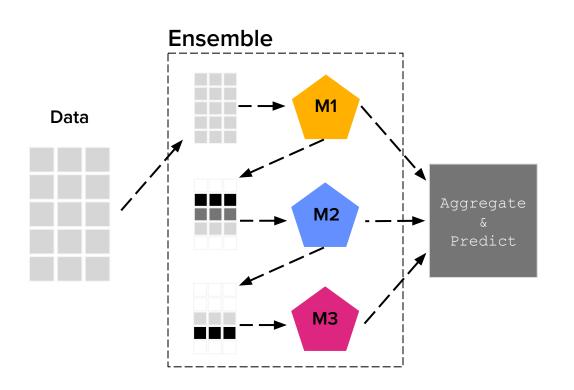
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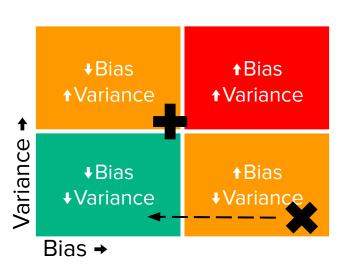
Ensemble methods leverage an assembly of base models





Ensembles can also be trained sequentially





Key Questions

I. How can ensembles reduce variance?

II. How can ensembles reduce bias?

III. How do these methods compare?

Key Questions

I. How can ensembles reduce *variance*?

II. How can ensembles reduce bias?

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The variance of an estimator depends on dataset size

Suppose we wanted to estimate the mean of a normal distribution given n i.i.d. samples $\{x_1, x_2 \dots x_n\}$; where $x_i \sim \mathcal{N}(\mu, \sigma^2)$.

The empirical mean is an unbiased estimate

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

$$E[\hat{\mu}] = \mu.$$

$$\operatorname{Var}[\hat{\mu}] = \operatorname{Var}\left[\frac{1}{n}\sum_{i=1}^{n}x_{i}\right]$$

$$= \frac{1}{n^{2}}\operatorname{Var}\left[\sum_{i=1}^{n}x_{i}\right] \quad \text{(Variance Scaling Property)}$$

$$= \frac{1}{n^{2}} \cdot n \cdot \operatorname{Var}[x_{i}] \quad \text{(Independence of Samples)}$$

$$= \frac{\sigma^{2}}{n} \quad \text{(Since } x_{i} \sim \mathcal{N}(\mu, \sigma^{2})\text{)}$$

If we had more data we could reduce the variance without increasing bias

If we had Bn points, we could form

$$S_1 = \{x_1, \dots x_n\}$$

$$S_2 = \{x_{n+1}, \dots x_{2n}\}$$

$$\vdots$$

$$S_B = \{x_{(B-1)n+1}, \dots x_{Bn}\}$$

$$\hat{\mu}_b = \sum_{(b-1)n+1}^{bn} x_i \qquad \hat{\mu}_B = \frac{1}{B} \sum_b \hat{\mu}_b$$

$$E[\hat{\mu}_B] = \mu$$

$$\operatorname{Var}[\hat{\mu}_{B}] = \operatorname{Var}\left[\frac{1}{B} \sum_{b} \hat{\mu}_{b}\right]$$

$$= \frac{1}{B^{2}} \operatorname{Var}\left[\sum_{b} \hat{\mu}_{b}\right]$$

$$= \frac{1}{B^{2}} \cdot B \cdot \operatorname{Var}\left[\hat{\mu}_{b}\right]$$

$$= \frac{1}{B^{2}} \cdot B \cdot \frac{\sigma^{2}}{n}$$

$$= \frac{\sigma^{2}}{Bn}$$



Is there anything we can do?

