

**ECE 102, Fall 2018**

Department of Electrical and Computer Engineering  
University of California, Los Angeles

**Midterm**

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UCLA True Bruin academic integrity principles apply.

Open: Two pages of cheat sheet allowed.

Closed: Book, computer, internet.

2:00-3:50pm.

Wednesday, 14 Nov 2018.

State your assumptions and reasoning.

No credit without reasoning.

Show all work on these pages.

Name: \_\_\_\_\_

Signature: \_\_\_\_\_

ID#: \_\_\_\_\_

Problem 1	_____	/	19
Problem 2	_____	/	17
Problem 3	_____	/	16
Problem 4	_____	/	20
Problem 5	_____	/	28
BONUS	_____	/	6 bonus points
Total	_____	/	100 points + 6 bonus points

**Problem 1** (19 points)

(a) (9 points) Determine if each of the following statements is true or false. Briefly explain your answer to receive full credit.

- i. (3 points) If  $x(t)$  is an energy signal, then  $y(t) = x(t) + 1$  is also an energy signal.

**Solution:** False

$x(t) + 1$  is not an energy signal, adding a constant to a signal will in general make its energy go to infinity. Consider for instance the finite energy signal:  $x(t) = e^{-t}u(t)$ , then

$$\int_{-\infty}^{+\infty} |x(t) + 1|^2 dt = \int_{-\infty}^{+\infty} (x^2(t) + 2x(t)) dt + \int_{-\infty}^{+\infty} 1 dt = \frac{1}{2} + 2 + \infty$$

Therefore,  $x(t) + 1$  is not an energy signal.

- ii. (3 points) If  $x(t)$  is an even signal, then  $y(t) = x(t - 1)$  is also an even signal.

**Solution:** False

Consider for instance the unit triangle  $x(t) = \Delta(t)$ , which is an even function. However, shifting the unit triangle to the right by one will make it defined only over  $t \geq 0$ , we then obtain  $x(t - 1) = \Delta(t - 1)$ , which is not even.

- iii. (3 points) If the input to an LTI system is periodic, then its output is also periodic.

**Solution:** True

If the input is periodic, then it can be written as:

$$x(t) = \sum_{k=-\infty}^{\infty} c_k e^{j\omega_0 kt}$$

where  $c_k$ 's are the Fourier series coefficients of  $x(t)$ . Then using the eigenfunction property, we obtain the corresponding output:

$$y(t) = \sum_{k=-\infty}^{\infty} \alpha_k c_k e^{j\omega_0 kt}$$

where  $\alpha_k$  is the eigenvalue that corresponds to  $e^{j\omega_0 kt}$ . Therefore,  $y(t)$  is also periodic.

- (b) (10 points) Is the following system linear? Is it time invariant? (Check both properties). Explain your answer.

$$y(t) = \begin{cases} x(t-1), & t \geq 1 \\ 0, & \text{otherwise} \end{cases}$$

**Solutions:** We can equivalently write the system as follows:

$$y(t) = x(t-1)u(t-1)$$

**Linearity:** Suppose to inputs  $x_1(t)$  and  $x_2(t)$ , we respectively get  $y_1(t)$  and  $y_2(t)$  as outputs. Now if we consider the following input  $x_3(t) = ax_1(t) + bx_2(t)$ , then its output:

$$y_3(t) = x_3(t-1)u(t-1) = (ax_1(t-1)u(t-1) + bx_2(t-1)u(t-1)) = ay_1(t) + by_2(t)$$

The system is then linear.

**Time Invariant:**

If we delay the input by  $\tau$ , i.e.  $x_\tau(t) = x(t-\tau)$ , the output is then:

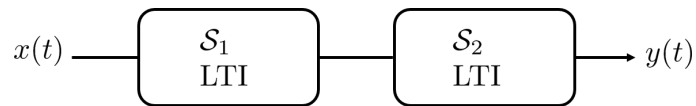
$$y_\tau(t) = x_\tau(t-1)u(t-1) = x(t-1-\tau)u(t-1)$$

Now if we delay the output, we get:

$$y(t-\tau) = x(t-\tau-1)u(t-\tau-1)$$

Since  $y(t-\tau) \neq y_\tau(t)$ , the system is not time-invariant.

