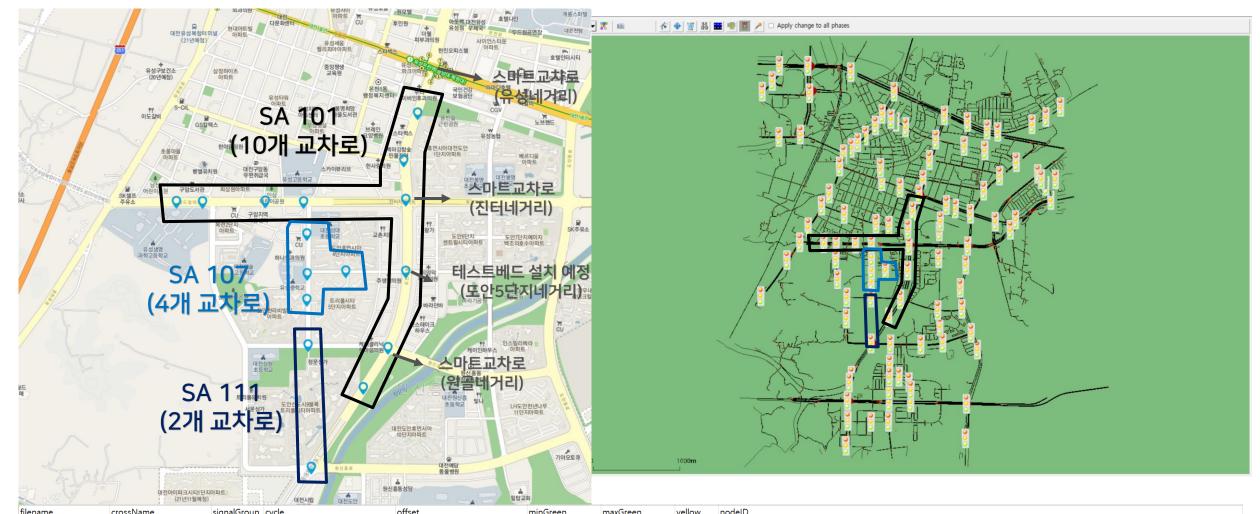
DQN 기반 다중 교차로 신호 최적화

2021/06/24 피민규



| Tilename | crossivame | signaiGroup | cycle | offset | minGreen | maxGreen | yellow | nodelD |
|------------------|----------------|-------------|-------------------------|-----------------------------|-------------------|-------------------|-------------|---|
| 1-1, 1-2번(단).xls | 도안1단지(단) | SA 101 | 180/180/180/180/180/180 | 115/103/103/103/115/115/115 | 51,60 | 51,180 | 0,3 | cluster_563100866_563103911_563103912 |
| 11-1번(단).xls | 원골(단) | SA 101 | 180/180/180/180/180/180 | 161/139/139/139/151/151/151 | 40,53,45 | 90,53,180 | 3,0,0 | cluster_563103888_563103891 |
| 5-1번(단).xls | 유성고후문(단)(5-1번) | SA 101 | 180/180/180/180/180/180 | 165/130/155/169/155/165/2 | 48,80 | 48,190 | 0,3 | cluster_563100016_563103847_563109512_563109513 |
| 5-2번3.xls | 상대초교(단) | SA 101 | 180/180/180/180/180/180 | 165/130/155/169/155/165/2 | 51,80 | 51,190 | 0,3 | cluster_563102154_563103845_563109514_563109515 |
| 8번4.xls | 도안5단지네거리 | SA 101 | 180/180/180/180/180/180 | 157/146/144/144/157/157/157 | 26,25,25,26,23,23 | 45,60,60,45,40,40 | 3,0,3,3,3,3 | cluster_563103437_563103890_563103913_563103914 |
| 구암119안전센터3.xls | 구암119안전센터삼거리 | SA 101 | 180/180/180/180/180/180 | 0/0/0/0/0/0/0 | 30,50 | 75,195 | 0,4 | cluster_563109510_563109511 |
| 원골네거리.xls | 원골네거리 | SA 101 | 180/180/180/180/180/180 | 157/144/144/144/157/157/157 | 15,37,15,51 | 45,130,30,85 | 4,3,3,4 | cluster_563103641_563103889_563103894_563103895 |
| 인삼골네거리.xls | 인삼골네거리 | SA 101 | 180/180/180/180/180/180 | 2/140/169/169/165/2/2 | 43,27,27,17 | 70,160,45,30 | 3,4,3,3 | cluster_563103433_563103849_563103871_563103872_563103873_563103874_563103875_563104618 |
| 도안5단지(단).xls | 도안5단지(단) | SA 107 | 120 | 0 | 29,50 | 29,140 | 0,3 | 563106861 |
| 유성중삼거리.xls | 유성중삼거리 | SA 107 | 120 | 0 | 26,27,26 | 55,65,65 | 3,0,3 | 563103625 |
| 휴먼시아4단지(단).xls | 휴먼시아4단지(단) | SA 107 | 120 | 70 | 28,50 | 28,140 | 0,3 | NA |
| 10번4.xls | 도안9단지4(10번) | SA 111 | 150/150/150/150/150/150 | 5/5/5/5/5/5 | 32,29,27,33 | 55,60,60,55 | 3,3,3,3 | 563103639 |
| 상대네거리.xls | 상대네거리 | SA 111 | 150/150/150/150/150/150 | 0/0/0/0/0/0/0 | 31,49,20,31 | 55,80,45,55 | 3,4,4,3 | cluster_563103476_563103477_563103812_563103813_563103814_563103815_563103816_563103817_563103820_563103821 |

