

Analysis Techniques

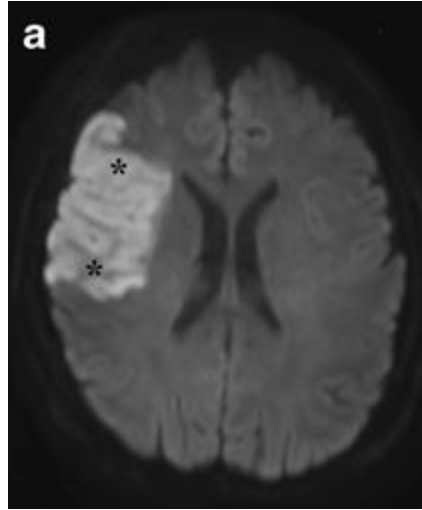
Ellie Thompson and Anna Schroder

Overview

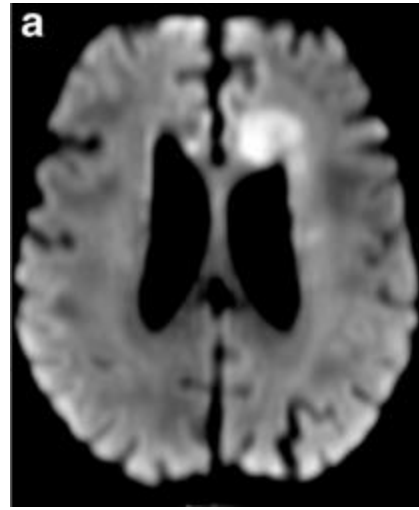
- Lecture
 - Introduction: using analysis techniques to gain biomedical insights from diffusion MRI
 - Diffusion tensor
 - Compartment models
 - Generating fODFs for tractography with constrained spherical deconvolution
- Coding Practicals
 - Practical 1: Diffusion tensor
 - Practical 2: Ball-and-stick model
 - Practical 3: Constrained Spherical Deconvolution
- Summary

Introduction

What can we do with diffusion MRI?



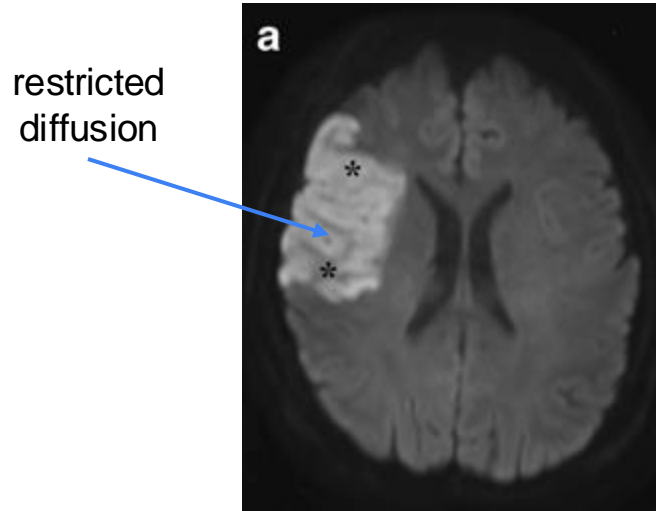
Acute stroke



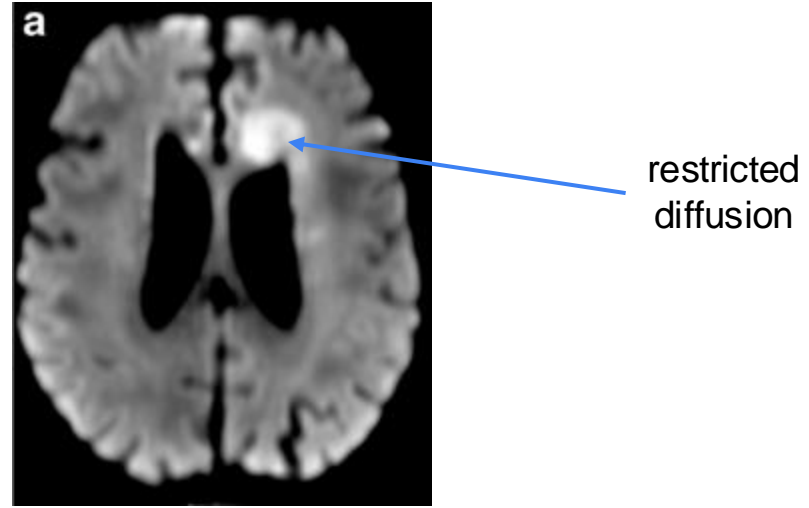
CNS lymphoma

Pre-processed scans provide some clinical insight, however they lack **quantitative biomarkers** or **complex microstructural** information

What can we do with diffusion MRI?



Acute stroke



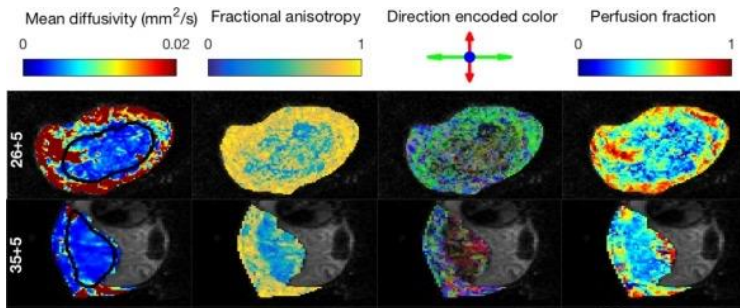
CNS lymphoma

Pre-processed scans provide some clinical insight, however they lack **quantitative biomarkers** or **complex microstructural** information

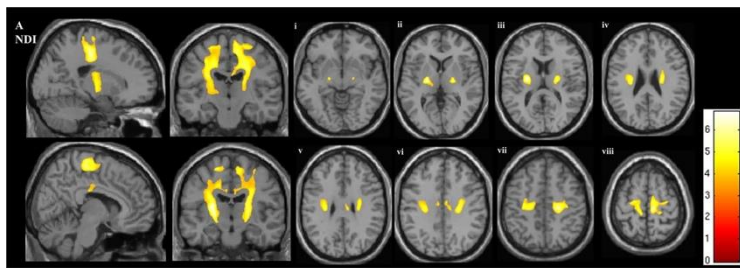
We can use analysis techniques to gain
biomedical insight from dMRI

Key applications

Microstructure modelling

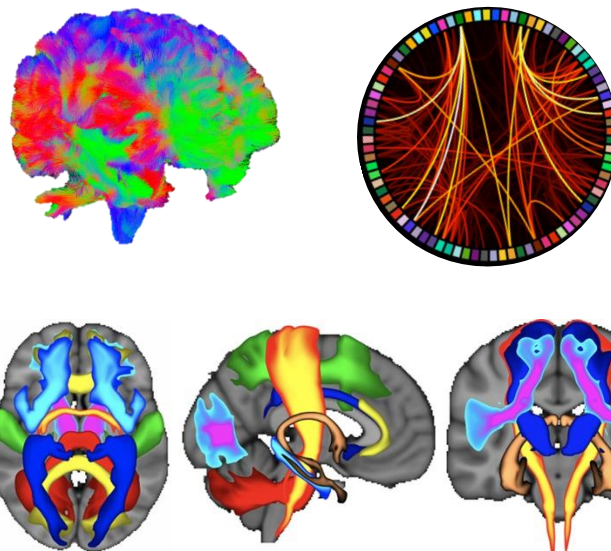


Slator PJ, et al. Placenta microstructure and microcirculation imaging with diffusion MRI. (2018)



Broad RJ, et al. Neurite orientation and dispersion density imaging (NODDI) detects cortical and corticospinal tract degeneration in ALS (2019)

Mapping white matter connections

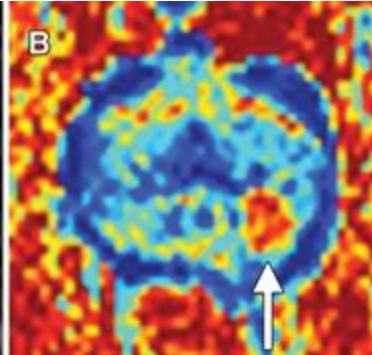
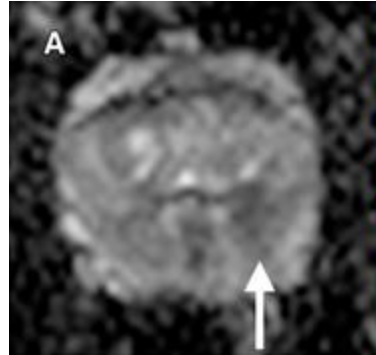


Warrington et al. Concurrent mapping of brain ontogeny and phylogeny within a common space: Standardized tractography and applications. (2022)

We can use analysis techniques to gain **biomedical insight** from dMRI

e.g. VERDICT-MRI: non-invasive histology for prostate cancer

Apparent diffusion coefficient (ADC) map



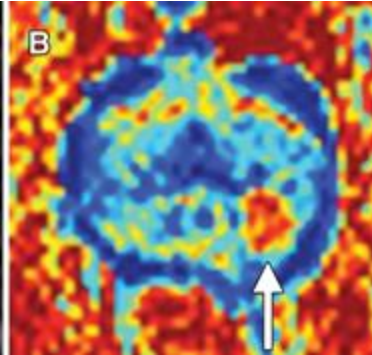
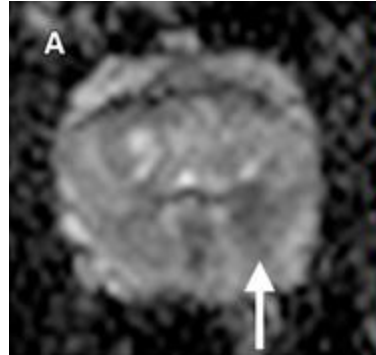
VERDICT intracellular volume fraction map

Images in a 57-year-old man with targeted biopsy-proven Gleason 3+4 prostate cancer.

We can use analysis techniques to gain **biomedical insight** from dMRI

e.g. VERDICT-MRI: non-invasive histology for prostate cancer

Apparent diffusion coefficient (ADC) map

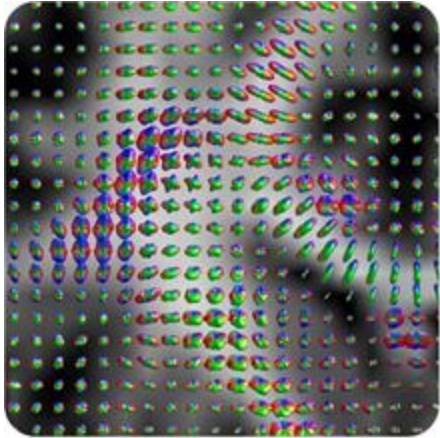


VERDICT
intracellular
volume fraction
map

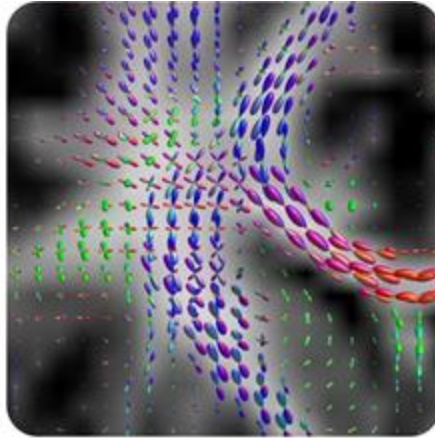
“New scanning technique reduces unnecessary biopsies by 90% meaning thousands of men could be spared pain and anxiety” - prostate cancer UK

We can use analysis techniques to gain **biomedical insight** from dMRI

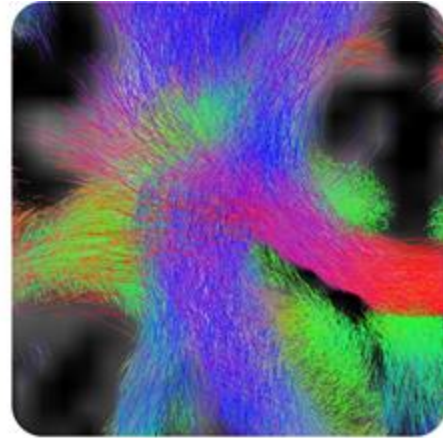
e.g. modelling fibre orientations for tractography



raw dMRI signal



fibre orientations



tractography

The Diffusion Tensor

The Diffusion Tensor

- The diffusion tensor characterises Gaussian diffusion in 3D in each voxel

Stejskal-Tanner equation:

$$S_k = S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

Diagram illustrating the Stejskal-Tanner equation and its components:

- S_k : Signal after applying a diffusion-weighted gradient k in direction $\hat{\mathbf{g}}_k$ with b-value b_k
- S_0 : Signal with no diffusion-weighted gradient applied
- b_k : B-value for gradient k (describing pulse sequence)
- $\hat{\mathbf{g}}_k$: Unit vector of the direction of gradient k
- \mathbf{D} : The diffusion tensor

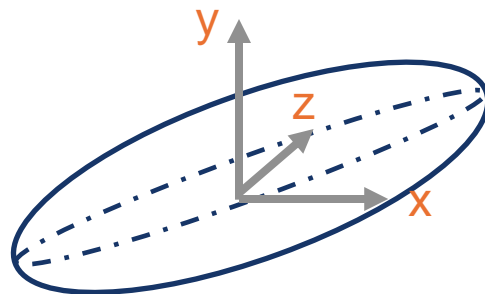
Legend:

- Measured (Green)
- Imaging parameters (Blue)
- To be estimated (Red)

What is the diffusion tensor?

