Ethan J. Park

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Portfolio: ethanjpark.github.io

Education

Master of Science in Robotics, Northwestern University, Evanston, IL 2018 - 2019

Winter Project: Plume Tracing using Behavior-Based Planning in UUV Simulator

Bachelor of Science in Computer Science, Northwestern University, Evanston, IL 2014 - 2018

Relevant Coursework

Robotics Swarms and Multi-Robot Systems **Active Learning in Robotics**

Soft Robotics

Modeling and Synthesis of Cyber-Physical Systems

Connected and Autonomous Vehicles

Embedded Systems in Robotics

Robotic Manipulation

Applied Mechatronics: Quadrotors

Computer Science

Artificial Intelligence Machine Learning

Design and Analysis of Algorithms

Relevant Experience

Intern June 2019 – August 2019

Monterey Bay Aquarium Research Institute

- Created ROS simulations using the Unmanned Underwater Vehicle Simulator of collaborative, multi-AUV scenarios for MBARI's Long Range AUVs.
 - (Intern Project: Developing a Simulator for Collaborating LRAUVs)
- Boat ops: launched and retrieved long-range AUVs deployed in Monterey Bay on R/V Paragon, aided in seafloor mapping test of Dorado-class AUVs on R/V Rachel Carson.

Software Lead Sept. 2014 – June 2018

Northwestern Solar Car Team

- Implemented CAN bus communication in C/C++ between Tritium IQ battery management system, Wavesculptor 20 motor controller, and two Arduino Dues.
- Wrote and maintained Arduino driver controls code; updated and controlled vehicle state based on various pin inputs and outputs and CAN communications with multiple other nodes
- Programmed driver control panel and LCD driver display, wired to an Arduino Due.

Software Developer Intern (Remote)

May 2017 - August 2017

Skive It, Inc

- Implemented user/device data telemetry for website and mobile app in JS and PHP
- Modified video-processing engine to show real-time style and mood in video
- Tested Bluetooth communications and robot functions on Sphero robot

Skills

Programming Languages: Python, C/C++, C#, HTML, CSS, Javascript, PHP Software and Tools: ROS, MATLAB, Ubuntu/Linux, Git, LaTeX, Mathematica

Hardware: Arduino, PIC32, mechatronics

Foreign Languages: Korean (fluent), German (basic proficiency)