Consider the datasets

$$S_1 = \{x_1 = 0.5, x_2 = 1.0, x_3 = 1.5\}$$

$$S_2 = \{x_4 = 0.5, x_5 = 0.8, x_6 = 1.2\}$$

$$\hat{\mu}_1 = \frac{1}{3}(\mathbf{0.4} + \mathbf{1.0} + 1.6) = \frac{1}{3}(3.0) = 1.0$$

$$\hat{\mu}_2 = \frac{1}{3}(0.5 + 0.7 + 1.2) = \frac{1}{3}(2.4) = 0.8$$

$$\hat{\mu}_2 = \frac{1}{3}(\mathbf{0.4} + \mathbf{1.0} + \mathbf{1.0}) = \frac{1}{3}(2.4) = 0.8$$

Bootstrapping: Mimic the *variability* of drawing more samples from the population by resampling the original data (with replacement)

Bootstrap Sampling: Sample with replacement

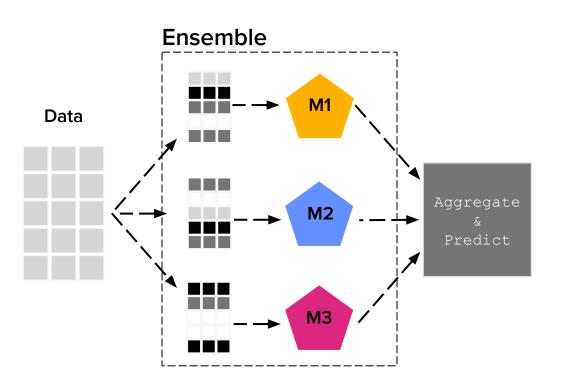
Original Dataset:

$$\{X_{1}, X_{2}, X_{3}, X_{4}, X_{5}\}$$

Bootstrap Realizations:

$$\begin{aligned} &\{X_{1}, X_{1}, X_{4}, X_{5}, X_{3}\} \\ &\{X_{5}, X_{2}, X_{3}, X_{5}, X_{1}\} \\ &\{X_{3}, X_{5}, X_{3}, X_{2}, X_{1}\} \end{aligned}$$

Bagging (Bootstrap Aggregation)

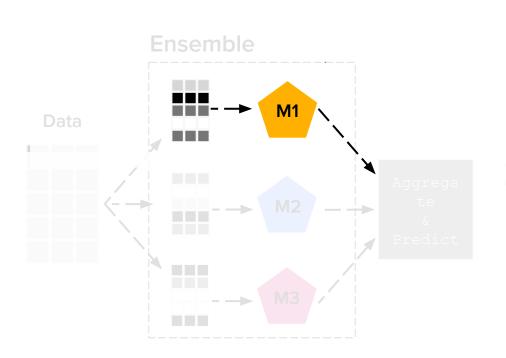


For regression:

$$\hat{y}_E(x_i) = \frac{1}{E} \sum_{e=1}^{E} y_e(x_i)$$

For classification:

$$\hat{y}_E(x_i) = \begin{cases} +1 & \sum_{e=1}^{E} y_e(x_i) > E/2\\ -1 & \text{otherwise} \end{cases}$$



$$t(x) = y_e(x) + \epsilon_e(x)$$

$$\implies \epsilon_e(x) = t(x) - y_e(x)$$

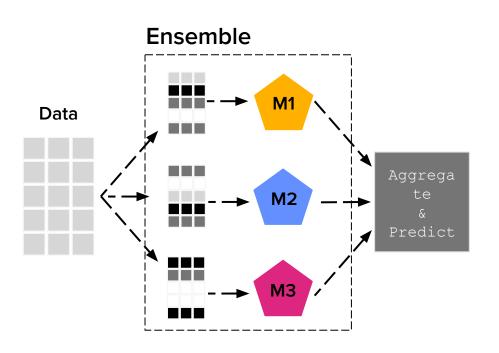
Single Bootstrap Model:

$$\mathbb{E}\left[\left(t(x) - y_e(x)\right)^2\right] = \mathbb{E}\left[\epsilon_e(x)^2\right]$$

$$\epsilon_{\text{avg}} = \frac{1}{E}\sum_{e=0}^{E}\mathbb{E}\left[\epsilon_e(x)^2\right]$$