제어 가능한 교차로 목록

• (단), 제어 불가능 신호(구암119안전센터) 제외, 총 8개







SA101 SA107 SA111

구암119안전센터삼거리

| 교사도명 : [푸임 119인진센터십기다 | | | ᄣᄭᅩ | 민요. | | 20 | ╨^다 | ᆫᆫ | 5A 101 | | 785 | 그걸 · | | |
|---------------------------------------|---------------|----------|----------------|-------------|-----|----------------|-------------|----------|----------------|------|------------|------------|----------|--------|
| | | | Φ | 1 | (| ⊅2 | Φ | 3 | Φ. | 4 | ¢ | 5 | | Ф6 |
| 구암119안전선 | 센터 | | | | | | | | | | | | | |
| _ _ | | | | | | | | | | | | | | |
| / | | | _ | | _ | | | | | : | | 선신호 | <u> </u> | |
| 유성생명고교 | 인삼골4 | | | | 1 | | | | | 33 | 수년 형사 5 | 동시 0초 진 | 핸 | |
| | | | _ | → | _ | → | | → | | | | <u>~</u> L | | |
| | | | | | | | 소방우 입력시어 | 선신호 | | | | | | |
| | | | | | | , | 입력시대 | I만 줄드 | | | | | | |
| | | | | | | | | | | | | | | |
| 교차로 구분 | | | A ⁻ | 1 | / | 42 | Α | 3 | Α | 4 | Α | \ 5 | | A6 |
| | RING A | | 4 | _ | 4 | _ | Ļ | | | | | | | |
| 교차로 운영 | | | | | | | <u>'</u> | | | | | | | |
| <u> </u> | RING B | | _ | > | _ | → | | | | | | | | |
| | | | B. | 1 | E | 32 | В | 3 | B | 4 | Е | 35 | | B6 |
| IGNAL TABLE | | | | | | | | | | | | | | |
| | | | 10 |) | , | 20 | | | | | | | | |
| OPTION | | | 10 | | | 20 | | | | | | | | |
| MIN. GREEN | | | 30 | | | 50 | | | | | | | | |
| | | | 30 75 | | | 50 95 | | | | | | | | |
| MAX. II | | | 75 | | | 95 95 | ļ | | | | | | | |
| VELL OW/DED) | | | | | | 4 | | | | | | | | |
| YELLOW(RED) | | | | | | 4 | | | | | | | | |
| BEF. PED. | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| WALK | | | | | | | | | | | | | | |
| WALK CLEAR | | | | | | | | | | | | | | |
| , , , , , , , , , , , , , , , , , , , | | | | | | | | | | | | | | |
| | PLAN : | TARL F | E | | | | | | | | | 에이=7 | 전 비(원 | ~일 : 0 |
| TIME PLAN 1 | 1 2 11 | | | PLAN | V 1 | TOE |) PLAN | V 2 | TOD | PLAI | | | | 월~금:8) |
| · 두 주기 마 연 시간분할(초) | 감응제어 | 구분 | | 수준 | ID | 시각 | | ID | 시각 | | ID | | | 요일/점말 |
| (소) 등 RING A. B 압버튼(X) | 검지기(O) 검지기(x) | <u> </u> | | | | | | | | | | | 0 4 | /DE |
| 1 180 1 0 50,130 | | \vdash | 00:00 | 1 | 1 | 00:00 | 1 | 1 | 00:00 | 1 | 3 | | | |
| 50,130 | | 2 | 07:00 | 2 | 2 | 07:00 09:30 | 2 | 2 | 09:30 21:00 | 2 | 3 6 | | | |
| ' crossName="구암119안전센 | 터삼거리" dat | | | | | | | | | | | | | |
| 01 0001141110 | 10 1 dae | · ' | | | | 019 | | | - 0, | | | | | |
| | | | | | | | | | | | | | | |

| <trafficsignal crossname="국앰119안선센터샴거리" crossno="68" date="2019⊣01-28" nodeid="cluster_563109510_563109511" signalgroup="SA 101" version="2"></trafficsignal> | |
|---|--|
| <schedule id="2" offset="0"></schedule> | |
| | |
| <pre><phase duration="50" maxdur="75" mindur="30" state="GGGGGGGGGG"></phase></pre> | |
| | |
| <pre><phase duration="130" maxdur="195" mindur="50" state="6666666666"></phase></pre> | |
| | |
| | |
| <todplan defaultplan="2" offset="0"></todplan> | |
| | |
| | |
| | |

Problem I

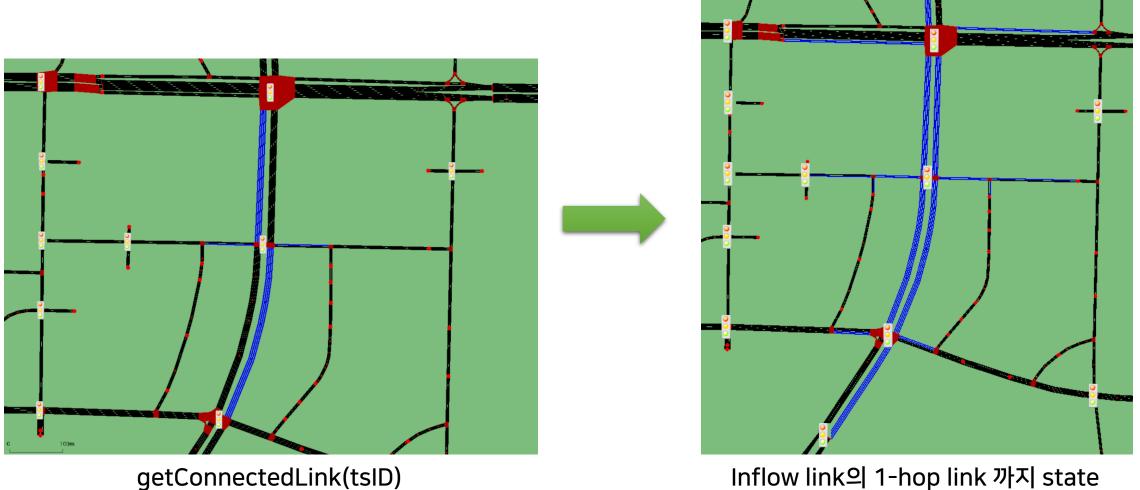
• 똑같은 상황에선, 똑같은 action을 줬을 때, 똑같은 보상을 받을 수 있어야 하지만, 주변 교차 로 때문에 그게 안됨

• 그럼 주변 교차로를 state에 포함하자

• 그 주변 교차로의 주변 교차로 때문에 안되려나? (1-hop, 2-hop ..)

- 가중치를 둬서 교차로가 멀어질수록 주변 교차로의 state에는 가중치를 곱하자
 - Ex. 1-hop 교차로 가중치 0.7, 2-hop 교차로 가중치 0.5 ···
 - 이 가중치를 학습할 수 있는 방법도 있을지?

