

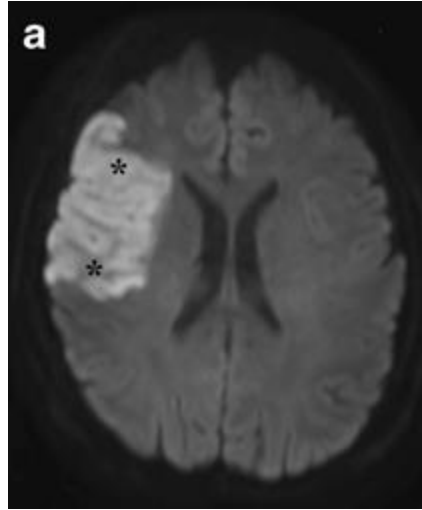
Analysis Techniques

Ellie Thompson and Anna Schroder

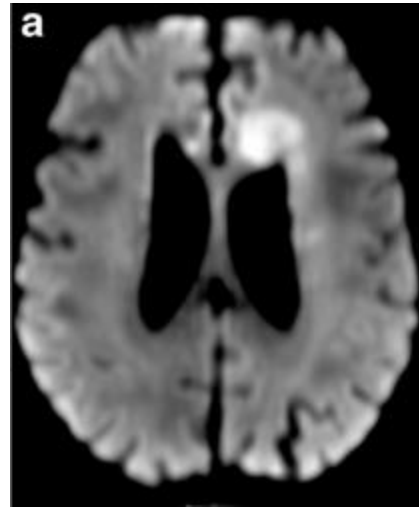
Overview

- Introduction: using analysis techniques to gain biomedical insights from diffusion MRI
- Practical 1: Diffusion tensor imaging
- Practical 2: Ball-and-stick model
- Practical 3: Constrained spherical deconvolution
- Summary

What can we do with diffusion MRI?



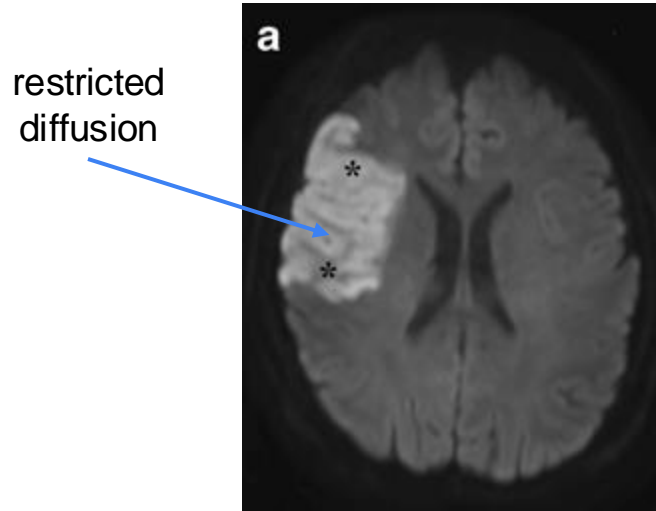
Acute stroke



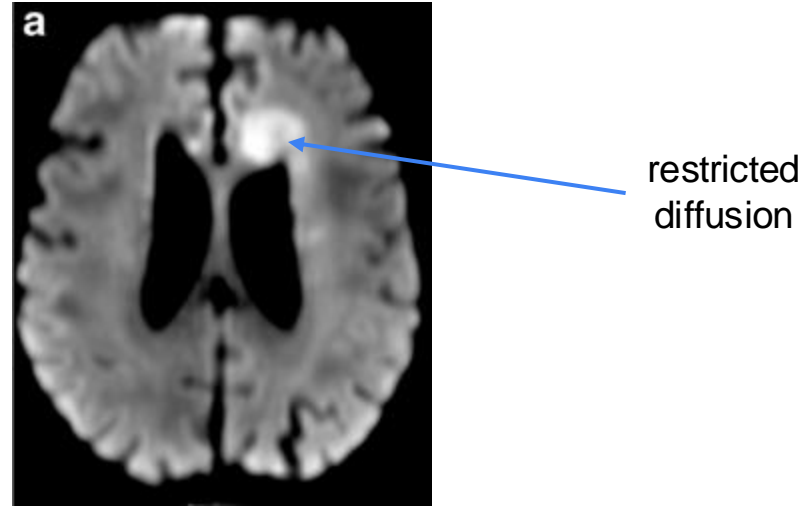
CNS lymphoma

Pre-processed scans provide some clinical insight, however they lack **quantitative biomarkers** or **complex microstructural** information

What can we do with diffusion MRI?



Acute stroke



CNS lymphoma

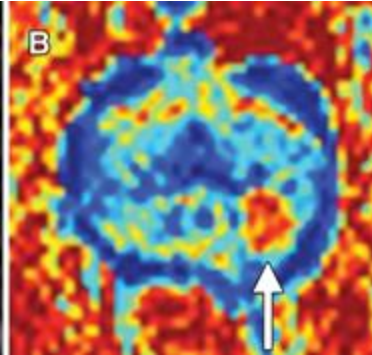
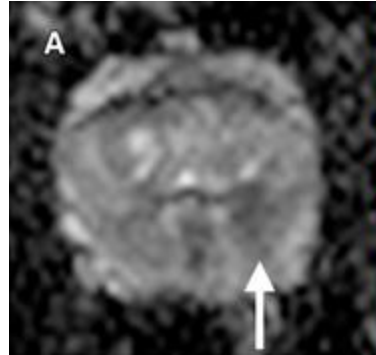
Pre-processed scans provide some clinical insight, however they lack **quantitative biomarkers** or **complex microstructural** information

We can use analysis techniques to gain
biomedical insight from dMRI

We can use analysis techniques to gain **biomedical insight** from dMRI

e.g. VERDICT-MRI: non-invasive histology for prostate cancer

Apparent diffusion coefficient (ADC) map



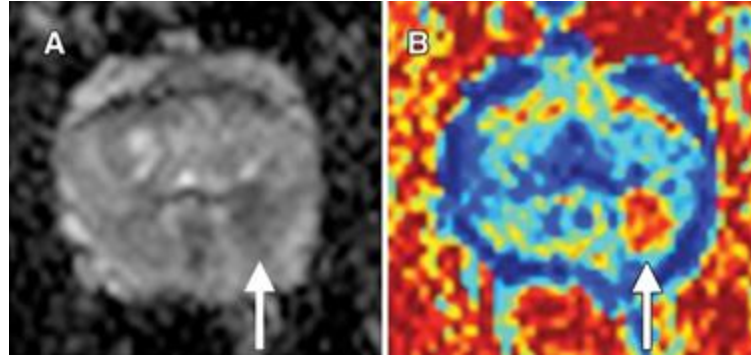
VERDICT
intracellular
volume fraction
map

Images in a 57-year-old man with targeted biopsy-proven Gleason 3+4 prostate cancer.

We can use analysis techniques to gain **biomedical insight** from dMRI

e.g. VERDICT-MRI: non-invasive histology for prostate cancer

Apparent diffusion coefficient (ADC) map

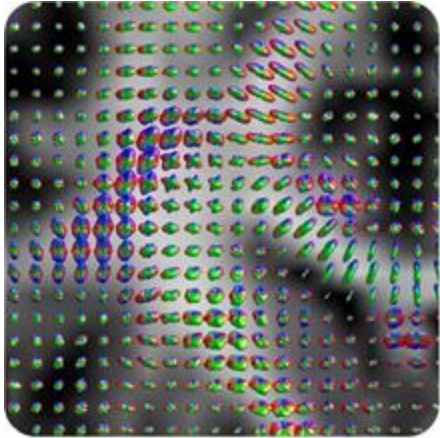


VERDICT
intracellular
volume fraction
map

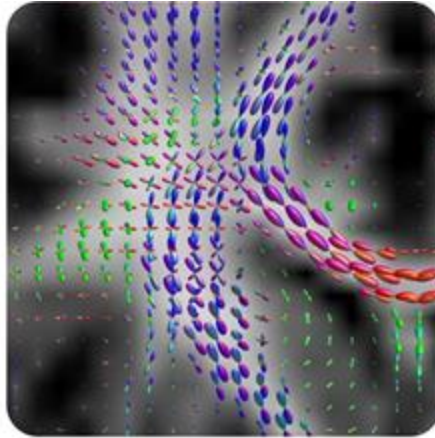
“New scanning technique reduces unnecessary biopsies by 90% meaning thousands of men could be spared pain and anxiety” - prostate cancer UK

We can use analysis techniques to gain **biomedical insight** from dMRI

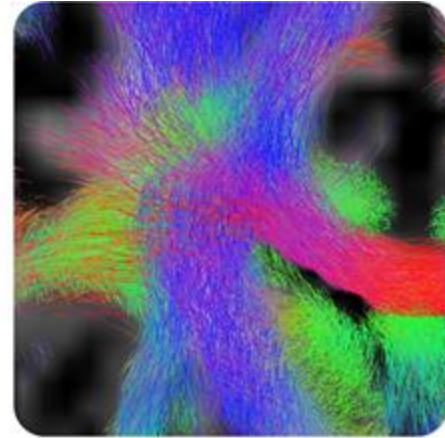
e.g. modelling fibre orientations for tractography



raw dMRI signal



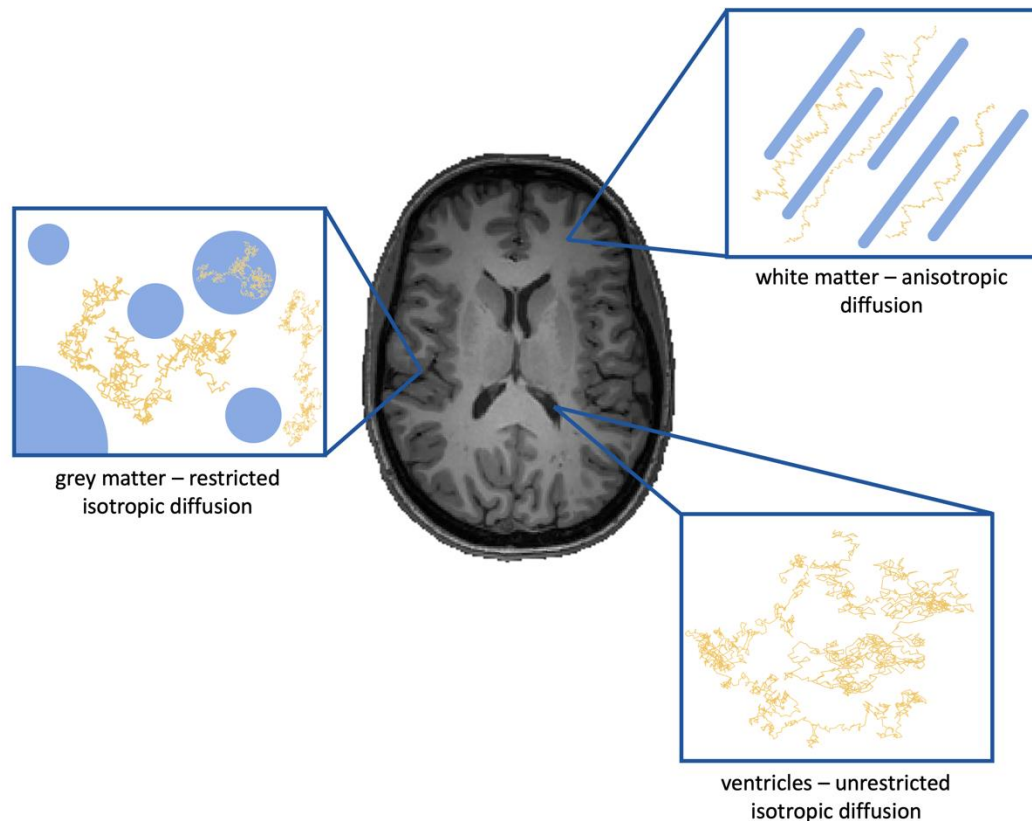
fibre orientations



tractography

Why does the diffusion MRI signal reflect tissue structure?