**Problem 2** (17 points) Consider the series cascade of the following two systems:



The system  $\mathcal{S}_1$  is LTI with impulse response

$$h_1(t) = \int_{-\infty}^t u(\tau) \delta(\tau - 2) d\tau$$

The system  $\mathcal{S}_2$  is also LTI, with unknown impulse response  $h_2(t)$  that we need to find. We are also given that, when the input  $x(t)$  is  $\delta(t)$ , the output  $y(t)$  is  $r(t - 3) + u(t - 2)$ .

*Note:  $r(t - 3)$  is the ramp function delayed by 3.*

This question continues on the next page.

- (a) (11 points) Find the impulse response  $h_2(t)$  of the system  $\mathcal{S}_2$  **and** determine if the system  $\mathcal{S}_2$  is causal.

**Solution:**

We first simplify the impulse response of the first system:

$$h_1(t) = \int_{-\infty}^t u(\tau)\delta(\tau-2)d\tau = \int_{-\infty}^t u(2)\delta(\tau-2)d\tau = \int_{-\infty}^t \delta(\tau-2)d\tau = u(t-2)$$

The impulse response of overall system is given by:

$$h_{eq}(t) = r(t-3) + u(t-2)$$

This is because it is given as the output of the overall system when the input is  $\delta(t)$ .

When the input is  $x(t) = \delta(t)$ , the intermediate signal between the two systems is the output of  $\mathcal{S}_1$  to the input  $\delta(t)$ . Therefore, the intermediate signal in this case is:  $h_1(t) = u(t-2)$ . Therefore, we have the following for system  $\mathcal{S}_2$ :

$$\text{Input: } u(t-2) \xrightarrow{\mathcal{S}_2} \text{output: } r(t-3) + u(t-2)$$

Since  $\mathcal{S}_2$  is LTI, we can deduce its step response (by shifting the output to the left by 2):

$$\text{Input: } u(t) \xrightarrow{\mathcal{S}_2} \text{output: } r(t-1) + u(t)$$

Therefore, the step response of  $\mathcal{S}_2$  is:

$$r(t-1) + u(t)$$

Thus, the impulse response of  $\mathcal{S}_2$  is:

$$h_2(t) = \frac{d}{dt}(r(t-1) + u(t)) = u(t-1) + \delta(t)$$

Since  $h_2(t) = 0$  for  $t < 0$ , the LTI system  $\mathcal{S}_2$  is causal.

*Note: We received answers like this: because in  $h_2(t)$  we have  $t-1$  in  $u(t-1)$  and  $t$  in  $\delta(t)$ , the system then depends on past and present values of the input, then it is causal. This is not a right justification, because  $h_2(t)$  is not the input-output relationship of the system, we used that justification when we have the mapping from the input to output. However, We can using  $h_2(t)$  represent the system in terms of its input-output mapping through convolution:*

$$y(t) = h_2(t) * z(t) = \int_{-\infty}^{\infty} h_2(\tau)z(t-\tau)d\tau$$

*where  $z(t)$  is the input to the second system. Now we check if  $y(t)$  depends on past values of input by checking the arguments of  $z$ . We have  $y(t)$  depends on  $z(t-\tau)$  and because  $h_2(\tau)$  is zero for  $\tau < 0$ ,  $\tau$  will always be positive so that  $z(t-\tau)$  will always be a past value of input for  $y(t)$ . This is why we can say that the system is causal.*

(b) (6 points) Find the output  $y(t)$  to the following input:

$$x(t) = (1 + e^{-t})\delta(t + 1)$$

**Solution:**

Using the sampling property, we can simplify  $x(t)$  as follows:

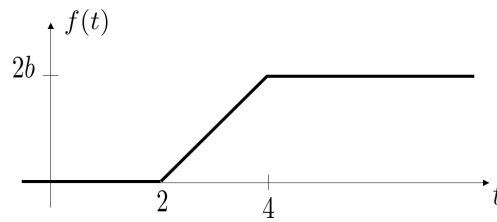
$$x(t) = (1 + e^{-t})\delta(t + 1) = (1 + e)\delta(t + 1)$$

