

Sound & Light (1)

1.1 Miscellaneous

% error = (observed - theoretical) / theoretical * 100%

1.2 Kinematics

x = (a/2)(Δt)^2 + v_0Δt + x_0 v = v_0 + aΔt

v^2 = v_0^2 + 2aΔx Δx = (v_0 + v) / 2 * Δt

1.3 Simple Harmonic Motion

x = A cos(ωt + φ) v = -ωA sin(ωt + φ) a = -ω^2 A cos(ωt + φ)

x_max = A v_max = ωA a_max = ω^2 A F_max = mω^2 A

1.3.1 Springs and Slinkies

x represents the distance from the equilibrium.

If you put a mass on top of the slinky, Δx_eq represents the difference between the original equilibrium and the new equilibrium.

F_s = kx = ma F_s_max = kΔx_eq = 9.8Δm

f = (1/2π)√(k/m) T = 2π√(m/k) ω = 2πf = √(m/k)

SPE = (1/2)kx^2 KE = (1/2)mv^2

TME = (1/2)kx^2 + (1/2)mv^2 = (1/2)kA^2 = (1/2)mv_max^2

1.3.2 Springs in parallel and series

Quantity	In Series	In Parallel
Equivalent spring constant	1/k_eq = 1/k_1 + 1/k_2	k_eq = k_1 + k_2
Deflection (elongation)	x_eq = x_1 + x_2	x_eq = x_1 = x_2
Force	F_eq = F_1 = F_2	F_eq = F_1 + F_2
Stored energy	E_eq = E_1 + E_2	E_eq = E_1 = E_2

1.3.3 Pendulums

f = (1/2π)√(g/L) T = 2π√(L/g)

1.4 Waves

T = 1/f v = λf v = Δx/Δt

1.4.1 Slinkies and strings with fixed ends

F_T = F_s = kx μ = m/L v = √(F_T/μ)

Given mass m_T hanging below a pulley, F_T = m_T g.

1.5 Standing waves

1.5.1 Open-open, closed-closed

n is the number of antinodes, or the n^th harmonic.

f_n = f_1 n = (nv) / 2L f_1 = v / 2L λ_n = 2L / n

1.5.2 Open-closed

f_n = f_1 n = (nv) / 4L f_1 = v / 4L λ_n = 2L / n

1.6 Sound

1.6.1 Speed of sound

v = 331√((T_c + 273) / 273) v ≈ 331 + 0.59T

1.6.2 Sound intensity

I = (Power (W)) / Area = (Power (W)) / (4πr^2)

I_dB = 10 log_10(I / 10^-12) I = 10^(I_dB / 10 - 12)

1.6.3 Doppler effect

[O] → [S] f_o = f_s (v + v_o) / v ← [O] [S] f_o = f_s (v - v_o) / v
[O] ← [S] f_o = f_s (v - v_s) / v [O] [S] → f_o = f_s (v + v_s) / v
[O] → ← [S] f_o = f_s (v + v_o) / (v - v_s) [O] → [S] → f_o = f_s (v + v_o) / (v + v_s)
← [O] ← [S] f_o = f_s (v - v_o) / (v - v_s) ← [O] [S] → f_o = f_s (v - v_o) / (v + v_s)

1.6.4 Constructive and Destructive Interference (2 dimensions)

For a point on the m^th antinodal/nodal line playing the same frequency with the same phase:

PD = mλ

where PD is the path length difference.

1.6.5 Beats

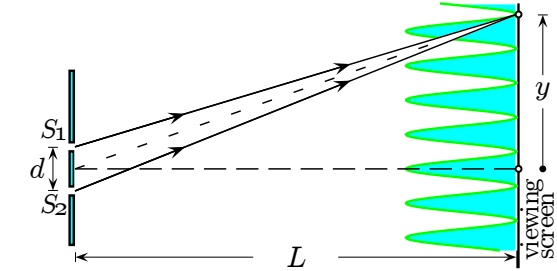
f_B = Δf

1.7 Light

1.7.1 Speed of light

$$c = 299\,792\,458 \frac{\text{m}}{\text{s}} \approx 3 * 10^8 \frac{\text{m}}{\text{s}}$$

1.7.2 Two-slit experiment



$$PD = \frac{dy}{L} = m\lambda$$

1.7.3 Mirror

$$r = 2f \quad \frac{1}{f} = \frac{1}{p} + \frac{1}{q} \quad M = \frac{h}{h_o} = \frac{-q}{p}$$

In a plane mirror, $p = -q$.