- 3x3 positive-definite symmetric matrix characterising displacement/diffusion in 3D

$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$

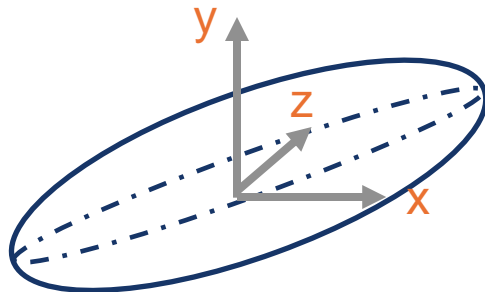


- D_{xx}, D_{yy}, D_{zz} : diffusion along 3 orthogonal axes (always positive)
- D_{xy}, D_{xz}, D_{yz} : correlation between displacements along these orthogonal axes (positive or negative)

What is the diffusion tensor?

- 3x3 positive-definite symmetric matrix characterising displacement/diffusion in 3D

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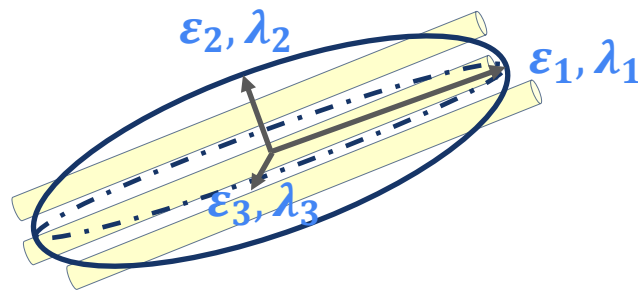
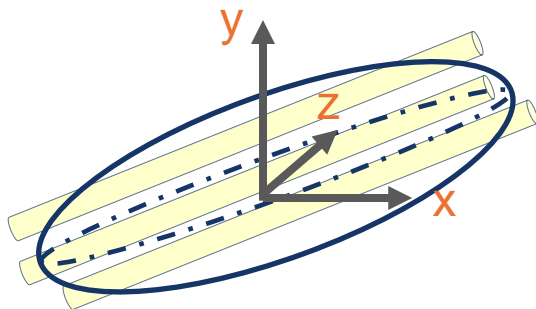


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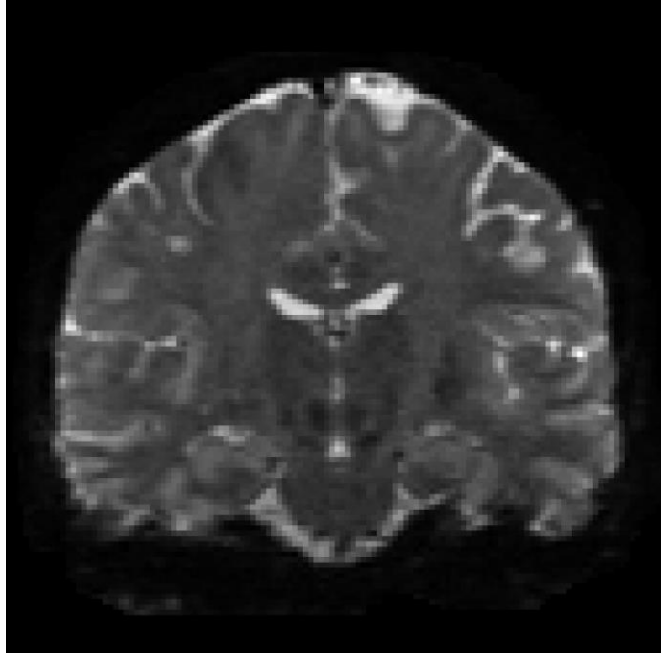
Ellipsoid from DT

- We can decompose the Diffusion tensor into eigen-values and eigen-vectors

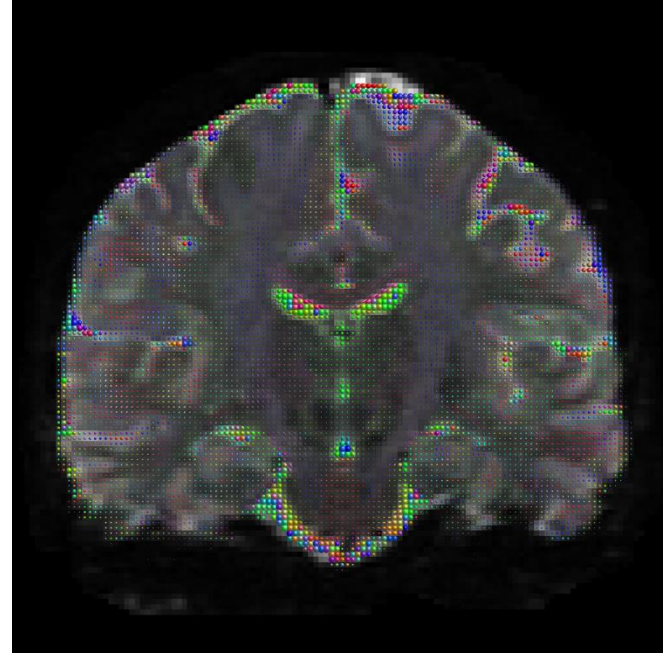
$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix} = [\varepsilon_1 \quad \varepsilon_2 \quad \varepsilon_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix}$$



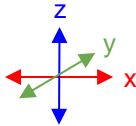
Diffusion Tensor in real data

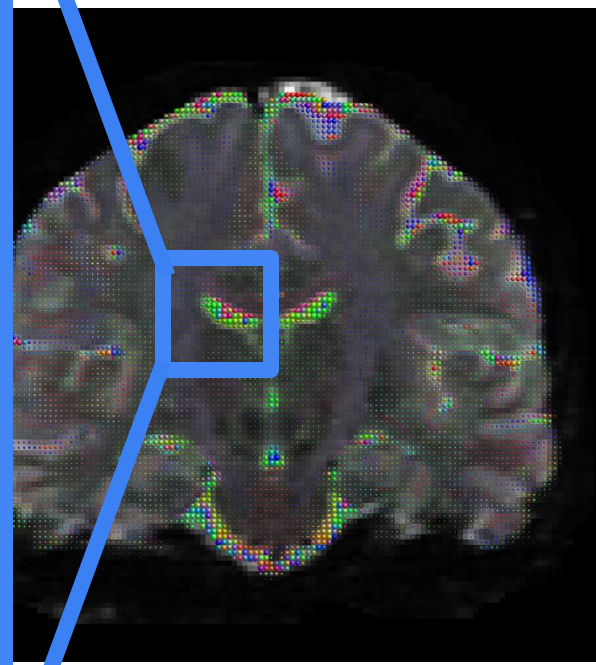
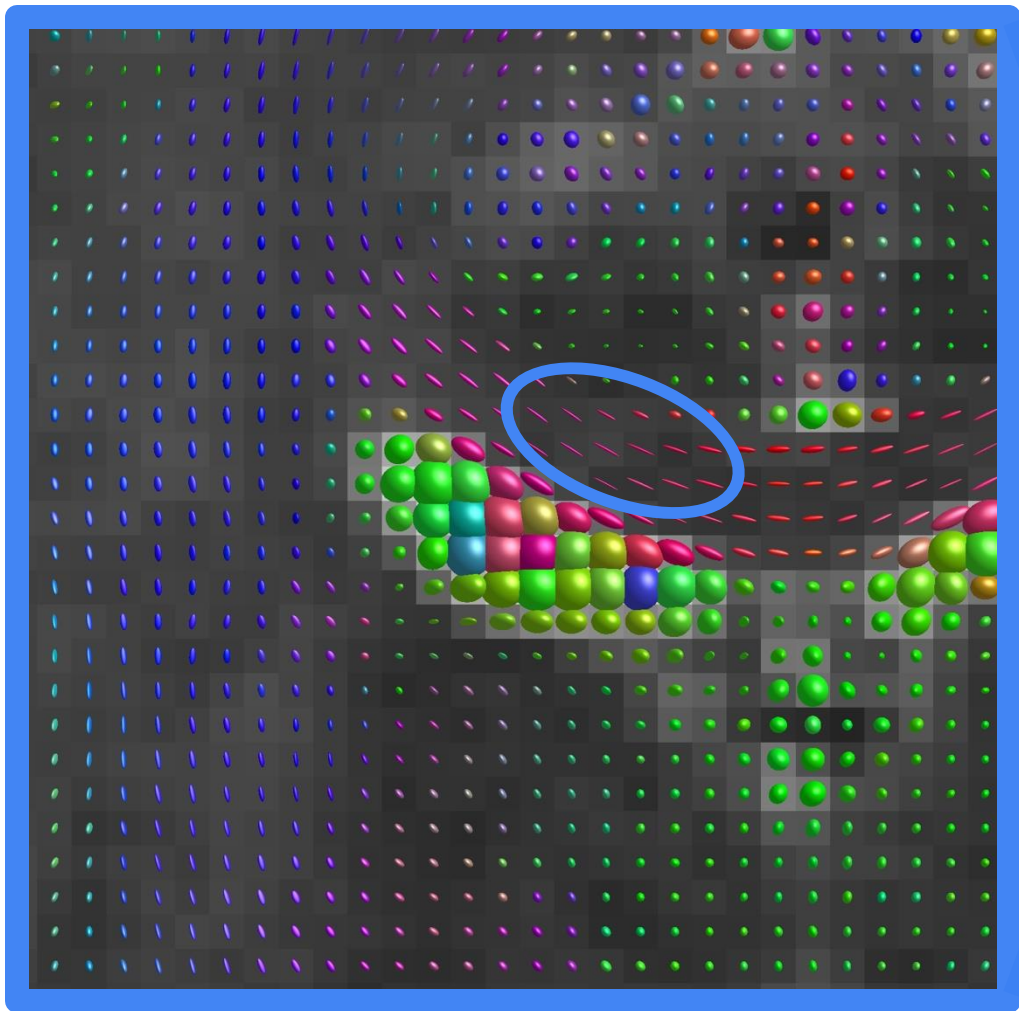


B0 diffusion signal

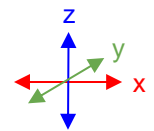


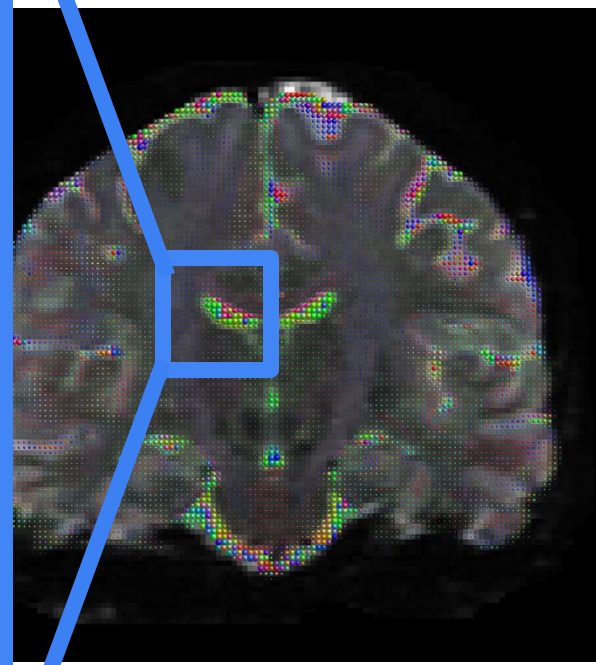
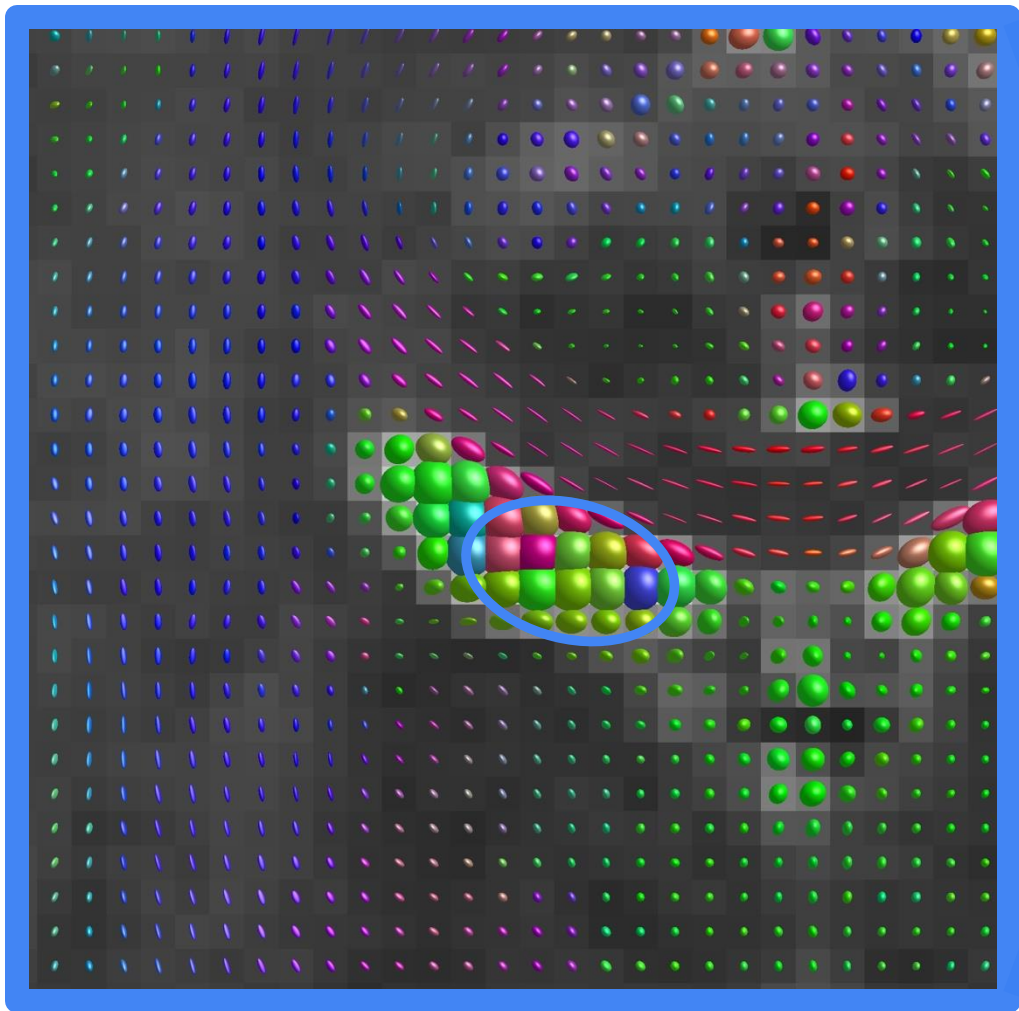
Diffusion tensors