Then,

$$\begin{aligned} y(t) &= h_{eq}(t) * x(t) \\ &= (r(t - 3) + u(t - 2)) * ((1 + e)\delta(t + 1)) = (1 + e)(r(t - 3 + 1) + u(t - 2 + 1)) \\ &= (1 + e)(r(t - 2) + u(t - 1)) \end{aligned}$$

**Problem 3** (16 points)

(a) (8 points) Consider the signal  $f(t)$  shown below:



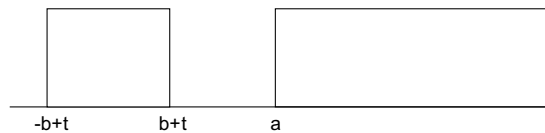
This signal can be written as

$$u(t - a) * \text{rect}\left(\frac{t}{2b}\right)$$

where  $a > 0$  and  $b > 0$ . Find  $a$  and  $b$ . (Hint: use the flip and drag technique.)

**Solution:**

Using the flip and drag technique, we have:



$f(t) = 0$  when there is no overlap, i.e., when  $b + t < a$  or  $t < a - b$ . We have  $f(t) = 0$  for  $t < 2$ , therefore

$$a - b = 2$$

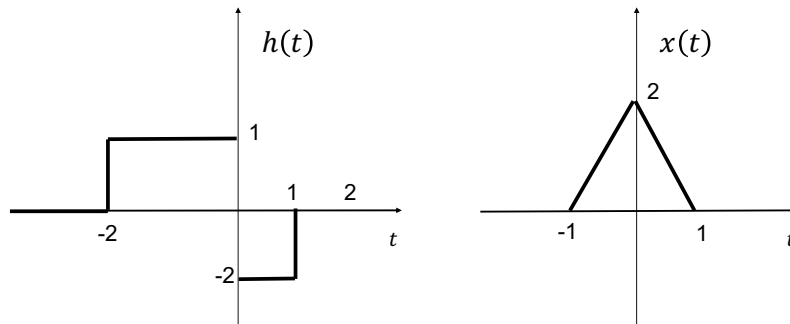
The total overlap happens when  $-b + t > a$  or  $t > a + b$ . The function  $f(t)$  reaches its maximum at  $2b$  and stays at this value for  $t > 4$ , thus

$$a + b = 4$$

Solving two equation, we get  $a = 3$  and  $b = 1$ .



- (b) (8 points) An input,  $x(t)$ , is given to an LTI system with impulse response  $h(t)$ . Both  $x(t)$  and  $h(t)$  are shown below.



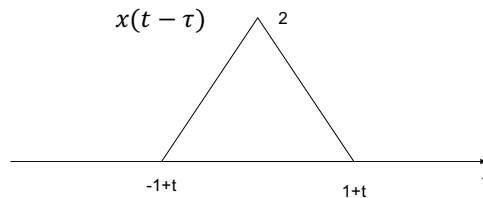
Let  $y(t)$  denote the output of the system, i.e.,  $y(t) = x(t) * h(t)$ . Find the value of  $t$  at which the output  $y(t)$  reaches its maximum value. Determine this maximum value.

*Note: to answer this question, you do **not** need to find  $y(t)$  for all  $t$ .*

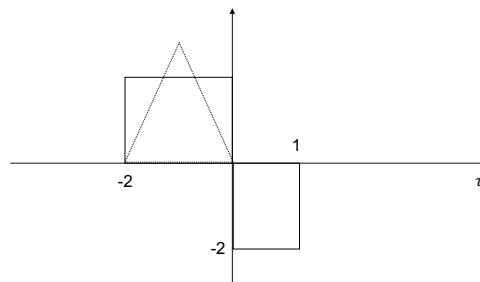
**Solution:**

We know that

$$y(t) = \int_{-\infty}^{+\infty} h(\tau)x(t - \tau)d\tau$$



The maximum value of  $y(t)$  happens when the triangle totally overlaps with the rectangle part of  $h(t)$  that only has positive values, as shown here:



This happens when  $1 + t = 0$  therefore,  $t = -1$ . In this case, the maximum value is the area of the triangle is:

$$y(-1) = \frac{2 \times 2}{2} = 2$$

**Problem 4** (20 points)

Consider the following two periodic signals  $f(t)$  and  $g(t)$ . They both have the same period  $T_0$ . Let  $f_k$  and  $g_k$  respectively denote the Fourier series coefficients of  $f(t)$  and  $g(t)$ .

