1		Ethan Wong
	ECE 102 HW3	
1. a)	y(+) = cos(+)x(+)	
	Try with 2 inputs, 2 respective outputs	
	$Y_{a}(t) = cos(t) x_{a}(t)$ $Y_{b}(t) = cos(t) x_{b}(t)$	
	$x(t) = d_1 x_a(t) + d_2 x_b(t)$	
	y(t) = d, cos(t) xa(t) - dz cos(t) xb(t)	
	y(+) = d, xa(+) + dz x b(+) [linear]	
7)	$y(t) = \frac{\partial}{\partial t} \left( \frac{1}{2} x(t)^2 \right)$	
	$\lambda(+) = x(+) \cdot \frac{9+}{9}x(+)$	
	modify the input and plug in	
	$\lambda^{5}(+) = \left[ \alpha x(+) \right] \cdot \frac{9+}{9} \left[ \alpha x(+) \right]$	
	$\forall z(t) = a[ax(t)] \cdot f[x(t)]$	
	[a2. y(t)] = [a. y(t)] No homogeneity -> [not 1]	near
c)	y(t) = ex(+)	(%)
	Modify the input and plug in  y,(t) = e dixa(t) = dz x s(t)	
	$Y_{i}(t) = e^{-t}$	
	$y_i(t) = [e^{d_i x_a(t)}] \cdot [e^{d_2 x_b(t)}]$ $y_i(t) \neq d_1 e^{x_i(t)} + d_2 e^{x_b(t)}$ Not equivalent $\rightarrow$ [not linear	
	y(t) 7 die 4 dze Not equilatent prot mear	
1/	y(t) = x(t) + 2a(t-1)	
0()	Modify the input and plug in	
	Y1(+) = [ax(+)] + 2a(+11)	
	Y.(+) = a(y(+)) No homogenesty > [not linear	1
2. a)	Express x2(t) and y2(t) in terms of x.(t) and y.(t) resp	pectively
	$X_2(t) = X_1(t) + X_1(t+1)$	
	42(+) = 4,(+) + 4,(++1)	
	X2(4) 157 12(4) 37	
	1.5	
	0.5	
	-1 1 2 3 4 -1 1 2 3 4 4	

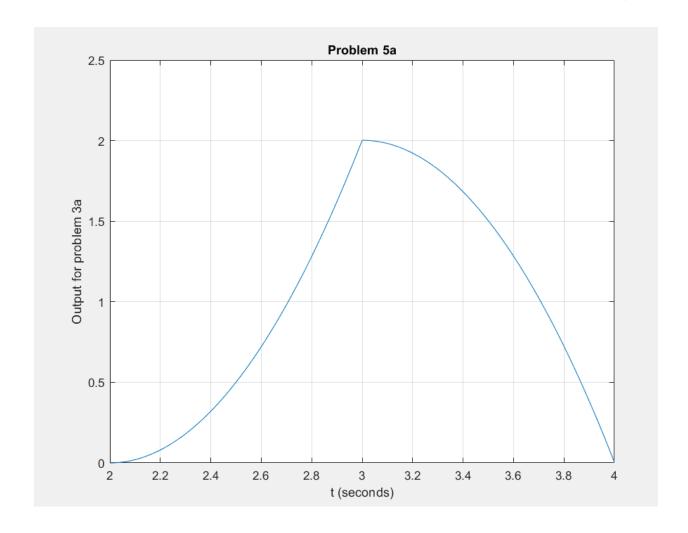
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6)
        Y1(+) = cos(+) w(+) when x1(+) = w(+)
        Yz(+) = cos(+)(a(++1)-u(+)) when xz(+)=rec+(++1)
                                            OR Xz(+) = u(++1) - u(+)
        Combine both scenarious and use properties of linearity
         Say: Xa(+) = X1(+) + X2(+)
              X_{\alpha}(+) = u(++1) \longrightarrow X_{\alpha}(+) = X_{\alpha}(++1)
         Plug new combined input in to receive new output
         Ya(+) = [cos(+):u(+)] + [cos(+) (a(++1) -u(+))]
         Yalt) = cos(+) u(++1)
              Xa(t) = x. (++1) -> Ya(t) = cos(t) u(+1) 7 not
              X_1(t+1) = X_1(t+1) \longrightarrow \cos(t+1) u(t+1) \rightarrow equivalent
        The time shift in the input does not produce an rolentical
           shift in the output | Not time - invariant
        i) f(+) = 2(++1) + 22(+-2) a(+) = e + u(+)
3. a)
           y(+) =[d(++1)+2d(+-2)] * [e+u(+)]
          \gamma(t) = [\partial(t+1) + e^{-t}u(t)] + [2\partial(t-2) + e^{-t}u(t)]

\gamma(t) = [e^{-t-1}u(t+1)] + [2e^{-t+2}u(t-2)]
        ii) f(t) = 2 rect (t - 3) g(t) = 2 r(t-1) rect (t - 3)
           y(t) = [2rect(t-\frac{3}{2})] + [2r(t-1)rect(t-\frac{3}{2})]
           y(t) = 5-00 9(T) f(+-T)OT
        Use intervals += 2, 2 c+ = 3, 3 c+ = 4, + > 4
                 19(2) f(1-2)
                                                1 glasfet-al
         + 47
        Z4+3 Po(T) f(+-T) T Nuoverlap
                                       3 < + = 4 (3(2) F(+-2)
                            5+2 4(2-1)02 1 +2 Z
        overlap
         51 4(2-1) 82
                      Combine all overlappings together
                                                        + 42
                          [2.(+-2)2]
                                                        26763
                            [-2 . (+-2) . (+-4)]
                                                        3 4+ 44
                                                        +>4
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b) i) y(+) = S+-T x(T)dT
