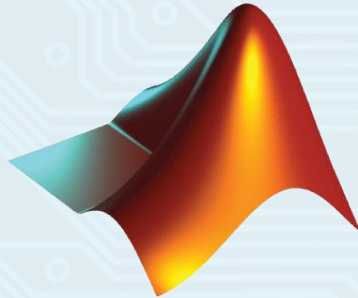


# Introduction to MATLAB



**MATLAB**

*Led by Nish, Jackie, Will, & Muchen*

```

1  b = sqrt(-1);
2
3  % RESISTOR
4  f1 = linspace(1e9, 3e9, 1000);
5  w = 2*pi.*f1;
6
7  Ca = 5e-12;
8  Cb = 1e-12;
9  R = 2000;
10 L = 50e-9;
11 ZCa = 1./(j.*w.*Ca);
12 ZCb = 1./(j.*w.*Cb);
13 ZL = j.*w.*L;
14 ZCaR = 1./(1/R + 1./Ca);
15 Ztop = 2*ZL + 2*ZCaR;
16 Ztotal_1 = 1./(1./Ztop + 1./ZCb);
17
18 figure(1)
19 plot(w,real(Ztotal_1))
20 title('Resistor Impedance v Freq (Real)')
21 xlabel('Frequency')
22 ylabel('Impedance (Real)')
23 figure(2)
24 plot(w,imag(Ztotal_1))
25 title('Resistor Impedance v Freq (Imaginary)')
26 xlabel('Frequency')
27 ylabel('Impedance (Imaginary)')
28
29 % INDUCTOR
30 f2 = linspace(1e9, 3e9, 1000);
31 w = 2*pi.*f2;
32
33 L = 30e-9;
34 Cs = 0.3e-12;
35 Rs = 0.035;
36 ZCs = 1./(j.*w.*Cs);
37 ZL = j.*w.*L;
38 ZLR = ZL + Rs;
39 Ztotal_2 = (ZLR.*ZCs)./(ZLR+ZCs);

```

# What is MATLAB?

- ▶ MATLAB (**matrix laboratory**) is a numerical computing environment and programming language
  
- ▶ MATLAB allows
  - Matrix manipulations
  - Plotting
  - Implementation of algorithms
  - Symbolic computing
  - Creation of user interfaces

# Basic Syntax

- ▶ Very similar to python
- ▶ **Operators:** = (assignment), +, -, \*, /, ^
- ▶ **Useful functions:** sqrt(), exp(), cos(), sin(), sum()
- ▶ **Constants:** pi = 3.1415..., eps = 2.2204e-16 (smallest amount by which 2 numbers can differ), inf (infinity), NaN (Not-number)
- ▶ **Logical Conditions:** ==, >, <, >=, <=, ~= (not equal), ~ (not), & (Element wise and), |(or)
- ▶ % for comments
- ▶ ; at the end of lines
- ▶ **help**

# Control Structures

## ► if

```
if(x==3)
    disp('x is 3')
elseif(x==5)
    disp('x is 5')
else
    disp('x is neither 5 nor 3')
end
```

## ► for

```
for i=start:increment:end
    loop contents
end
```

## ► while

```
while(loopCondition)
    loop contents
end
```

## ► break used to break out of loops

```
s = 0;

while 1
    if a > limit
        break
    end
    s = s + a;
end
```

# Matrices/Vectors

- ▶ Enclosed under []
- ▶ Rows separated by ;
- ▶ Columns Separated by space
- ▶ [1 2 9.3 11.2] is a row vector since it only has one row but 4 columns
- ▶ [1; 2.5; 9.3; 11.2] is a column vector since it only has one column but 4 rows
- ▶ Vector addressing done with (), so x(3) will be 3rd row of x
- ▶  $x(\text{start}:\text{increment}:\text{end})$  will give all elements starting at start skipping everything until the next increment and ending end
- ▶ Useful functions: *diag()*, *eye()* for identity matrix

```
>> [1 2.5 9.3 11.2]

ans =

    1.0000    2.5000    9.3000   11.2000

>> [1;2.5;9.3;11.2]

ans =

    1.0000
    2.5000
    9.3000
   11.2000

>> [1 2.5;9.3 11.2]

ans =

    1.0000    2.5000
    9.3000   11.2000

>>
```