$$= \mathbb{E}\left[\epsilon(x)^2\right]$$





$$\hat{y}_E(x_i) = \frac{1}{E} \sum_{e=1}^{E} y_e(x_i)$$

$$\mathbb{E}\left[\left(t(x) - y_E(x)\right)^2\right] = \mathbb{E}\left[\left(t(x) - \frac{1}{E}\sum_{e=1}^E y_e(x)\right)^2\right]$$

$$= \mathbb{E}\left[\left(t(x) - \frac{1}{E}\sum_{e=1}^E (t(x) - \epsilon_e(x))\right)^2\right]$$

$$= \mathbb{E}\left[\left(\frac{1}{E}\sum_{e=1}^E \epsilon_e(x)\right)^2\right]$$

$$= \mathbb{E}\left[\frac{1}{E^2}\sum_{i=1}^E \sum_{j=1}^E \epsilon_i(x)\epsilon_j(x)\right]$$

$$= \frac{1}{E^2} \sum_{i=1}^{E} \sum_{j=1}^{E} \mathbb{E} \left[\epsilon_i(x) \epsilon_j(x) \right]$$



$$\frac{1}{E^2} \sum_{i=1}^{E} \sum_{j=1}^{E} \mathbb{E}\left[\epsilon_i(x)\varepsilon_j(x)\right] = \frac{1}{E^2} \sum_{i=1}^{E} \mathbb{E}\left[\epsilon_i(x)^2\right] + \frac{1}{E^2} \sum_{i \neq j} \mathbb{E}\left[\epsilon_i(x)\epsilon_j(x)\right]$$

Assume:
$$\mathbb{E}\left[\epsilon_i(x)\right] = 0$$
 $\mathbb{E}\left[\epsilon_i(x)\epsilon_j(x)\right] = 0$

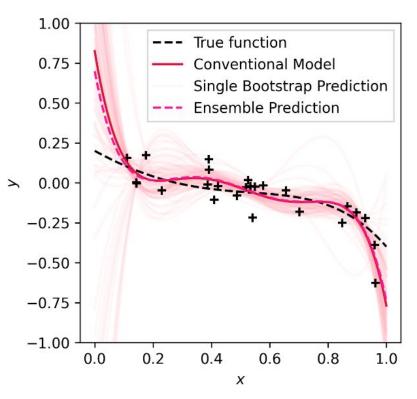
$$= \frac{1}{E^2} \sum_{i=1}^{E} \mathbb{E}\left[\epsilon_i(x)^2\right] + 0$$

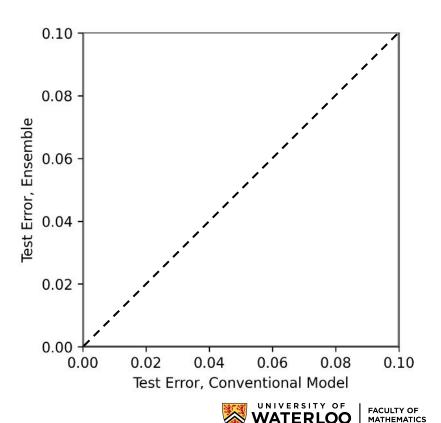
Ensemble:
$$= \frac{1}{E} \mathbb{E} \left[\epsilon(x)^2 \right]$$