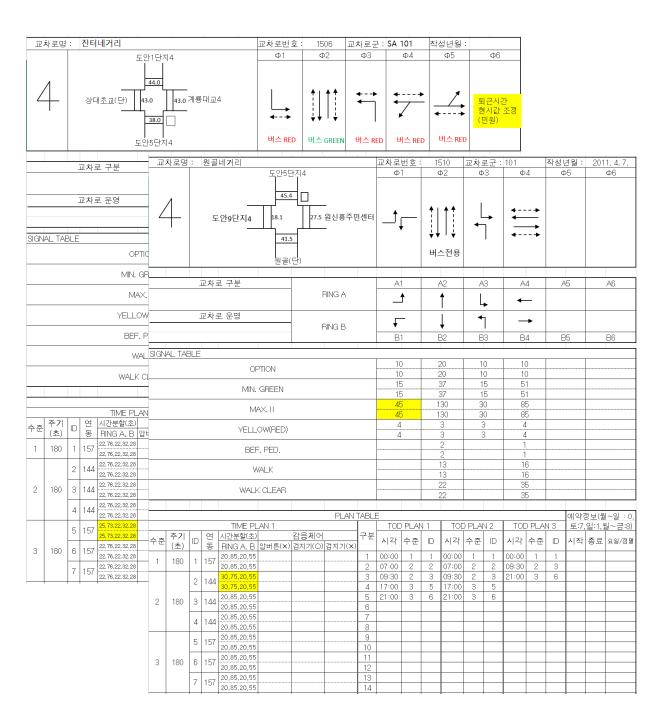
ex) 도안5단지네거리



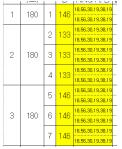
Inflow link의 1-hop link 까지 state 2-hop(?)

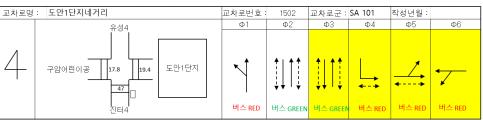
Problem II

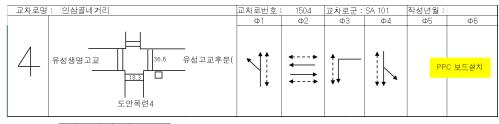
- Actor critic 계열 수렴 잘 안 되고, DQN이 훨씬 잘 됨
- DQN 적용을 위한 Discrete Action 설계
 - TOD 변경이나 민원으로 인한 현시값 조정이 있는 경우, 많이 안 바 뀌고 현시 2개 가지고 조정함
 - 현시를 주고 빼기 유리한 신호는 신호 길이가 가장 긴 주 도로 방향 현시인 것으로 보임
 - 주 도로 현시와 나머지 현시 중 하나를 선택해서 조정하자

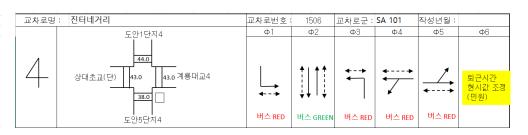


SA 101 그룹 현시 정보



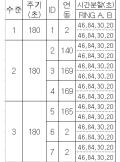


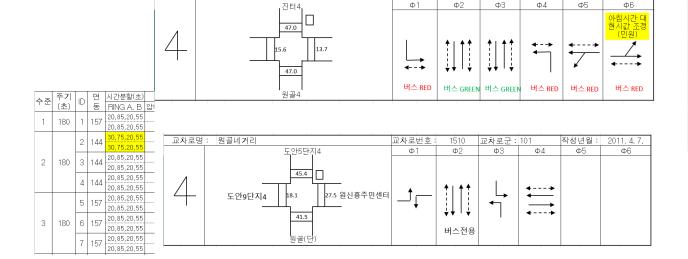




교차로번호:

교차로군 : SA 101





교차로명: 도안5단지네거리



SA101

| 수준 | 주기 (초) | ID | 연 동 | 시간분할(초) RING A. B & |
|----|-----------|----|--------|----------------------------------|
| 1 | 180 | 1 | 157 | 22,76,22,32,28 |
| | | 2 | 144 | 22,76,22,32,28 |
| 2 | 180 | 3 | 144 | 22,76,22,32,28 |
| | | 4 | 144 | 22,76,22,32,28 |
| | | 5 | 157 | 25,73,22,32,28 25,73,22,32,28 |
| 3 | 180 | 6 | 157 | 22,76,22,32,28 22,76,22,32,28 |
| | | 7 | 157 | 22,76,22,32,28 |

| 수준 | 주기 (초) | ID | 연 똥 | 시간분할(초) RING A. B | 입 |
|----|-----------|----|-----|--|---|
| 1 | 180 | 1 | 157 | 29,35,35,29,26,26 29,35,35,29,26,26 | |
| | | 2 | 146 | 29,33,33,29,26,30 29,33,33,29,26,30 | |
| 2 | 180 | 3 | 144 | 29,35,35,29,26,26 29,35,35,29,26,26 | |
| | | 4 | 144 | 29,35,35,29,26,26 29,35,35,29,26,26 | |
| | | 5 | 157 | 29,35,35,29,26,26 29,35,35,29,26,26 | |
| 3 | 180 | 6 | 157 | 29,35,35,29,26,26 29,35,35,29,26,26 | |
| | | 7 | 157 | 29,35,35,29,26,26 29,35,35,29,26,26 | |

DQN Agent

• 각 교차로 마다 총 8개의 agent를 독립적으로 생성(상호작용 x, 다른 agent가 무슨 action을 하는지 모름)

State

- 1-hop 까지 lane별 density
- State space : 1-hop 까지 연결 된 lane 수
- 아직 가중치는 도입 안 함 done

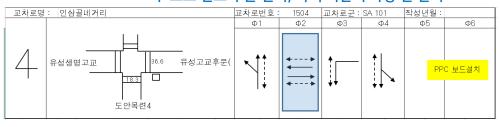
Action

- 주 도로 방향 현시와 나머지 현시 중 하나 선택해서 증감
- Action space : (현시 수 주 도로 방향 현시)*2
- 변경 안하는 것도 추가 해야 함 done