# Matrices/Vectors

For the vector  $x = -4 : 2 : 10$ , use MATLAB to determine

1. `length(x)`
2. `size(x)`
3. `x'`
4. `size(x')`
5. `min(x)`
6. `max(x)`
7. `sum(x)`
8. `find(x)`
9. `find(x < 0)`
10. `find(x,3)`

# Plots

- ▶ `plot(x,y)` % plot y vs x where x and y are vectors and have equal number of elements
- ▶ Labelling can be done using `xlabel()` and `ylabel()`, `title()` (to title the graph)
- ▶ “hold on;” to draw several plots in the same window
- ▶ `figure;` to open a new window for plots/graphs
- ▶ `legend()` to add legends
- ▶ `subplot()` for subplots

# Plot Exercise

**Plot  $y(t)$**   $y(t) = 1 - e^{-t} \quad t \geq 0$

Step 1: Generate a time vector  $t$  of 1000 points uniformly spaced between 0 and 10

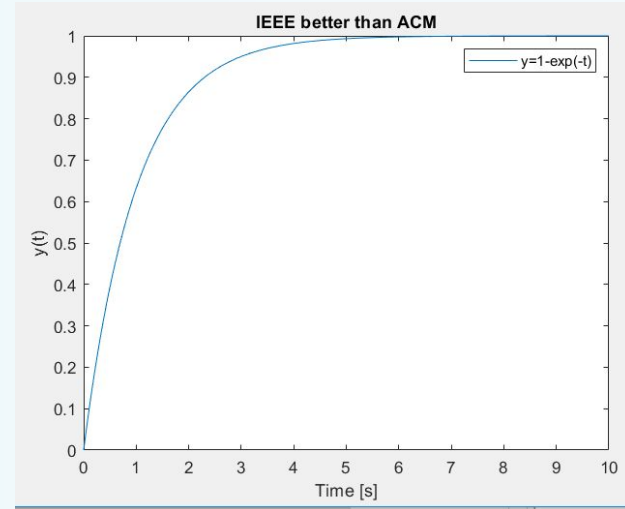
Step 2: Generate a vector  $y$  whose elements represent the values of the response at the time instants in  $t$

Step 3: Plot  $y$  versus  $t$ , and use the *legend()* to label the curve

- `plot(x,y)` % plot  $y$  vs  $x$  where  $x$  and  $y$  are vectors and have equal number of elements
- Labelling can be done using `xlabel()` and `ylabel()`, `title()` (to title the graph)
- “hold on;” to draw several plots in the same window
- `figure;` to open a new window for plots/graphs
- `legend()` to add legends
- `subplot()` for subplots