One bootstrap model:
$$= \mathbb{E}\left[\varepsilon(x)^2\right]$$

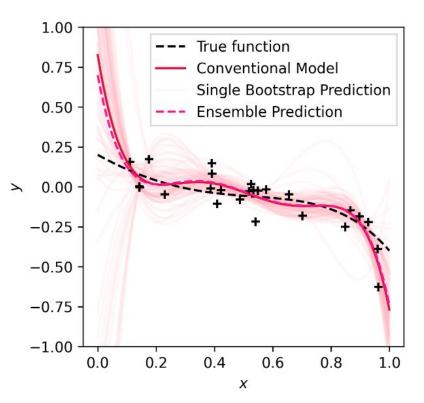


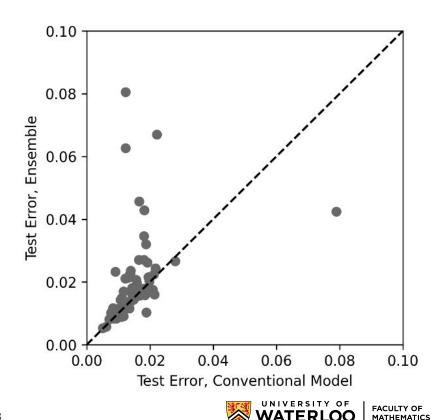
Linear models are not good candidates for bagging



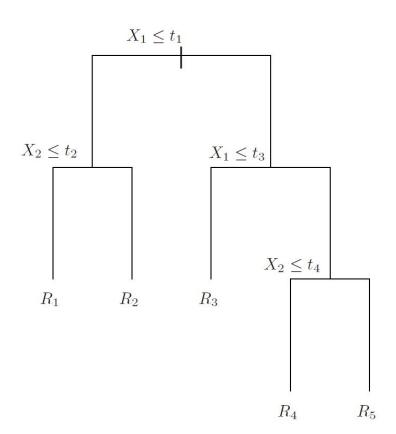


Linear models are not good candidates for bagging



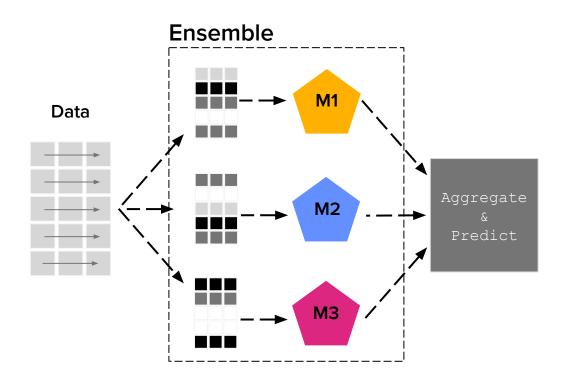


Decision trees are good candidates for bagging

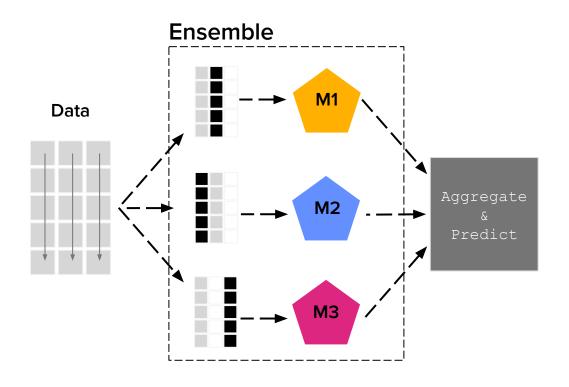




Injecting variability by resampling observations

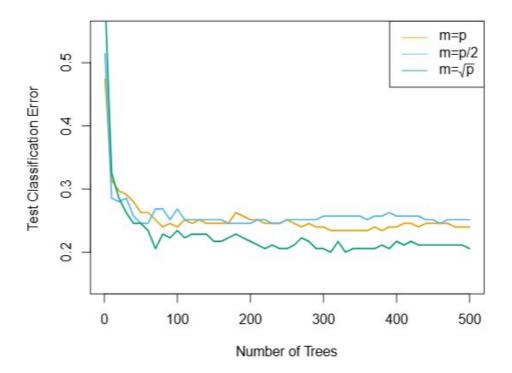


Injecting variability by resampling features



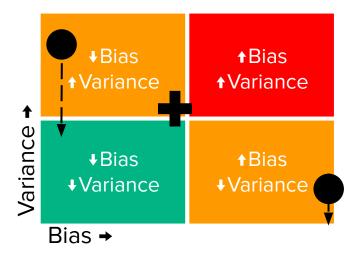
Random Forests

- Reduce correlation between trees by providing a random subset of input features
- Before each split, select m features at random as candidates for splitting