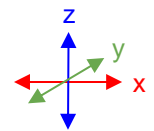


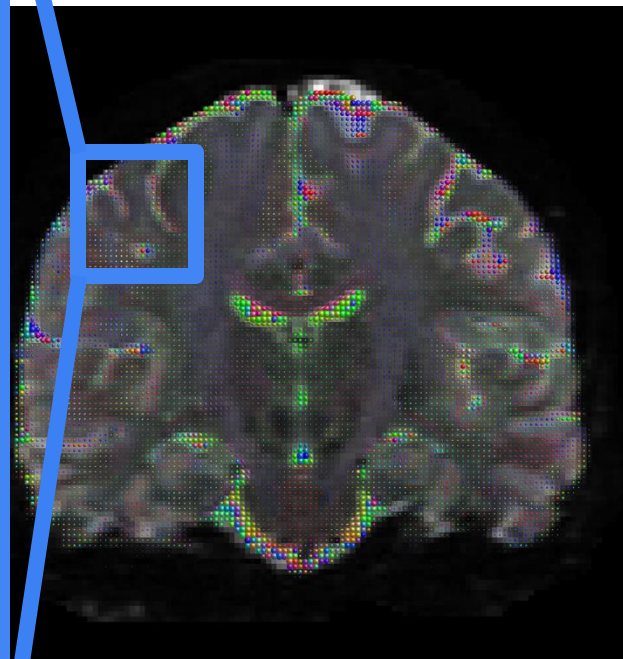
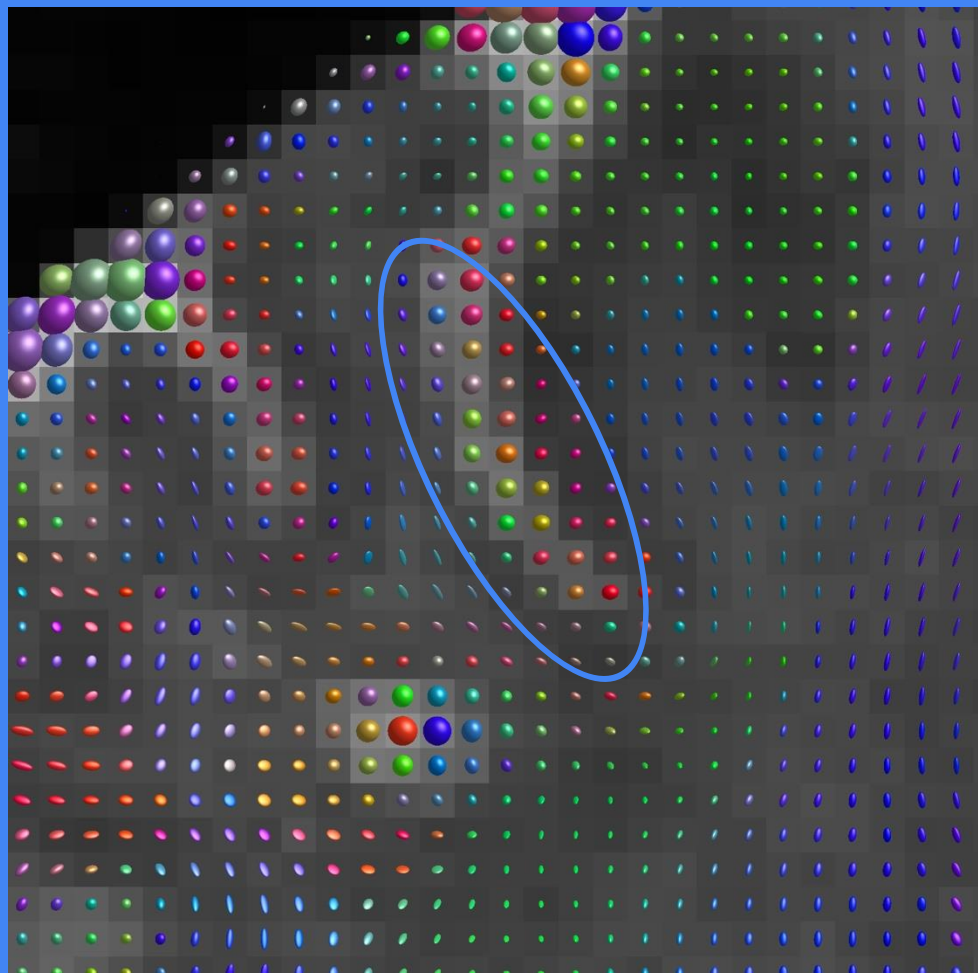
Diffusion tensors



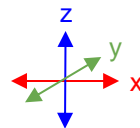


Diffusion tensors

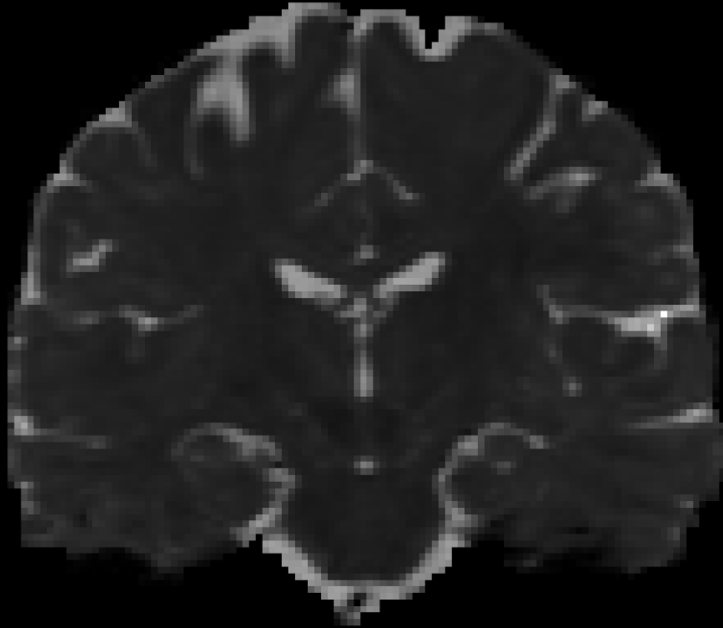




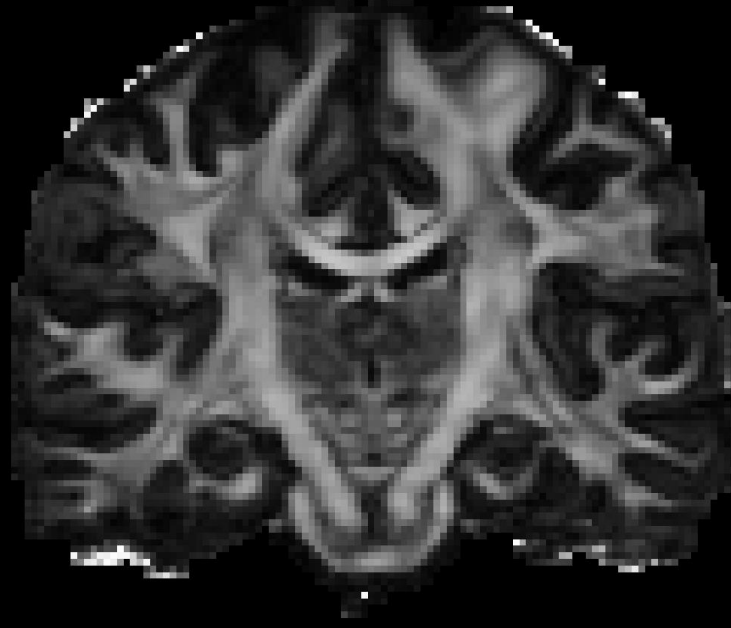
Diffusion tensors



Scalar measures derived from the diffusion tensor



Mean Diffusivity (MD) = mean of the tensor eigenvalues



Fractional Anisotropy (FA) = normalised variance of tensor eigenvalues

Axial
Diffusivity,

Radial
Diffusivity

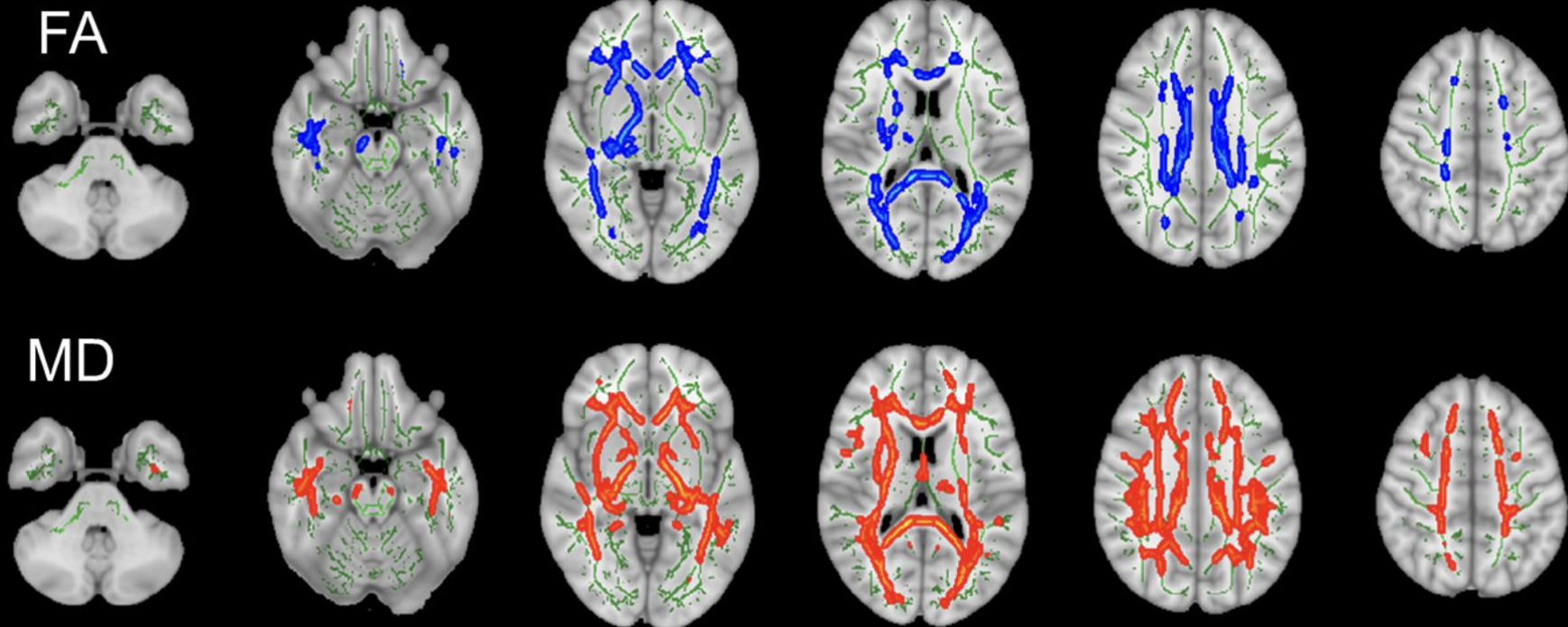
...

