Math 123 Problem Set 2 Due: Sunday 2/13 at 11:59 p.m. EST

Instruction: Read the homework policy. For problems 4 and 5, include printed copies of your code with your final homework submission. A simple demo MATLAB code to load images can be found in the HW2 folder on Canvas. You should submit a PDF copy of the homework and any associated codes on Gradescope. Your PDF must be a single file, not multiple images.

- **1.** Consider the following 2 by 3 matrix, $\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ -2 & 1 & 0 \end{bmatrix}$.
- (a) Find the right singular vectors i.e. eigenvectors of $\mathbf{A}^T \mathbf{A}$. Let \mathbf{V} denote the matrix of the normalized eigenvectors.
- (b) Find the singular values of A. Let Σ be a diagonal matrix that consists the singular values in the main diagonal.
- (c) Find the left singular vectors of **A**. Let **U** denote the matrix of the normalized left singular vectors.
- (d) Write the singular value decomposition (SVD) of **A** i.e. show that $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$.
- (e) Write the reduced SVD of **A**.
- (f) Using the SVD of **A**, compute $||\mathbf{A}||_2$ and $||\mathbf{A}||_F$.

[Remark: Show detailed work. You can certainly check your result numerically but no credit will be given to answers that rely on the results of numerical solvers].

- **2.** Consider the matrix $\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 20 & 0 & 0 \\ 1 & 0 & 0 & 7 \end{bmatrix}$.
- (a) Find the singular decomposition of **A**.
- (b) Express the matrix \mathbf{A} as a sum of rank 1 outer products.
- (c) What is the rank of A? Justify your answer using the SVD of A.
- (d) Let $\hat{\mathbf{A}}_1$ be the best rank-1 approximation of \mathbf{A} . Give an explicit form of $\hat{\mathbf{A}}_1$.
- (e) Let $\hat{\mathbf{A}}_2$ be the best rank-2 approximation of \mathbf{A} . Give an explicit form of $\hat{\mathbf{A}}_2$.
- (f) Compute $||\hat{\mathbf{A}}_1 \mathbf{A}||_F$ and $||\hat{\mathbf{A}}_1 \mathbf{A}||_2$.
- (g) Compute $||\hat{\mathbf{A}}_2 \mathbf{A}||_F$ and $||\hat{\mathbf{A}}_2 \mathbf{A}||_2$.

[Remark: To compute the singular value decomposition in (a), you can use any solver in MATLAB or Python].

3. The squared Frobenius norm of the m by n matrix \mathbf{A} is defined as $||\mathbf{A}||_F^2 = \sum_{i,j} a_{i,j}^2$, where $a_{i,j}$ is the (i,j)-th entry of \mathbf{A} . More compactly, $||\mathbf{A}||_F^2 = \operatorname{trace}(\mathbf{A}^T\mathbf{A})$. trace denotes the trace of a matrix defined as the sum of the diagonal values of matrix. Let $\mathbf{A} = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T$ denote the singular value decomposition of the m by n matrix \mathbf{A} of rank r.

- (a) For any m by n matrix \mathbf{X} , prove that $||\mathbf{U}\mathbf{X}||_F^2 = ||\mathbf{X}||_F^2$. [Hint: Use the definition of the Frobenius norm in terms of the trace product.]
- (b) For any m by n matrix \mathbf{Z} , prove that $||\mathbf{Z}\mathbf{V}||_F^2 = ||\mathbf{Z}||_F^2$. [Hint: Use the definition of the Frobenius norm in terms of the trace product and the cyclic property of the trace i.e. $\operatorname{trace}(\mathbf{ABC}) = \operatorname{trace}(\mathbf{BCA}) = \operatorname{trace}(\mathbf{CAB})$.]
- (c) Using the results in (a) and (b), prove that $||\mathbf{A}||_F^2 = ||\mathbf{\Sigma}||_F^2$.
- (d) Using your result in (c), prove that $||\mathbf{A}||_F^2 = \sum_{i=1}^r \sigma_i^2$.
- 4. Load the matrix A_test from the HW2 folder on Canvas. Let A denote this matrix.
- (a) Implement the power method and find the first right singular vector \mathbf{v}_1 and corresponding largest singular value σ_1 of \mathbf{A} .
- (b) Check if your result in (a) agrees with SVD of **A** obtained from a solver of your interest e.g. in MATLAB or Python.
- (c) Let **A** be a generic m by n matrix with $m \ll n$. What is the computational complexity of \mathbf{Bz} where $\mathbf{B} = \mathbf{A}^T \mathbf{A}$ and \mathbf{z} is an n-dimensional vector? What is the computational complexity of $\mathbf{A}^T(\mathbf{Az})$ i.e. computing \mathbf{Bz} in two steps by first applying \mathbf{A} and then \mathbf{A}^T ? Briefly discuss the implication of this result. [Remark: The cost of the elementary operations is assumed to be 1. For instance, the sum of two numbers a and b costs 1 i.e. the computational complexity is 1. The dot product of two n-dimensional vectors costs 2n-1 since we require n multiplications and n-1 additions.]

[Note on (c): You could ignore the cost of transposing and assume that $\mathbf{B} = \mathbf{A}^T \mathbf{A}$ is given i.e. the focus is on the cost of \mathbf{Bz} as compared to the cost of $\mathbf{A}^T(\mathbf{Az})$.]

- 5. In this problem, we apply the singular value decomposition to the image compression problem. We consider the image of the panises flower shown in Figure 1. In mathematical terms, the image is a a 1528×1225 matrix where each entry has a value from 0 to 255. The value 0 indicates black and the value 255 indicates white. The values in between represent the different intensities of gray.
- (a) In a programming language of your choice, load the image and store it as a matrix \mathbf{A} of size 1528×1225 . Compute the singular decomposition of \mathbf{A} . To compute the singular decomposition of \mathbf{A} , you can use any existing SVD algorithm. For example, in MATLAB, you can compute the SVD using $[\mathtt{U},\mathtt{S},\mathtt{V}] = \mathtt{svd}(\mathtt{A})$.
- (b) Using your result in (a), what is the rank of the matrix **A**?
- (c) Order the singular values in decreasing order and plot the values. What could you say about the decay of singular values?
- (d) Compute the truncated singular value decomposition of \mathbf{A} by considering only the first k=10 largest singular values. Let $\hat{\mathbf{A}}$ denote the resulting matrix. Show the resulting matrix $\hat{\mathbf{A}}$ as an image. Describe the quality of the image.



Figure 1: panises are not too happy about being compressed

- (e) Repeat the experiment in (d) by considering the following cases: (a) k = 25, (b) k = 50, (c) k = 100. Describe its quality of the images for each case. The image refers to the visualization of the matrix $\hat{\mathbf{A}}$.
- (f) In practice, it is important to identify a suitable truncation parameter k. Using the Eckart-Young theorem, propose a systematic way to choose k. What value do you obtain for this data?
- (g) Assume that storing a single pixel costs 1 byte of memory. How many bytes do we need to store a general $m \times n$ matrix \mathbf{A} ? Assume that \mathbf{A} is rank r. How many bytes do we need to store the reduced SVD of \mathbf{A} ? If we do truncated SVD with $k \ll r$, how many bytes do we need to store the truncated SVD? Apply your results to the panises image matrix and discuss the computational advantages of working with a truncated SVD.