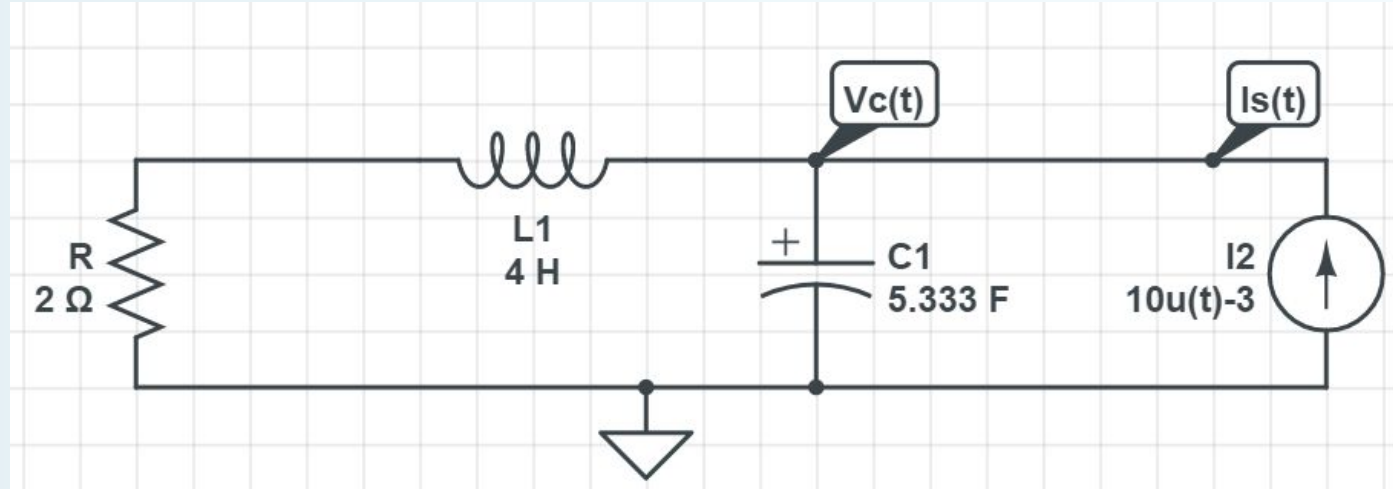


```
% plot exercise  
t=linspace(0,10,1000);  
y=1-exp(-t);  
  
figure(1)|  
plot(t,y)  
xlabel('Time [s]')  
ylabel('y(t)')  
title('IEEE better than ACM')  
legend('y=1-exp(-t)')
```