Measures derived from the diffusion tensor

Significantly lower
in MS

Significantly higher
in MS

DTI



Fitting the diffusion tensor from an image

- Fitting the 6 variables of the diffusion tensor (D_{xx} , D_{xy} , D_{xz} , D_{yy} , D_{yz} , D_{zz}) from the diffusion image requires a minimum of 6 diffusion directions ($+S_0$)
- Methods:
 - least squared (linear, weighted, non-linear)
 - Bayesian MCMC

Fitting the diffusion tensor from an image

- Fitting the 6 variables of the diffusion tensor (D_{xx} , D_{xy} , D_{xz} , D_{yy} , D_{yz} , D_{zz}) from the diffusion image requires a minimum of 6 diffusion directions (+ S_0)
- Methods:
 - least squared (linear, weighted, non-linear)
 - Bayesian MCMC
- Minimise the following function:

$$f = \sum_k \|S_k - S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)\|$$

Compartment Models

Compartment models

- Different tissues characterised by different biophysical models
- The signal is represented as a linear combination of the different compartments
- Exchange between compartments assumed to be negligible

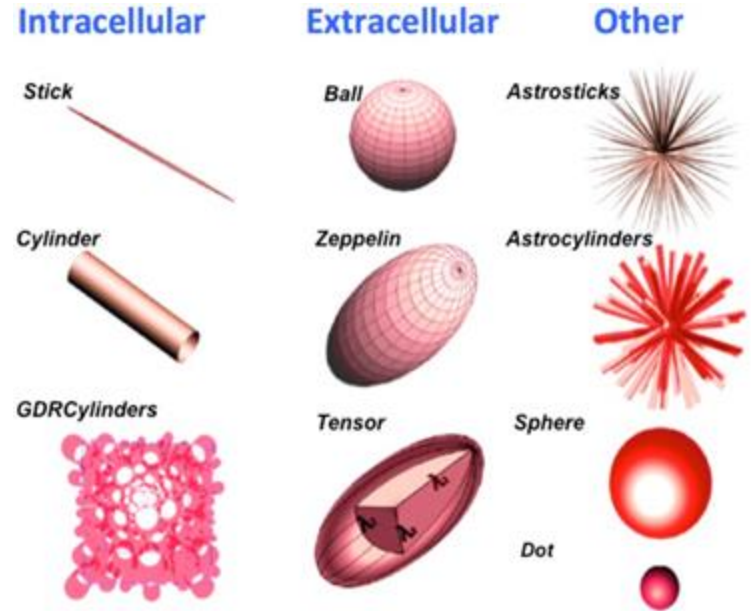
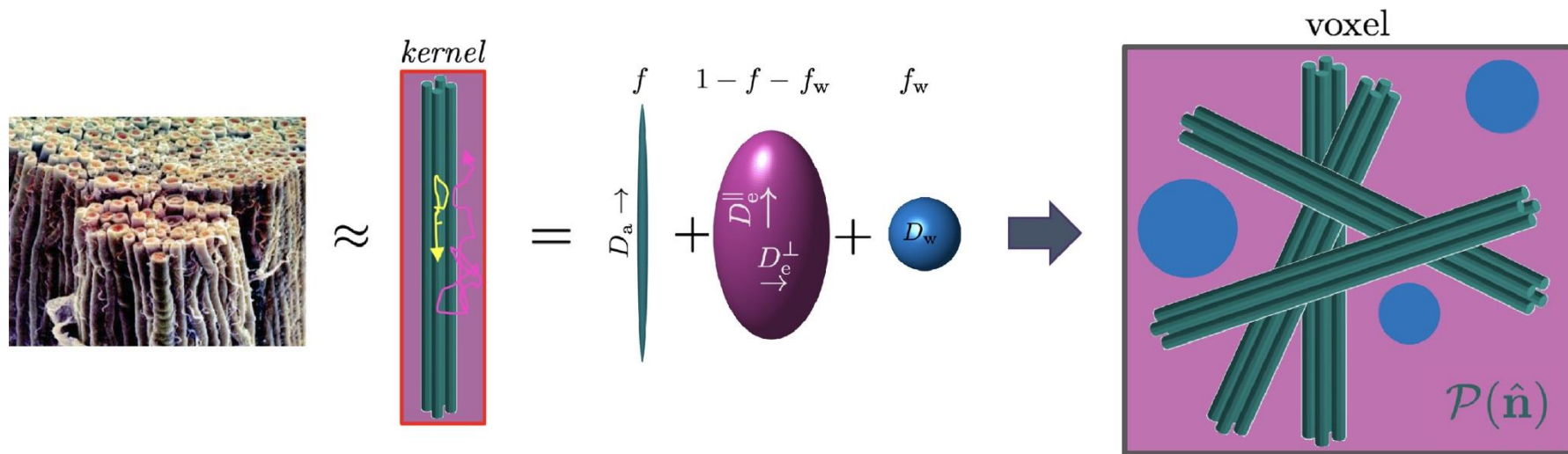


Figure from: Ferizi, U., Schneider, T., Panagiotaki, E., Nedjati-Gilani, G., Zhang, H., Wheeler-Kingshott, C.A.M. and Alexander, D.C. (2014), A ranking of diffusion MRI compartment models with in vivo human brain data. *Magn. Reson. Med.*, 72: 1785-1792. <https://doi.org/10.1002/mrm.25080>

The standard model for dMRI

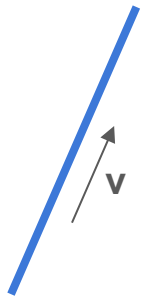


- Stick compartment: axons
- Zeppelin compartment: hindered diffusion in the extra-axonal space
- Free water compartment: partial volume contributions from the CSF

Novikov DS, Fieremans E, Jespersen SN, Kiselev VG. Quantifying brain microstructure with diffusion MRI: Theory and parameter estimation. NMR Biomed. 2019 Apr;32(4):e3998. doi: 10.1002/nbm.3998. Epub 2018 Oct 15.

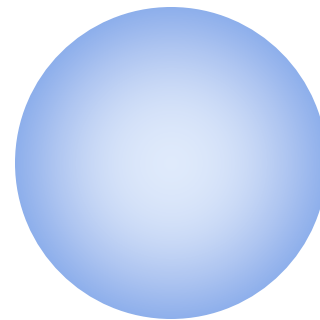
Coelho S, Baete SH, Lemberskiy G, Ades-Aron B, Barrol G, Veraart J, Novikov DS, Fieremans E. Reproducibility of the Standard Model of diffusion in white matter on clinical MRI systems. Neuroimage. 2022 Aug 15;257:119290. doi: 10.1016/j.neuroimage.2022.119290. Epub 2022 May 8.

A simple compartment model: Ball and Stick Model



stick

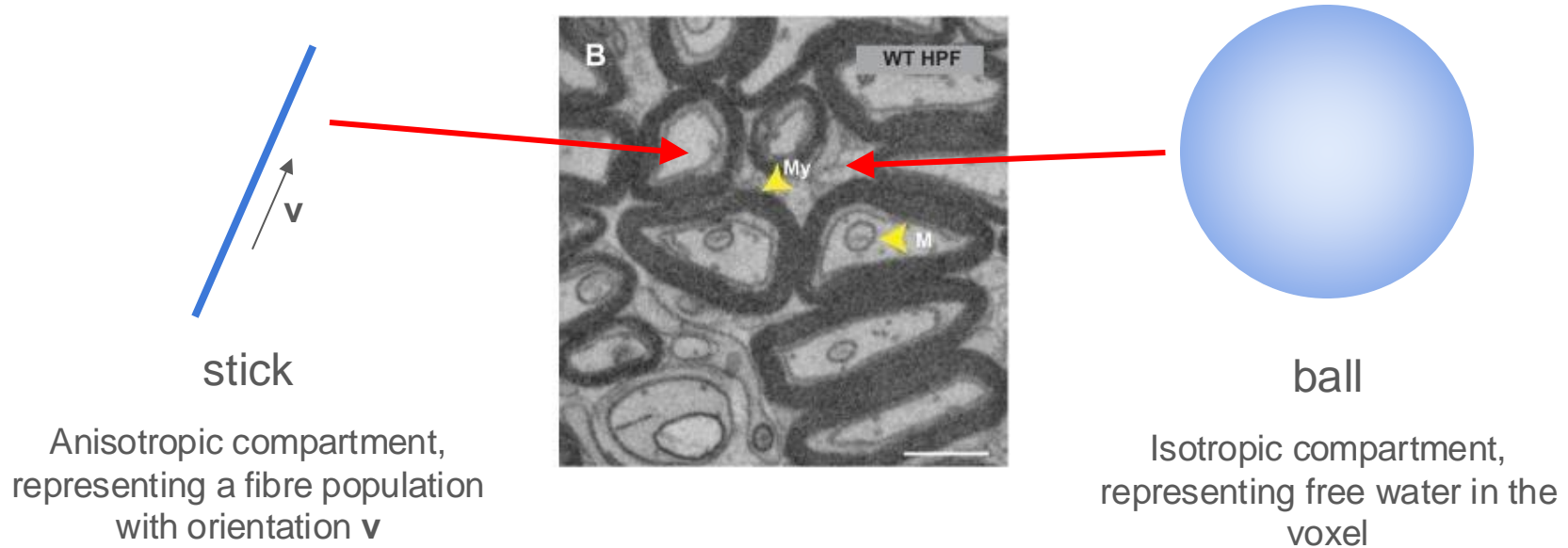
Anisotropic compartment,
representing a fibre population
with orientation \mathbf{v}



ball

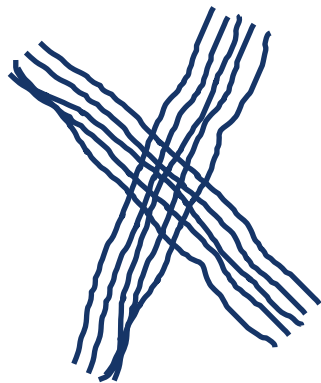
Isotropic compartment,
representing free water in the
voxel

A simple compartment model: Ball and Stick Model

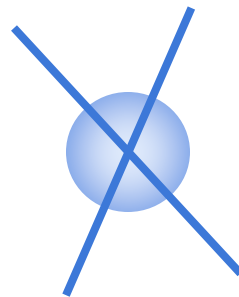


Ball and Stick Model

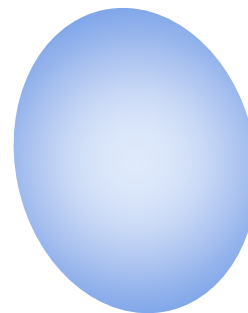
This allows us to model crossing fibre populations, which is not possible with DTI



Intersecting fibre
populations



Ball and stick
model



Tensor

Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0[(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

signal from “ball”
compartment



signal from “stick”
compartment: fibre
population with direction \mathbf{v}





Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0 [(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

Diagram illustrating the Ball and Stick Model components:

- S_0 : signal when $b = 0$
- $(1 - f)$: volume fraction of isotropic compartment
- $\exp(-b_k d)$: signal from "ball" compartment (mean diffusivity d)
- f : volume fraction of anisotropic compartment
- $\exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)$: signal from "stick" compartment (fibre population with direction \mathbf{v})



Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0 [(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

Diagram illustrating the Ball and Stick Model equation and its components:

- S_k : signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k .
- S_0 : signal when $b = 0$.
- $(1 - f)$: volume fraction of isotropic compartment.
- $\exp(-b_k d)$: signal from "ball" compartment, where d is the mean diffusivity.
- f : volume fraction of anisotropic compartment.
- $\exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)$: signal from "stick" compartment: fibre population with direction \mathbf{v} .


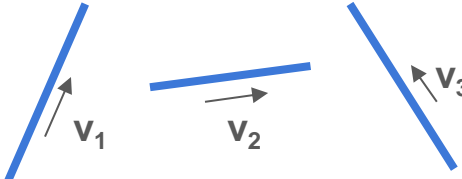
Legend:

- Measured: S_k , S_0
- Imaging parameters: b_k , d
- To be estimated: f , \mathbf{v}

Ball and Stick Model – extending to multiple fibre populations

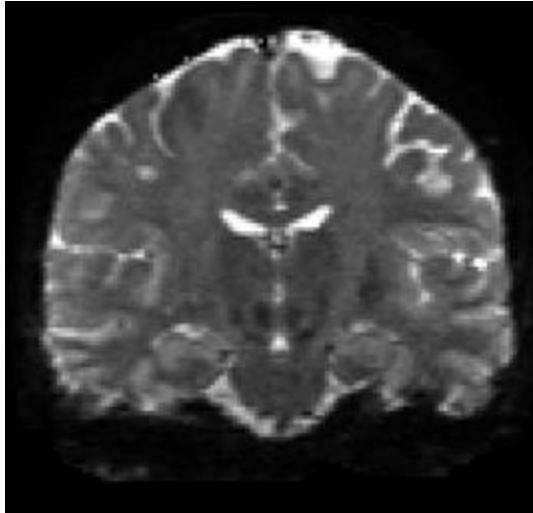
$$S_k = S_0 \left[\left(1 - \sum_{i=1}^N f_i \right) \underbrace{\exp(-b_k d)}_{\text{signal from "ball"}} + \sum_{i=1}^N \underbrace{f_i \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v}_i)^2)}_{\text{signal from "stick" compartment: fibre population with direction } \mathbf{v}_i} \right]$$

volume fraction of anisotropic compartment i

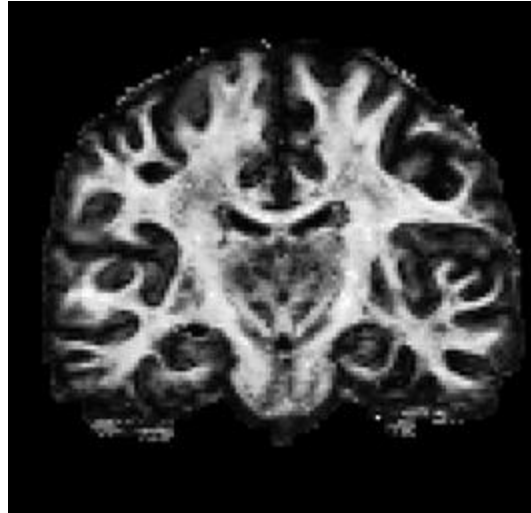



The diagram illustrates the components of the Ball and Stick model. A blue sphere represents the isotropic 'ball' compartment. Three blue line segments represent the anisotropic 'stick' compartments, each with a direction vector \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 respectively. The equation shows the total signal S_k as the sum of the signal from the ball and the weighted sum of signals from the sticks, where the weight is the volume fraction f_i and the exponential term accounts for the orientation relative to the gradient \mathbf{g}_k .