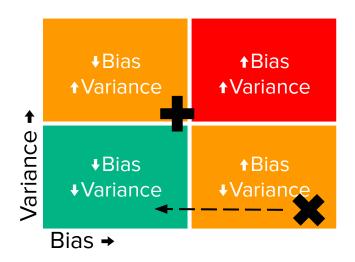




Bagging targets variance, has little effect on bias



Ensembles can also be trained sequentially



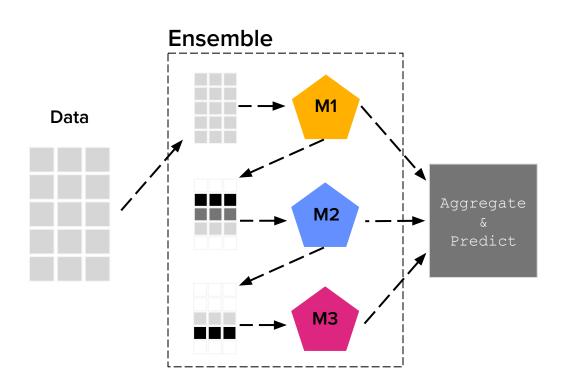
Key Questions

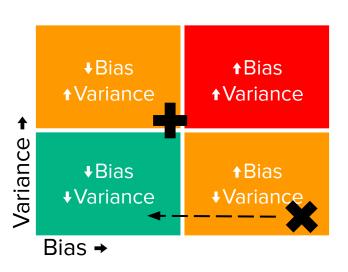
I. How can ensembles reduce variance?

II. How can ensembles reduce bias?

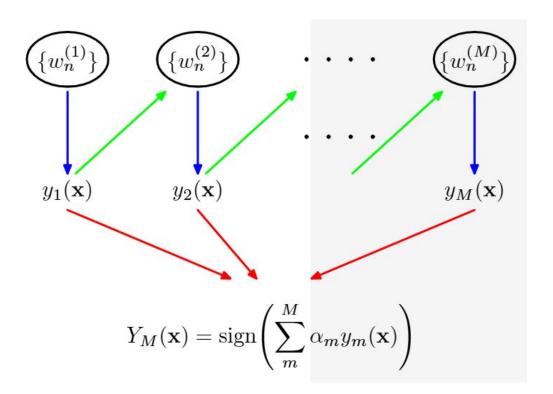
III. When should we use one approach or the other?

Ensembles can also be trained sequentially



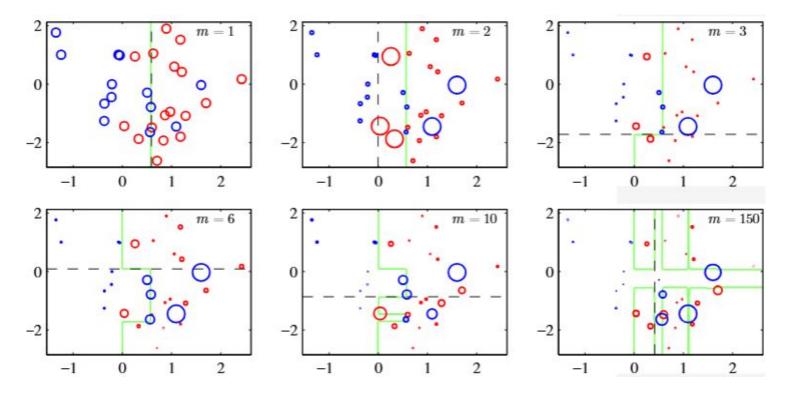


Boosting turns a weak model into a strong model





AdaBoost (Adaptive Boosting)