1.7.4 Lenses

$$\frac{1}{f} = (n - 1) \left(\frac{1}{r_1} - \frac{1}{r_2} \right) \quad \frac{1}{f} = \frac{1}{p} + \frac{1}{q} \quad M = \frac{h}{h_o} = \frac{-q}{p}$$

Multiple lenses

$$p_2 = \Delta x - q_1$$

1.7.5 Mirrors and Lenses

Real \iff inverted, virtual \iff upright.

	Converging	Diverging
Mirror		
Lens		
focal length	+	-
object distance	image	image
∞ to $2f$	Real smaller	Virtual smaller
$2f$ to f	Real larger	
f to 0	Virtual larger	
0 to $-f$	Virtual smaller	Virtual larger
$-f$ to $-2f$		Real larger
$-2f$ to $-\infty$		Real smaller

1.7.6 Refraction / Snell’s Law

The **normal line** is the line perpendicular to the surface which touches the intersection of the surface and the light ray.

The **incident angle** is the angle between the ray of light and the normal line.

θ_1 and θ_2 are both measured from the normal line, not the surface.

Refraction occurs when the speed of light in two media are different and light hits the boundary of the two media. The frequency of the light will stay the same, but the speed, wavelength, and direction will change.

$$n = \frac{c}{v} \quad n_1 \sin \theta_1 = n_2 \sin \theta_2$$

1.7.7 Ray diagrams

Mathematics (2)

2.1 Logarithms

$$\log_b(MN) = \log_b(M) + \log_b(N)$$

$$\log_b\left(\frac{M}{N}\right) = \log_b(M) - \log_b(N)$$

$$\log_b(M^p) = p \cdot \log_b(M)$$

$$\log_b(a) = \frac{\log_x(a)}{\log_x(b)}$$

$$\log_b(b) = 1$$

2.2 Notation

deg $p(x)$ means the degree of polynomial p .

LC $p(x)$ means the leading coefficient of polynomial p .

2.3 Rational functions

For a rational function $f(x) = \frac{p(x)}{q(x)}$, cancel out any common factors, then:

- For all rational functions:
 - VA: roots of $q(x)$
 - Roots: roots of $p(x)$
- When deg $p(x) = \text{deg } q(x)$:
 - HA: $y = \frac{\text{LC } p(x)}{\text{LC } q(x)}$
- When deg $p(x) < \text{deg } q(x)$:
 - HA: $y = 0$
- When deg $p(x) > \text{deg } q(x)$:
 - HA: none
 - slant asymptote: $\frac{p(x)}{q(x)}$ excluding remainder

2.4 Polynomials

2.4.1 Linear equations

Slope-intercept form: $y = mx + b$

Point-slope form: $y - y_1 = m(x - x_1)$ for point (x, y)

Standard form: $ax + by = c$

2.4.2 Quadratic equations

Standard form: $y = ax^2 + bx + c$

Vertex form: $y = a(x - h)^2 + k$ for vertex (h, k)

Sum of roots: $-\frac{b}{a}$

Product of roots: $\frac{c}{a}$

2.4.3 Higher-degree polynomials

In a polynomial

$$a_nx^n + a_{n-1}x^{n-1} + \cdots + a_1x + a_0 = 0$$

, with roots

$$r_1, r_2, r_3, \dots, r_n$$

then:

$$r_1 + r_2 + r_3 + \cdots + r_n = \sum_{k=1}^n nr_k = -\frac{a_{n-1}}{a_n}$$

2.5 Sequences and Series

2.5.1 Explicit formulas

Aritmetic sequence: $a_n = a_1 + r(n - 1)$

Geometric sequence: $a_n = a_1 * r^{n-1}$

Harmonic sequence: $a_n = \frac{1}{a_1 + r(n - 1)}$

2.5.2 Arithmetic and Geometric Series

In the following equations, substituting $j = 1$ with $j = 0$, $j - 1$ with j , and a_1 with a_0 will produce the same result.

$$\sum_{j=1}^n (a_1 + r(j - 1)) = \frac{n}{2}(2a_1 + (n - 1)d)$$

$$\sum_{j=1}^n (a_1 * r^{j-1}) = \frac{a_1(1 - r^n)}{1 - r}$$

$$\sum_{j=1}^\infty (a_1 * r^{j-1}) = \frac{a_1}{1 - r} \text{ for } r \in [-1, 1]$$

