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Ethan Weber

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EDUCATION

http://ethanweber.me/

Massachusetts Institute of Technology (MIT)

Cambridge, MA

Candidate for Bachelor of Science in Electrical Engineering and Computer Science • GPA: 4.8/5.0

June 2020

New Holstein High School

New Holstein, WI

• **GPA:** 4.0/4.0 • **Rank:** 1/90

Sep 2012 – May 2016

Relevant Coursework

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• Advances in Computer Vision • Machine Learning • Underactuated Robotics • Performance Engineering • Design and Analysis of Algorithms

EXPERIENCE

Research at the MIT CSAIL

Cambridge, MA

Undergraduate Researcher in the Torralba Lab

Sep 2019 - current

- Published first-author paper to ECCV 2020 on detecting natural disasters in imagery (http://incidentsdataset.csail.mit.edu/).
- Planning 3 CVPR paper submissions on (1) depth prediction with multi-view invariant constraints, (2) efficient instance segmentation dataset creation, and (3) damage assessment of imagery in the latent space.

Undergraduate Researcher in the Robot Locomotion Group

Sep 2017 - May 2019

- Created a pipeline for self-supervised instance segmentation and automatic sparse keypoint discovery for robotic manipulation. See the project at http://sparkey.xyz/ and code at https://github.com/ethanweber/sparkey.
- Worked with NASA's humanoid robot, Valkyrie and Atlas for motion planning and fall recovery. Implemented algorithms in and out of simulation. Used Drake (http://drake.mit.edu/) and collaborated with Toyota Research Institute.

Undergraduate Researcher in the Model-Based Embedded and Robotics Systems Group

Sep 2016 – Jun 2017

• Worked on using a land rover and a quadcopter in cooperation to navigate an area and perform tasks autonomously.

Dense Reconstruction for Augmented Reality

Sunnyvale, CA

Computer Vision Software Engineering Intern at Niantic, Inc.

May 2019 – Aug 2019

• Creating dense reconstruction software for real-time augmented reality applications.

Art Recommendations with the Microsoft HoloLens

Cambridge, MA

Deep Learning Intern at Microsoft

Jan 2019 - Feb 2019

• Wrote an augmented reality application for the Microsoft HoloLens to recommend art with computer vision in The Metropolitan Museum of Art. The open-sourced repo is at https://github.com/microsoft/HoloLens-Art-Recommendations.

Subject Tracking for Autonomous Quadcopters

Redwood City, CA

Deep Learning Intern at Skydio

Jun 2018 – Aug 2018

• Created and evaluated convolutional recurrent neural networks for trajectory prediction using images for semantic scene understanding.

Deep Learning and Computer Vision

Palo Alto, CA

Deep Learning Intern at The Markov Corporation

Jan 2018 – Feb 2018

• Worked on deep learning for stereo vision with computer vision algorithms in OpenCV and CNNs in Keras and TensorFlow.

Autonomous Vehicle Software Development for Volvo Cars

Detroit, MI

Summer Intern at Zenuity (Volvo / Autoliv)

Jun 2017 – Aug 2017

• Implemented computer vision algorithms, tests, and created software for autonomous valet parking.

Projects

Satellite Imagery Competition

Sep 2019 – Apr 2020

• Presented at ICLR 2020 <u>AI for Earth Sciences</u> workshop for prize-winning <u>submission</u> in the <u>xView2</u> building damage assessment comp.

Atenta: Correcting Posture with Webcams

Mar 2018 - current

• Built application to detect and correct posture with laptop webcams. See blog post here.

MIT - HackMIT 2017

Sep 2017

• Won "Best Use of Amadeus APIs" and "Best Travel Hack" for AR travel application.

University of Michigan—Ann Arbor - MHacks 6

Sep 2015

• Built project to help the visually impaired through object recognition and vibration feedback. Won "Best Use of Microsoft Technology".

LEADERSHIP

SpecialX Director

Cambridge, MA May 2018 – May 2019

• Organized VC and startup events, tech talks, an AR/VR demo day, and experiment with new ways to improve MIT's campus through tech.

• Started recurring "Conversations" event to connect like-minded students on campus over a free meal.

SKILLS

TechX

Computer: Python, PyTorch, TensorFlow, Keras, C++, C, Java, JavaScript, HTML, CSS, C#, Linux, Hardware, CAD

Activities: TechX, Jump Rope Club Co-founder, Camp Kesem Counselor, AI at MIT, Contracting, CSAIL Research, Zeta Psi Fraternity