Reward

- + (1-hop 까지 lane별 차량 통과 수의 합)
- -100 (증감 하다가 최소 녹색이나 최대 녹색을 넘어가면)

주 현시 주 도로 신호 주는 현시, 녹색 시간이 가장 긴 현시



주 현시: 2

나머지 현시: 1, 3, 4 (3개)

Action space: 6

Action: [0,1,2, 3,4,5]

나머지 신호에서 주 현시에 3초만큼 줌 주 현시에서 나머지 신호에 3초만큼 줌



두 현시 : 2

나머지 현시 : 1, 3, 4 (3개) Action space : 7

변경 안함

Action: [0, 1,2,3, 4,5,6]

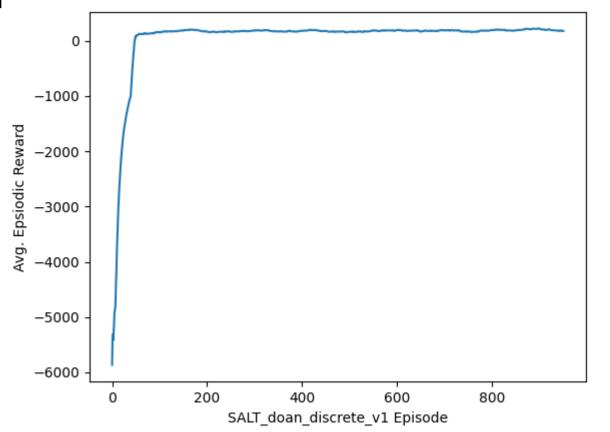
나머지 신호에서 주 현시에 3초만큼 줌 주 현시에서 나머지 신호에 3초만큼 결

인삼골네거리의 경우 2현시 제외하고 이미 모두 최소 녹색

학습 결과

- 1 epoch당 약 23초
- Penalty에 대해서는 50 epoch만에 학습 함
- Y 축 스케일 때문에 제대로 확인 불가..





Action 파라미터 조정 실험

- 교차로 마다 신호 조정 효과가 다를 수 있음
- 3초, 5초, 7초에 대해서 실험

주 현시(?) 주 도로 신호 주는 현시, 녹색 시간이 가장 긴 현시



주 현시: 2

나머지 현시 : 1, 3, 4 (3개)

Action space: 7

변경 안함

Action: [0, 1,2,3, 4,5,6]

나머지 신호에서 주 현시에 3초만큼 줌 주 현시에서 나머지 신호에 3초만큼 줌

학습 결과



학습 결과 - 각 교차로별 reward

train agent reward



- → Epsilon_min 값이 0.1이라 학습할 땐 계속 탐험하는게 원인
- → Test 할 땐 마이너스 보상 없이 잘 동작함

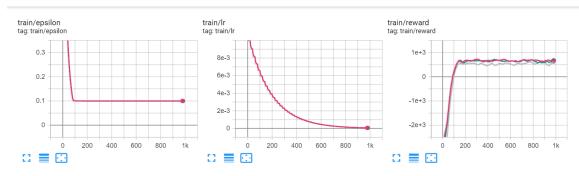
train

50 -50

-150

II 🔳 🖸

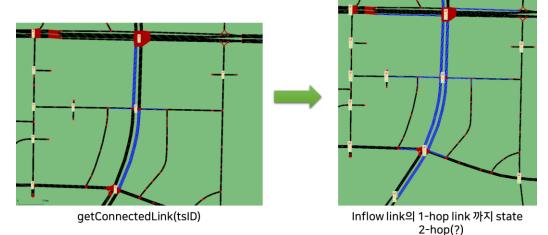
600



400 600

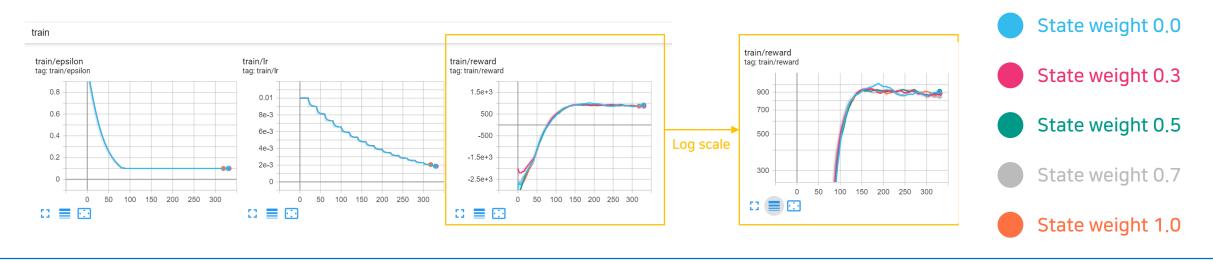
State weight 조정 실험

- 1-hop lane까지
- State 가중치 1, 0.7, 0.5, 0.3, 0.0 에 대해서 실험
- Reward는 가중치 1로 고정, 1-hop lane까지 차량 통과량 합/100