2.5.3 Special Sums

$$\sum_{j=1}^n c = nc$$

$$\sum_{j=1}^n ca_j = c \sum_{j=1}^n a_j$$

$$\sum_{j=1}^n (a_j + b_j) = \sum_{j=1}^n a_j + \sum_{j=1}^n b_j$$

$$\sum_{j=1}^n j = \frac{n(n + 1)}{2}$$

$$\sum_{j=1}^n j^2 = \frac{n(n + \frac{1}{2})(n + 1)}{3}$$

$$\sum_{j=1}^n j^3 = \frac{n^2(n + 1)^2}{4}$$

2.6 Trigonometry

°	rad	sin	cos	tan
0°	0	0	1	0
30°	$\frac{\pi}{6}$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{3}}$
45°	$\frac{\pi}{4}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1
60°	$\frac{\pi}{3}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$
90°	$\frac{\pi}{2}$	1	0	undef

2.6.1 Law of Sines and Cosines

$$\frac{\sin(A)}{a} = \frac{\sin(B)}{b} = \frac{\sin(C)}{c} \qquad c^2 = a^2 + b^2 - 2ab \cos(C)$$

2.6.2 Triangle area

$$K = \frac{1}{2}bh \qquad K = \frac{1}{2}bc \sin(A) \qquad K = \sqrt{s(s - a)(s - b)(s - c)}$$

2.6.3 More identities

$(\sin A)^2 + (\cos A)^2 = 1$

$(\tan A)^2 + 1 = (\sec A)^2$

$\sin(\frac{\pi}{2} - x) = \cos(x)$

$(\cot A)^2 + 1 = (\csc A)^2$

$\cos(-x) = \cos(x)$

$\sin(-x) = -\sin(x)$

$\tan(-x) = -\tan(x)$

2.6.4 Slope

Where α is the angle between the line and the x-axis, and m is the slope of the line:

$$m = \tan \alpha$$

2.6.5 Sum and difference formulas

$\sin(A + B) = \sin(A) \cos(B) + \cos(A) \sin(B)$

$\sin(A - B) = \sin(A) \cos(B) - \cos(A) \sin(B)$

$\cos(A + B) = \cos(A) \cos(B) - \sin(A) \sin(B)$

$\cos(A - B) = \cos(A) \cos(B) + \sin(A) \sin(B)$

$\tan(A + B) = \frac{\tan(A) + \tan(B)}{1 - \tan(A) \tan(B)}$

$\tan(A - B) = \frac{\tan(A) - \tan(B)}{1 + \tan(A) \tan(B)}$

$\sin(2A) = 2 \sin(A) \cos(A)$

$\cos(2A) = (\cos A)^2 - (\sin A)^2 = 2(\cos A)^2 - 1 = 1 - 2(\sin A)^2$

$\tan(2A) = \frac{2 \tan(A)}{1 - (\tan A)^2}$

2.7 Vectors

$\vec{v} + \vec{w} = \begin{bmatrix} v_x + w_x \\ v_y + w_y \\ v_z + w_z \end{bmatrix}$

$c * \vec{v} = \begin{bmatrix} c * v_x \\ c * v_y \\ c * v_z \end{bmatrix}$

$\vec{v} \cdot \vec{w} = v_x w_x + v_y w_y + v_z w_z = |\vec{v}| |\vec{w}| \cos(\theta)$

$|\vec{v} \times \vec{w}| = |\vec{v}| |\vec{w}| \sin(\theta) = \text{area of parallelogram}$

$\vec{v} \times \vec{w} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix}$

$\vec{v} \times \vec{w} \perp \vec{v} \quad \vec{v} \times \vec{w} \perp \vec{w}$

$\vec{v} \perp \vec{w} \iff \vec{v} \times \vec{w} = \vec{0} \quad \vec{v} \parallel \vec{w} \iff \vec{v} \cdot \vec{w} = 0$

$\hat{v} = \frac{\vec{v}}{|\vec{v}|} \quad \text{proj}_{\vec{b}} \vec{v} = \frac{\vec{v} \cdot \vec{b}}{\vec{b} \cdot \vec{b}} * \vec{b} = (|\vec{v}| \cos(\theta)) \hat{b}$

Right-hand rule

To determine the direction of $\vec{v} \times \vec{w}$, put the side of the right hand on \vec{v} and curl the fingers toward \vec{w} . The direction the thumb is pointing is the direction of $\vec{v} \times \vec{w}$.