- (a) (6 points) If  $f(t) = -g\left(t + \frac{T_0}{2}\right)$ , how is  $f_k$  related to  $g_k$ ?

**Solution:** We have:

$$f(t) = \sum_{k=-\infty}^{+\infty} f_k e^{j\omega_0 k t} \quad \text{and,} \quad g(t) = \sum_{k=-\infty}^{+\infty} g_k e^{j\omega_0 k t}$$

Now, if  $f(t) = -g\left(t + \frac{T_0}{2}\right)$ , then

$$\begin{aligned} f(t) &= -g\left(t + \frac{T_0}{2}\right) \\ &= \sum_{k=-\infty}^{+\infty} -g_k e^{j\omega_0 k \left(t + \frac{T_0}{2}\right)} \\ &= \sum_{k=-\infty}^{+\infty} -g_k e^{j\omega_0 k \frac{T_0}{2}} e^{j\omega_0 k t} \\ &= \sum_{k=-\infty}^{+\infty} -g_k e^{j \frac{2\pi}{T_0} k \frac{T_0}{2}} e^{j\omega_0 k t} \\ &= \sum_{k=-\infty}^{+\infty} -g_k e^{j\pi k} e^{j\omega_0 k t} = \sum_{k=-\infty}^{+\infty} -g_k (-1)^k e^{j\omega_0 k t} \\ &= \sum_{k=-\infty}^{+\infty} f_k e^{j\omega_0 k t} \end{aligned}$$

Therefore,

$$f_k = -(-1)^k g_k$$

(b) (6 points) If  $f(t) = -f\left(t + \frac{T_0}{2}\right)$ , for what  $k$  are the coefficients  $f_k$  zero?

**Solution:** If  $f(t) = -f\left(t + \frac{T_0}{2}\right)$ , Then using the previous conclusion, we have:

$$f_k = -(-1)^k f_k$$

Therefore, for even  $k$ :

$$f_k = -f_k \rightarrow f_k = 0$$

(c) (8 points) This question has two parts. *Note: part (c) is independent of parts (a) and (b).*

- i. (4 points) Let  $f_e(t)$  denote the even part of  $f(t)$ . Express the Fourier series coefficients of  $f_e(t)$  in terms of  $f_k$ .

**Solution:**

The even part of the signal is:  $f_e(t) = \frac{f(t) + f(-t)}{2}$ ,  $f(-t)$  is also periodic we thus have:

$$\begin{aligned} f_e(t) &= \frac{f(t) + f(-t)}{2} \\ &= \frac{\sum_{k=-\infty}^{+\infty} f_k e^{j\omega_0 kt} + \sum_{k=-\infty}^{+\infty} f_k e^{-j\omega_0 kt}}{2} \\ &= \frac{1}{2} \left( \sum_{k=-\infty}^{+\infty} f_k e^{j\omega_0 kt} + \sum_{k=-\infty}^{+\infty} f_{-k} e^{j\omega_0 kt} \right) \\ &= \frac{1}{2} \sum_{k=-\infty}^{+\infty} (f_k + f_{-k}) e^{j\omega_0 kt} \\ &= \sum_{k=-\infty}^{+\infty} \frac{1}{2} (f_k + f_{-k}) e^{j\omega_0 kt} \end{aligned}$$

Therefore, the Fourier series coefficients of  $f_e(t)$  is  $\frac{1}{2}(f_k + f_{-k})$ .

- ii. (4 points) Determine the DC component of  $f_o(t)$ , the odd part of  $f(t)$ .

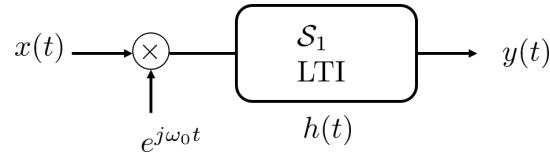
**Solution:** The Fourier coefficients of the odd part of the signal is  $f_{o,k} = \frac{1}{2}(f_k - f_{-k})$ .

Therefore at  $k = 0$ ,  $f_{o,0} = \frac{1}{2}(f_0 - f_{-0}) = 0$ .