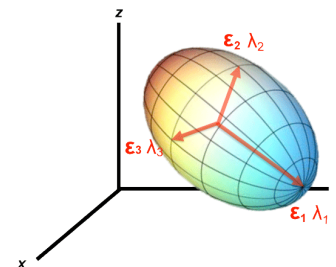
- The diffusion of water molecules depends on the local tissue environment
- We can infer properties of the underlying tissue by fitting models to the diffusion-weighted signal



Signal representations vs models

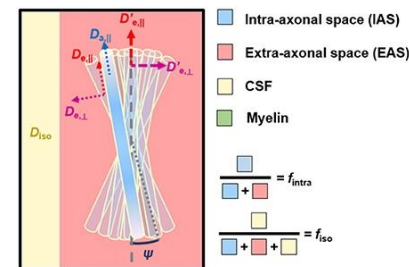
Signal representations describe the signal through mathematical formulae (basis functions)

- General and have few assumptions – independent of a theory
- Coefficients of the basis may be sensitive to pathological changes
- e.g Diffusion tensor, diffusion kurtosis



Biophysical models are based on theories that relate the signal to biological properties of the tissue

- provide key insight how biophysical parameters will affect the signal
- difficult to validate



Estimating diffusivity

- We can relate the diffusion MRI signal to the diffusivity within a voxel using a simple exponential model
- Single measure of diffusivity within a voxel

Measured
Imaging parameters
To be estimated

$$S_k = S_0 \exp(-b_k d)$$

B-value for gradient k

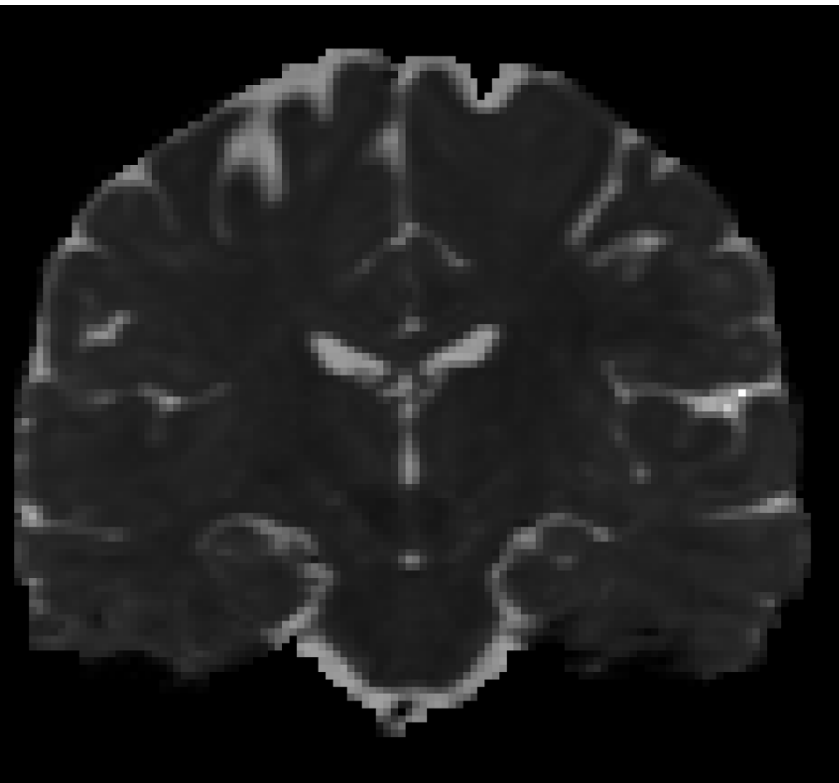
Signal after applying a diffusion-weighted gradient k in direction q_k with b-value b_k

Signal with no diffusion-weighted gradient applied

Diffusivity within a voxel

The diagram illustrates the exponential model for diffusion MRI signal. The equation $S_k = S_0 \exp(-b_k d)$ is centered. Above it, the text 'Measured' is in green, 'Imaging parameters' is in blue, and 'To be estimated' is in red. Arrows point from these labels to the corresponding parts of the equation: 'Measured' points to S_k , 'Imaging parameters' points to S_0 , and 'To be estimated' points to b_k . To the right, 'B-value for gradient k' is in black, with an arrow pointing to b_k . Below the equation, three arrows point to descriptive text: one from S_k to 'Signal after applying a diffusion-weighted gradient k in direction q_k with b-value b_k ', one from S_0 to 'Signal with no diffusion-weighted gradient applied', and one from d to 'Diffusivity within a voxel'.

Estimating diffusivity



Measured
Imaging parameters
To be estimated

$$S_k = S_0 \exp(-b_k d)$$

B-value for
gradient k

Applying a
gradient k
b-value b_k

Signal with no
diffusion-weighted
gradient applied

Diffusivity
within a voxel

The Diffusion Tensor

- The diffusion tensor enables us to characterise Gaussian diffusion in 3D in each voxel

$$S_k = S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

Diagram illustrating the Diffusion Tensor equation and its components:

- S_k : Signal after applying a diffusion-weighted gradient k in direction $\hat{\mathbf{g}}_k$ with b-value b_k
- S_0 : Signal with no diffusion-weighted gradient applied
- b_k : B-value for gradient k
- $\hat{\mathbf{g}}_k$: Unit vector of the direction of gradient k
- \mathbf{D} : The diffusion tensor

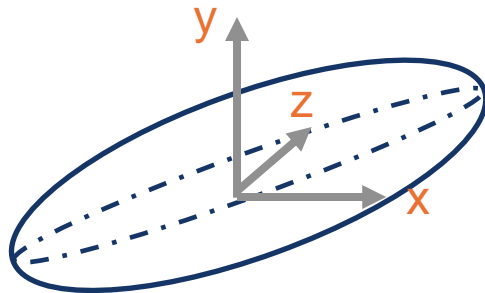
Legend:

- Measured (Green)
- Imaging parameters (Blue)
- To be estimated (Red)

What is the diffusion tensor?

- 3x3 positive-definite symmetric matrix characterising displacement/diffusion in 3D

$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$

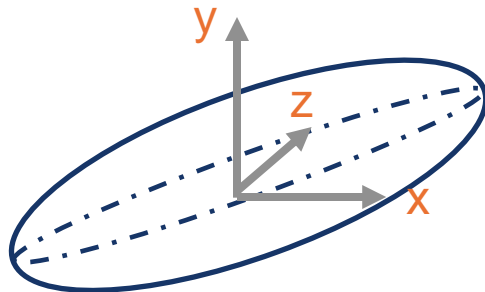


- D_{xx}, D_{yy}, D_{zz} : diffusion along 3 orthogonal axis (always positive)
- D_{xy}, D_{xz}, D_{yz} : correlation between displacements along these orthogonal axis (positive or negative)

What is the diffusion tensor?

- 3x3 positive-definite symmetric matrix characterising displacement/diffusion in 3D

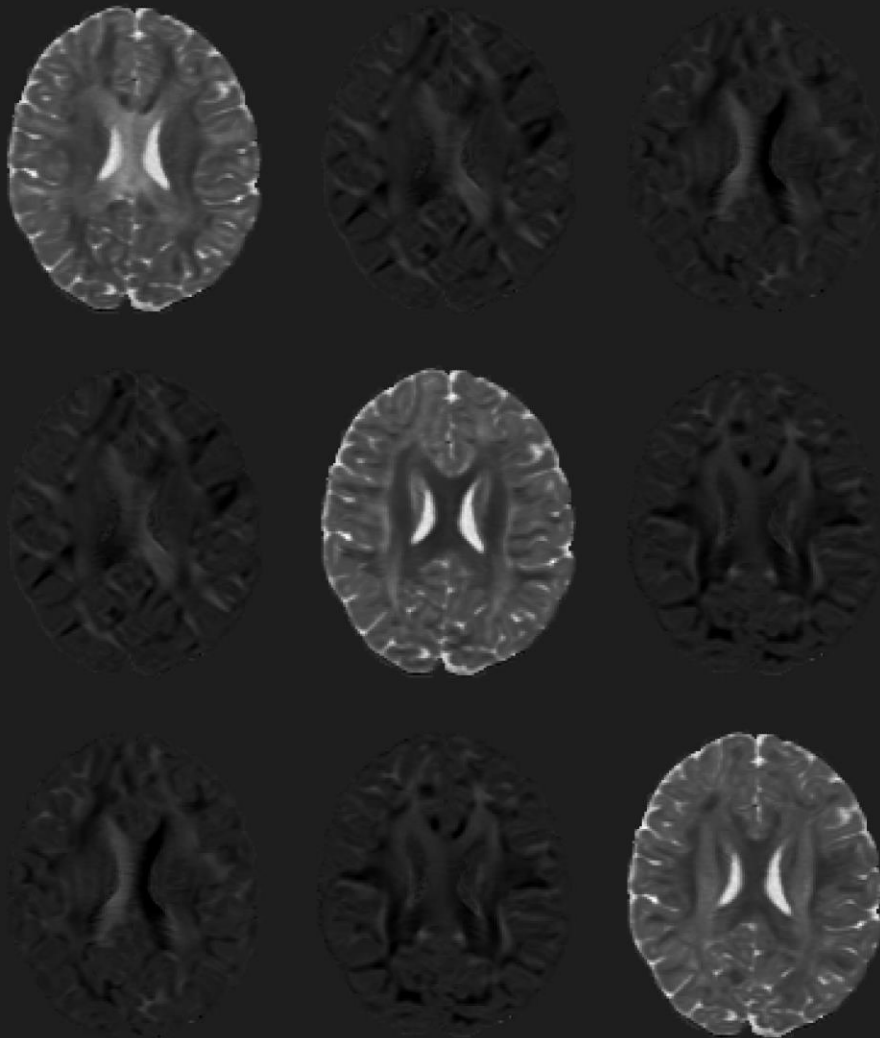
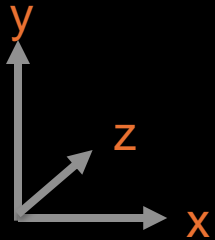
$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$



- D_{xx}, D_{yy}, D_{zz} : diffusion along 3 orthogonal axis (always positive)
- D_{xy}, D_{xz}, D_{yz} : correlation between displacements along these orthogonal axis (positive or negative)

The elements of diffusion tensor in the brain

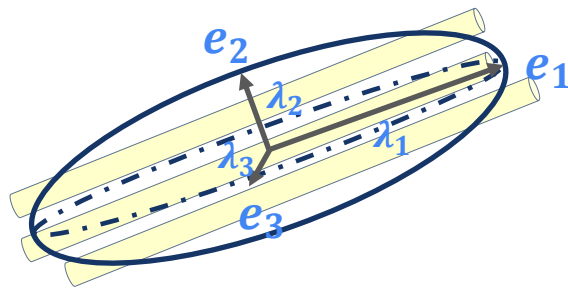
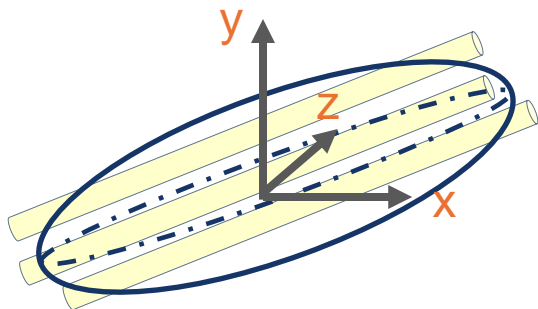
$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$



