

# ETHAN VILLALOVOZ

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[github.com/ethanvillalovoz](https://github.com/ethanvillalovoz) | [ethanvillalovoz.com](http://ethanvillalovoz.com) | US Citizen

## EDUCATION

### Georgia Institute of Technology

Master of Science in Computer Science — GPA: 4.0/4.0

- Relevant Coursework: Robotics, Computer Graphics

Jan 2026 – Dec 2027

Atlanta, GA

### Washington State University

Bachelor of Science in Computer Science — GPA: 3.94/4.0

Aug 2021 – May 2025

Pullman, WA

## TECHNICAL SKILLS

**Languages:** Python, C/C++, SQL, JavaScript, TypeScript, HTML/CSS, C#, MATLAB, R, Haskell, Swift

**Developer Tools:** Git, GitHub, GitHub Actions, Docker, Bash, Conda, AWS, Postman, Jupyter, MLflow, DVC, MySQL

**Libraries/Frameworks:** React, Next.js, FastAPI, PyTorch, Pandas, LangChain, Hugging Face Transformers, OpenCV

## EXPERIENCE

### Microsoft

Software Engineer Intern

- Commerce and Ecosystems

May 2026 – Jul 2026

Redmond, WA

### Washington State University

Undergraduate Research Assistant

Jan 2024 – May 2025

Pullman, WA

- Executed large-scale empirical evaluations of a **Bayesian Optimization-based prompt search** method for LLM-driven code generation, measuring functional correctness across **164 HumanEval+** tasks and multiple models
- Built and ran reproducible experiment pipelines for **test-driven code synthesis**, benchmarking prompt optimization against **Chain-of-Thought** and **OPRO** baselines using pass@1 accuracy across HumanEval+ tasks
- Analyzed performance trends across optimization iterations, demonstrating **sample-efficient improvements** in code correctness through continuous embedding-space search with **Gaussian Process** surrogate models

### Carnegie Mellon University

Robotics Institute Summer Scholar

Jun 2024 – Aug 2024

Pittsburgh, PA

- Developed a novel hierarchical **reward learning framework** using **Bayesian inference** to align robotic actions with human preferences from iterative **state corrections**, significantly enhancing robot adaptability
- Implemented a **proactive clarification dialogue** system that improved task accuracy by **30%** by resolving uncertainty through targeted human queries, reducing errors and advancing interactive human-robot collaboration
- Engineered a modular, extensible **Python**-based simulation environment using **Markov Decision Processes (MDP)**, supporting robust evaluation and iterative development of learning algorithms in simulated robotics tasks

### Google

Software Engineering Intern (STEP)

May 2023 – Aug 2023

Sunnyvale, CA

- Developed and deployed **5 C++ and SQL**-based analytics jobs for internal database queue metrics, significantly reducing operational costs and enabling data-driven decision-making in collaboration with engineering stakeholders
- Optimized data sampling strategies to scale job execution from **1%** to **100%** dataset coverage within **4 hours**, achieving a **66%** reduction in runtime and improving the scalability, accuracy, and efficiency of internal analytics workflows
- Built interactive, real-time dashboards using **HTML** and **SQL**-based queries, delivering actionable insights to internal teams across engineering and operations, and enabling faster decision-making through intuitive visualizations
- Implemented live-update statistical features on client dashboards with **HTML** and database-driven queries, enhancing stakeholder visibility into queue activity, reducing detection latency, and enabling more responsive system oversight

## PUBLICATIONS

**An Exploratory Study of Bayesian Prompt Optimization for Test-Driven Code Generation with Large Language Models.** S. Tomar, A. Deshwal, [E. Villalovoz](#), M. Fazzini, H. Cai, J.R. Doppa. *arXiv*, 2025.

**Social Triangles and Aggressive Lines: Multi-Robot Formations Impact Navigation and Approach.** A. Bacula, [E. Villalovoz](#), D. Flynn, A. Mehta, H. Knight. *International Conference on Intelligent Robots and Systems (IROS)*, 2023.