map_102.png

(a) Original Map
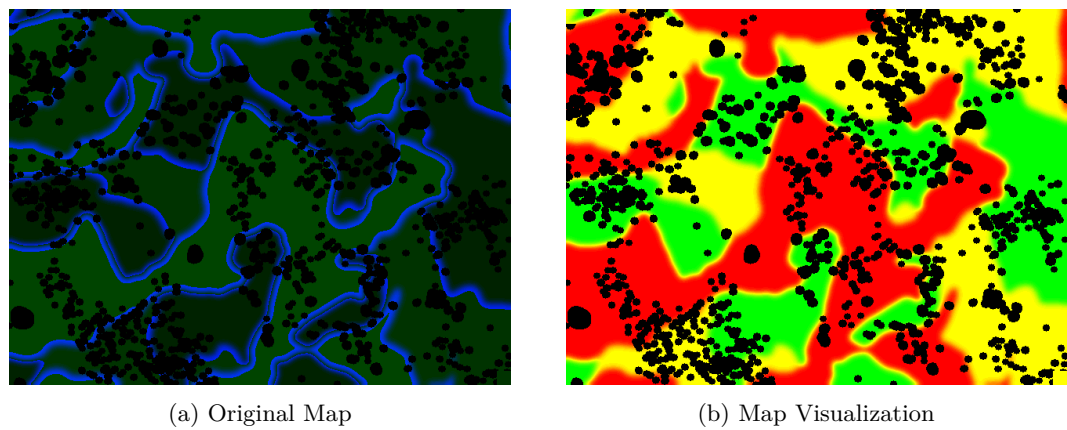

(b) Map Visualization

Figure 1: Input Map

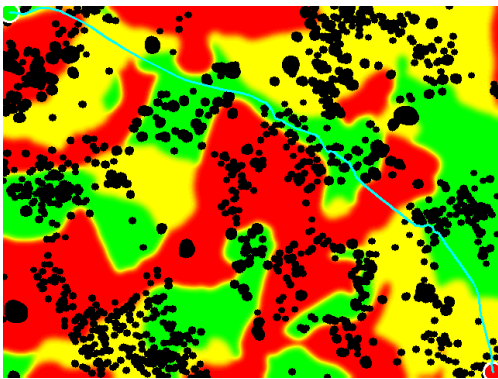# 1 Analysis

1.1 Optimal Path

Optimal path cost: 2000.04

Figure 2: Map with best Path

1.2 Label Statistic

Obstacle ids: [0]

O	0	30	31	32	33	34	35	36	37	38	39	40	41
70714	70714	43175	4700	2840	2217	1842	1700	1504	1471	1428	1345	1441	1472
23.0%	23.0%	14.1%	1.5%	0.9%	0.7%	0.6%	0.6%	0.5%	0.5%	0.5%	0.4%	0.5%	0.5%

43	44	45	46	47	48	49	50	51	52	53	54	55	56
1902	2728	57694	3835	2472	2014	1890	1770	1688	1770	1804	1837	1992	2264
0.6%	0.9%	18.8%	1.2%	0.8%	0.7%	0.6%	0.6%	0.5%	0.6%	0.6%	0.6%	0.6%	0.7%

58	59	60
3578	6347	71486
1.2%	2.1%	23.3%