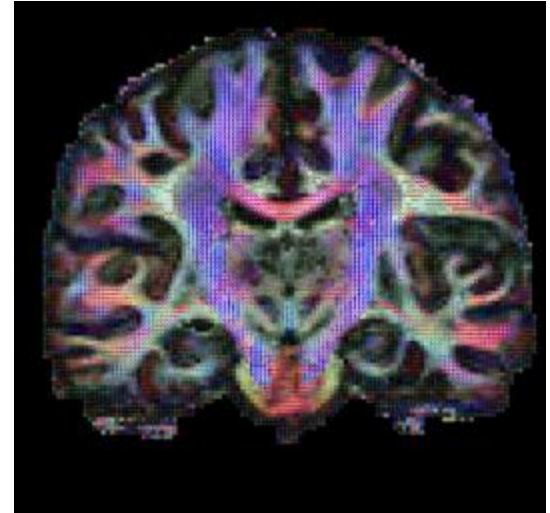
Ball and Stick Model in real data



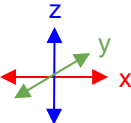
B0 diffusion signal



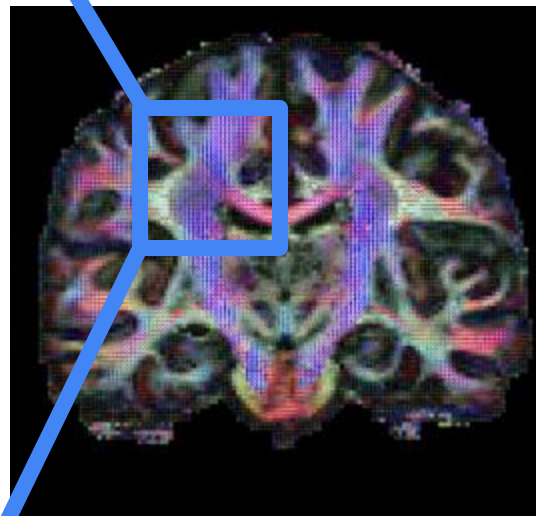
Fibre volume fraction



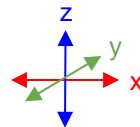
Sticks visualised as
vectors



B

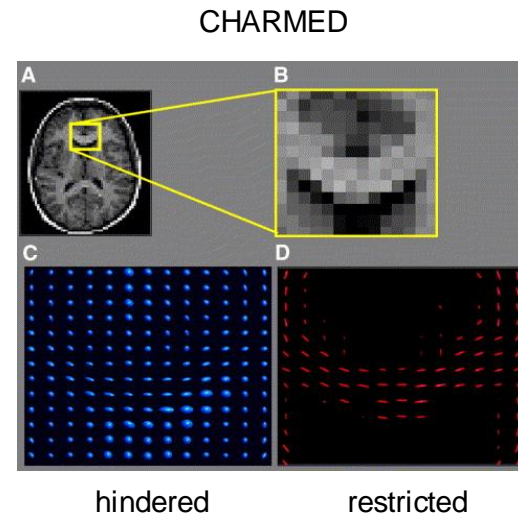


Sticks visualised as
vectors

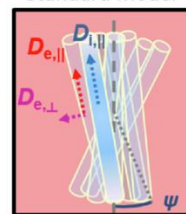


More advanced compartment models

- White matter
 - CHARMED: Composite hindered and restricted model of diffusion. *Assaf and Basser (2005) NeuroImage*
 - NODDI: Neurite orientation dispersion and density imaging. *Zhang et al (2012) NeuroImage*
- Grey matter
 - SANDI: Soma and neurite density imaging. *Palombo et al (2020) NeuroImage*
 - NEXI: neurite exchange imaging. *Jelescu et al (2022) NeuroImage*
- Tumours
 - VERDICT: Vascular, Extracellular, and Restricted Diffusion for Cytometry in Tumours. *Panagiotaki et al (2014), Cancer Res*

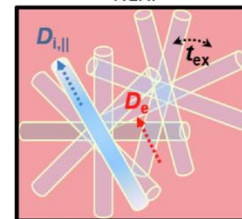


Standard Model



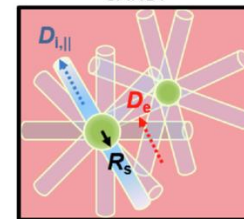
$$\frac{\text{blue}}{\text{blue} + \text{red}} = f$$

NEXI



$$\frac{\text{blue}}{\text{blue} + \text{red}} = f$$

SANDI



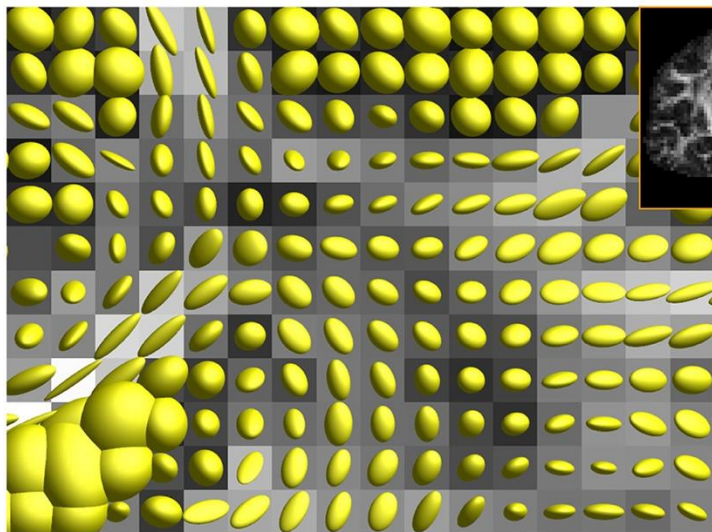
$$\frac{\text{blue}}{\text{blue} + \text{red} + \text{green}} = f \quad \frac{\text{green}}{\text{blue} + \text{red} + \text{green}} = f_s$$

Generating fibre orientation distribution functions (fODFs) with constrained spherical deconvolution

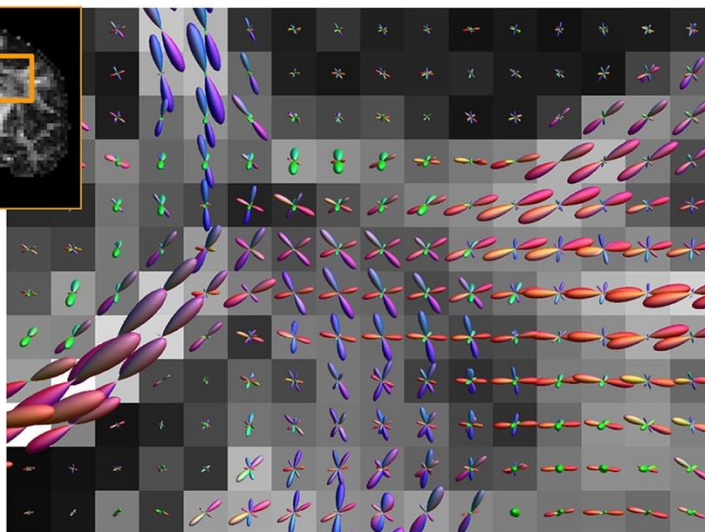
Spherical Deconvolution

- Method for obtaining a continuous fibre orientation distribution function: fODF
- Provides fibre orientations for tractography

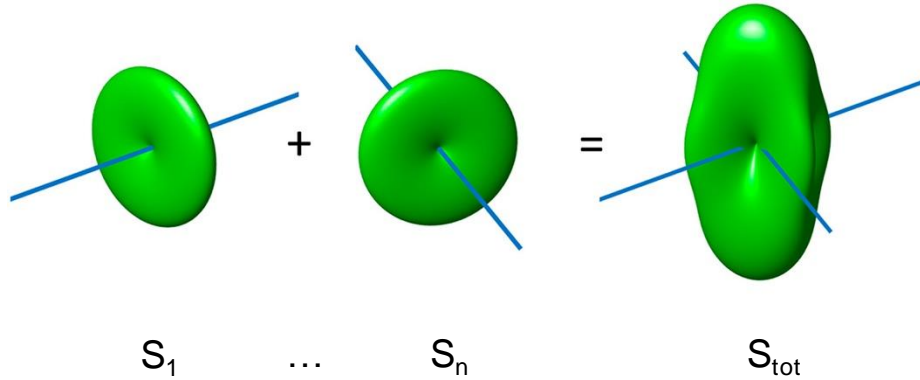
Single Fibre (DTI)



Multiple Fibres (SD)

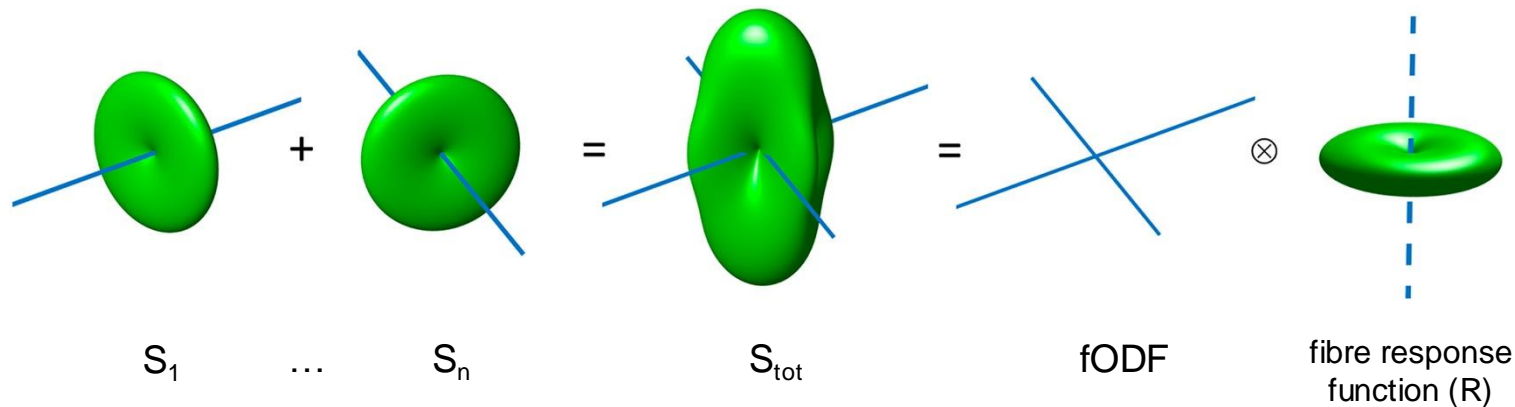


Spherical Deconvolution



- The diffusion-weighted signal is a linear combination of signals from the different fibre populations in a voxel

Spherical Deconvolution



- The diffusion-weighted signal is a linear combination of signals from the different fibre populations in a voxel
- The measured signal is the convolution of the *fibre response function* (signal from a single, coherently-oriented fibre bundle) with the fODF
- The fODF is obtained by deconvolving the measured signal with the fibre response function

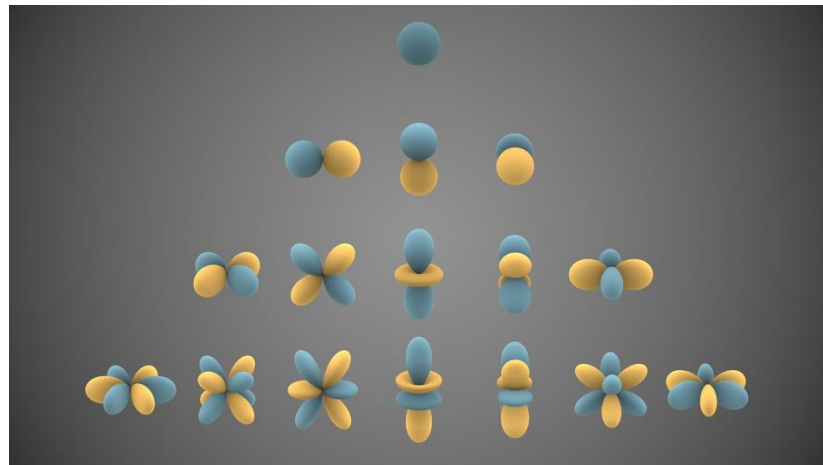
Spherical Harmonic Basis

- The fODF is typically expressed as a weighted sum of spherical harmonics up to degree l_{max} :

$$f(\theta, \phi) = \sum_l^{l_{max}} \sum_{m=-l}^l c_{lm} Y_{lm}(\theta, \phi)$$

coefficients to
be estimated

spherical
harmonics

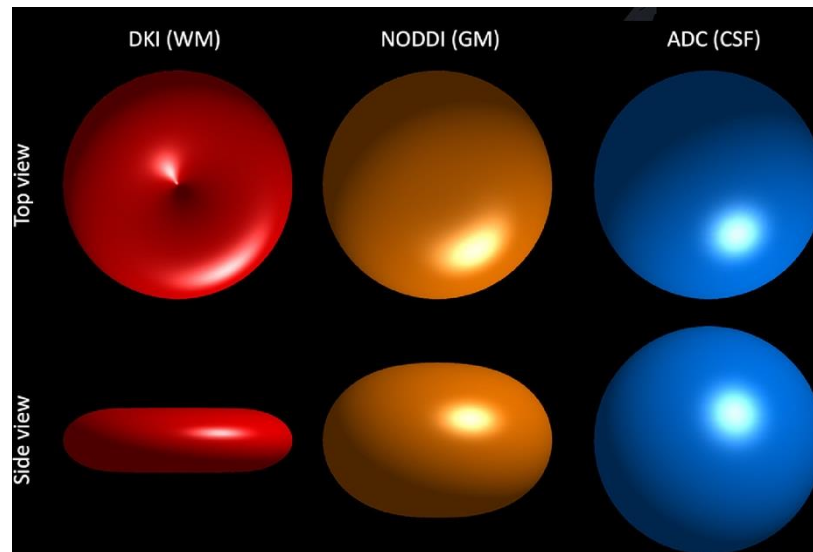


By Inigo.quilez - Own work, CC BY-SA 3.0,
<https://commons.wikimedia.org/w/index.php?curid=32782753>