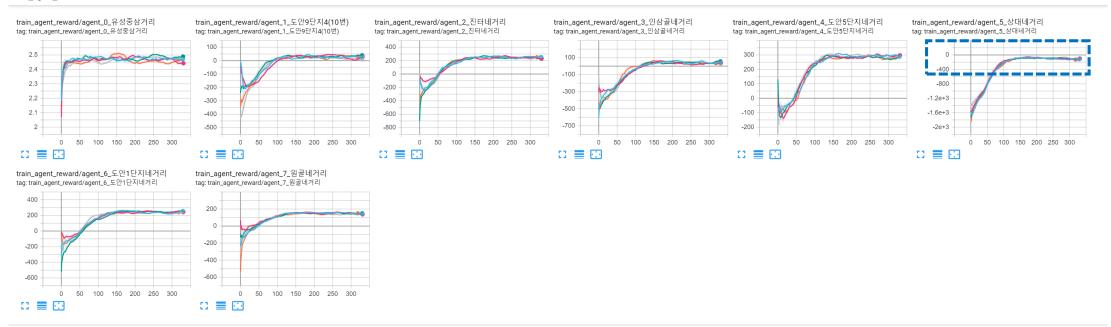




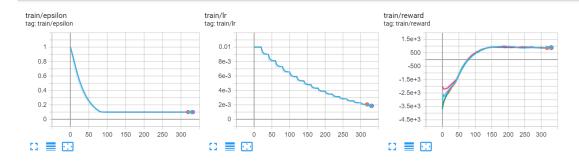


학습 결과 - 각 교차로별 reward

train_agent_reward



train

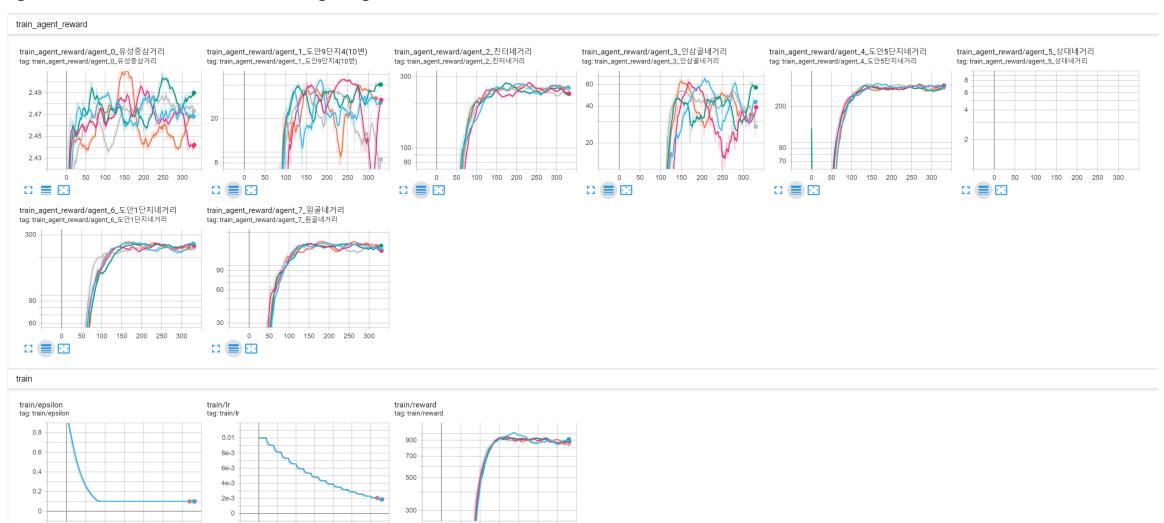


학습 결과 - 각 교차로별 reward

50 100 150 200 250 300

E3 = E3

Ignore outliers in chart scaling, log scale



50 100 150 200 250 300

결과 비교

200번 model 기준

| State | Total | | | | Act | tion | | | |
|--------|--------|------|--------|-----|------|--------|-----|--------|-----|
| weight | Reward | 유성중3 | 도안9단지4 | 진터4 | 인삼골4 | 도안5단지4 | 상대4 | 도안1단지4 | 원골4 |
| 0.0 | 1292.5 | 0 | 0 | 0 | 6 | 0 | 0 | 0 | 0 |
| 0.3 | 1294.5 | 0 | 0 | 0 | 6 | 0 | 0 | 10 | 0 |
| 0.5 | 1292.3 | 0 | 0 | 6 | 3 | 0 | 2 | 0 | 4 |
| 0.7 | 1295.2 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1.0 | 1294.5 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 기존 신호 | 1309.8 | | | | | | | | |