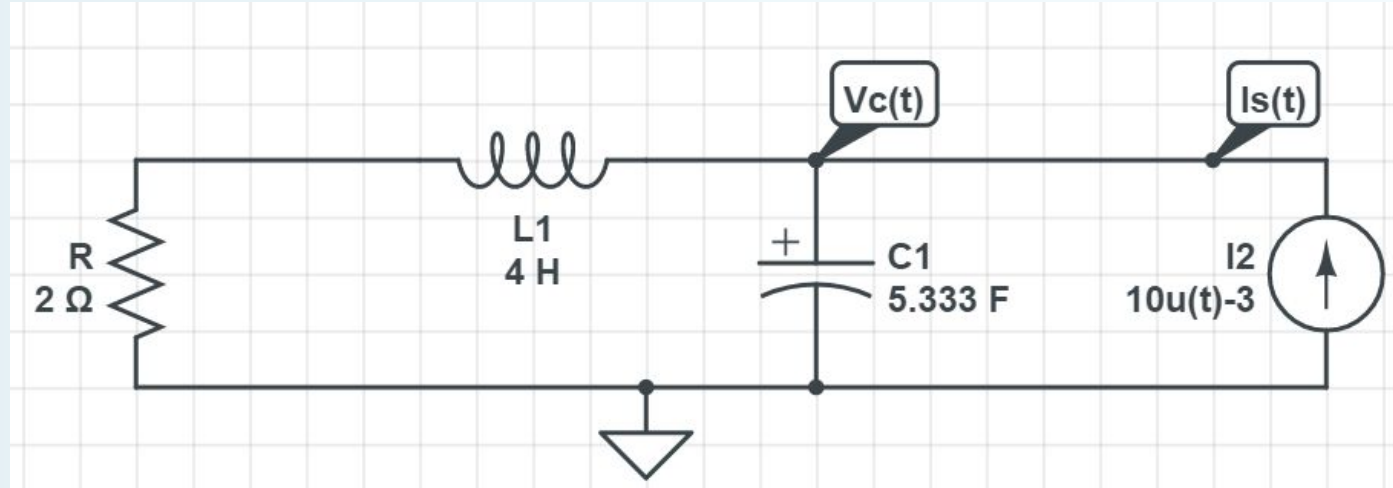
# A problem from EE 210

*Determine and Sketch  $V_c(t)$*



# A problem from EE 210

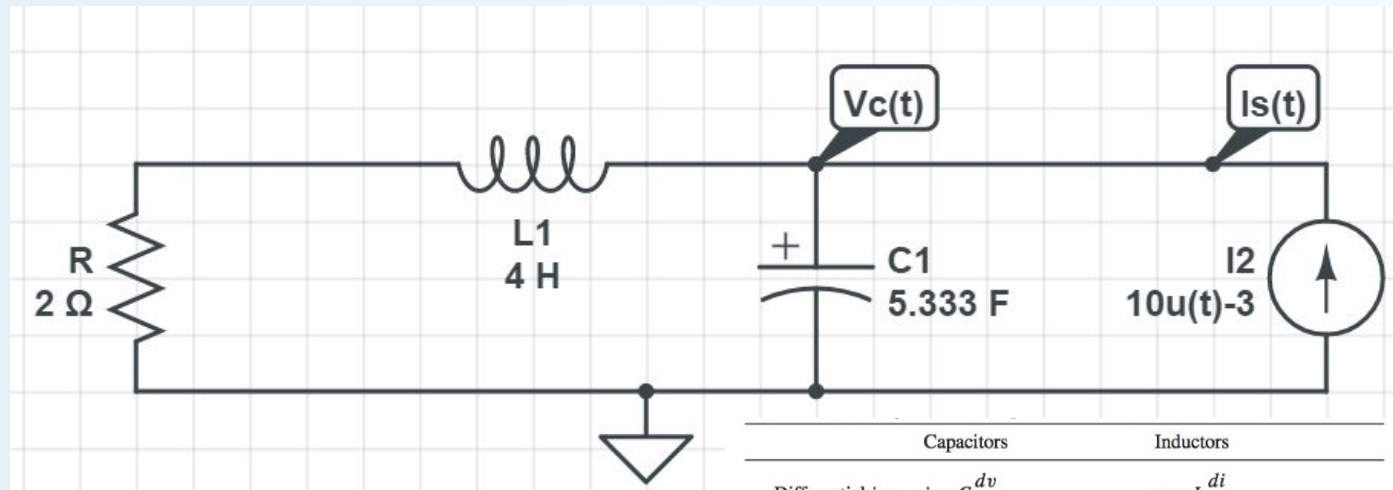
*Determine and Sketch  $V_c(t)$*



What is the general solution algorithm for driven RLC circuits with a constant source present after  $t=0$ ?