2.8 Polar

2.8.1 Polar and Cartesian sytems

With point $(x, y) = (r; \theta) = (r; \beta)$, where θ is CCW from the x-axis and β is a bearing, CW from the y-axis:

$x = r \cos(\theta) = r \sin(\beta)$

$y = r \sin(\theta) = r \cos(\beta)$

$r = \sqrt{x^2 + y^2}$

$\theta \equiv \arctan(\frac{y}{x}) \quad \beta \equiv \arctan(\frac{x}{y})$

2.8.2 Converting functions

Try these substitutions in order:

$x^2 = x^2 + y^2$

$\tan \theta = \frac{y}{x}$

$x = r \cos \theta$

$y = r \sin \theta$

2.8.3 Limaçons and Petals

The function $y = A \cos(B(\theta + C)) + D$ is equivalent to $y = A \cos(B\theta) + D$ rotated C degrees/radians clockwise.

When C is 0 and B is 1, the x-intercepts are $A \pm D$ and the y-intercepts are $\pm D$, and it forms a limaçon.

When C is 0, but $B \neq 1$, then this sometimes still holds. The x-intercepts may also be $\pm A \pm D$.

There are B petals, with the axis of the first petal on the positive x-axis.

When B is even and $|D| < 1$, then the number of petals is $2B$.

Using sin instead of cos, limaçons have their axes on the positive y-axis, while for petals, the first petal starts from the positive x-axis and curves upwards.

2.9 Complex

$$\text{cis}(\theta) = e^{i\theta} = \cos(\theta) + i \sin(\theta)$$

To find the n^{th} root of $x_r \text{cis}(x_\theta)$, solve the equation $z_r^n \text{cis}(nz_\theta) = x_r \text{cis}(x_\theta + 360^\circ k)$ for $k \in \mathbb{R}$.

2.10 Function domain

Function	Domain x	Range y
$\log(x)$	$(0, \infty)$	\mathbb{R}
\sqrt{x}	$[0, \infty)$	$[0, \infty)$
$\arcsin(x)$	$[-1, 1]$	$[-\frac{\pi}{2}, \frac{\pi}{2}]$
$\arccos(x)$	$[-1, 1]$	$[0, \pi]$
$\arctan(x)$	\mathbb{R}	$(-\frac{\pi}{2}, \frac{\pi}{2})$

Calculus Theorems (3)

1 Completeness

1.3 Completeness

Theorem (Completeness of the Real Numbers). Every nonempty subset S of \mathbb{R} which is bounded above has a least upper bound $\sup S$.

Definition of Supremum ($\sup S$). A number such that

- (1) $s \leq \sup S$ for every $s \in S$ (which just says that $\sup S$ is an upper bound for S)
- (2) If u is any upper bound for S , then $\sup S \leq u$ (which says that $\sup S$ is the least upper bound for S).

Definition of Infimum ($\inf S$). A number such that

- (1) $\inf S \leq s$ for every $s \in S$ (i.e. $\inf S$ is an lower bound for S)
- (2) If l is any upper bound for S , then $l \leq \inf S$ (i.e. $\inf S$ is the greatest lower bound for S).

Theorem. Every nonempty subset S of \mathbb{R} which is bounded below has a greatest lower bound.

Theorem. If $\min S$ exists, then $\min S = \inf S$.

Theorem. If $A \subset \mathbb{R}$ and $c \geq 0$, and $cA := \{ca : a \in A\}$, $\sup cA = c \sup A$.

1.4 Consequences of Completeness

Theorem (Rationals between Reals). For every two real numbers a and b with $a < b$, there exists a rational number r satisfying $a < r < b$.

1.5 Nested Intervals Theorem

Nested Intervals Theorem.

If $I_n = [a_n, b_n] = \{x \in \mathbb{R} : a_n \leq x \leq b_n\}$ s.t. $a_n \leq a_{n+1}$ and $b_{n+1} \leq b_n$ for $n \in \mathbb{N}$, so that $I_1 \supseteq I_2 \supseteq I_3 \supseteq I_4 \supseteq \dots$, then $\bigcap_{n=1}^\infty I_n \neq \emptyset$.