- compact representation reduces noise
- convolution is a simple product in spherical harmonic domain – computationally efficient

Step 1: Estimating the fibre response function

- The DW signal that would be acquired for single coherent fibre population
- Model based approaches: eg. axially symmetric tensor
- Direct empirical measurements from single-fibre voxels
- Response function can be derived for each tissue type (multi-tissue)

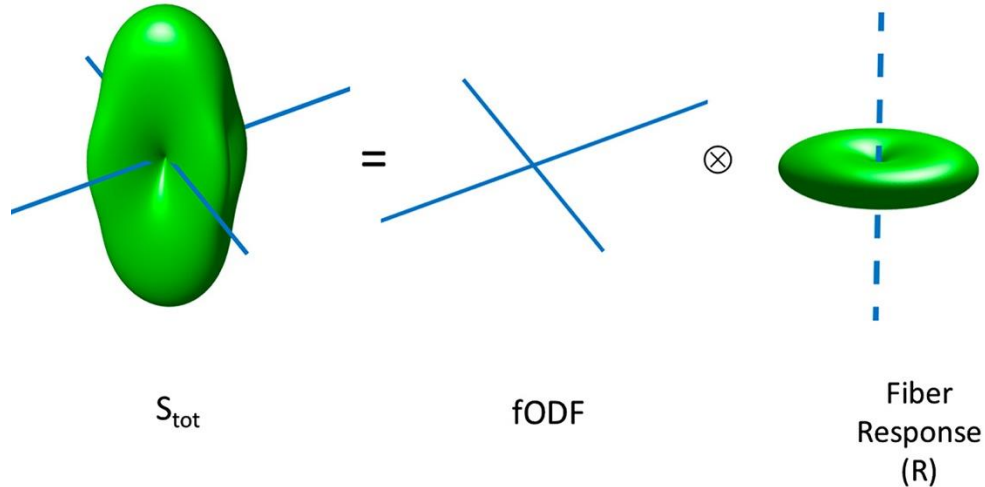


Examples of tissue-specific response functions derived from different models

Spherical deconvolution with tissue-specific response functions and multi-shell diffusion MRI to estimate multiple fiber orientation distributions (mFODs)": <https://www.sciencedirect.com/science/article/pii/S1053811920306923>

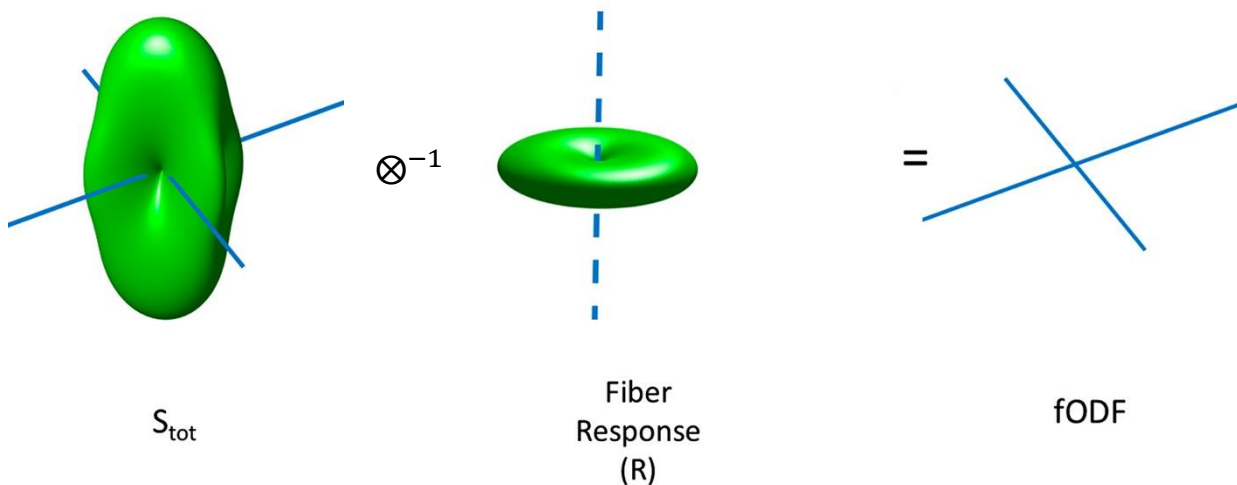
Step 2: Using the fibre response function to determine the fODF

- We can deconvolve the measured signal with the response function, R , to obtain the fODF



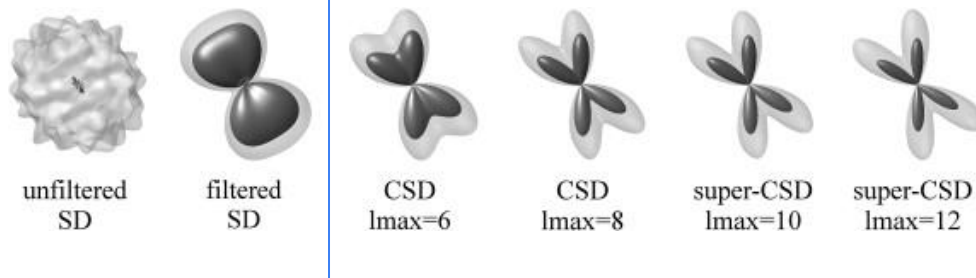
Step 2: Using the fibre response function to determine the fODF

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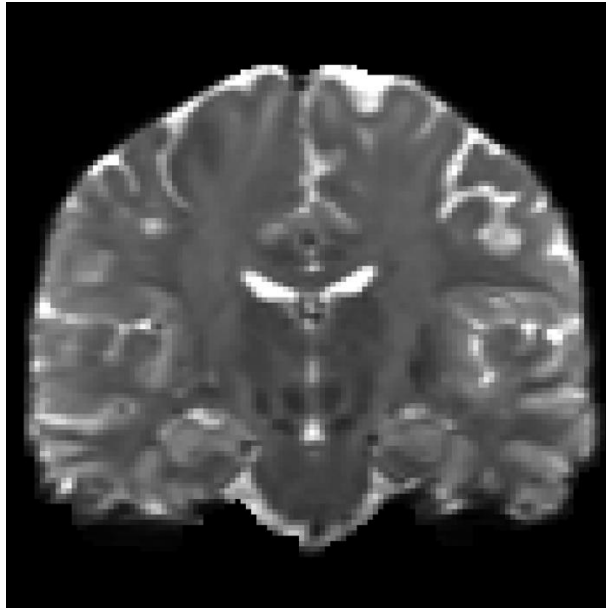


Constrained Spherical Deconvolution

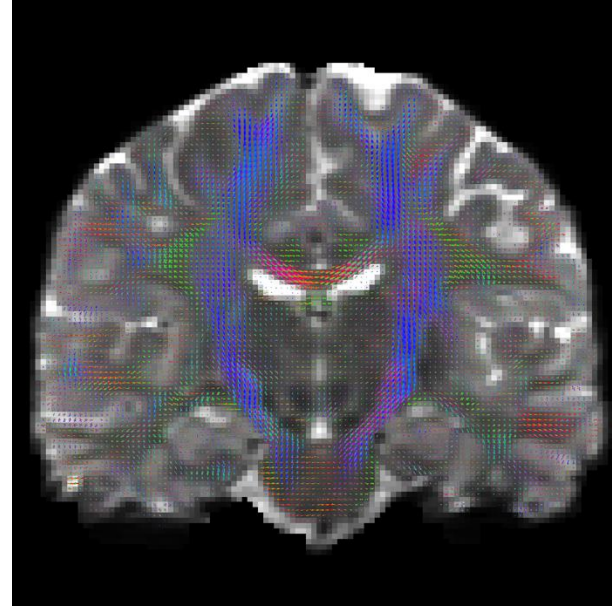
- The spherical deconvolution operation is ill-posed and susceptible to noise
- Tournier et al (2007) introduced a **non-negativity constraint** to the reconstructed fODF
- This drastically improves the robustness to noise and improves angular resolution



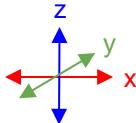
CSD in real data

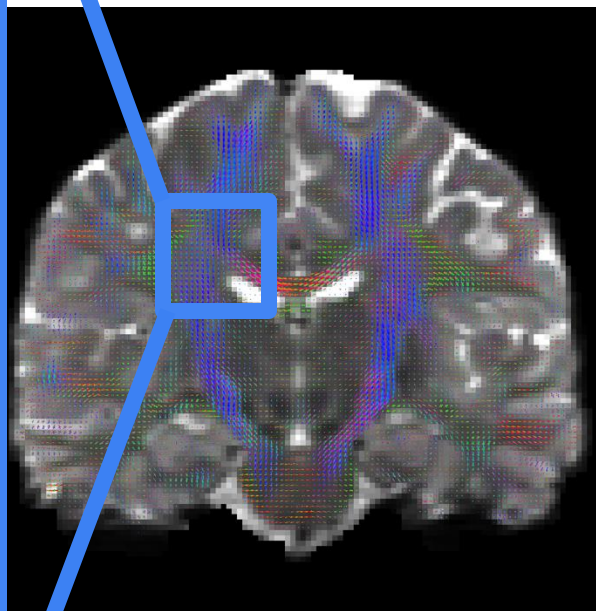
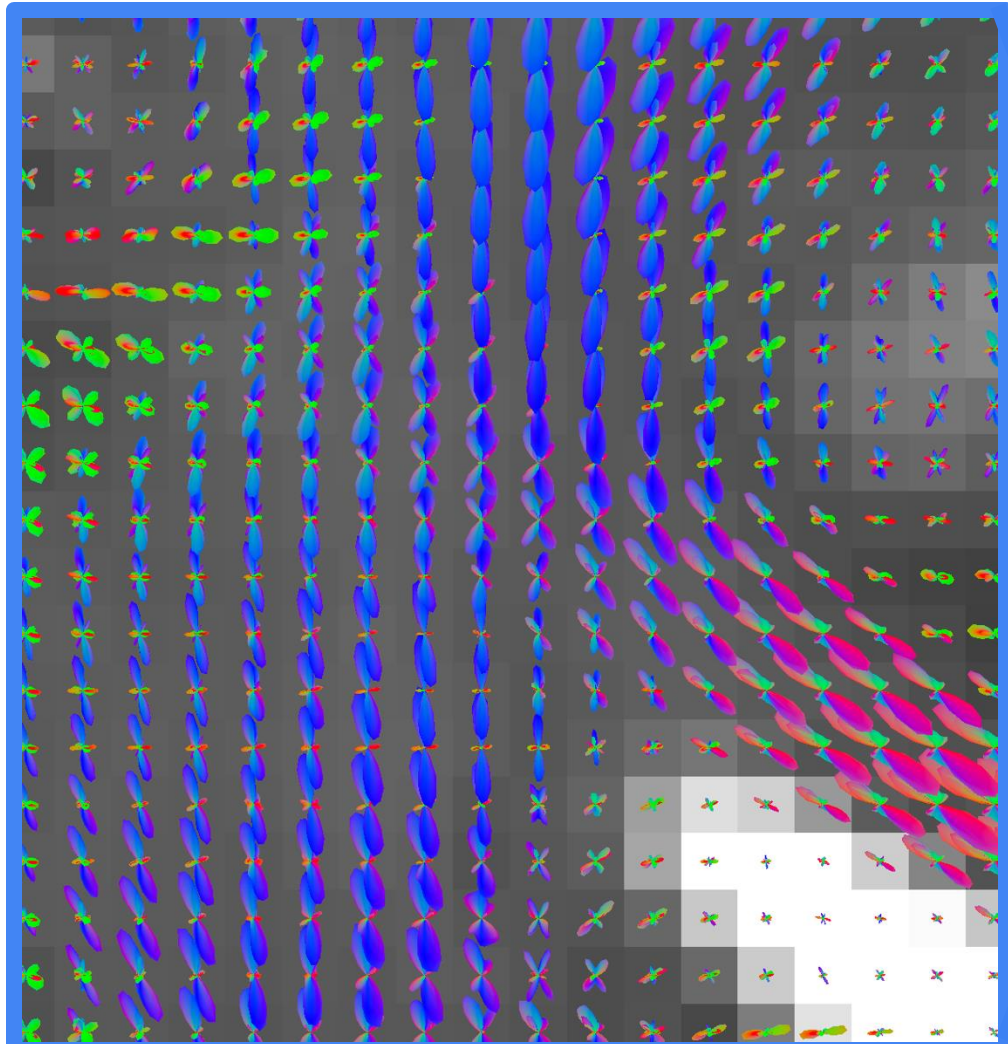


B0 diffusion signal

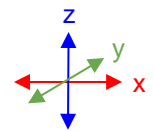


fODFs





fODFs



Coding Practicals

Coding practicals

- Three coding practicals:
 - Diffusion tensor
 - Ball-and-stick model
 - Spherical deconvolution
- Estimate model parameters in each voxel of the FiberCup dataset¹

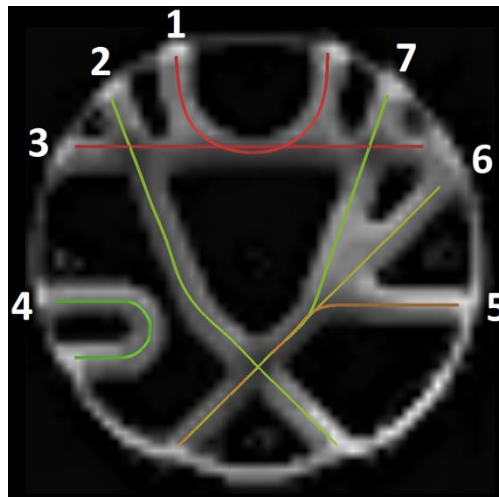


https://github.com/ethompson93/dmri_analysis_techniques

¹Poupon, C., Laribiere, L., Tournier, G., Bernard, J., Fournier, D., Fillard, P., Descoteaux, M., et al. (2010). A Diffusion Hardware Phantom Looking Like a Coronal Brain Slice. *Proceedings of the International Society for Magnetic Resonance in Medicine*.