Action 수정

- 2현시 3
- 3현시 7
- 4현시 15
- 5현시 31
- 6현시 53

```
action space

60

50

40

30

20

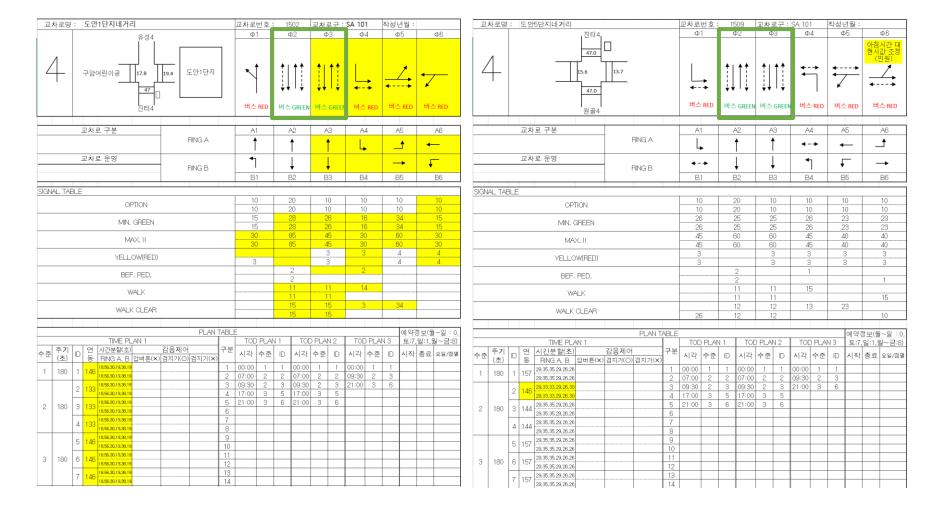
10

2 3 4 5 6
```

```
action list phase num2 = getActionList(phase num = 2, max phase = 0)
print("action space: {} \text{\text{Mnaction list: {}}".format(len(action list phase num2), action list phase num2)}
action space: 3
action list: [[-1, 1], [1, -1], [0, 0]]
action list phase num3 = getActionList(phase num = 3. max phase = 0)
print("action space: {} \text{\text{Mnaction list: {}}".format(len(action list phase num3), action list phase num3)}
action space: 7
action list: [[-1, 0, 1], [1, -1, 0], [-1, 1, 0], [1, 0, -1], [-2, 1, 1], [2, -1, -1], [0, 0, 0]]
action_list_phase_num4 = getActionList(phase_num = 4, max_phase = 0)
print("action space: {} \text{\text{Mnaction list: {}}".format(len(action list phase num4), action list phase num4)}
action space: 15
action list: [[-2, 0, 1, 1], [-1, 0, 0, 1], [-2, 1, 0, 1], [-1, 0, 1, 0], [-2, 1, 1, 0], [1, -1, 0, 0], [-1, 1, 0, 0], [2, -1, -1,
0]. [1, 0, -1, 0]. [2, -1, 0, -1]. [1, 0, 0, -1]. [2, 0, -1, -1]. [-3, 1, 1, 1]. [3, -1, -1, -1]. [0, 0, 0, 0]]
action_list_phase_num5 = getActionList(phase_num = 5, max_phase = 0)
print("action space: {} \text{\mathbb{H}} maction list: {}".format(len(action list phase num5), action list phase num5))
action space: 31
action list: [[-3, 0, 1, 1, 1], [-2, 0, 0, 1, 1], [-3, 1, 0, 1, 1], [-2, 0, 1, 0, 1], [-3, 1, 1, 0, 1], [-1, 0, 0, 0, 1], [-2, 1, 0,
0, 1], [-2, 0, 1, 1, 0], [-3, 1, 1, 1, 0], [-1, 0, 0, 1, 0], [-2, 1, 0, 1, 0], [-1, 0, 1, 0, 0], [-2, 1, 1, 0, 0], [1, -1, 0, 0, 0],
[-1, 1, 0, 0, 0], [2, -1, -1, 0, 0], [1, 0, -1, 0, 0], [2, -1, 0, -1, 0], [1, 0, 0, -1, 0], [3, -1, -1, -1, 0], [2, 0, -1, -1, 0],
[2, -1, 0, 0, -1], [1, 0, 0, 0, -1], [3, -1, -1, 0, -1], [2, 0, -1, 0, -1], [3, -1, 0, -1, -1], [2, 0, 0, -1, -1], [3, 0, -1, -1, -1]
1], [-4, 1, 1, 1, 1], [4, -1, -1, -1, -1], [0, 0, 0, 0, 0]]
action_list_phase_num6 = getActionList(phase_num = 6, max_phase = 0)
print("action space: {} \text{\text{\mathematics}}".format(len(action_list_phase_num6), action_list_phase_num6))
action space: 53
action list: [[-4, 0, 1, 1, 1, 1], [-3, 0, 0, 1, 1, 1], [-4, 1, 0, 1, 1], [-3, 0, 1, 0, 1, 1], [-4, 1, 1, 0, 1, 1], [-2, 0, 0, 0,
1, 1], [-3, 1, 0, 0, 1, 1], [-3, 0, 1, 1, 0, 1], [-4, 1, 1, 1, 0, 1], [-2, 0, 0, 1, 0, 1], [-3, 1, 0, 1, 0, 1], [-2, 0, 1, 0, 0, 1],
[-3, 1, 1, 0, 0, 1], [-2, 1, 0, 0, 0, 1], [-3, 0, 1, 1, 1, 0], [-4, 1, 1, 1, 1, 0], [-2, 0, 0, 1, 1, 0], [-3, 1, 0, 1, 1, 0], [-2, 0,
1, 0, 1, 0], [-3, 1, 1, 0, 1, 0], [-2, 1, 0, 0, 1, 0], [-2, 0, 1, 1, 0, 0], [-3, 1, 1, 1, 0, 0], [-2, 1, 0, 1, 0, 0], [-2, 1, 1, 0,
0, 0], [2, -1, -1, 0, 0, 0], [2, -1, 0, -1, 0, 0], [3, -1, -1, -1, 0, 0], [2, 0, -1, -1, 0, 0], [2, -1, 0, 0, -1, 0], [3, -1, -1, 0, 0]
-1, 0], [2, 0, -1, 0, -1, 0], [3, -1, 0, -1, -1, 0], [2, 0, 0, -1, -1, 0], [4, -1, -1, -1, 0], [3, 0, -1, -1, -1, 0], [2, -1, 0, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, -1, 
0, 0, -1], [3, -1, -1, 0, 0, -1], [2, 0, -1, 0, 0, -1], [3, -1, 0, -1, 0, -1], [2, 0, 0, -1, 0, -1], [4, -1, -1, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3, 0, -1, 0, -1], [3,
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[3, 0, 0, -1, -1, -1], [4, 0, -1, -1, -1, -1], [-5, 1, 1, 1, 1, 1], [5, -1, -1, -1, -1, -1], [0, 0, 0, 0, 0]
```

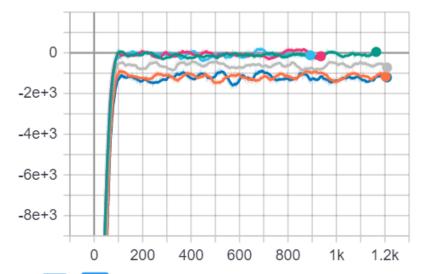
6현시 교차로

• 학습 잘 안되면 2,3현시 합쳐서 5현시로 변경 후 실험



6개 실험 결과(state weight와 add time 변경)

train/reward_40ep_mean tag: train/reward_40ep_mean



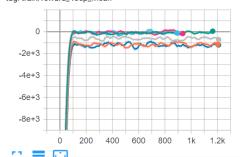
| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |

| Name | Smoothed | Value | Step | Time | Relative |
|--|----------|--------|--------|---------------------|-------------|
| SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32s |
| SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59s |
| SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23s |

State Weight 0.0 Add Time 3

```
state_weight 0.0 addtime 3 model_num 1160
0-hop lanes Fixed Time Passed Sum 23470.0 RL Passed Sum 23285.0 Imp -0.79
1-hop lanes Fixed Time Passed Sum 40341.0 RL Passed Sum 40110.0 Imp -0.57
0-hop lanes Fixed Time AverageSpeed mean 19.4 RL AverageSpeed mean 19.06 Imp -1.75
1-hop lanes Fixed Time AverageSpeed mean 27.76 RL AverageSpeed mean 27.71 Imp -0.18
0-hop lanes Fixed Time WaitingTime Sum 57474.3 RL WaitingTime Sum 57305.8 Imp 0.29
1-hop lanes Fixed Time WaitingTime Sum 66382.5 RL WaitingTime Sum 66186.1 Imp 0.3
0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.11 Imp -0.0
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.045 Imp -0.0
0-hop lanes Fixed Time SumTravelTime sum 1085114.0 RL SumTravelTime sum 1163920.0 Imp -7.26
1-hop lanes Fixed Time SumTravelTime sum 1328766.0 RL SumTravelTime sum 1417314.0 Imp -6.66
0-hop lanes Fixed Time WaitingQLength mean 1.207 RL WaitingQLength mean 1.196 Imp 0.91
1-hop lanes Fixed Time WaitingQLength mean 0.446 RL WaitingQLength mean 0.443 Imp 0.67
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |

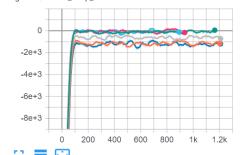


| 1 | Name | Smoothed | Value | Step | Time | Relative |
|---|--|----------|--------|--------|---------------------|------------|
| | SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| | SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| | SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| | SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| | SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| | SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |
| | | | | | | |

State Weight 0.0 Add Time 5