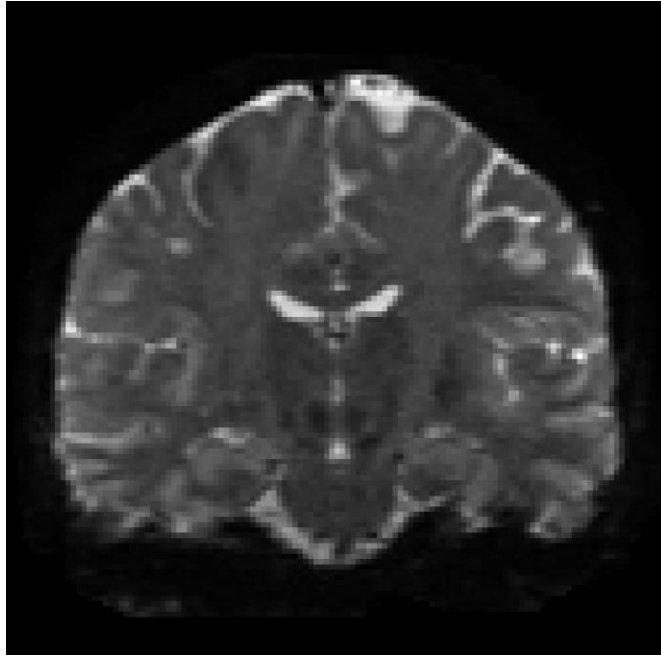
Ellipsoid from DT

- We can decompose the Diffusion tensor into eigen-values and eigen-vectors

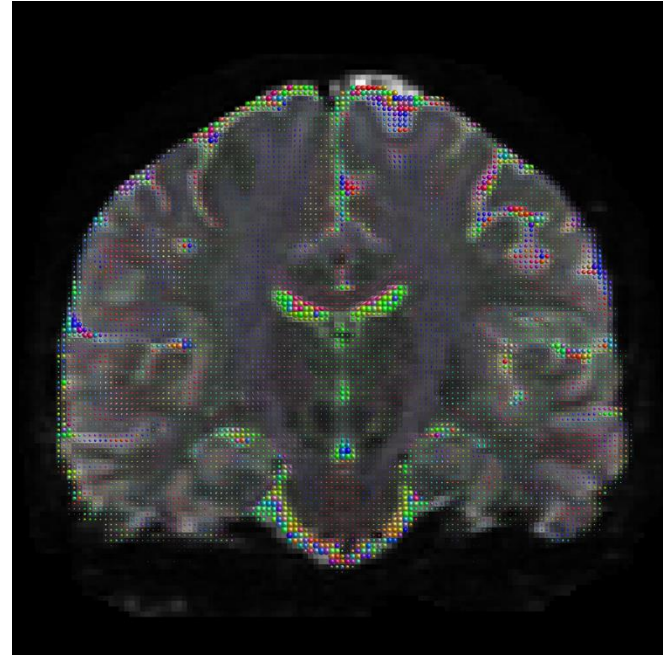
$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix} = [\mathbf{e}_1 \quad \mathbf{e}_2 \quad \mathbf{e}_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \mathbf{e}_1 \\ \mathbf{e}_2 \\ \mathbf{e}_3 \end{bmatrix}$$



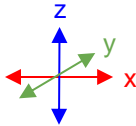
Diffusion Tensor in real data

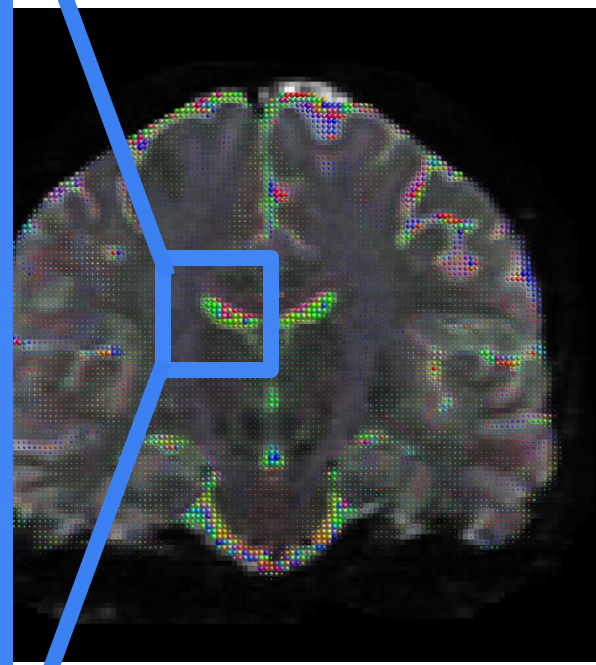
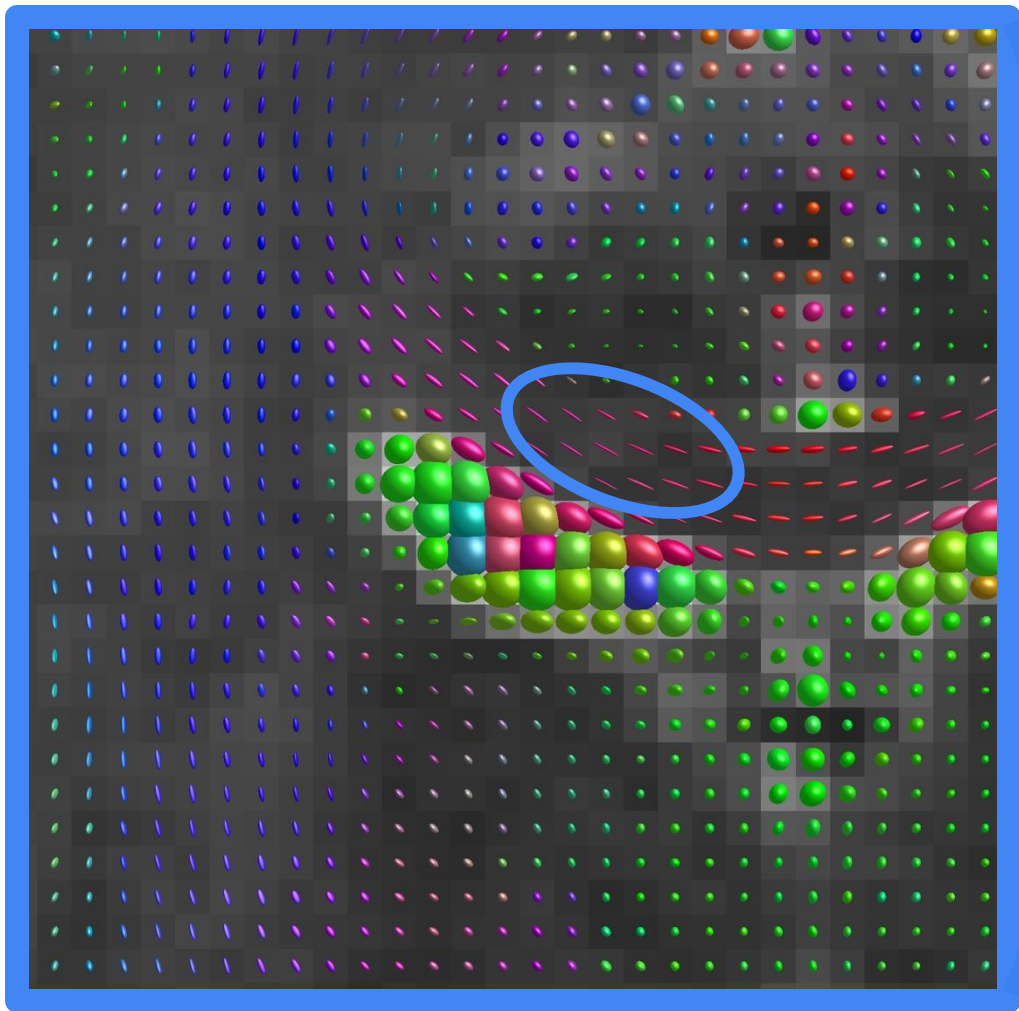


B0 diffusion signal

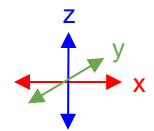


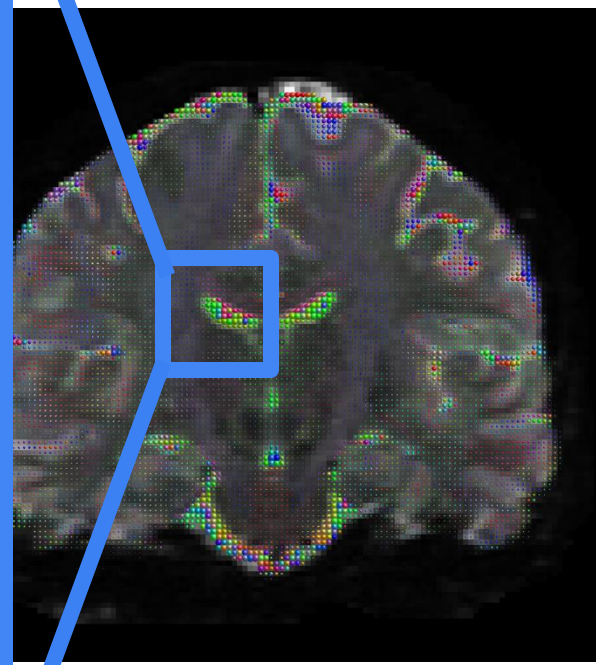
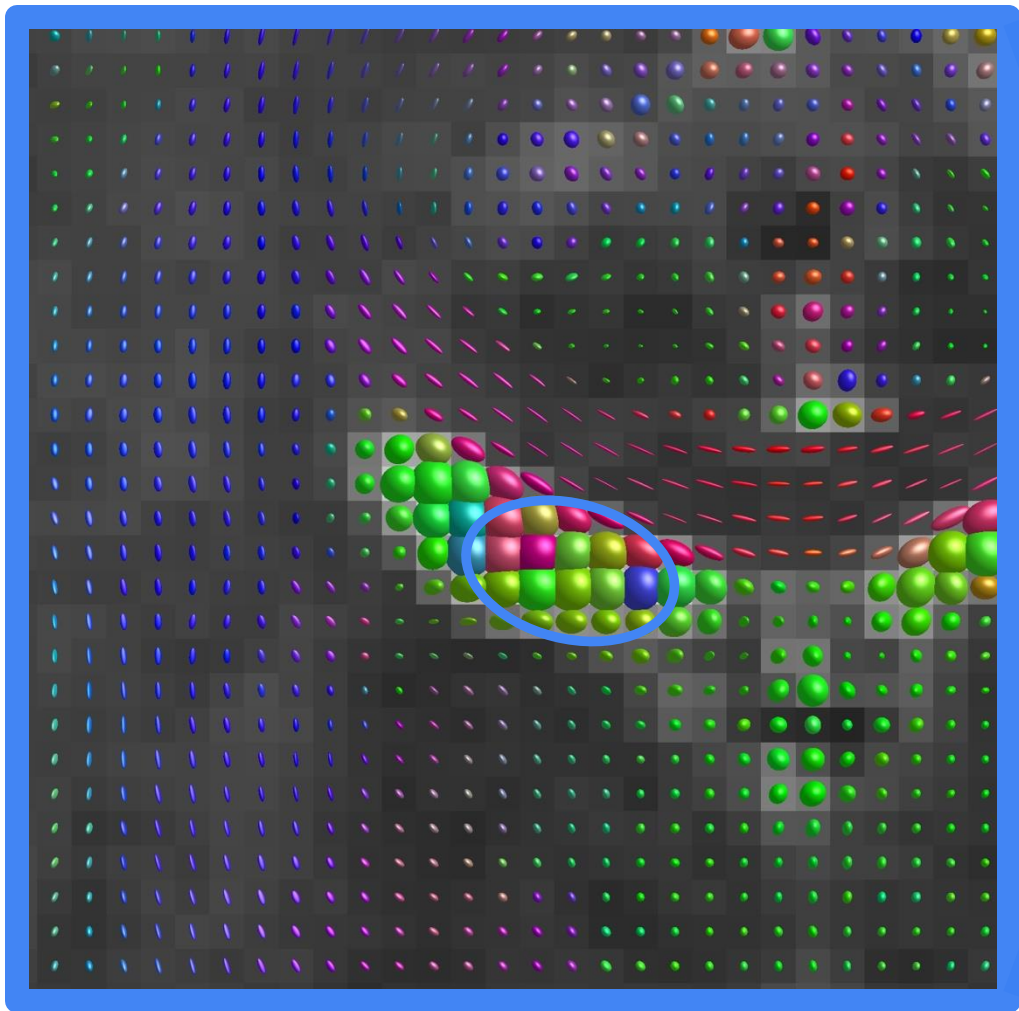
Diffusion tensors