If $\inf\{b_n - a_n\} = 0$, then $\bigcap_{n=1}^\infty I_n \{x\}$, where

$x = \sup\{a_n\} = \inf\{b_n\}$.

1.6 Capture Theorem

Capture Theorem. If A is a nonempty subset of \mathbb{R} , then:

- (i) If A is bounded above, then any open interval containing $\sup A$ contains an element of A .
- (ii) Similarly, if A is bounded below, then any open interval containing $\inf A$ contains an element of A .

1.7 Binary Search

If we binary-search for x over $I_1 = [a_1, b_1]$ for $a_1, b_1 \in \mathbb{Q}$, we define I_n s.t. either $I_n := [a_{n-1}, \frac{a_{n-1}+b_{n-1}}{2}]$ or $I_n := [\frac{a_{n-1}+b_{n-1}}{2}, a_{n+1}]$, and we define $a_n := \inf I_n$ and $b_n := \sup I_n$. We define A to be the set of all a_n , and B to be the set of all b_n .

Then, the size of $I_n = \frac{b_1-a_1}{2^n} = b_n - a_n$, and $\bigcap_{n=1}^\infty I_n \{x\}$, where

$x = \sup\{a_n\} = \inf\{b_n\}$.

2 Limits

2.4 ε - δ definition of a Limit

Definition of Limit. If $\lim_{x \rightarrow a} f(x) = L$, then for any $\varepsilon > 0$, there exists $\delta > 0$ s.t. for any $x \in (a - \delta, a) \cup (a, a + \delta)$, $f(x) \in (L - \varepsilon, L + \varepsilon)$.

Alternatively,

Definition of Limit. If $\lim_{x \rightarrow a} f(x) = L$, then for any $\varepsilon > 0$, there exists $\delta > 0$ s.t. for any $|f(x) - L| < \varepsilon$ whenever $0 < |x - a| < \delta$.

2.6 Limit Laws

Theorem (Limit Laws). Let $c \in \mathbb{R}$ be a constant and suppose the limits $\lim_{x \rightarrow a} f(x)$ and $\lim_{x \rightarrow a} g(x)$ exist. Then

- (i) $\lim_{x \rightarrow a} (f(x) \pm g(x)) = \lim_{x \rightarrow a} f(x) \pm \lim_{x \rightarrow a} g(x)$
- (ii) $\lim_{x \rightarrow a} (cf(x)) = c \lim_{x \rightarrow a} f(x)$
- (iii) $\lim_{x \rightarrow a} (f(x)g(x)) = \lim_{x \rightarrow a} f(x) \lim_{x \rightarrow a} g(x)$
- (iv) $\lim_{x \rightarrow a} f(x)g(x) = \lim_{x \rightarrow a} f(x) \lim_{x \rightarrow a} g(x)$, provided that $\lim_{x \rightarrow a} g(x) \neq 0$
- (v) See (i).
- (vi) $\lim_{x \rightarrow a} x^n = (\lim_{x \rightarrow a} x)^n$
- (vii) $\lim_{x \rightarrow a} \sqrt{f(x)} = \sqrt{\lim_{x \rightarrow a} f(x)}$
- (viii) $\lim_{x \rightarrow a} \frac{a(x)b(x)}{c(x)b(x)} = \lim_{x \rightarrow a} \frac{a(x)}{c(x)}$

These laws also apply to one-sided limits.

Theorem (Operations on infinity). For $x \in \mathbb{R}$,

$$\infty + x = \infty \qquad -\infty + x = -\infty \qquad \frac{x}{\pm\infty} = 0$$

$$x * \infty = \begin{cases} \infty & \text{if } x > 0 \\ -\infty & \text{if } x < 0 \end{cases}$$

$$x * -\infty = \begin{cases} -\infty & \text{if } x > 0 \\ \infty & \text{if } x < 0. \end{cases}$$

Definition of Indeterminate forms. The following forms are indeterminate and you cannot evaluate them.

$$\frac{0}{0}, \frac{\pm\infty}{\pm\infty}, 0 * \pm\infty, \infty - \infty$$

Theorem (L'Hopital's Rule). If f and g are differentiable and $g'(x) \neq 0$ on an open interval I that surrounds a , and $\lim_{x \rightarrow a} \frac{f(x)}{g(x)} \in \{\frac{0}{0}, \pm\frac{\infty}{\infty}\}$, then $\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \frac{f'(x)}{g'(x)}$.