```
state_weight 0.0 addtime 5 model_num 1200
0-hop lanes Fixed Time Passed Sum 23442.0 RL Passed Sum 23305.0 Imp -0.58
1-hop lanes Fixed Time Passed Sum 40281.0 RL Passed Sum 40145.0 Imp -0.34
0-hop lanes Fixed Time AverageSpeed mean 19.33 RL AverageSpeed mean 19.03 Imp -1.55
1-hop lanes Fixed Time AverageSpeed mean 27.74 RL AverageSpeed mean 27.7 Imp -0.14
0-hop lanes Fixed Time WaitingTime Sum 56955.6 RL WaitingTime Sum 57135.6 Imp -0.32
1-hop lanes Fixed Time WaitingTime Sum 65884.0 RL WaitingTime Sum 66070.2 Imp -0.28
0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.108 Imp 1.82
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.044 Imp 2.22
0-hop lanes Fixed Time SumTravelTime sum 1086715.0 RL SumTravelTime sum 1111648.0 Imp -2.29
1-hop lanes Fixed Time SumTravelTime sum 1328535.0 RL SumTravelTime sum 1358979.0 Imp -2.29
0-hop lanes Fixed Time WaitingQLength mean 1.213 RL WaitingQLength mean 1.163 Imp 4.12
1-hop lanes Fixed Time WaitingQLength mean 0.447 RL WaitingQLength mean 0.431 Imp 3.58
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |

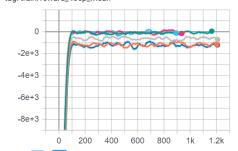


| | Name | Smoothed | Value | Step | Time | Relative |
|---|--|----------|--------|--------|---------------------|------------|
| | SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| | SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| | SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| | SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| 0 | SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| | SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |

State Weight 0.0 Add Time 7

```
state_weight 0.0 addtime 7 model_num 1200
0-hop lanes Fixed Time Passed Sum 23492.0 RL Passed Sum 23321.0 Imp -0.73
1-hop lanes Fixed Time Passed Sum 40382.0 RL Passed Sum 40168.0 Imp -0.53
0-hop lanes Fixed Time AverageSpeed mean 19.57 RL AverageSpeed mean 19.13 Imp -2.25
1-hop lanes Fixed Time AverageSpeed mean 27.96 RL AverageSpeed mean 27.73 Imp -0.82
0-hop lanes Fixed Time WaitingTime Sum 56066.5 RL WaitingTime Sum 57014.1 Imp -1.69
1-hop lanes Fixed Time WaitingTime Sum 64354.3 RL WaitingTime Sum 66060.0 Imp -2.65
0-hop lanes Fixed Time AverageDensity mean 0.109 RL AverageDensity mean 0.109 Imp -0.0
1-hop lanes Fixed Time AverageDensity mean 0.044 RL AverageDensity mean 0.045 Imp -2.27
0-hop lanes Fixed Time SumTravelTime sum 1083783.0 RL SumTravelTime sum 1149243.0 Imp -6.04
1-hop lanes Fixed Time SumTravelTime sum 1323546.0 RL SumTravelTime sum 1402532.0 Imp -5.97
0-hop lanes Fixed Time WaitingQLength mean 1.203 RL WaitingQLength mean 1.181 Imp 1.83
1-hop lanes Fixed Time WaitingQLength mean 0.443 RL WaitingQLength mean 0.439 Imp 0.9
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |

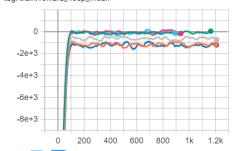


| Name | Smoothed | Value | Step | Time | Relative |
|--|----------|--------|--------|---------------------|------------|
| SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |

State Weight 0.5 Add Time 3

```
state_weight 0.5 addtime 3 model_num 930
0-hop lanes Fixed Time Passed Sum 23456.0 RL Passed Sum 23384.0 Imp -0.31
1-hop lanes Fixed Time Passed Sum 40342.0 RL Passed Sum 40272.0 Imp -0.17
0-hop lanes Fixed Time AverageSpeed mean 19.46 RL AverageSpeed mean 18.84 Imp -3.19
1-hop lanes Fixed Time AverageSpeed mean 27.85 RL AverageSpeed mean 27.62 Imp -0.83
0-hop lanes Fixed Time WaitingTime Sum 56837.5 RL WaitingTime Sum 58378.3 Imp -2.71
1-hop lanes Fixed Time WaitingTime Sum 65571.4 RL WaitingTime Sum 67380.4 Imp -2.76
0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.11 Imp -0.0
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.045 Imp -0.0
0-hop lanes Fixed Time SumTravelTime sum 1084396.0 RL SumTravelTime sum 1157365.0 Imp -6.73
1-hop lanes Fixed Time SumTravelTime sum 1325445.0 RL SumTravelTime sum 1407277.0 Imp -6.17
0-hop lanes Fixed Time WaitingQLength mean 1.213 RL WaitingQLength mean 1.196 Imp 1.4
1-hop lanes Fixed Time WaitingQLength mean 0.447 RL WaitingQLength mean 0.442 Imp 1.12
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |

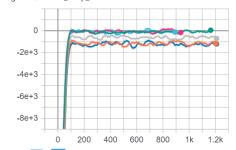


| ı | | Name | Smoothed | Value | Step | Time | Relative |
|---|---|--|----------|--------|--------|---------------------|------------|
| ı | | SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| ı | | SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| | | SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| | | SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| ı | 0 | SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| ı | | SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |
| | | | | | | | |