FiberCup Data

- Built as part of a MICCAI challenge and mimics a coronal section (3 slices) of the brain
- Diffusion MRI simulated from known ground truth fibre bundles



Poupon, C., Laribiere, L., Tournier, G., Bernard, J., Fournier, D., Fillard, P., Descoteaux, M., et al. (2010). [A Diffusion Hardware Phantom Looking Like a Coronal Brain Slice](#). *Proceedings of the International Society for Magnetic Resonance in Medicine*.

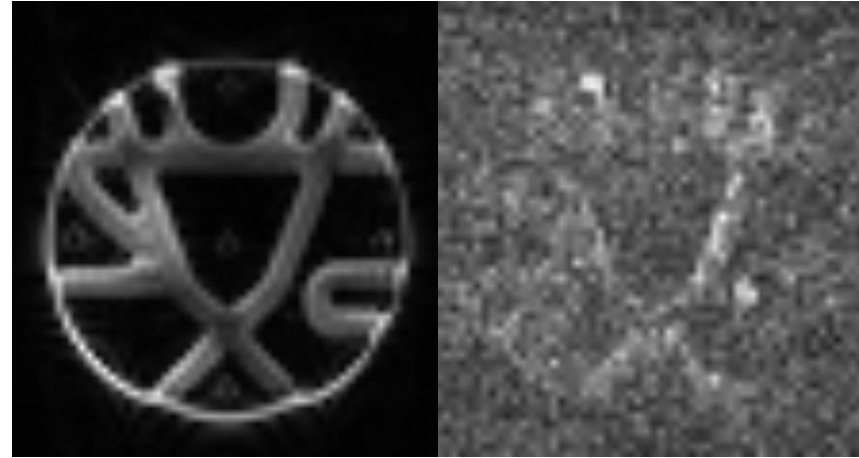
Fillard, P., Descoteaux, M., Goh, A., Gouttard, S., Jeurissen, B., Malcolm, J., Ramirez-Manzanares, A., et al. (2011). [Quantitative Evaluation of 10 Tractography Algorithms on a Realistic Diffusion MR Phantom](#). *NeuroImage*, 56(1), 234–220.

FiberCup Data

- Built as part of a MICCAI challenge and mimics a coronal section (3 slices) of the brain
- Diffusion MRI simulated from known ground truth fibre bundles

Files:

- Diffusion weighted images “fibrecup.nii.gz”
- White matter mask “wm_mask.nii.gz”
- B-values and b-vectors in the ‘grad.txt’ file



wm_mask.nii.gz



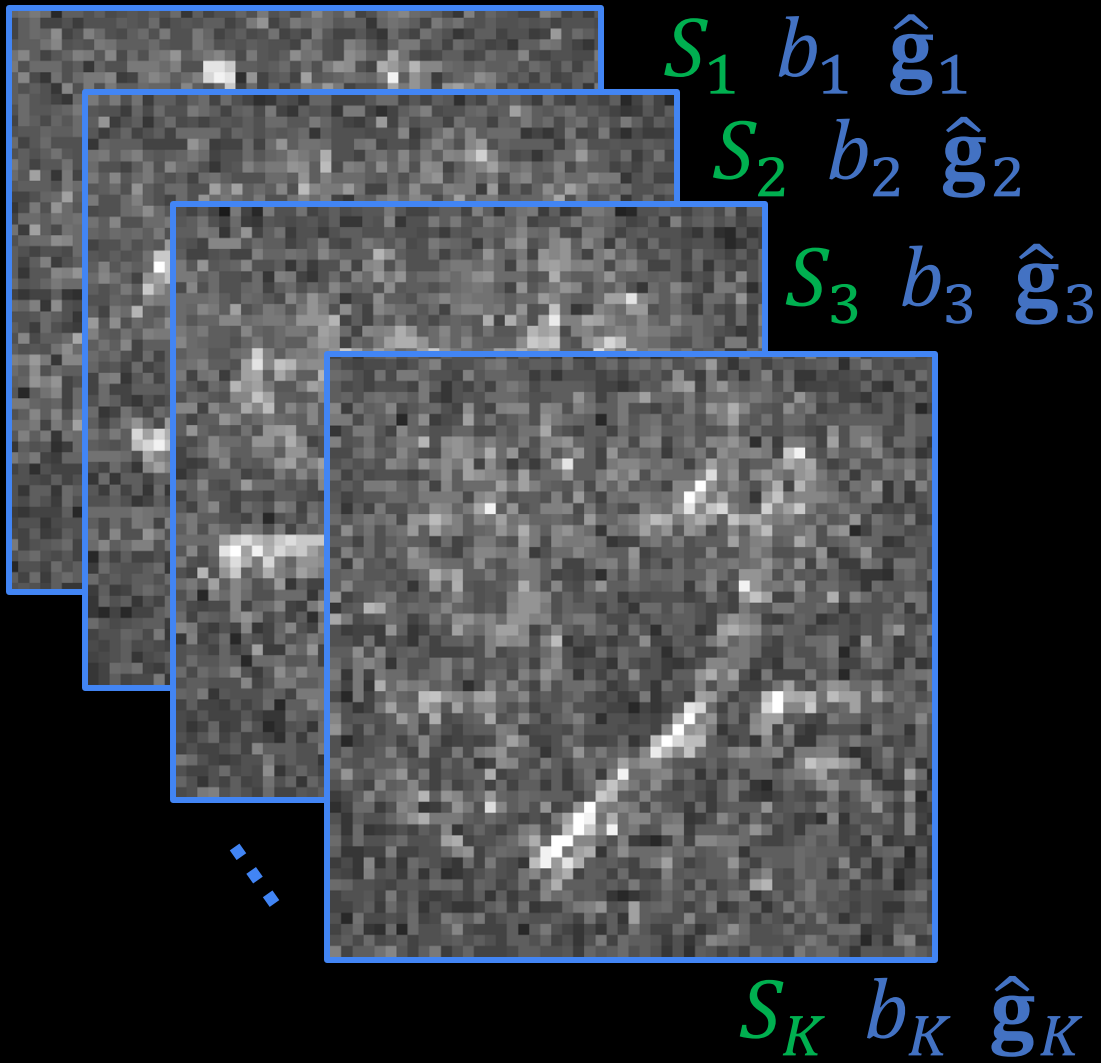
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Summary of the practical – overall picture + specific aims of the tasks

- **Aim:** fit parameters of interest
 - Diffusion tensor: D_{xx} , D_{yy} , D_{zz} , D_{xy} , D_{xz} , D_{yz}
 - Ball and stick: stick volume fraction f , and direction in terms of θ , ϕ
- **How?** Find parameter values **for each voxel** that minimise error between model and measurements
- We'll use non-linear least squares – scipy optimise least-squares
- In each voxel we use measurements from all gradient directions to fit the model

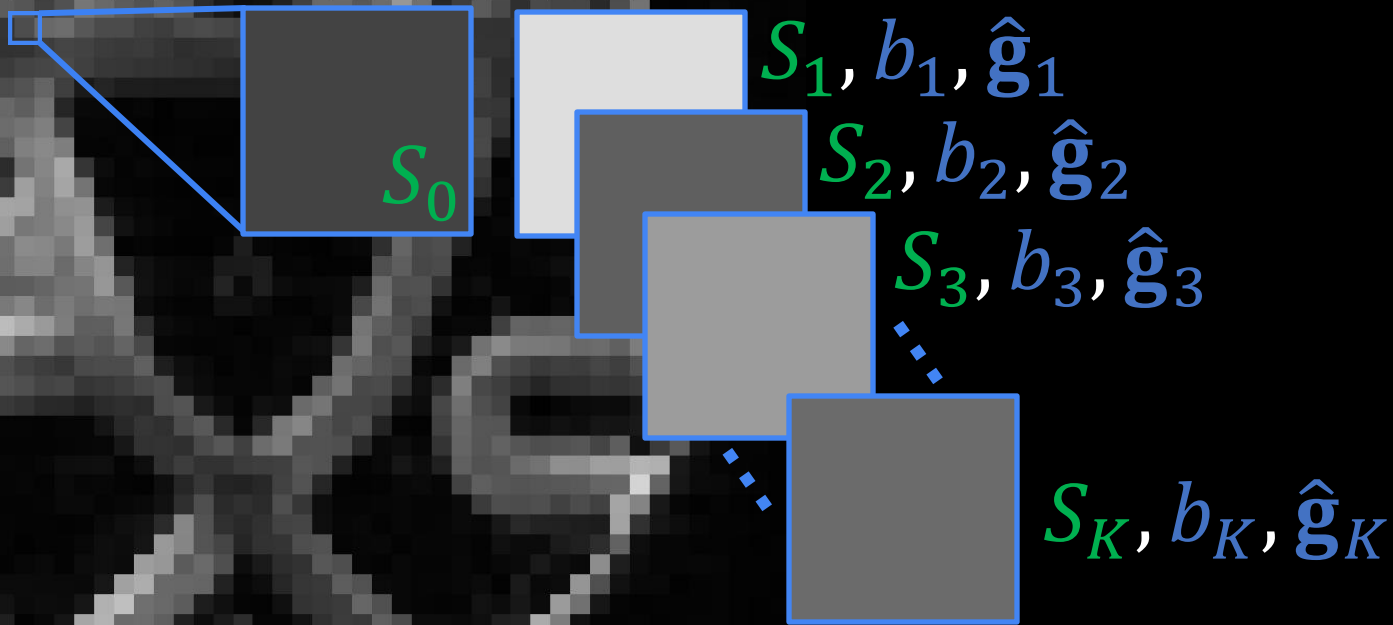












Measured signal

Simulated signal

 S_0 $S_1, b_1, \hat{\mathbf{g}}_1$ $S_2, b_2, \hat{\mathbf{g}}_2$ $S_3, b_3, \hat{\mathbf{g}}_3$ \vdots $S_K, b_K, \hat{\mathbf{g}}_K$