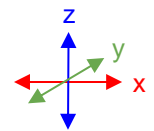


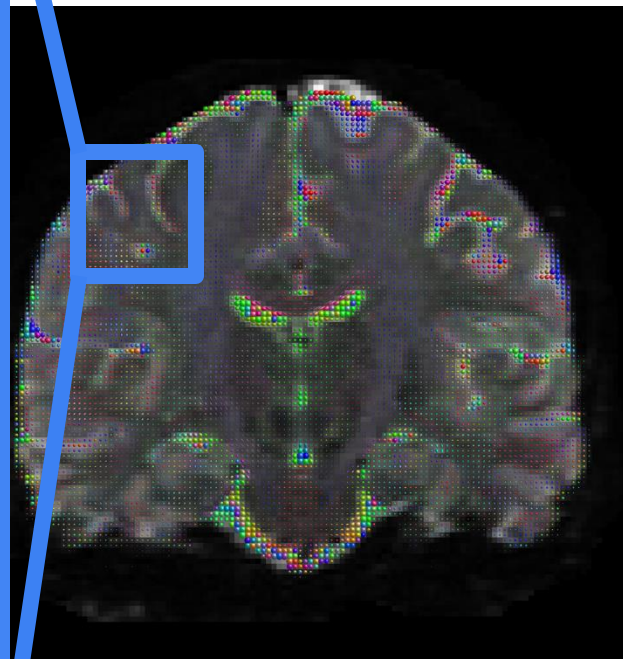
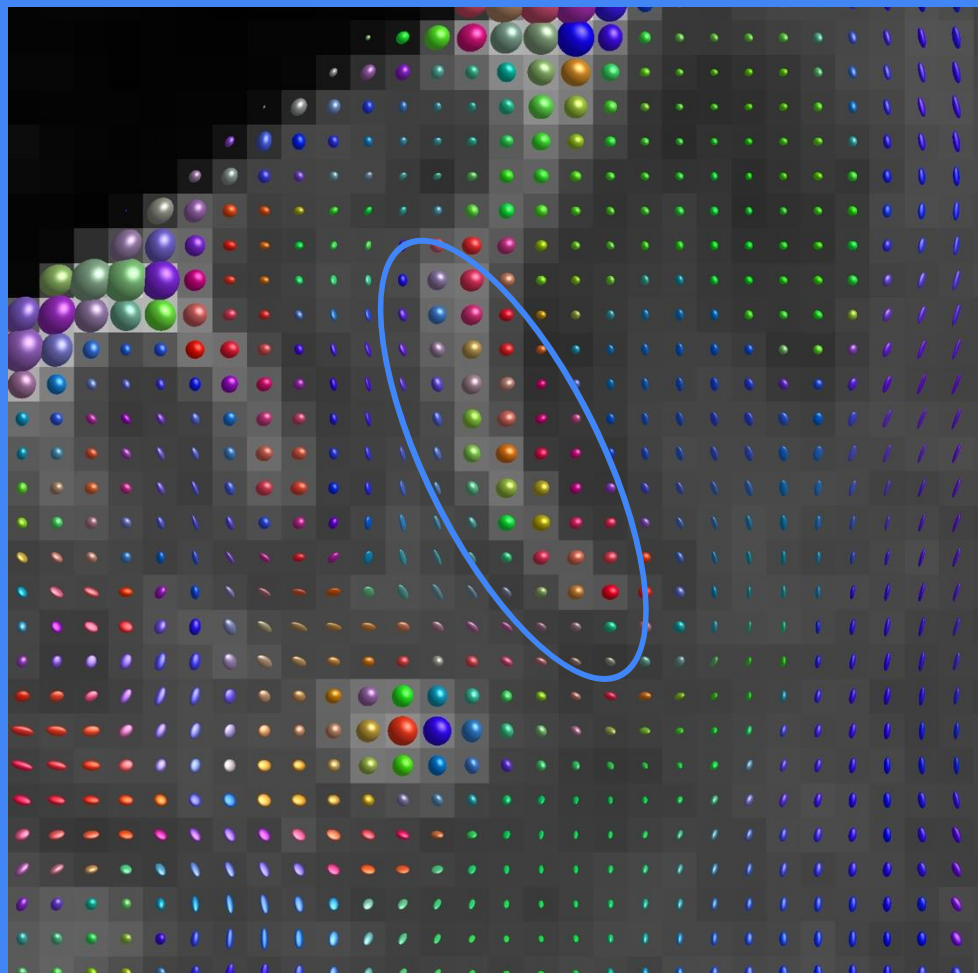
Diffusion tensors



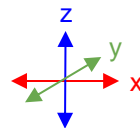


Diffusion tensors

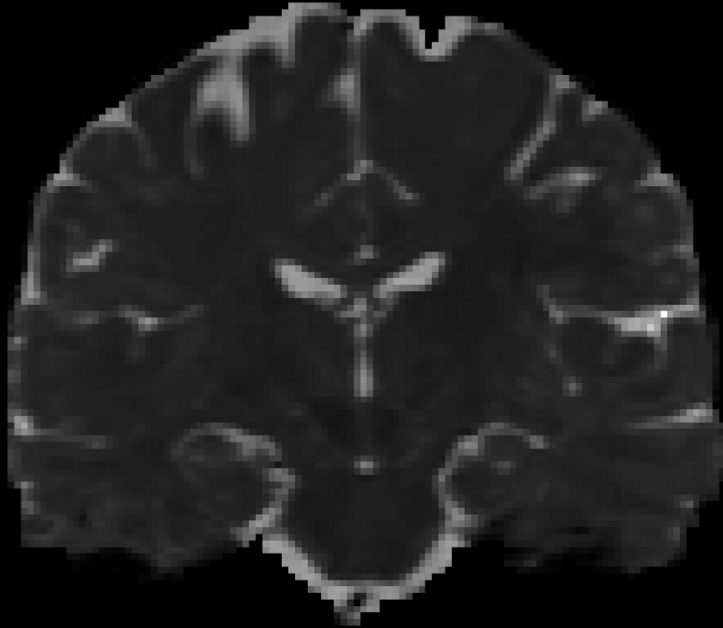




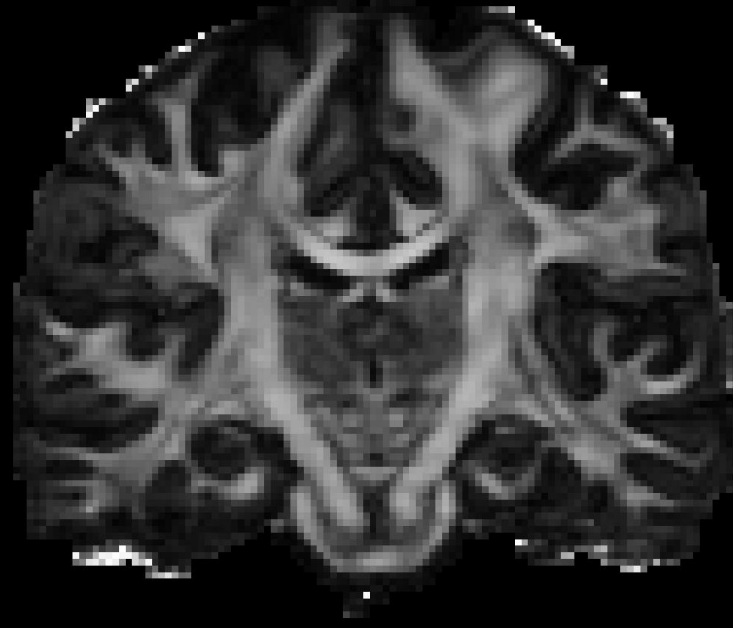
Diffusion tensors



Measures derived from the diffusion tensor



Mean Diffusivity (MD) = mean of the tensor eigenvalues



Fractional Anisotropy (FA) = normalised variance of tensor eigenvalues

Axial
Diffusivity,

Radial
Diffusivity

...

Fitting the diffusion tensor from an image

- Fitting the 6 variables of the diffusion tensor ($D_{xx}, D_{xy}, D_{xz}, D_{yy}, D_{yz}, D_{zz}$) from the diffusion image requires a minimum of 6 diffusion directions (+S(0))
- Methods:
 - Linear least squared
 - Weighted linear least squares
 - Non-linear least squares, etc

Fitting the diffusion tensor from an image

- Fitting the 6 variables of the diffusion tensor ($D_{xx}, D_{xy}, D_{xz}, D_{yy}, D_{yz}, D_{zz}$) from the diffusion image requires a minimum of 6 diffusion directions (+S(0))
- Methods:
 - Linear least squared
 - Weighted linear least squares
 - Non-linear least squares, etc
- Minimise the following function:

$$S_k - S_0 \exp(-b_k \hat{\mathbf{g}}_k^T \mathbf{D} \hat{\mathbf{g}}_k)$$

Coding practicals

- Three coding practicals:
 - Diffusion tensor
 - Ball-and-stick model
 - Spherical deconvolution
- Estimate model parameters in each voxel of the FiberCup dataset¹



https://github.com/ethompson93/dmri_analysis_techniques

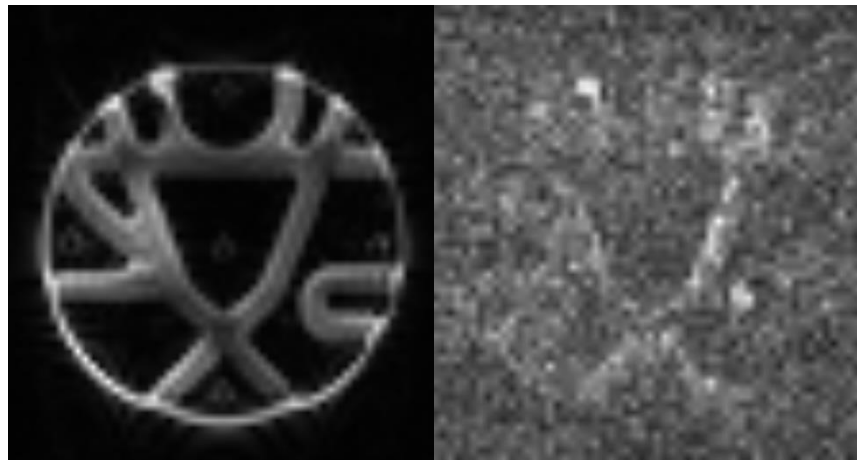
¹Poupon, C., Laribiere, L., Tournier, G., Bernard, J., Fournier, D., Fillard, P., Descoteaux, M., et al. (2010). A Diffusion Hardware Phantom Looking Like a Coronal Brain Slice. *Proceedings of the International Society for Magnetic Resonance in Medicine*.

