Q1: (a) log(s) < log(1) < n.log(n) < n.2017 < n.log(n) / 10 < 1.01 Thus, finsewiguns (d) No. Counter example: fox) = 2nlogn+n & O(nlogn+n) glx) = nlogn & O (nlogn) fix)-gix)=nlogn+n e O(nlogn) & w(n)

To meet the time complexity requirement, we will consider merge-sort as the sorting algorithm Thus, we have the following algorithm based on marge-sort. merge Count Conflicts ( list ):  $n \leftarrow ux.size()$ U← List[o: NI] L2← list[n:] count ~ merge Count Conflicts C les+ merge Count Conflicts ( L2) list clear() while i = 4. size() and j < (z. size() do: if i == U. size() then List append (12) else if  $j == L_2.size()$  then lict. append (li) break else if rank (li[i]) > rank (la[j]) then list. push c Liti]> list. push ( botis) Count += L1. size() DC-count Conflicts (list1, list2): return Merge Count Conflicts ( list2) Andy sis: Assume in list 2, rank cMis=j, then Mi will be placed as jth nurie in the sorted list, and along the

to count the steps needed for sorting list 2 to rank-decreasing order.

process of moving. Mi to Mis, it will need j-i # unions which means it has conflict with each one of them.

In mergelomet Conflicts, we expect be is smaller than bl. so every time we push an element into bist, we actually move that element bisize() # forward. Thus, count += bisize().

Complexity analysis:

Assume for M<sub>1</sub>, M<sub>2</sub>,..., M<sub>n</sub> e Ust 1, rank(M<sub>1</sub>) > rank(M<sub>2</sub>) >... > rank(M<sub>n</sub>)

Assume the original sequence of Cist 2 is the same as list 1. Now, to court the conflicts is equivalent

T(x) = P(x) and  $P(x) = 2 \cdot P(\frac{\pi}{2}) + O(\pi)$  while loop total n times.

By master theorem, Time Ocn. Lycn) ).

Q3:

Assume the input set of intervals is I, and for each input interval i, i = [beginsi), endsis].

Then we design the algorithm as follow:

greedy Check ( I ): cur — begin (ICO) for i=1 to n-1 if Cur+2 < begin([[i])

Cur = begin([[i]) else if cur +2 < end (I [i]) else return NO. end loop return YES

Complexity constysis:

Tens = Dens, since we only overote a times at word case to check each interval in input I.

Suppose 5g is the greedy solution set of points and S is some other hypothetical optimal solution

For every keth point in Sg, it is less than keth point in S.

Proof of Optimal: By our claim, we know that whenever we wond to pick the (k+1)th point,

Sq will have a wider varge to pick point. This means if Sq does not

exist, 5 does not exist neither. Thus, Sg is the optimal solution. Proof of Claim:

=0, Sg[0] = begin(I[0]) ≤ S[0] s end (I[0]). Holds

i=k, Sq[k] = S[k]

is kt1, there are two cases:  $O Sg[k] + 2 \leq beginc[[k+1])$ 

Sq[kti] = hegincl[kti]) = S[kti] = endcl[kti],

(3) Legia (IEkHI) & Sq. [k]+2 & end (I[kHI])

Sg [k+1] = Sg [k]+2 & STk]+2 & STk+1]

Thus, ZH holds.

Therefore, by POMI. We prove that Solli] = Stir for C=0,..., ... .

Let A= [a1, ..., an]. We will design the olynamic-programing algorithm as follow: minimize ( A, i, k, W, set, map. push): if map (i, k) does not exist then . of (push) then set.push (Ali-17) if i = A size or k = 0 then return abs (W) sı ← set 52 4- set a = find (A, i+1, R, W, S1, O) b = find (A, it, K-1, W-ALI], set 2, 1) if a < b then set € 51 map(i,k)=aelse set ← 52 map ci, k) = b return mapcinks DP-minimize (A, k, W): 11 Set: vector of numbers, solution set. " map, hash table to store map (i, k) = minimize (A, i, k, W. set. map) minimize (A, o, k, W, set. map). return set. Correctness analysis: A set A={a,..., an}, for each ai, only 2 possibilities: Daits. then k-1 and W-ai @ aid S. then k and W we will compare the result of these two to consider wether include as or not. Complexity analysis: Ten = pens and pens is for minimize (...).

Q4:

[ca) = P(n) and P(n) is for minimize(...).

Since we use haph table to store each result of Link), whenever map with, onists, we only need Oct) to read that data. Therefore, in total, we need at least not times to calculate all levels of results. Then, P(n) EO(n-k).

Since k and Ware positive integer, from the question we get that k = W.

Therefore, T(n) 60(n.W).

Q5:

We will design the following DTS algorithm:

```
DFSCG, v, paths.
     mark v as visited
     for u in v. neighbor() do
           if u is not visited then
              mark u as visited
               path. push cuj
               DFS ( G, u, path )
         else posth. pop()
              mark ( path Epath. size()-1], u) as circular
             for p = parch. size()-2 down to 0 do
                 mark (pathtp], pathtp#1) as circular
                 if porth [p] = u then
    end loop end loop end loop.
                     6reak
apca);
   1/V: the set of vertices, E: the set of edges.
   " path: empty set of edges
  for v in V do
       if v is not visited then
            path.clear()
            DFSCG, v. path)
 end loop
 return all edges marked as circular.
```

Analysis:

We know that DFS algorithm checks the sub-vertex of every path, thus such path that firms circular will be found. The time complexity of DFS is Ocman), and for marking the edges as circular, it will require k times to call and (k-1) times for every edge connecting it. Thus, T can t D cm +n)