Ethan J. Musser

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EDUCATION

University of Pennsylvania, School of Engineering & Applied Science

Master of Science in Engineering, Robotics

Expected Graduation May 2022 GPA: 3.75/4.00

Temple University, College of Engineering

Graduated May 2020

Bachelor of Science, Mechanical Engineering

cum laude

Relevant Coursework:

o Model Predictive Control

• Robotic Manipulation

 $\circ\,$ Advanced Dynamics

o Mobile Robotics

• Nonlinear Control

• Legged Locomotion

• Autonomous Racing

Mechatronics

EXPERIENCE

Graduate Researcher

Kod*Lab (GRASP Laboratory)

March 2021 – Present Philadelphia, PA

- Design for manufacture and assembly a 13-degree-of-freedom quadrupedal robot with an actuated coronal-plane spinal rotation that can execute highly-dynamic, active-spine behaviors in challenging environments
- \circ Designed and simulated controllers for bounding and pronking gaits on an 8-degree-of-freedom quadruped in C++
- o Modeled full SolidWorks assemblies of two quadrupedal legged robots, each containing over 100 unique parts

Research Assistant

May 2019 - March 2021

Temple Robotics and Artificial Intelligence Laboratory (TRAIL)

Philadelphia, PA

- Collaborated with PI to develop an optimal, 3D quadrotor path-planner using OMPL and Google OR-Tools in ROS 1 for use in at-sea inspection of ship substructure and superstructure
- Created a follower controller that mimiced vehicle acceleration and braking profiles while following another vehicle on the Duckiebot mobile robot platform

Lead Data Acquisition Engineer

January 2019 - May 2020

Temple Formula Racing (Formula SAE Student Organization)

Philadelphia, PA

- Implemented a data acquisition unit including Hall effect sensors, strain gauges, linear potentiometers, rotary encoders, and inertial measurement units to measure parameters of vehicle steering and suspension dynamics
- Coordinated a five-member team to establish and maintain a timeline to complete a project for an external sponsor, meeting deadlines and maintaining a \$1,250 budget
- o Identified design requirements, constraints, and objectives through professional interviews and surveys

Teaching Assistant for Linear Systems & Computer-Aided Design Courses
Temple University College of Engineering

January 2019 – May 2020 Philadelphia, PA

o Developed lesson plans and instructed students as a class and through one-on-one tutoring sessions

Student Machinist

August 2018 - May 2019

Temple University College of Engineering Machine Shop

Philadelphia, PA

- o Designed and produced components for academic use, employing precise subtractive manufacturing methods
- o Provided individual and group lessons on machine operation, machining practices, and part design

Product Development Intern

May 2018 - August 2018

May 2018

Blade Diagnostics Corporation

 $Pittsburgh,\ PA$

- Designed and fabricated a testing fixture which rapidly validated the frequency response of several hundred speakers
- o Designed for manufacture and assembly components for use in an integrally bladed rotor testing platform in PTC Creo
- Collaborated with supervisors to prepare parts and bills of materials for manufacturing

TECHNICAL SKILLS

Design: SolidWorks, PTC Creo Parametric, Simulink, ANSYS Mechanical & Fluent, NI LabVIEW, Motion-

Genesis Kane, AutoCAD, Design for Manufacture & Assembly (DFMA)

Programming: Python, C++, MATLAB, Robot Operating System (ROS 1 & 2), Git, Docker, Bash, Java

Fabrication: Haas CNC Vertical Mill & Lathe, CNC Router, Manual Vertical Mill & Metalworking Lathe, Fused

Deposition Modeling (FDM) 3D Printing, TIG Welding, Carbon Fiber Layup, General Shop Tools