# A problem from EE 210

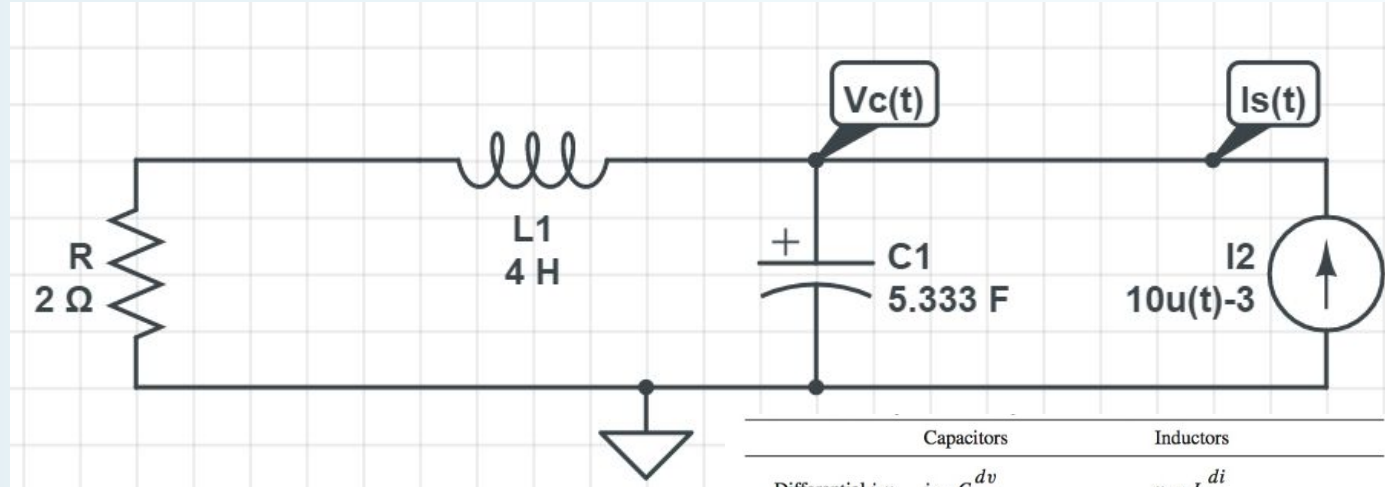
Determine and Sketch  $V_C(t)$



	Capacitors	Inductors
Differential $i-v$	$i = C \frac{dv}{dt}$	$v = L \frac{di}{dt}$
Integral $i-v$	$v_C(t) = \frac{1}{C} \int_{-\infty}^t i_C(\tau) d\tau$	$i_C(t) = \frac{1}{L} \int_{-\infty}^t v_L(\tau) d\tau$
DC equivalent	Open-circuit	Short-circuit
Two in series	$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$	$L_{eq} = L_1 + L_2$
Two in parallel	$C_{eq} = C_1 + C_2$	$L_{eq} = \frac{L_1 L_2}{L_1 + L_2}$
Stored energy	$W_C = \frac{1}{2} C v_C^2$	$W_L = \frac{1}{2} L i_L^2$

# A problem from EE 210

Determine and Sketch  $V_C(t)$



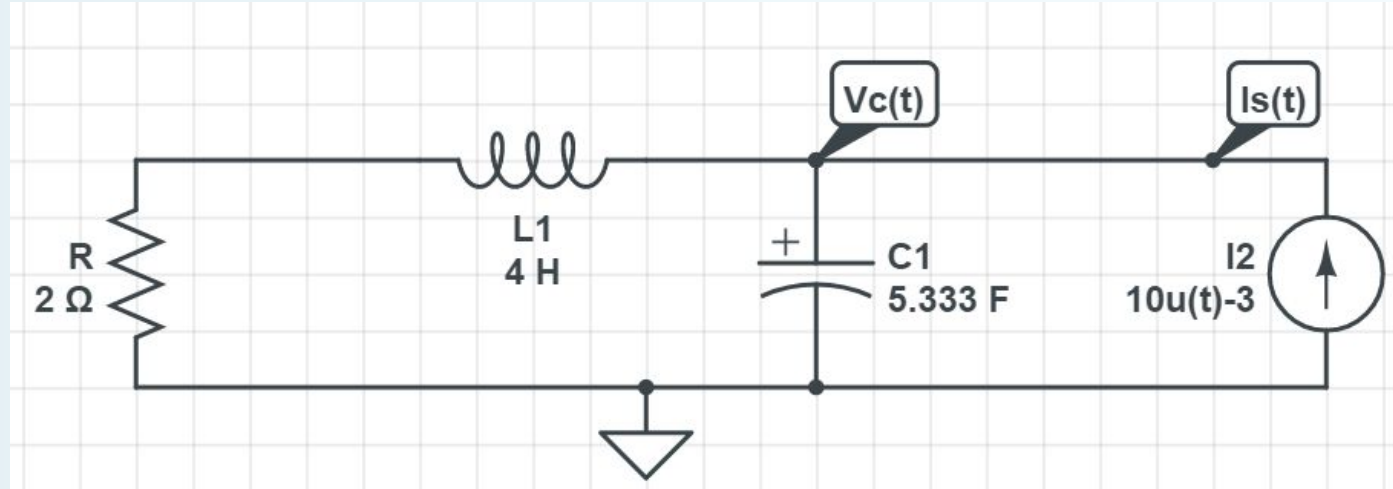
$$V_C(t) = -6 \quad t < 0$$

$$= 14 + \frac{5}{2}e^{-\frac{2t}{3}} - \frac{45}{2}e^{-\frac{t}{6}} \quad t > 0$$