FiberCup Data

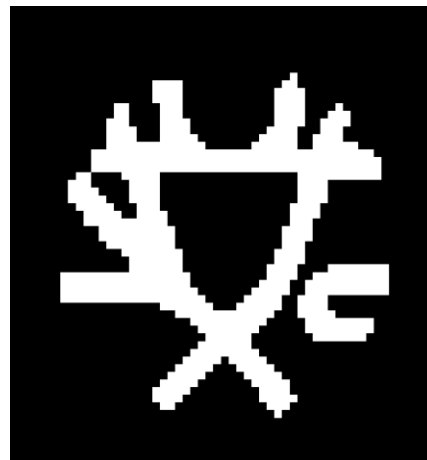
- Built as part of a MICCAI challenge and mimics the coronal section (3 slices) of the brain with deep and superficial U-fibre bundles Diffusion MRI simulated from known ground truth fibre bundles

grad.txt			
0	0	0	0
1	0	0	2000
0	-0.987414	-0.158158	2000
-0.026007	-0.761231	0.64796	2000
0.591136	0.716668	0.370062	2000
-0.236071	0.388148	0.890848	2000
-0.893021	0.197543	0.40434	2000
0.796184	-0.220899	0.56329	2000
0.233964	-0.963062	0.133318	2000
0.935686	-0.189418	0.29768	2000

fibrecup.nii.gz



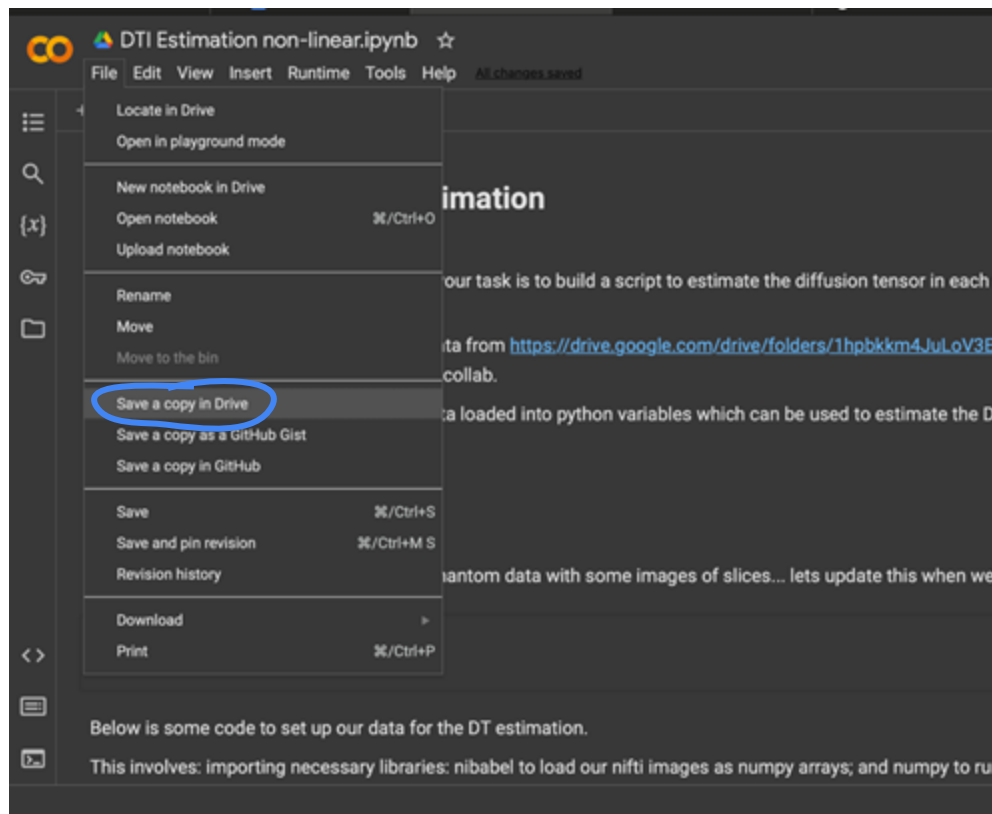
wm_mask.nii.gz



Poupon, C., Laribiere, L., Tournier, G., Bernard, J., Fournier, D., Fillard, P., Descoteaux, M., et al. (2010). [A Diffusion Hardware Phantom Looking Like a Coronal Brain Slice](#). *Proceedings of the International Society for Magnetic Resonance in Medicine*.

Fillard, P., Descoteaux, M., Goh, A., Gouttard, S., Jeurissen, B., Malcolm, J., Ramirez-Manzanares, A., et al. (2011). [Quantitative Evaluation of 10 Tractography Algorithms on a Realistic Diffusion MR Phantom](#). *NeuroImage*, 56(1), 234–220.

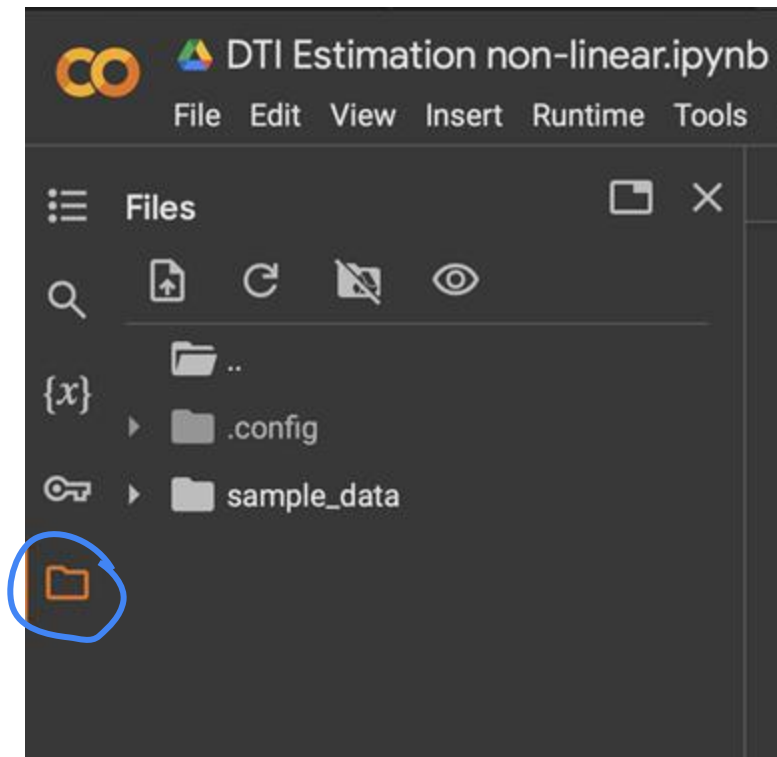
Making your own copy of the practicals



https://github.com/ethompson93/dmri_analysis_techniques

Uploading the data

- Download the sample data from https://drive.google.com/drive/folders/12hHKJoAXDB-AsNTzxXf4ZvSbfq-_7qmX?usp=sharing (link in Colab and on Github)
- Upload to “files”



Diffusion Tensor: Coding Exercise

- Estimate the diffusion tensor in each voxel in a phantom dataset

$$S_k = S_0 \exp(-b_k \hat{g}_k^T \mathbf{D} \hat{g}_k)$$

Measured
Imaging parameters
To be estimated

$$\mathbf{D} = \begin{pmatrix} D_{xx} & D_{xy} & D_{xz} \\ D_{xy} & D_{yy} & D_{yz} \\ D_{xz} & D_{yz} & D_{zz} \end{pmatrix}$$



https://github.com/ethompson93/dmri_analysis_techniques

Compartment models

- Different tissues characterised by different biophysical models
- The signal is represented as a linear combination of the different compartments
- Exchange between compartments assumed to be negligible

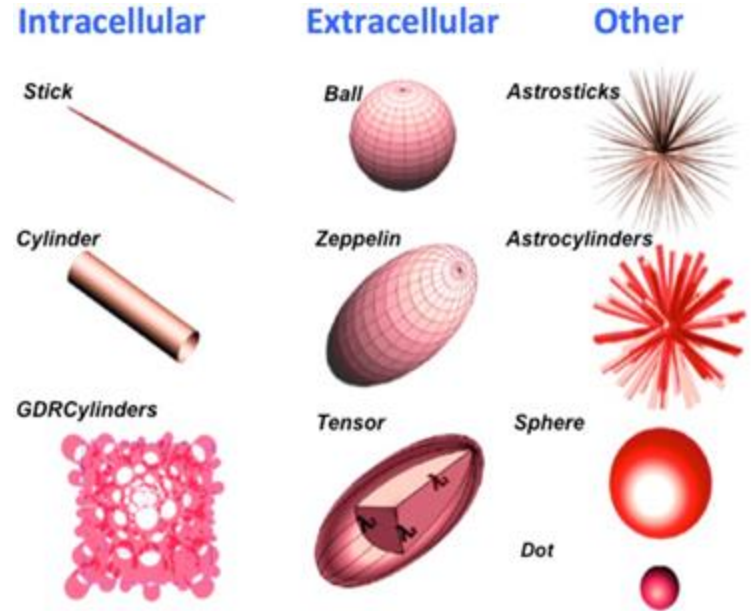
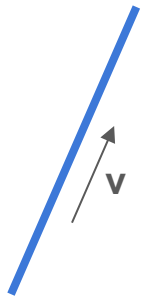


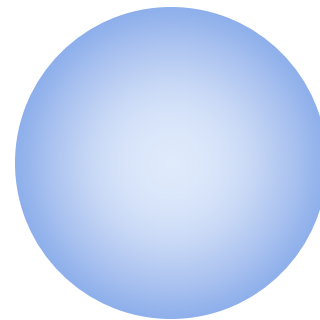
Figure from: Ferizi, U., Schneider, T., Panagiotaki, E., Nedjati-Gilani, G., Zhang, H., Wheeler-Kingshott, C.A.M. and Alexander, D.C. (2014), A ranking of diffusion MRI compartment models with in vivo human brain data. *Magn. Reson. Med.*, 72: 1785-1792. <https://doi.org/10.1002/mrm.25080>

A simple compartment model: Ball and Stick Model



stick

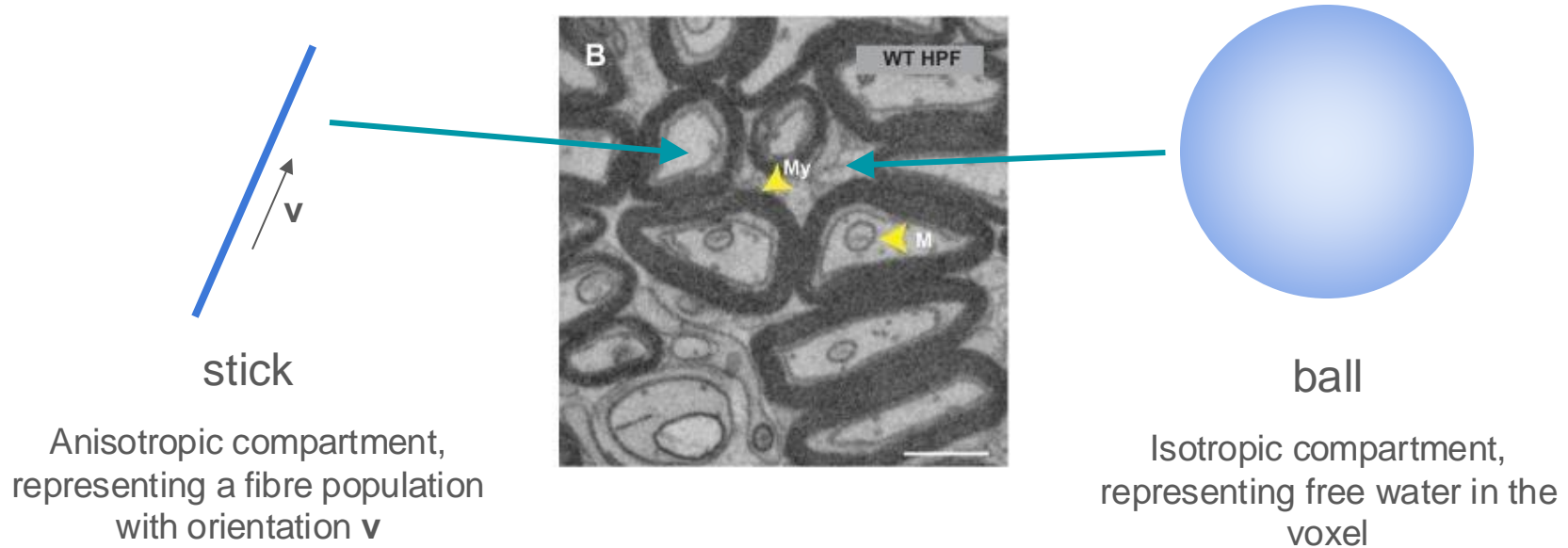
Anisotropic compartment,
representing a fibre population
with orientation \mathbf{v}



ball

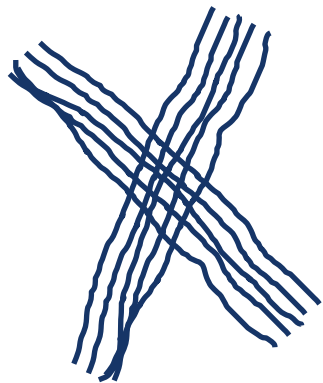
Isotropic compartment,
representing free water in the
voxel