Algorithm 2 AdaBoost Algorithm

- 1: **Initialize** $\{w_n\}$: $w_n^{(1)} = \frac{1}{N}$ for n = 1, ..., N.
- 2: **for** m = 1, ..., M **do**
- 3: **Fit** a classifier $y_{e,\theta}(x)$: $\operatorname{argmin}_{\theta} \sum_{n=1}^{N} w_n^{(e)} \mathbf{1} (y_{e,\theta}(x_n) \neq t_n)$
- 4: Compute: $\epsilon_m = \frac{\sum_{n=1}^{N} w_n^{(e)} \mathbf{1}(y_{e,\theta}(x_n) \neq t_n)}{\sum_{n=1}^{N} w_n^{(e)}}$
- 5: Compute: $\alpha_e = \ln\left(\frac{1-\epsilon_e}{\epsilon_e}\right)$
- 6: **Update** data weights:

$$w_n^{(m+1)} = w_n^{(m)} \exp \{\alpha_e \mathbf{1} (y_e(x_n) \neq t_n)\}$$

- 7: end for
- 8: **return** $Y_E(x) = \text{sign}\left(\sum_{e=1}^{E} \alpha_e y_{e,\theta}(x)\right) = 0$



Key Questions

I. How can ensembles reduce variance?

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Bagging

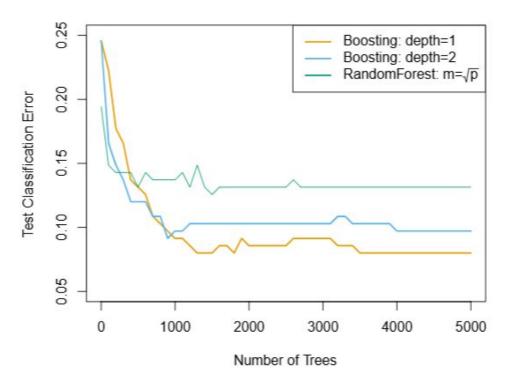
Boosting







Comparing Boosting and Bagging



Now that we're at the end of the lecture, you should be able to...

- ★ Explain the **bias-variance decomposition** and demonstrate how it impacts model generalization.
- ★ Implement **bagging techniques** and analyze how aggregating models reduces variance without increasing bias.
- Implement boosting methods and illustrate how they sequentially reduce bias by focusing on prior errors.
- ★ Compare bagging and boosting strategies and recommend appropriate use cases.
- ★ Develop random forests by selecting random subsets of features to decorrelate decision trees and reduce overfitting.
- ★ Evaluate the impact of ensemble size on **test error reduction**.
- ★ Implement ensemble algorithms for regression and classification tasks and assess their performance on various datasets.

Ensemble methods in unsupervised learning

Loda: Lightweight on-line detector of anomalies

Tomáš Pevný^{1,2}

Received: 2 November 2014 / Accepted: 25 June 2015 / Published online: 21 July 2015 © The Author(s) 2015

Abstract In supervised learning it has been shown that a collection of weak classifiers can result in a strong classifier with error rates similar to those of more sophisticated methods. In unsupervised learning, namely in anomaly detection such a paradigm has not yet been demonstrated despite the fact that many methods have been devised as counterparts to supervised binary classifiers. This work partially fills the gap by showing that an ensemble of very weak detectors can lead to a strong anomaly detector with a performance equal to or better than state of the art methods. The simplicity of the proposed ensemble system (to be called Loda) is particularly useful in domains where a large number of samples need to be processed in real-time or in domains where the data stream is subject to concept drift and the detector needs to be updated on-line. Besides being fast and accurate, Loda is also able to operate and update itself on data with missing variables. Loda is thus practical in domains with sensor outages. Moreover, Loda can identify features in which the scrutinized sample deviates from the majority. This capability is useful when the goal is to find out what has caused the anomaly. It should be noted that none of these favorable properties increase Loda's low time and space complexity. We compare Loda to several state of the art anomaly detectors in two settings: batch training and on-line training on data streams. The results on 36 datasets from UCI repository illustrate the strengths of the proposed system, but also provide more insight