	Capacitors	Inductors
Differential $i-v$	$i = C \frac{dv}{dt}$	$v = L \frac{di}{dt}$
Integral $i-v$	$v_C(t) = \frac{1}{C} \int_{-\infty}^t i_C(\tau) d\tau$	$i_L(t) = \frac{1}{L} \int_{-\infty}^t v_L(\tau) d\tau$
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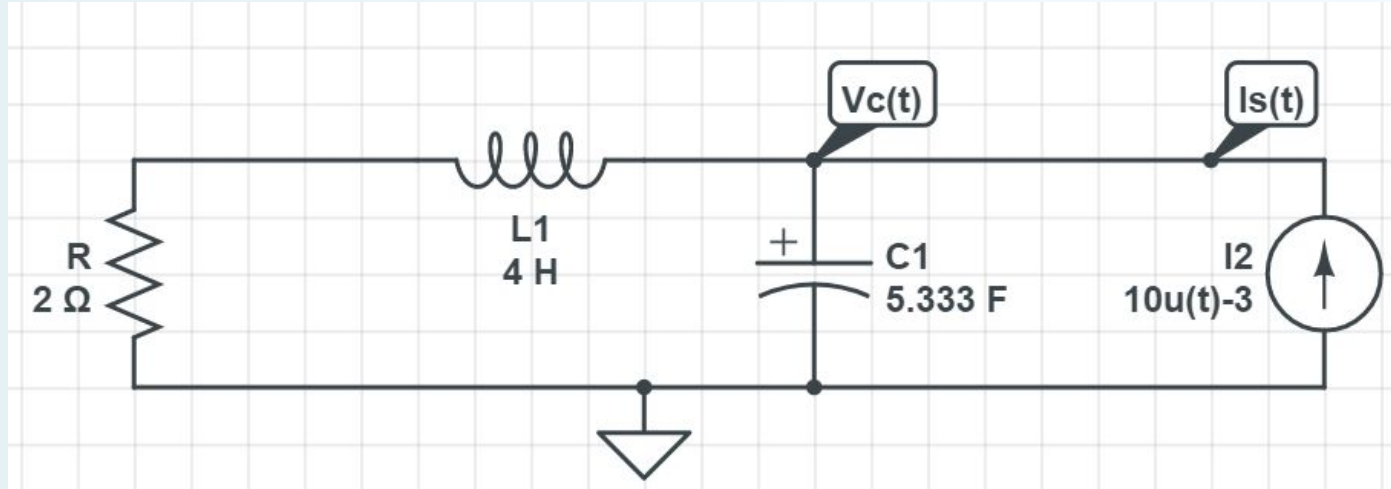
# A problem from EE 210

~~Determine and Sketch  $V_c(t)$~~



# A problem from EE 210

~~Determine and Sketch  $V_c(t)$~~



With MATLAB you can sketch without determining  $V_c(t)$ !

# A problem from EE 210

Step1: define variables R,C,L

Step2: rewrite ODE with characteristic polynomial

step3: define vectors P,Q

step4: create time vector, input vector and output vector like what we did

step5: use *lsim()* command

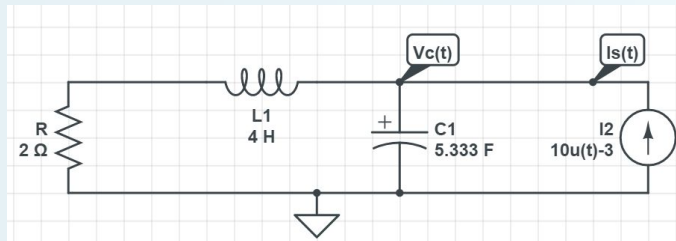
step6: just plot!

$$\frac{d^2 v_c}{dt^2} + \frac{R}{L} \frac{dv_c}{dt} + \frac{1}{LC} v_c = \frac{1}{C} \frac{di}{dt} + i \frac{R}{LC}$$