A simple compartment model: Ball and Stick Model

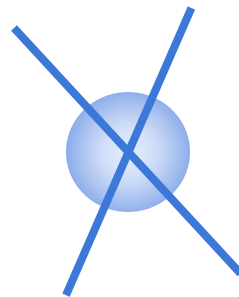


Ball and Stick Model

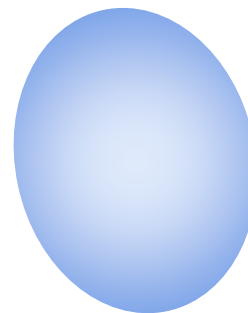
This allows us to model crossing fibre populations, which is not possible with DTI



Intersecting fibre
populations



Ball and stick
model



Tensor

Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0[(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

signal from “ball”
compartment



signal from “stick”
compartment: fibre
population with direction \mathbf{v}



Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0 [(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

Diagram illustrating the Ball and Stick Model equation:

- S_0 : signal when $b = 0$
- $(1 - f)$: volume fraction of isotropic compartment
- $\exp(-b_k d)$: signal from "ball" compartment (mean diffusivity d)
- f : volume fraction of anisotropic compartment
- $\exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)$: signal from "stick" compartment (fibre population with direction \mathbf{v})

Ball and Stick Model

signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k :

$$S_k = S_0 [(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

Diagram illustrating the Ball and Stick Model equation:

- S_k : signal measured for a diffusion weighted gradient with direction \mathbf{g}_k and b-value b_k .
- S_0 : signal when $b = 0$.
- $(1 - f)$: volume fraction of isotropic compartment.
- $\exp(-b_k d)$: signal from "ball" compartment, where d is the mean diffusivity.
- f : volume fraction of anisotropic compartment.
- $\exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)$: signal from "stick" compartment: fibre population with direction \mathbf{v} .


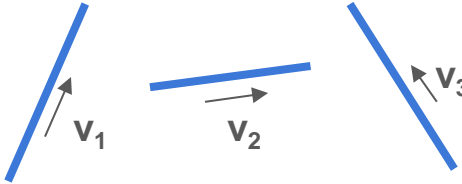
Legend:

- Measured: S_k
- Imaging parameters: S_0 , b_k , d
- To be estimated: f , \mathbf{v}

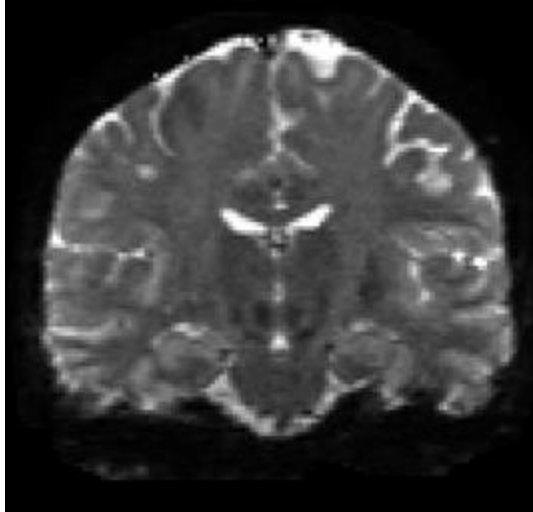
Ball and Stick Model – extending to multiple fibre populations

$$S_k = S_0 \left[\left(1 - \sum_{i=1}^N f_i \right) \underbrace{\exp(-b_k d)}_{\text{signal from "ball"}} + \sum_{i=1}^N \underbrace{f_i \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v}_i)^2)}_{\text{signal from "stick" compartment: fibre population with direction } \mathbf{v}_i} \right]$$

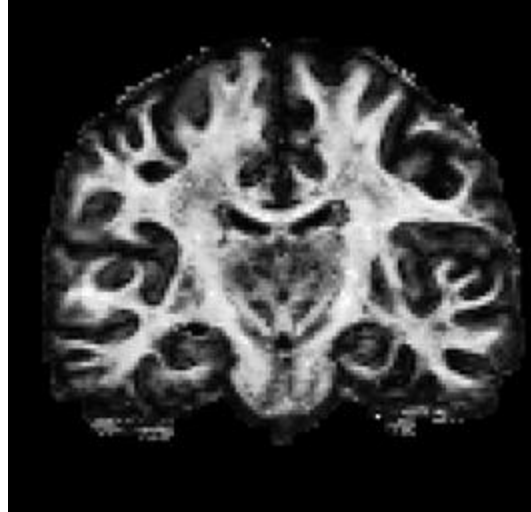
volume fraction of anisotropic compartment i

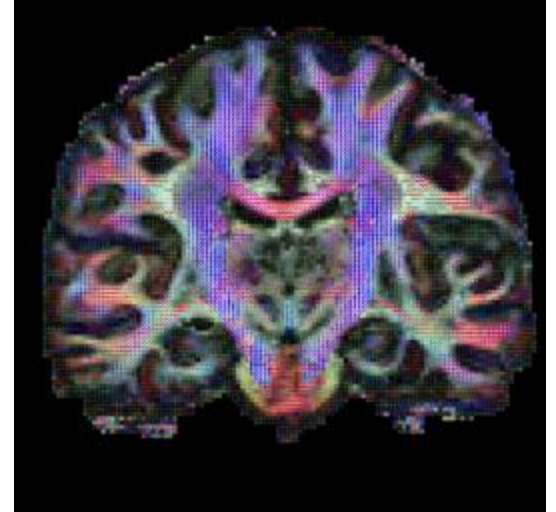
Ball and Stick Model in real data



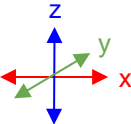
B0 diffusion signal

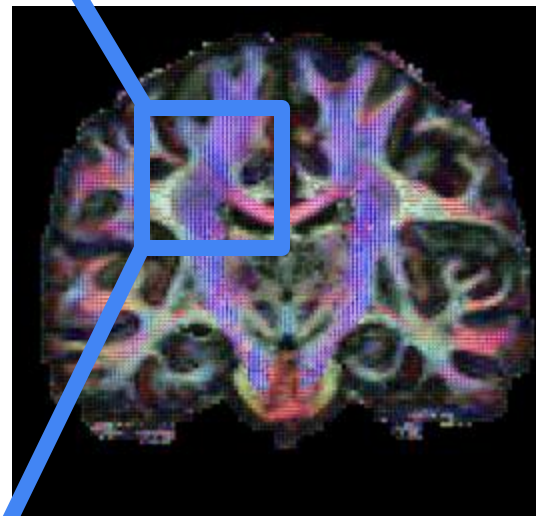
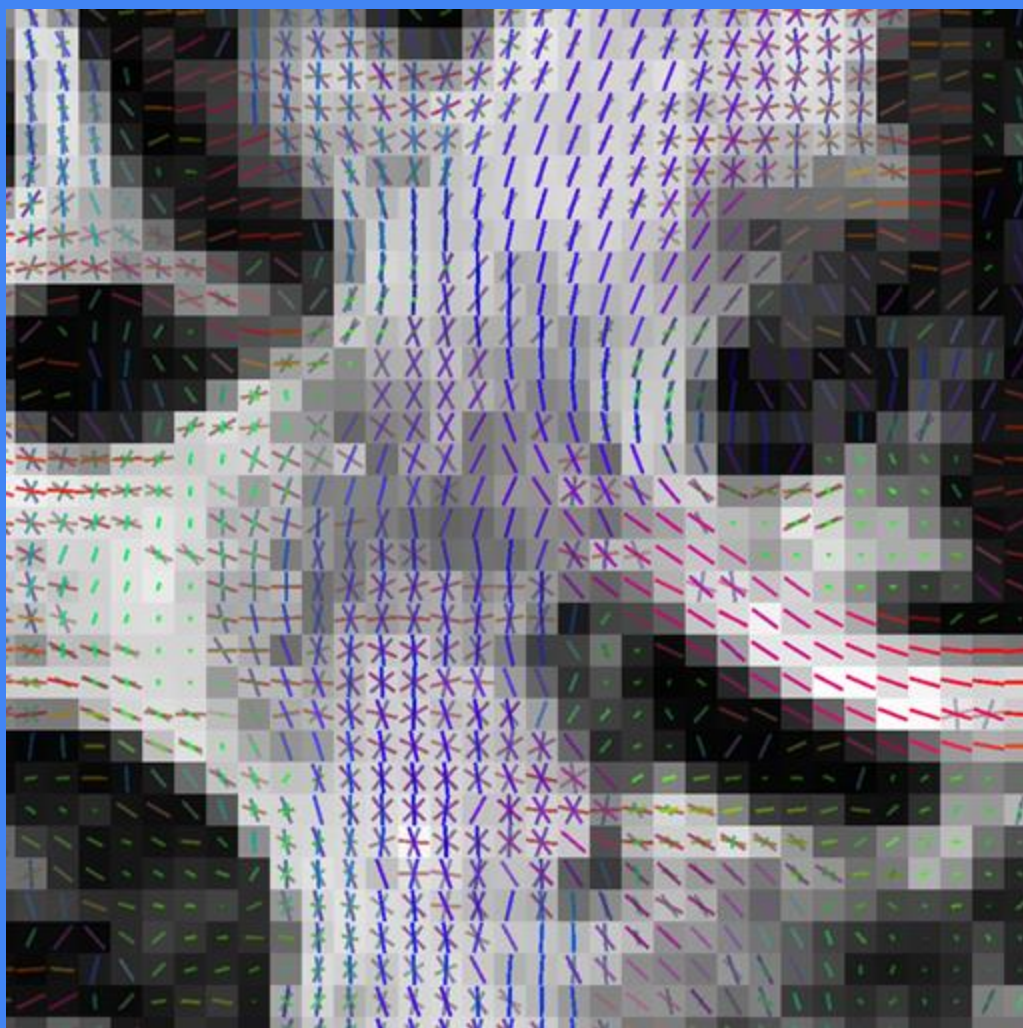


Fibre volume fraction

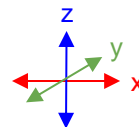


Sticks visualised as
vectors



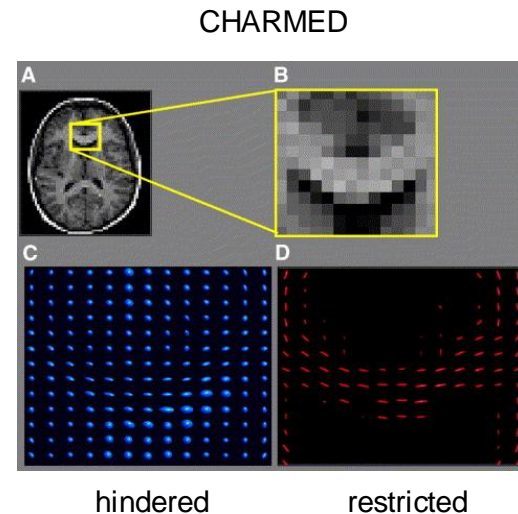


Sticks visualised as vectors

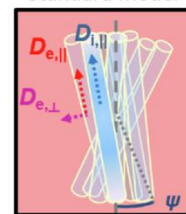


More advanced compartment models

- White matter
 - CHARMED: Composite hindered and restricted model of diffusion. *Assaf and Basser (2005) NeuroImage*
 - NODDI: Neurite orientation dispersion and density imaging. *Zhang et al (2012) NeuroImage*
- Grey matter
 - SANDI: Soma and neurite density imaging. *Palombo et al (2020) NeuroImage*
 - NEXI: neurite exchange imaging. *Jelescu et al (2022) NeuroImage*
- Tumours
 - VERDICT: Vascular, Extracellular, and Restricted Diffusion for Cytometry in Tumours. *Panagiotaki et al (2014), Cancer Res*