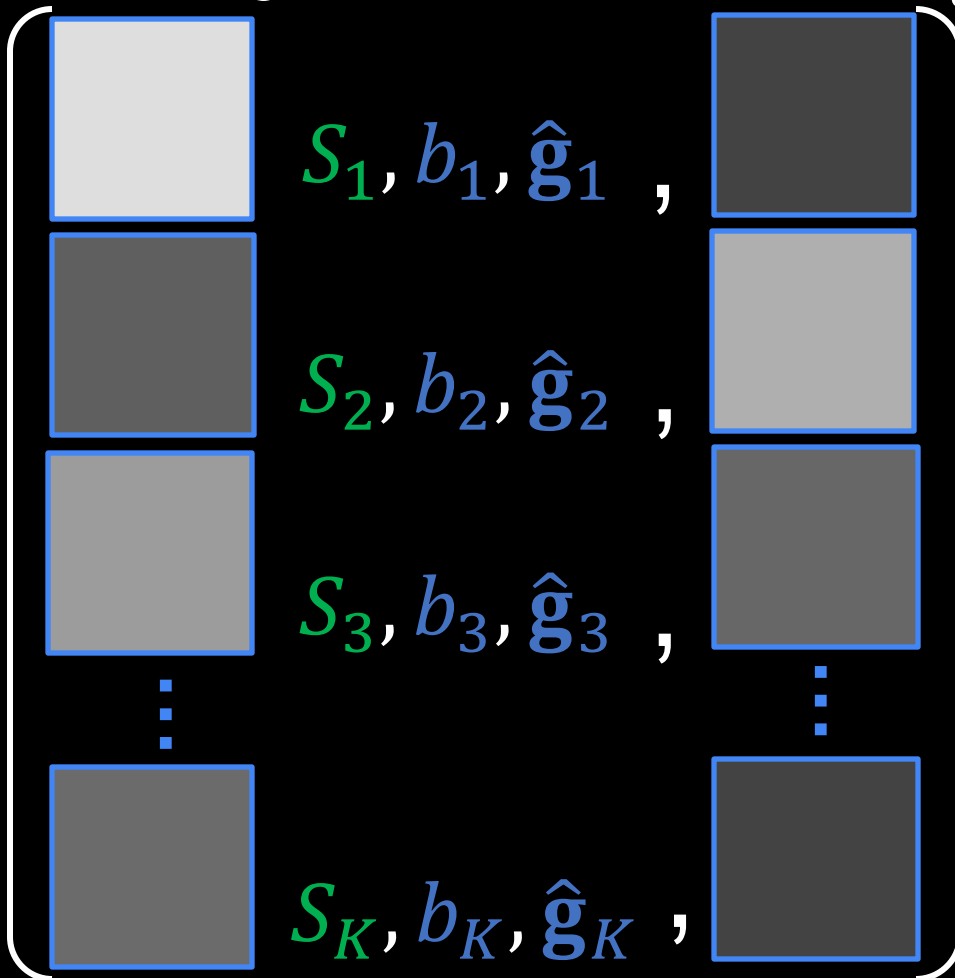

$$S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

$$\mathbf{D} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} * 0.003$$

Measured signal

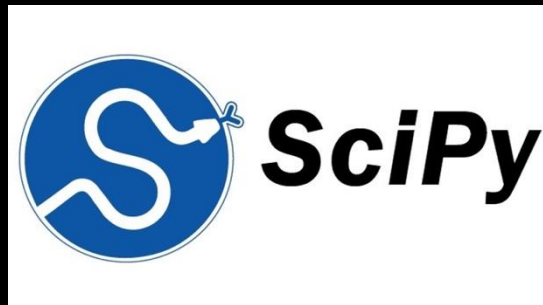
Simulated signal

SSE



$$S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

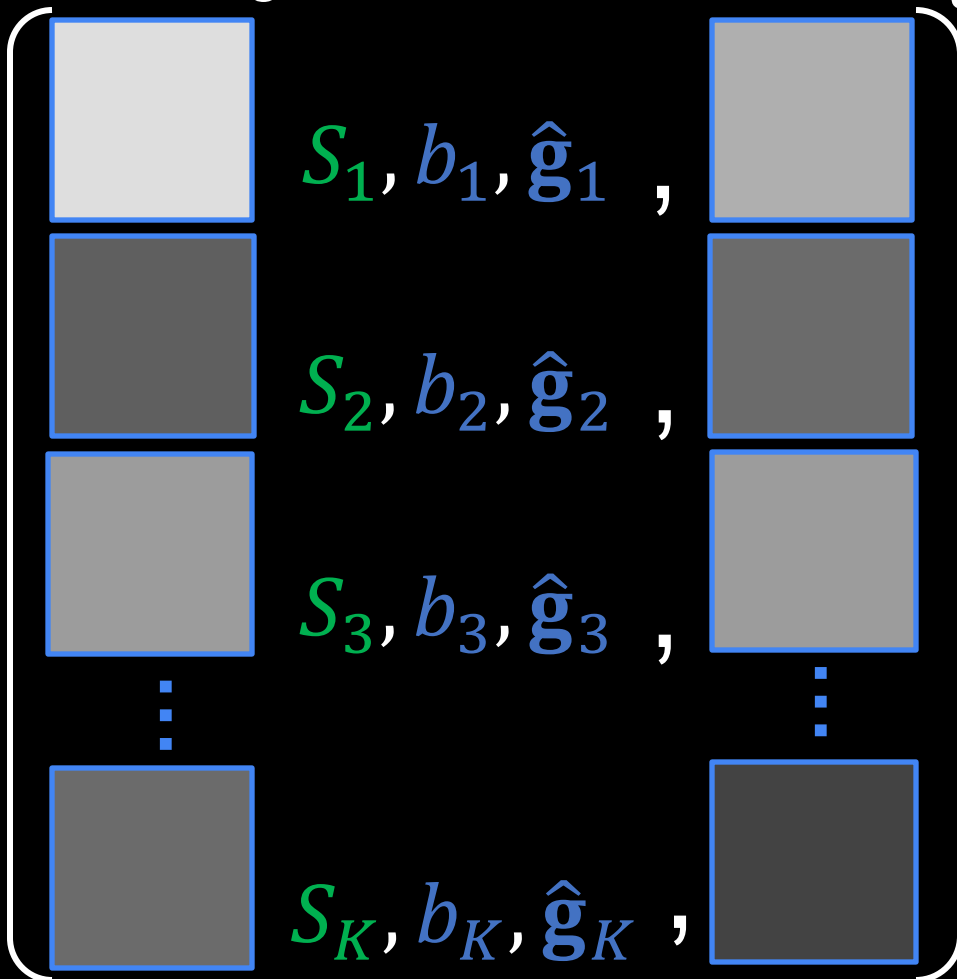
$$\mathbf{D} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} * 0.003$$



Measured signal

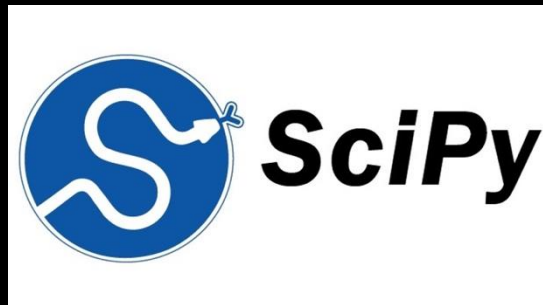
Simulated signal

SSE



$$S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

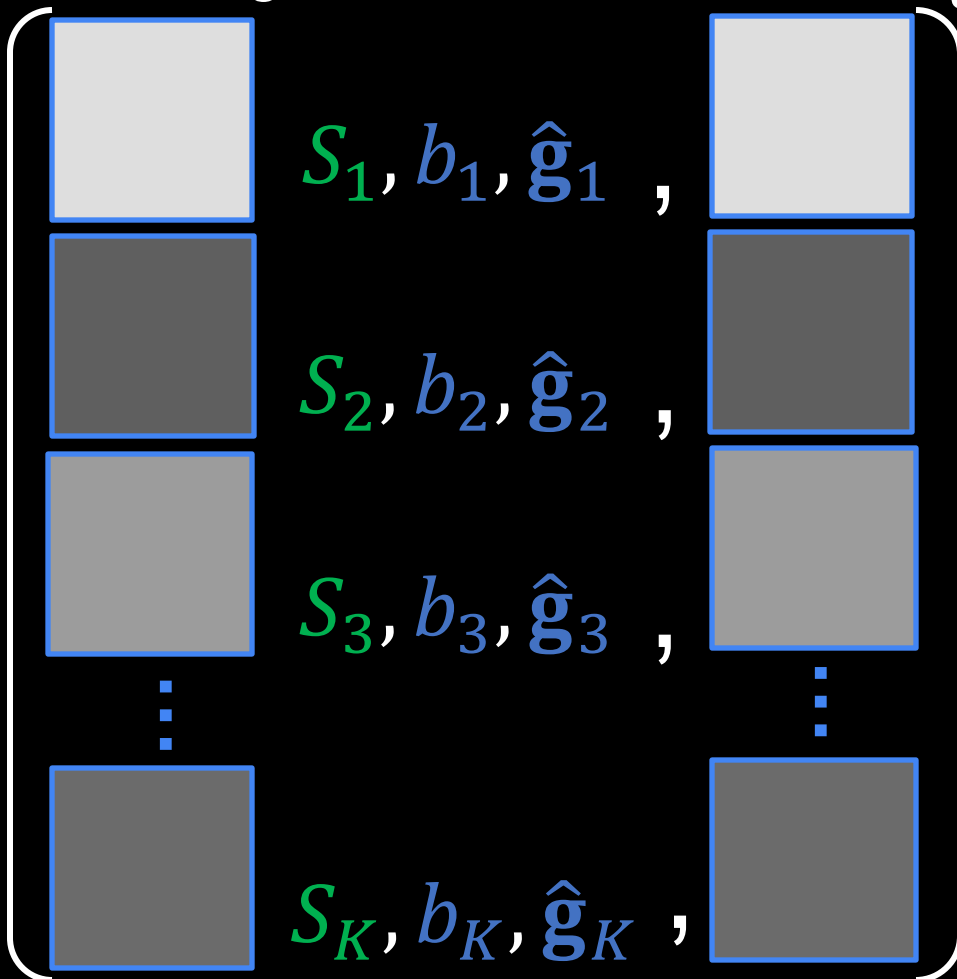
$$\mathbf{D} = \begin{pmatrix} 0.5 & 0.1 & 0 \\ 0.1 & 1 & 0.2 \\ 0 & 0.2 & 1 \end{pmatrix} * 0.003$$



Measured signal

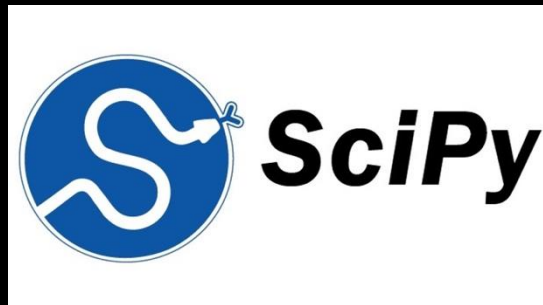
Simulated signal

SSE



$$S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

$$\mathbf{D} = \begin{pmatrix} 0.8 & 0.1 & 0.3 \\ 0.1 & 0.5 & 0.1 \\ 0.3 & 0.1 & 0.6 \end{pmatrix} * 0.003$$



Simulated signal



⋮



$$s_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

Simulated signal



$$s_0 \exp(-b_1 \hat{\mathbf{g}}_1^T \mathbf{D} \hat{\mathbf{g}}_1)$$



$$s_0 \exp(-b_2 \hat{\mathbf{g}}_2^T \mathbf{D} \hat{\mathbf{g}}_2)$$



$$s_0 \exp(-b_3 \hat{\mathbf{g}}_3^T \mathbf{D} \hat{\mathbf{g}}_3)$$

⋮

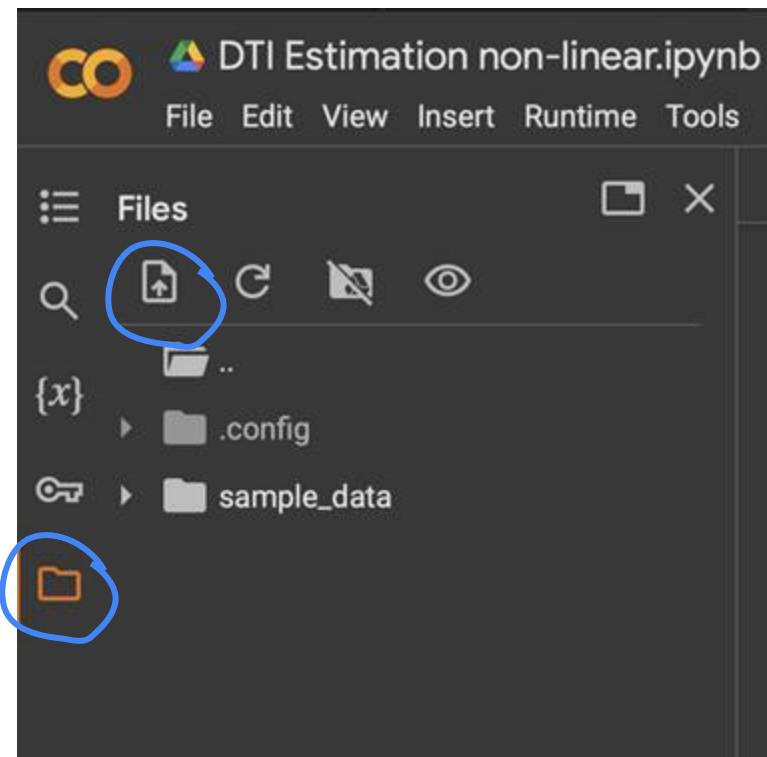


$$s_0 \exp(-b_K \hat{\mathbf{g}}_K^T \mathbf{D} \hat{\mathbf{g}}_K)$$

Get into groups! (2 or 3 people)

Uploading the data

- Download the sample data from <https://drive.google.com/drive/folders/12hHKJoAXDB-AsNTzxXf4ZvSbfq-7qmX?usp=sharing> (link in Colab and on Github)
- Upload to “files”



Diffusion Tensor: Coding Exercise

- Estimate the diffusion tensor in each voxel in a phantom dataset

$$S_k = S_0 \exp(-b_k \hat{g}_k^T \mathbf{D} \hat{g}_k)$$

Measured
Imaging parameters
To be estimated

$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$



https://github.com/ethompson93/dmri_analysis_techniques

Ball and Stick Model: Coding Exercise

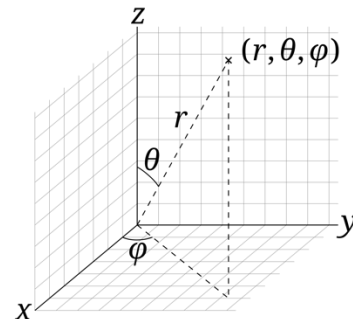
$$S_k = S_0 \left[(1 - f) \underbrace{\exp(-b_k d)}_{\text{signal from "ball" compartment}} + f \underbrace{\exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)}_{\text{signal from "stick" compartment with direction } \mathbf{v}} \right]$$

- We want to estimate f and \mathbf{v} in each voxel
- We express \mathbf{v} in spherical coordinates (θ, ϕ) for efficiency
- Need to convert to Cartesian coordinates for dot product with \mathbf{g} :

$$x = \sin \theta \cos \phi$$

$$y = \sin \theta \sin \phi$$

$$z = \cos \theta$$



CSD coding exercise

- We will use DIPY, an open-source python library, to perform constrained spherical deconvolution on the Fibercup phantom
- The notebook will take you through the steps of estimating the fibre response function and running the constrained spherical deconvolution

Different Software for dMRI analysis

Not an exhaustive list!

DIPY



dmipy

Public



Conclusions

- Analysis techniques unlock biological insight from dMRI
 - e.g. microstructural information and fibre orientations for tractography
- The diffusion tensor quantifies anisotropy in the diffusion signal, but lacks microstructural specificity
- Compartment models, such as ball-and-stick, characterise different tissue environments with biophysical models
- Constrained spherical deconvolution is a method for estimating the fibre orientation distribution function

Acknowledgements



Professor Danny Alexander and the CU-MONDAI group
at UCL Hawkes Institute

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