State Weight 0.5 Add Time 7

```
state_weight 0.5 addtime 7 model_num 1200
0-hop lanes Fixed Time Passed Sum 23501.0 RL Passed Sum 23351.0 Imp -0.64
1-hop lanes Fixed Time Passed Sum 40363.0 RL Passed Sum 40207.0 Imp -0.39
0-hop lanes Fixed Time AverageSpeed mean 19.72 RL AverageSpeed mean 19.22 Imp -2.54
1-hop lanes Fixed Time AverageSpeed mean 27.95 RL AverageSpeed mean 27.75 Imp -0.72
0-hop lanes Fixed Time WaitingTime Sum 56002.3 RL WaitingTime Sum 56692.7 Imp -1.23
1-hop lanes Fixed Time WaitingTime Sum 64981.8 RL WaitingTime Sum 65542.5 Imp -0.86
0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.108 Imp 1.82
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.044 Imp 2.22
0-hop lanes Fixed Time SumTravelTime sum 1091096.0 RL SumTravelTime sum 1109893.0 Imp -1.72
1-hop lanes Fixed Time SumTravelTime sum 1332110.0 RL SumTravelTime sum 1357099.0 Imp -1.88
0-hop lanes Fixed Time WaitingQLength mean 1.206 RL WaitingQLength mean 0.43 Imp 3.37
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |



| Name | Smoothed | Value | Step | Time | Relative |
|--|----------|--------|--------|---------------------|------------|
| SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |

State Weight 1.0 Add Time 3

```
state_weight 1.0 addtime 3 model_num 890

0-hop lanes Fixed Time Passed Sum 23518.0 RL Passed Sum 23260.0 Imp -1.1

1-hop lanes Fixed Time Passed Sum 40348.0 RL Passed Sum 40128.0 Imp -0.55

0-hop lanes Fixed Time AverageSpeed mean 19.63 RL AverageSpeed mean 19.25 Imp -1.94

1-hop lanes Fixed Time AverageSpeed mean 27.92 RL AverageSpeed mean 27.82 Imp -0.36

0-hop lanes Fixed Time WaitingTime Sum 56186.2 RL WaitingTime Sum 56370.6 Imp -0.33

1-hop lanes Fixed Time WaitingTime Sum 64940.4 RL WaitingTime Sum 64710.8 Imp 0.35

0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.106 Imp 3.64

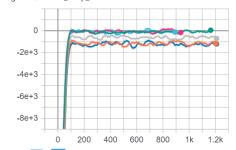
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.043 Imp 4.44

0-hop lanes Fixed Time SumTravelTime sum 1080619.0 RL SumTravelTime sum 1098473.0 Imp -1.65

1-hop lanes Fixed Time SumTravelTime sum 1321483.0 RL SumTravelTime sum 1342992.0 Imp -1.63

0-hop lanes Fixed Time WaitingQLength mean 0.443 RL WaitingQLength mean 0.423 Imp 4.51
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |



| | | Name | Smoothed | Value | Step | Time | Relative |
|---|---|--|----------|--------|--------|---------------------|------------|
| | | SALT_doan_discrete_v2/sw0.0_at3_07-08_18-46-37 | 45.61 | 79.55 | 1.164k | Fri Jul 9, 09:27:35 | 14h 40m 32 |
| | | SALT_doan_discrete_v2/sw0.0_at5_07-08_19-15-51 | -721 | -765.3 | 1.209k | Fri Jul 9, 10:23:57 | 15h 7m 40s |
| | | SALT_doan_discrete_v2/sw0.0_at7_07-08_19-15-59 | -1169 | -1228 | 1.203k | Fri Jul 9, 10:23:34 | 15h 7m 8s |
| | | SALT_doan_discrete_v2/sw0.5_at3_07-08_18-38-51 | -166.3 | -150.7 | 936 | Fri Jul 9, 06:35:14 | 11h 55m 59 |
| | 0 | SALT_doan_discrete_v2/sw0.5_at7_07-08_19-16-06 | -1206 | -1308 | 1.208k | Fri Jul 9, 10:23:51 | 15h 7m 17s |
| | | SALT_doan_discrete_v2/sw1.0_at3_07-08_17-04-23 | -119.4 | -131.3 | 892 | Fri Jul 9, 04:19:10 | 11h 14m 23 |
| 1 | | | | | | | |

실험 결과 요약

• State weight는 1이 가장 좋음

```
state_weight 1.0 addtime 3 model_num 890

0-hop lanes Fixed Time Passed Sum 23518.0 RL Passed Sum 23260.0 Imp -1.1

1-hop lanes Fixed Time Passed Sum 40348.0 RL Passed Sum 40128.0 Imp -0.55

0-hop lanes Fixed Time AverageSpeed mean 19.63 RL AverageSpeed mean 19.25 Imp -1.94

1-hop lanes Fixed Time AverageSpeed mean 27.92 RL AverageSpeed mean 27.82 Imp -0.36

0-hop lanes Fixed Time WaitingTime Sum 56186.2 RL WaitingTime Sum 56370.6 Imp -0.33

1-hop lanes Fixed Time WaitingTime Sum 64940.4 RL WaitingTime Sum 64710.8 Imp 0.35

0-hop lanes Fixed Time AverageDensity mean 0.11 RL AverageDensity mean 0.106 Imp 3.64

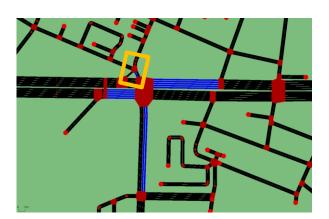
1-hop lanes Fixed Time AverageDensity mean 0.045 RL AverageDensity mean 0.043 Imp 4.44

0-hop lanes Fixed Time SumTravelTime sum 1080619.0 RL SumTravelTime sum 1098473.0 Imp -1.65

1-hop lanes Fixed Time WaitingQLength mean 1.201 RL WaitingQLength mean 1.145 Imp 4.66

1-hop lanes Fixed Time WaitingQLength mean 0.443 RL WaitingQLength mean 0.423 Imp 4.51
```

| State Weight | Add Time |
|--------------|----------|
| 0.0 | 3 |
| 0.0 | 5 |
| 0.0 | 7 |
| 0.5 | 3 |
| 0.5 | 7 |
| 1.0 | 3 |



getConnectedLink()가 불안정해서 그럴 가능성이 있음