

Applications of the Laplace Transform

1. Differential and Integro-Differential Equations:

The Laplace transform of a differential equation is an algebraic equation that can be readily solved. The method is general and can solve a linear differential equation with constant coefficients of any order.



This method gives the total response, which includes zero-input and zero-state components. The initial condition terms in the response give rise to the zero-input response and the input terms correspond to the zero-state response.

Q. Using the Laplace transform, solve the following differential equations:

(a). $(D^2 + 3D + 2) y(t) = D x(t)$

with $y(0^-) = \dot{y}(0^-) = 0$ and $x(t) = u(t)$

(b). $(D^2 + 4D + 4) y(t) = (D + 1) x(t)$

with $y(0^-) = 2$, $\dot{y}(0^-) = 1$ and $x(t) = e^{-t} u(t)$

A. (a). $(s^2 + 3s + 2) Y(s) = s \cdot \frac{1}{s} = 1$

$$\Rightarrow Y(s) = \frac{1}{s^2 + 3s + 2} = \frac{1}{s+1} - \frac{1}{s+2}$$

$$\Rightarrow y(t) = (e^{-t} - e^{-2t}) u(t)$$

(b). $(s^2 Y(s) - 2s - 1) + 4(s Y(s) - 2) + 4 Y(s) = (s+1) \cdot \frac{1}{s+1} = 1$

$$\Rightarrow Y(s) = \frac{2s+10}{(s+2)^2} = \frac{2}{s+2} + \frac{6}{(s+2)^2}$$

$$\Rightarrow y(t) = (2 + 6t) e^{-2t} u(t)$$

Q. Consider a causal LTIC system described by the DE :

$$2 \dot{y}(t) + 6 y(t) = \dot{x}(t) - 4 x(t)$$

(a). Compute the zero-input response if $y(0^-) = -3$.

(b). Compute the zero-state response if $x(t) = e \delta(t - \pi)$.

A. (a). For the zero-input response,

$$2[s Y(s) - y(0^-)] + 6 Y(s) = 0$$

$$\Rightarrow Y(s) = \frac{-3}{s+3} \quad \text{or} \quad y_{zi}(t) = -3 e^{-3t} u(t)$$

(b). For the zero-state response,

$$2 s Y(s) + 6 Y(s) = s X(s) - 4 X(s)$$

$$x(t) = e \delta(t - \pi) \iff e^{-(s\pi - 1)}$$

$$\Rightarrow Y(s) = \frac{s-4}{2s+6} X(s)$$

$$\Rightarrow y_{zs}(t) = \frac{e}{2} \left[\delta(t - \pi) - 7 e^{-3(t-\pi)} u(t - \pi) \right]$$

Q. Consider a causal LTIC system described by the DE:

$$\dot{y}(t) + 2y(t) = \dot{x}(t)$$

(a). Write the system transfer function.

(b). Determine the unit impulse response of this system.

(c). Determine the output $y(t)$ if the input $x(t) = e^{-t} u(t)$ and $y(0^-) = \sqrt{2}$.

A. (a). $s Y(s) + 2 Y(s) = s X(s)$

$$\text{Hence, } H(s) = \frac{Y(s)}{X(s)} = \frac{s}{s+2}$$

(b). $H(s) = \frac{s}{s+2} = 1 - \frac{2}{s+2}$

$$\Rightarrow h(t) = \delta(t) - 2e^{-2t} u(t)$$

(c). $s Y(s) - \sqrt{2} + 2 Y(s) = s \cdot \frac{1}{s+1}$

$$\Rightarrow Y(s) = \frac{\sqrt{2}+2}{s+2} - \frac{1}{s+1}$$

$$\Rightarrow y(t) = (\sqrt{2}+2)e^{-2t} u(t) - e^{-t} u(t)$$

Q. Using the Laplace transform, solve the following simultaneous differential equations:

$$(D+3)y_1(t) - 2y_2(t) = x(t)$$

$$-2y_1(t) + (2D+4)y_2(t) = 0$$

Assume all initial conditions to be zero and the input $x(t) = u(t)$.

A. Taking the Laplace transforms,

$$(s+3)y_1(s) - 2y_2(s) = \frac{1}{s}$$

$$-2y_1(s) + (2s+4)y_2(s) = 0$$

$$\Rightarrow y_1(s) = \frac{s+2}{s(s^2+5s+4)} = \frac{1}{2s} - \frac{1}{3(s+1)} - \frac{1}{6(s+4)}$$

$$y_2(s) = \frac{1}{s(s^2+5s+4)} = \frac{1}{4s} - \frac{1}{3(s+1)} + \frac{1}{12(s+4)}$$

$$\Rightarrow y_1(t) = \left(\frac{1}{2} - \frac{1}{3}e^{-t} - \frac{1}{6}e^{-4t} \right) u(t)$$

$$y_2(t) = \left(\frac{1}{4} - \frac{1}{3}e^{-t} + \frac{1}{12}e^{-4t} \right) u(t)$$

$$\text{and } H_1(s) = \frac{y_1(s)}{x(s)} = \frac{s+2}{s^2+5s+4}, \quad H_2(s) = \frac{1}{s^2+5s+4}$$