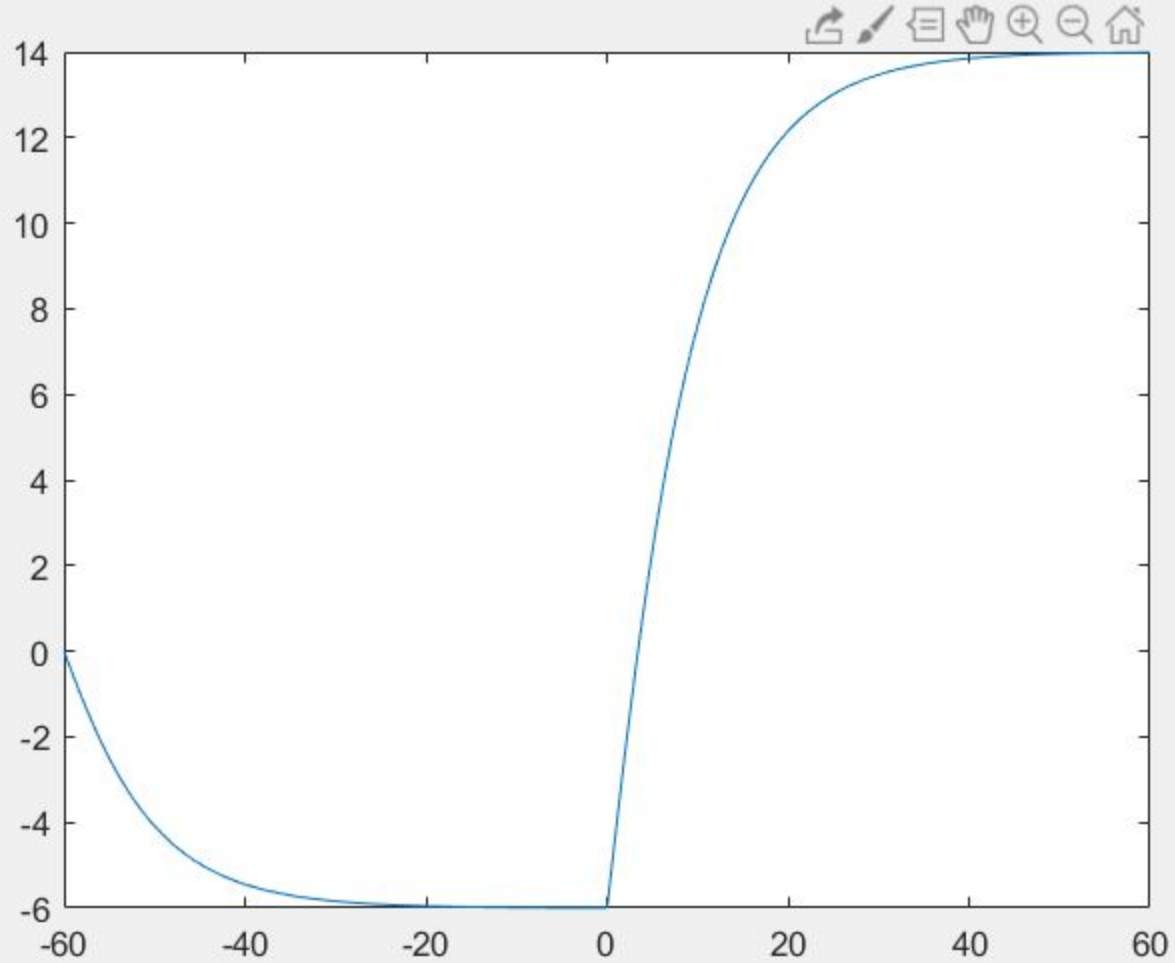
$$\left( s^2 + \frac{R}{L} s + \frac{1}{LC} \right) V = \left( \frac{1}{C} s + \frac{R}{LC} \right) I$$

$$Q = \begin{bmatrix} 1 & \frac{R}{L} & \frac{1}{LC} \end{bmatrix}$$

$$P = \begin{bmatrix} \frac{1}{C} & \frac{R}{LC} \end{bmatrix}$$







# Thanks for attending!

*See you next time!*