In fact, any odd signal has zero DC component.

**Problem 5** (28 points)

Consider the following system ( $\omega_0 > 0$ ):



The system  $\mathcal{S}_1$  is LTI and  $h(t)$  represents its impulse response.

- (a) (10 points) Show that the overall system, with input  $x(t)$  and output  $y(t)$ , is not time-invariant.

**Solution:** The input-output relationship of the system is given by:

$$y(t) = [e^{j\omega_0 t} x(t)] * h(t) = \int_{-\infty}^{+\infty} h(\tau) e^{j\omega_0(t-\tau)} x(t-\tau) d\tau = e^{j\omega_0 t} \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega_0 \tau} x(t-\tau) d\tau$$

If we delay the input, i.e.,  $x_\alpha(t) = x(t - \alpha)$ , the corresponding output is:

$$y_\alpha(t) = e^{j\omega_0 t} \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega_0 \tau} x_\alpha(t-\tau) d\tau = e^{j\omega_0 t} \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega_0 \tau} x(t-\alpha-\tau) d\tau$$

On the other hand, if we shift the output, we have:

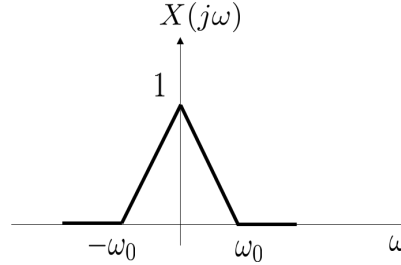
$$y(t - \alpha) = e^{j\omega_0(t-\alpha)} \int_{-\infty}^{+\infty} h(\tau) e^{-j\omega_0 \tau} x(t-\alpha-\tau) d\tau$$

Since  $y(t - \alpha) \neq y_\alpha(t)$ , the system is not TI.

(b) (12 points) Consider the following impulse response for system  $S_1$ :

$$h(t) = e^{j\frac{\omega_0}{2}t} \text{sinc}\left(\frac{\omega_0}{2\pi}t\right)$$

We give the system an input  $x(t)$ , where  $x(t)$  has the following Fourier transform  $X(j\omega)$ :



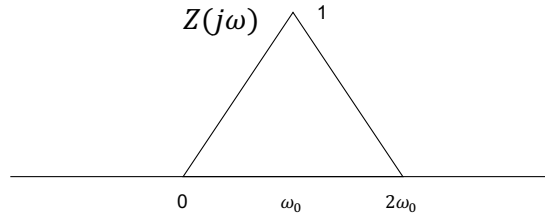
Find and sketch the Fourier transform  $Y(j\omega)$  of the corresponding output  $y(t)$ . After this, determine (i) if  $y(t)$  is real and (ii) if  $y(t)$  is even. *Note: you do not need to give an expression for  $Y(j\omega)$ , a sketch of it is enough. There is some space on the next page if needed.*

**Solution:**

If  $z(t) = x(t)e^{j\omega_0 t}$ , then using the Fourier transform properties, we have:

$$Z(j\omega) = X(j(\omega - \omega_0))$$

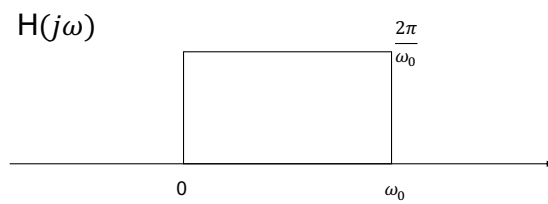
Here is a sketch of  $Z(j\omega)$ :