       h(+)=S+-T 2(T) dT
      h(t) = u(t) - u(t - T)
    17) y(+) = Zn=-00 x(+-nTs)
       h(t) = \frac{8}{1000} d(t - nTs)
   i) [d(t-3)+d(t+2)]. [e^{3t}u(-t)+d(t+2)+2] \rightarrow Expand
e^{3(t-3)}u(-t+3)+e^{3(t+2)}u(-t-2)+d(t-1)+d(t+4)+2+2
[e^{3(t-3)}u(-t+3)+e^{3(t+2)}u(-t-2)+d(t-1)+d(t+4)+4]
    ii) of [(u(+) - u(++1)) + u(+-2)]
     ult) $ u(t) = 500 u(v)u(t-v)dv
                   = u(+) . Stldz
                   = + · u(+) -> 7 v(+)
    Expand of [(u1+) - u(+11)) $ u(+-2)]
            of[r(+-2) - r(+-1)]
              (4-2) - u(+-1)
d) i) x(t) and h(t) both odd
       y(t) = x(t) & h(t) -> y(t) is an over function
      y(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau
     Substitute T with (I'= - T)
      y(+) = 5-0x(-v') . h(++v')dv'
    Switch signs of x(t) and h(t) -> can do this ble they are odd
     Y(+) = 5-0 -x(T') . -h(-+- T') dT'
     y(t) = 5-0 x(T) . h(-t-V') dt'
     y(t) = y(-t) -> [True: y(t) is an even function
    11) y(t) = x(t) & h(t) y(2+) = h(2+) $ x(2+)
                              x(t) = u(t)
     say h(t) = d(t)
        h(2+) = \frac{1}{2}\partial(+)
                                  x(2t) = u(2t) \rightarrow u(t)
                              y(2+) = u(+) = = 2 d(+)
    y(+) = a(+) $ 2(+)
                              y(2+) = = u(+)
    y (+) = u(+)
          False: y(+) = y(2+) in this scenario
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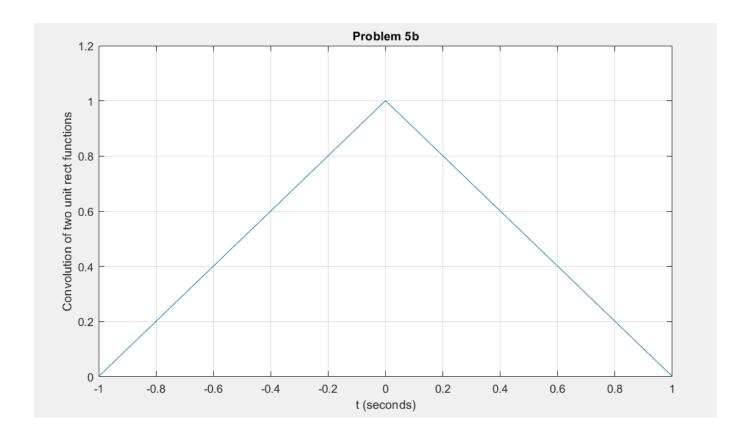
4.	S, : y(+) = 5-0x(v-to)dv
	$S_2: h_2(t) = u(t-2)$
	Sz: hz(+) = u(+13)
a)	y(+) = S-a x(I-to) dI
	Substitution: (7-to) -> 7'
	Y(+) = S-10 x(T')dI
	$Y(t) = \int_{-\infty}^{+\infty} x(\tau') d\tau$ $Y(t) = \int_{-\infty}^{+\infty} x(\tau) d\tau$ $h(t) = \int_{-\infty}^{+\infty} x(\tau) d\tau \longrightarrow \int_{-\infty}^{+\infty} h(t) = u(t - t_0) \int_{-\infty}^{+\infty} x(\tau') d\tau$
	h(t) = S-10 d(T)dT -> [h(t) = u(t-to)]
	neq(t)
b)	x(t) -> Seg -> w(t)
	heq(+) = - (h2(+) & h3(+)) + h(+)
	heq(+) = -(u(+-2) & u(++3)) + u(+-to)
	heq(+) = - r(++1) + u(+-+0)
	1/2 man 1 ma
c)	x(t) = g(t) + g(t-3)
	y(t) = x(t) & heq(t)
	y(+) = [2(+) + 2(+-3)] * [-r(++1) + u(+-+0)]
	$y(t) = -r(t+1) - r(t-2) + u(t-t_0) + u(t-t_0-3)$
	The state of the s
	y (+) - 7 - ext (3 - x 2 ) - 2 & construction and characteristic life (+) y
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5a)
    a = [1:0.001:2];
    b = (a - 1) * 2;
    len = length(a);
    temp = ones(1, len);
    c = temp * 2;
    [x, z] = nconv(c, a, b, a);
    plot(z, x);
    title('Problem 5a'); ylabel('Output for problem 3a'); xlabel('t (seconds)');
    grid on;
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5b)
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a = [-0.5:0.001:0.5];
len = length(a);
b = ones(1, len);
[x, z] = nconv(b, a, b, a);
plot(z, x);
title('Problem 5b'); ylabel('Convolution of two unit rect functions'); xlabel('t (seconds)');
grid on;
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5c)
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a = [-0.5:0.001:0.5];
len = length(a);
b = ones(1, len);
[x, z] = nconv(b, a, b, a); %result from part b
[x, z] = nconv(b, a, x, z);
plot(z, x);
title('Problem 5c'); ylabel('Convolution of a rect * rect * rect'); xlabel('t (seconds)');
grid on;
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