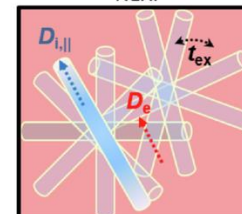


Standard Model



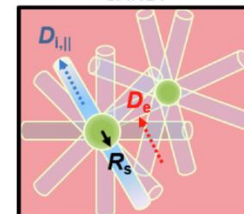
$$\frac{\text{blue box}}{\text{blue box} + \text{red box}} = f$$

NEXI



$$\frac{\text{blue box}}{\text{blue box} + \text{red box}} = f$$

SANDI



$$\frac{\text{blue box}}{\text{blue box} + \text{red box} + \text{green box}} = f \quad \frac{\text{green box}}{\text{blue box} + \text{red box} + \text{green box}} = f_s$$

Ball and Stick Model: Coding Exercise

- Open up the second colab notebook to begin the exercise
- You will need to upload the data again, either from gdrive or github
- This time we will be fitting the ball-and-stick model to our data

$$S_k = S_0[(1 - f) \exp(-b_k d) + f \exp(-b_k d (\mathbf{g}_k \cdot \mathbf{v})^2)]$$

signal from “ball”
compartment



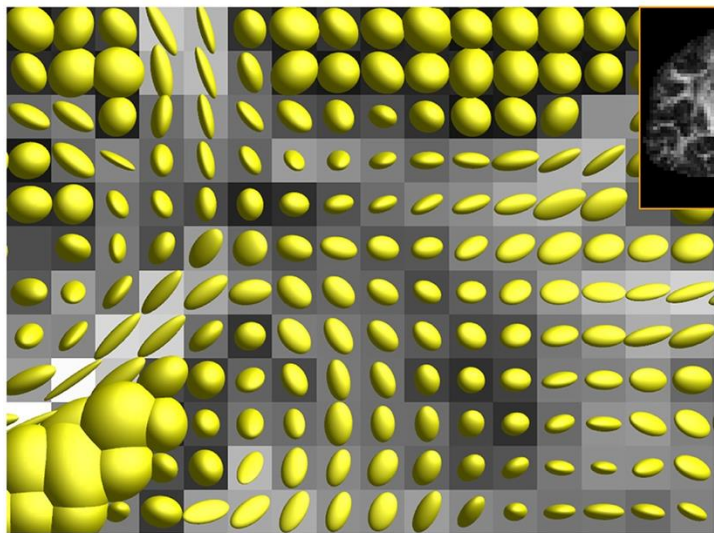
signal from “stick”
compartment: fibre
population with direction \mathbf{v}



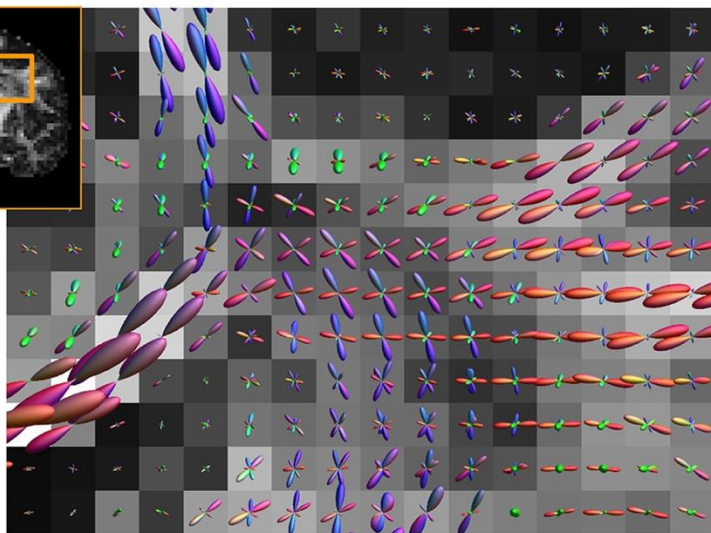
Spherical Deconvolution

- Method for obtaining a continuous fibre orientation distribution function: fODF
- Provides fibre orientations for tractography

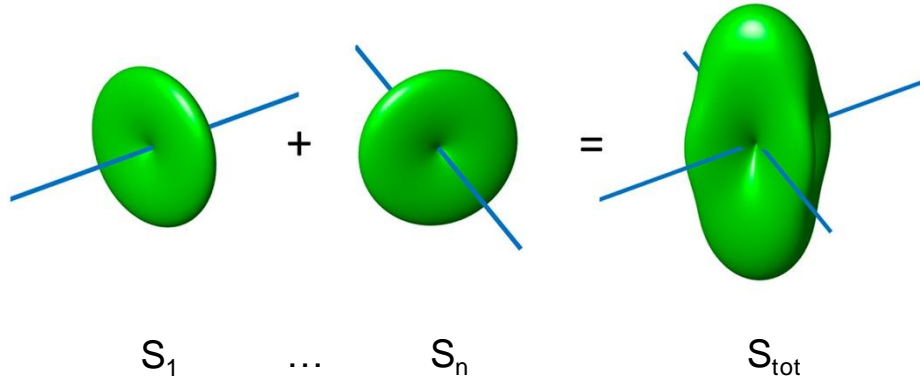
Single Fibre (DTI)



Multiple Fibres (SD)

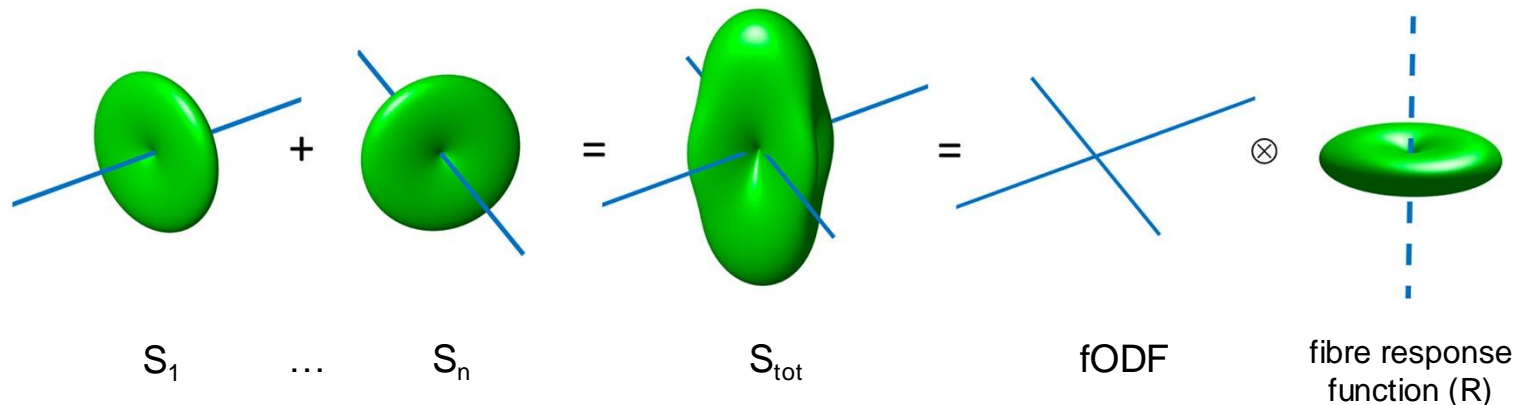


Spherical Deconvolution



- We assume that the diffusion-weighted signal is equivalent for all fibre populations in the brain (fibre response function)
- The measured signal is a linear combination of signals from all the fibre populations within a voxel

Spherical Deconvolution



- We assume that the diffusion-weighted signal is equivalent for all fibre populations in the brain (fibre response function)
- The measured signal is a linear combination of signals from all the fibre populations within a voxel
- The fODF is obtained by deconvolving the measured signal with the fibre response function

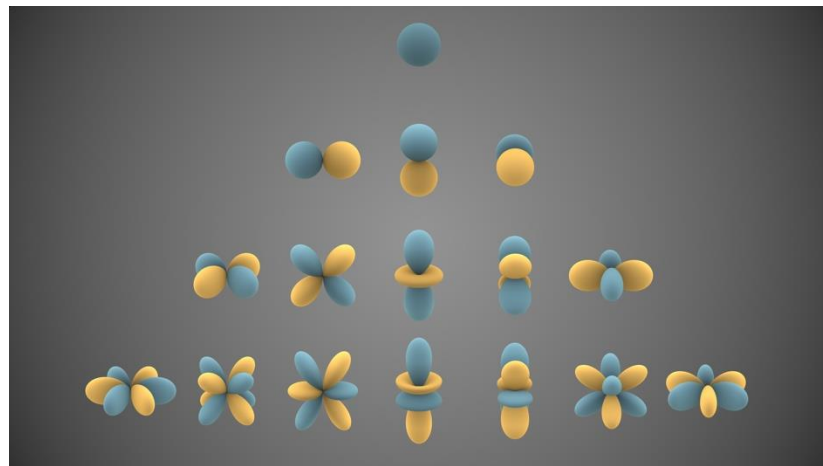
Spherical Harmonic Basis

- We can represent the fODF as a weighted sum of spherical harmonics up to a degree l_{max} :

$$f(\theta, \phi) = \sum_l^{l_{max}} \sum_{m=-l}^l c_{lm} Y_{lm}(\theta, \phi)$$

coefficients to
be estimated

spherical
harmonics



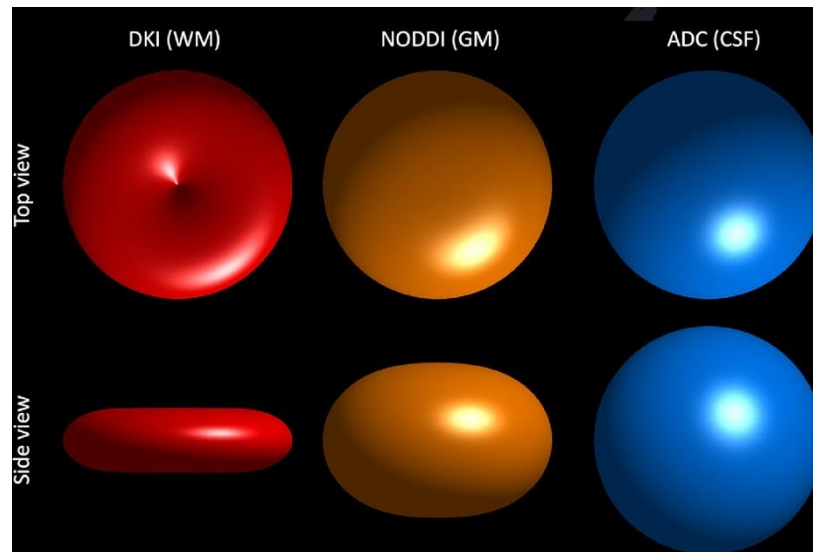
By Inigo.quilez - Own work, CC BY-SA 3.0,
<https://commons.wikimedia.org/w/index.php?curid=32782753>

Advantages:

- compact representation reduces noise
- convolution is a simple product in spherical harmonic domain – easier computation

Step 1: Estimating the fibre response function

- The DW signal that would be acquired for single coherent fibre population
- Model based approaches: eg. axially symmetric tensor
- Direct empirical measurements from single-fibre voxels
- Response function can be derived for each tissue type (multi-tissue)