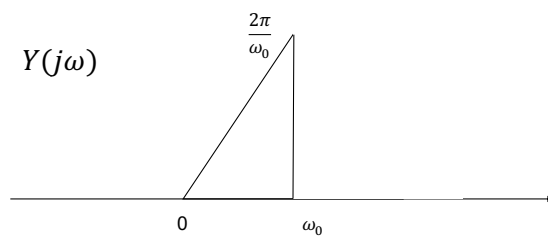
Now using the properties we find the Fourier transform of  $h(t)$ ,

$$\begin{aligned} \text{sinc}(t) &\longleftrightarrow \text{rect}\left(\frac{\omega}{2\pi}\right) \\ \text{sinc}\left(\frac{\omega_0}{2\pi}t\right) &\longleftrightarrow \frac{2\pi}{\omega_0} \text{rect}\left(\frac{\omega}{2\pi} \cdot \frac{2\pi}{\omega_0}\right) \\ e^{j\frac{\omega_0}{2}t} \text{Sinc}\left(\frac{\omega_0}{2\pi}t\right) &\longleftrightarrow \frac{2\pi}{\omega_0} \text{rect}\left(\frac{\omega - \frac{\omega_0}{2}}{\omega_0}\right) \end{aligned}$$

Therefore,  $H(j\omega)$  is as follows:



Since  $y(t) = h(t) * z(t)$ , therefore  $Y(j\omega) = H(j\omega)X(j\omega)$ . Therefore,



Since  $Y^*(j\omega) \neq Y(-j\omega)$ ,  $y(t)$  is not real.

Since  $Y(j\omega)$  is not even,  $y(t)$  is not even.

(c) (6 points) Suppose

$$z(t) = y(3t - 2)$$

Express  $Z(j\omega)$  in terms of  $Y(j\omega)$ . *Note: part (c) is independent of parts (a) and (b).*

**Solution:**

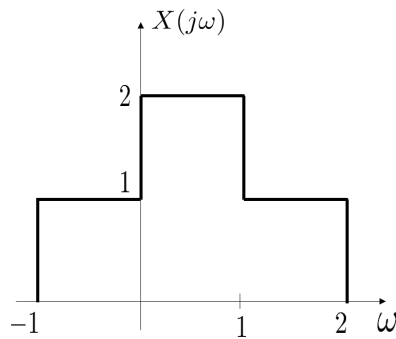
Using the properties:

$$\begin{aligned}y(t) &\longleftrightarrow Y(j\omega) \\y(3t) &\longleftrightarrow \frac{1}{3}Y\left(\frac{j\omega}{3}\right) \\y\left(3\left(t - \frac{2}{3}\right)\right) &\longleftrightarrow \frac{1}{3}e^{-j\frac{2}{3}\omega}Y\left(\frac{j\omega}{3}\right)\end{aligned}$$



**BONUS** (6 points)

(a) (4 points) The Fourier transform  $X(j\omega)$  of a signal  $x(t)$  is given as follows:



Find the phase of  $x^2(t)$ .

**Solution:**

Let  $F(j\omega) = X(j(\omega + \frac{1}{2}))$ . Thus,  $F(j\omega)$  is real and even. Therefore,

$$f(t) = e^{-jt\frac{1}{2}}x(t)$$

is a real function. Thus,

$$x(t) = e^{jt\frac{1}{2}}f(t)$$

and,

$$x^2(t) = e^{jt}f^2(t)$$

Therefore the phase of  $x^2(t)$  is  $t$ .

- (b) (2 points) If a signal  $x(t)$  is causal with  $x(0) = 0$ , how can we retrieve  $x(t)$  from its even component  $x_e(t)$ ?

**Solution:**

Since this signal is causal, therefore:

$$x(t) = 0, \text{ for } t < 0$$

$$x_e(t) = \frac{x(t) + x(-t)}{2} = \begin{cases} \frac{x(-t)}{2}, & t < 0 \\ \frac{x(t)}{2}, & t > 0 \end{cases}$$