Other theorems

Composite Function Theorem. If f is continuous at L and $\lim_{x \rightarrow a} g(x) = L$, then $\lim_{x \rightarrow a} f(g(x)) = f(\lim_{x \rightarrow a} g(x)) = f(L)$

2.12 Squeeze Theorem

Squeeze Theorem. Let f , g , and h be defined for all $x \neq a$ over an open interval containing a . If

$$f(x) \leq g(x) \leq h(x)$$

for all $x \neq a$ in an open interval containing a and

$$\lim_{x \rightarrow a} f(x) = L = \lim_{x \rightarrow a} h(x)$$

where $L \in \mathbb{R}$, then $\lim_{x \rightarrow a} g(x) = L$.

3 Continuity

Definition of Continuity at a point. Function f is continuous at point a if $\lim_{x \rightarrow a} f(x) = f(a)$.

Definition. f has a **removable discontinuity** if $\lim_{x \rightarrow a} f(x) = L \in \mathbb{R}$ (in this case either $f(a)$ is undefined, or $f(a)$ is defined by $L \neq f(a)$).

Definition. f has a **jump discontinuity** if $\lim_{x \rightarrow a^-} f(x) = L_1 \in \mathbb{R}$ and $\lim_{x \rightarrow a^+} f(x) = L_2 \in \mathbb{R}$ but $L_1 \neq L_2$.

Definition. f has an **infinite discontinuity** at a if $\lim_{x \rightarrow a^-} f(x) = \pm\infty$ or $\lim_{x \rightarrow a^+} f(x) = \pm\infty$

Intermediate Value Theorem. If f is continuous on $[a, b]$, then for any real number L between $f(a)$ and $f(b)$ there exists at least one $c \in [a, b]$ such that $f(c) = L$. In other words, if f is continuous on $[a, b]$, then the graph must cross the horizontal line $y = L$ at least once between the vertical lines $x = a$ and $x = b$.

Aura Theorem. If $f(x)$ is continuous and $f(a) \neq 0$, then there exists an open interval containing a such that for all x in the interval, $\text{sgn}(f(x)) = \text{sgn}(f(a))$.

4 Derivatives

The derivative is the instantaneous rate of change, and the slope of the tangent line to the point.

Definition of Derivative ($f'(a)$).

$$\frac{d}{da}f(a) = f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} = \lim_{h \rightarrow 0} \frac{f(a + h) - f(a)}{h}$$

Theorem (Tangent line to a point). The equation of the tangent line to the point $(a, f(a))$ is

$$y = f'(a)(x - a) + f(a)$$

Derivative Rules

Theorem (Difference Rule).

$$\frac{d}{dx}(f(x) - g(x)) = \frac{d}{dx}f(x) - \frac{d}{dx}g(x)$$

Theorem (Sum Rule).

$$\frac{d}{dx}(f(x) + g(x)) = \frac{d}{dx}f(x) + \frac{d}{dx}g(x)$$

Theorem (Constant Multiple Rule).

$$\frac{d}{dx}(cf(x)) = c\frac{d}{dx}f(x)$$

Theorem (Product Rule).

$$\begin{aligned} \frac{d}{dx}(f(x)g(x)) &= f'(x)g(x) + f(x)g'(x) \\ \frac{d}{dx}(f(x)g(x)h(x)) &= f'(x)g(x)h(x) + f(x)g'(x)h(x) \\ &\quad + f(x)g(x)h'(x) \end{aligned}$$

and so on.

Theorem (Quotient Rule).

$$\frac{d}{dx} \frac{f(x)}{g(x)} = \frac{f'(x)g(x) - f(x)g'(x)}{(g(x))^2}$$

Theorem (Power Rule).

$$\frac{d}{dx}x^n = nx^{n-1}$$

for $n \in \mathbb{R}$

Theorem (Chain Rule).

$$\frac{d}{dx}f(g(x)) = f'(g(x))g'(x) \qquad \frac{dy}{dx} = \frac{dy}{db} \frac{db}{dx}$$

Theorem (Derivative of inverse functions). Let $x \in \mathbb{R}$ and f be a differentiable, one-to-one function at x . Then if $f'(x) \neq 0$, then

$$(f^{-1})'(f(x)) = \frac{1}{f'(x)}$$

Theorem (Derivatives of exponentials and logs).