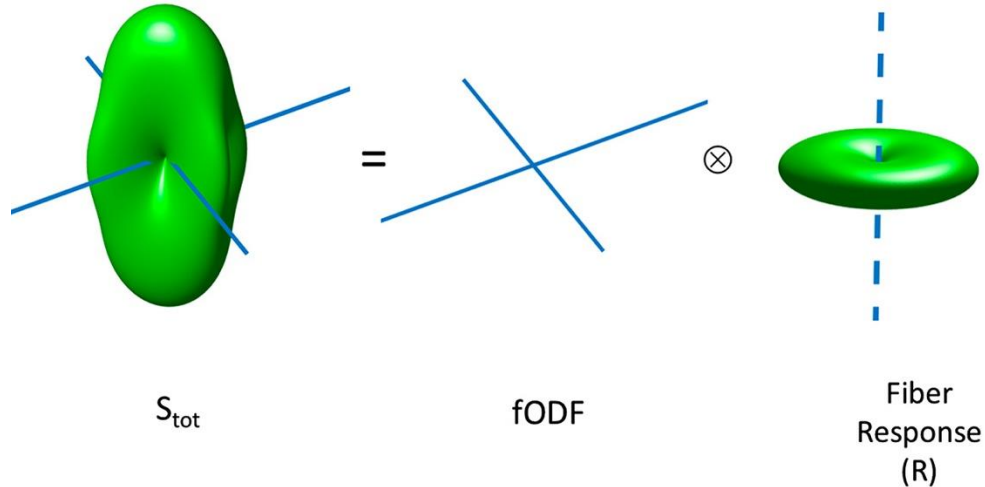


Examples of Response Functions derived from different models

Spherical deconvolution with tissue-specific response functions and multi-shell diffusion MRI to estimate multiple fiber orientation distributions (mFODs)": <https://www.sciencedirect.com/science/article/pii/S1053811920306923>

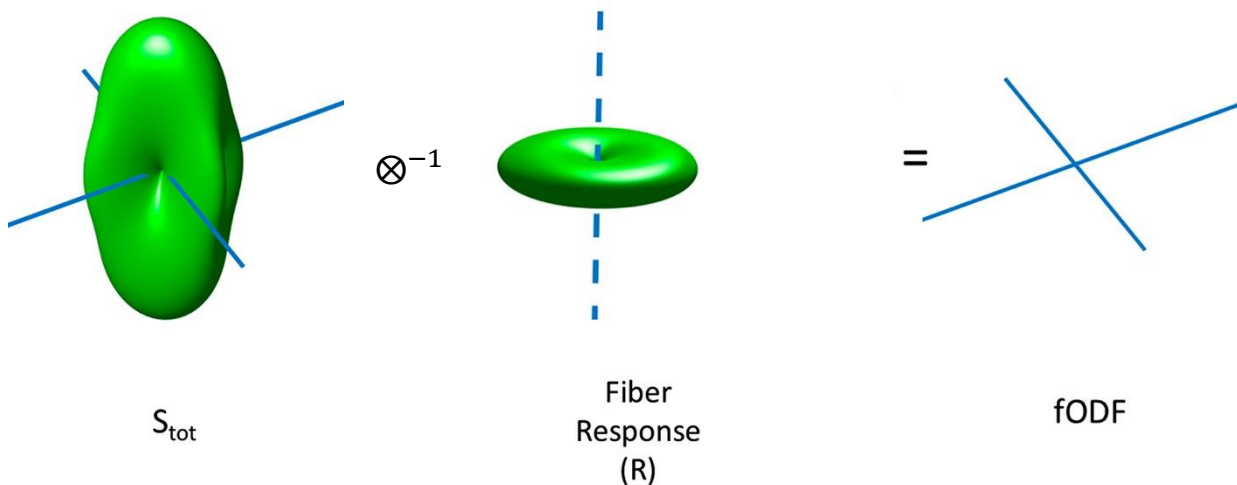
Step 2: Using the fibre response function to determine the fODF

- We can deconvolve the measured signal with the response function, R , to obtain the fODF



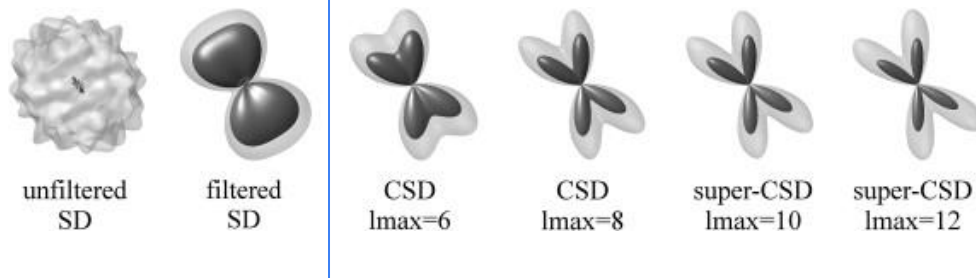
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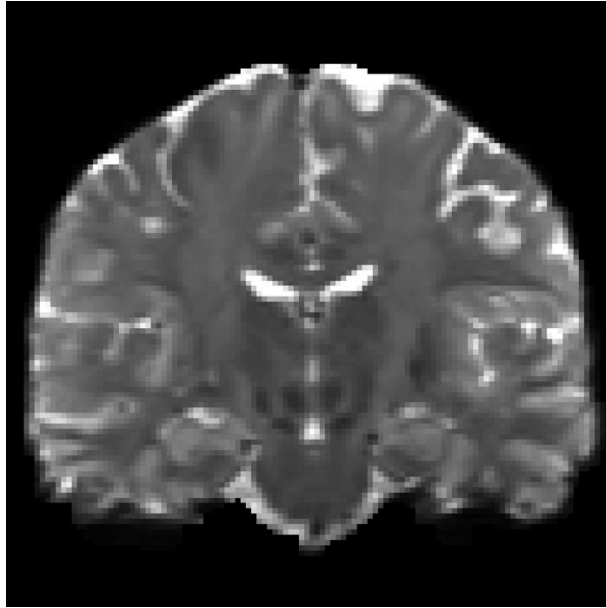


Constrained Spherical Deconvolution

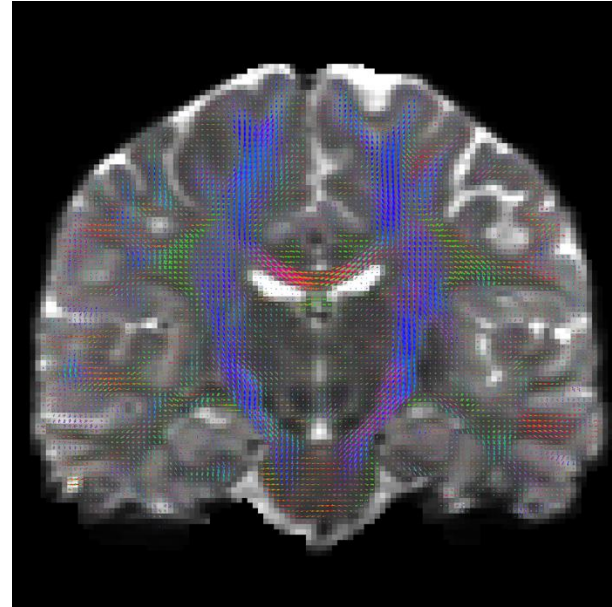
- The spherical deconvolution operation is ill-posed and susceptible to noise
- Tournier et al (2007) introduced a **non-negativity constraint** to the reconstructed fODF
- This drastically improves the robustness to noise and improves angular resolution



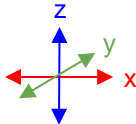
CSD in real data

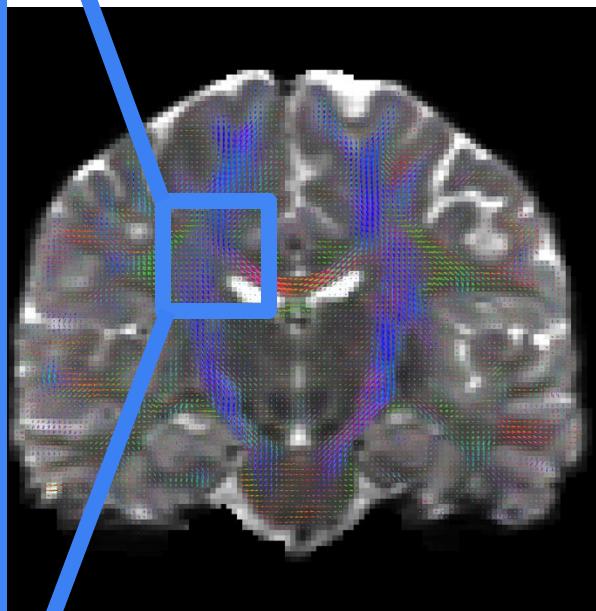
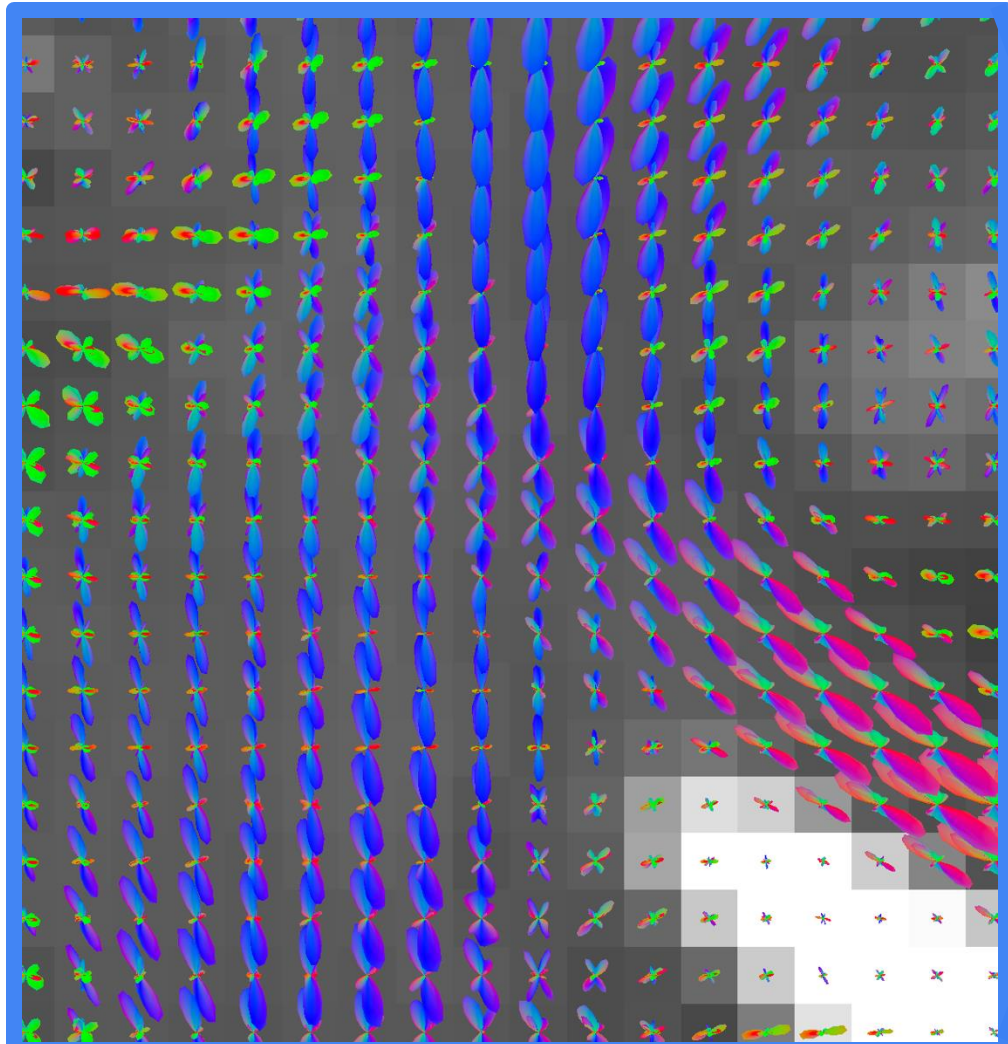


B0 diffusion signal

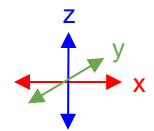


fODFs





fODFs



CSD coding exercise

- We will use DIPY – an open-source python library for diffusion MRI analysis
- We perform constrained spherical deconvolution on the Fibercup phantom
- The notebook will take you through the steps of estimating the fibre response function and running the constrained spherical deconvolution

Conclusions

- Analysis techniques unlock biological insight from diffusion MRI scans
 - e.g. microstructural metrics and fibre orientations for tractography
- The diffusion tensor provides insight into the diffusion signal, but lacks microstructural specificity
- Compartment models, such as ball-and-stick, characterise different tissue environments with biophysical models
- Constrained spherical deconvolution is a method for estimating the fibre orientation distribution function

Acknowledgements



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