Therefore,

$$x(t) = 2x_e(t), \text{ for } t > 0$$

and

$$x(t) = 0, \text{ for } t \leq 0$$

# Fourier Transform Tables

Property	Signal	Transform
Linearity	$\alpha x_1(t) + \beta x_2(t)$	$\alpha X_1(j\omega) + \beta X_2(j\omega)$
Duality	$X(t)$	$2\pi x(-\omega)$
Conjugate symmetry	$x(t)$ real	$X^*(j\omega) = X(-j\omega)$ Magnitude: $ X(-j\omega)  =  X(j\omega) $ Phase: $\Theta(-\omega) = -\Theta(\omega)$ Real part: $X_r(-j\omega) = X_r(j\omega)$ Imaginary part: $X_i(-j\omega) = -X_i(j\omega)$
Conjugate antisymmetry	$x(t)$ imaginary	$X^*(j\omega) = -X(-j\omega)$ Magnitude: $ X(-j\omega)  =  X(j\omega) $ Phase: $\Theta(-\omega) = -\Theta(\omega) \mp \pi$ Real part: $X_r(-j\omega) = -X_r(j\omega)$ Imaginary part: $X_i(-j\omega) = X_i(j\omega)$
Even signal	$x(-t) = x(t)$	$X(j\omega)$ : even
Odd signal	$x(-t) = -x(t)$	$X(j\omega)$ : odd
Time shifting	$x(t - \tau)$	$X(j\omega) e^{-j\omega\tau}$
Frequency shifting	$x(t) e^{j\omega_0 t}$	$X(j(\omega - \omega_0))$
Modulation property	$x(t) \cos(\omega_0 t)$	$\frac{1}{2} [X(j(\omega - \omega_0)) + X(j(\omega + \omega_0))]$
Time and frequency scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$
Differentiation in time	$\frac{d^n}{dt^n} [x(t)]$	$(j\omega)^n X(j\omega)$
Differentiation in frequency	$(-jt)^n x(t)$	$\frac{d^n}{d\omega^n} [X(j\omega)]$
Convolution	$x_1(t) * x_2(t)$	$X_1(j\omega) X_2(j\omega)$
Multiplication	$x_1(t) x_2(t)$	$\frac{1}{2\pi} X_1(j\omega) * X_2(j\omega)$
Integration	$\int_{-\infty}^t x(\lambda) d\lambda$	$\frac{X(j\omega)}{j\omega} + \pi X(0) \delta(\omega)$
Parseval's theorem	$\int_{-\infty}^{\infty}  x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(j\omega) ^2 d\omega$	

**Table 4.4** – Fourier transform properties.

Additional properties:	$x(t)$ : even and real	$X(j\omega)$ : even and real
	$x(t)$ : odd and real	$X(j\omega)$ : odd and imaginary
	$x(t)$ : even and imaginary	$X(j\omega)$ : even and imaginary
	$x(t)$ : odd and imaginary	$X(j\omega)$ : odd and real

Name	Signal	Transform
Rectangular pulse	$x(t) = A \text{rect}(t/\tau)$	$X(j\omega) = A\tau \text{sinc}\left(\frac{\omega\tau}{2\pi}\right)$
Triangular pulse	$x(t) = A \Lambda(t/\tau)$	$X(j\omega) = A\tau \text{sinc}^2\left(\frac{\omega\tau}{2\pi}\right)$
Right-sided exponential	$x(t) = e^{-at} u(t)$	$X(j\omega) = \frac{1}{a + j\omega}$
Two-sided exponential	$x(t) = e^{-a t }$	$X(j\omega) = \frac{2a}{a^2 + \omega^2}$
Signum function	$x(t) = \text{sgn}(t)$	$X(j\omega) = \frac{2}{j\omega}$
Unit impulse	$x(t) = \delta(t)$	$X(j\omega) = 1$
Sinc function	$x(t) = \text{sinc}(t)$	$X(j\omega) = \text{rect}\left(\frac{\omega}{2\pi}\right)$
Constant-amplitude signal	$x(t) = 1, \text{ all } t$	$X(j\omega) = 2\pi \delta(\omega)$
	$x(t) = \frac{1}{\pi t}$	$X(j\omega) = -j \text{sgn}(\omega)$
Unit-step function	$x(t) = u(t)$	$X(j\omega) = \pi \delta(\omega) + \frac{1}{j\omega}$
Modulated pulse	$x(t) = \text{rect}\left(\frac{t}{\tau}\right) \cos(\omega_0 t)$	$X(j\omega) = \frac{\tau}{2} \text{sinc}\left(\frac{(\omega - \omega_0)\tau}{2\pi}\right) + \frac{\tau}{2} \text{sinc}\left(\frac{(\omega + \omega_0)\tau}{2\pi}\right)$

Note:

$$\text{sinc}(\alpha) = \frac{\sin(\pi\alpha)}{\pi\alpha}$$

$$\text{rect}(t/\tau) = u(t + \tau/2) - u(t - \tau/2)$$

**Table 4.5** – Some Fourier transform pairs.