$$\begin{aligned} \frac{d}{dx}e^x &= e^x & \frac{d}{dx}\ln x &= \frac{1}{x} \\ \frac{d}{dx}a^x &= a^x \ln(a) & \frac{d}{dx}\log_a x &= \frac{1}{x \ln(a)} \end{aligned}$$

Theorem (Derivatives of trig functions).

$$\begin{aligned} \sin'(x) &= \cos(x) & \cos'(x) &= -\sin(x) \\ \sec'(x) &= \sec(x)\tan(x) & \csc'(x) &= -\csc(x)\cot(x) \\ \tan'(x) &= \sec(x)^2 & \cot'(x) &= -\csc(x)^2 \end{aligned}$$

$$\begin{aligned} \arcsin'(x) &= \frac{1}{\sqrt{1-x^2}} & \arccos'(x) &= -\frac{1}{\sqrt{1-x^2}} \\ \operatorname{arcsec}'(x) &= \frac{1}{|x|\sqrt{x^2-1}} & \operatorname{arccsc}'(x) &= -\frac{1}{|x|\sqrt{x^2-1}} \\ \arctan'(x) &= \frac{1}{1+x^2} & \operatorname{arccot}'(x) &= -\frac{1}{1+x^2} \end{aligned}$$

5 Derivative Applications

5.7 Mean Value Theorem

Theorem (Mean Value Theorem). If the function f is continuous on $[a, b]$ and differentiable on (a, b) , then there exists $c \in (a, b)$ s.t.

$$f'(c) = \frac{f(b) - f(a)}{b - a} = \frac{\Delta f(x)}{\Delta x} \text{ on } [a, be]$$

Theorem (Some colloraries to the MVT). If $f(x)$ is differentiable on I , then:

- $f'(x) > 0$ for $x \in I \iff f(x)$ is strictly increasing for $x \in I$.
- $f'(x) \geq 0$ for $x \in I \iff f(x)$ is increasing or constant for $x \in I$.
- $f'(x) = 0$ for $x \in I \iff f(x)$ is constant for $x \in I$.
- $f'(x) \leq 0$ for $x \in I \iff f(x)$ is decreasing or constant for $x \in I$.
- $f'(x) < 0$ for $x \in I \iff f(x)$ is strictly decreasing for $x \in I$.

Antiderivative

Definition of Antiderivative. The antiderivative F of a function f is the function such that $F'(x) = f(x)$.

$$F(x) = \int f(x)dx$$

5.3, 5.10, 5.11, 5.16 Extrema

Definition of Critical point of f . A number c in the domain of f where $f'(c) = 0$ or $f'(c)$ does not exist.

Definition of Stationary point of f . A number c in the domain of f where $f'(c) = 0$

Fermat's Theorem. The local maxima and minima of f are critical points of f .

Exteme Value Theorem. If f is continuous on $[a, b]$, then it has an absolute max and an absolute min.

Theorem (Method to find absolute minima and maxima). Store the critical points of f in the array C . Then, the absolute maximum is $\max\{f(c) : c \in C\}$ and the absolute minimum is $\min\{f(c) : c \in C\}$.

Theorem (First Derivative Test). If f is continuous over I , and $c \in I$ is a critical point of f , and f is differentiable over $I \setminus c$, then:

- If $f'(x)$ is decreasing at c , then $f(c)$ is a local max.
- If $f'(x)$ is increasing at c , then $f(c)$ is a local min.
- If $f'(x)$ has the same sign before and after c , then $f(c)$ is neither a local max nor a local min.

Definition of Concavity. f is concave up on I if the tangent line to f at each point in I is lower than the graph of f .

f is concave down on I if the tangent line to f at each point in I is higher than the graph of f .

Theorem (Test for Concavity). If $f''(x) > 0$ for all $x \in I$, then f is concave up on I .

If $f''(x) < 0$ for all $x \in I$, then f is concave down on I .

Theorem (Second Derivative Test). If f'' is continuous on an interval containing c , where c is the x -value of a stationary point of f . Then,

- If $f''(c) > 0$, then $f(c)$ is a local max.
- If $f''(c) < 0$, then $f(c)$ is a local min.

Trimm's Single Extremum Theorem. If f is continuous on an interval I , and f has a single local extremum (max or min), then that extremum is a global max or min.