# Eleftherios Triantafyllidis

■ <u>eleftherios.triantafyllidis@gmail.com</u>

Ohttps://github.com/etriantafyllidis ❖ (+44) 7535-059586 ❖ Edinburgh, United Kingdom

#### ACADEMIC EXPERIENCE

#### The University of Edinburgh

Sep. 2019 - Present

Ph.D., in Robotics and HCI/HRI Research

Edinburgh, United Kingdom

- Researching effective ways of maximising and transferring human dexterity and cognition, via multimodal VR/MR solutions and metrics, to intelligent agents, by leveraging hierarchical imitation learning. In particular:
  - o Solving complex long-horizon robotic tasks via hybrid hierarchical learning architectures, with a focus on emerging behaviour, reusable demonstrations and solving multi-skill tasks from single policies.
  - o Investigation of different multimodal interfaces and their influence towards human perception;
  - o Evaluation metrics and standardisation of tools for capturing human motor performance;
- Supervisory Team: Dr. Zhibin Li and Prof. Taku Komura
- EPSRC Funded full-time scholarship award for the duration of the studies

## The University of Edinburgh

Sep. 2018 - Sep. 2019

Edinburgh, United Kingdom

- M.Sc. by Research, in Robotics and HCI/HRI
- Awarded with distinction 1<sup>st</sup> class honours /GPA equivalent: 4.0 (180 ECTS)
- EPSRC Funded full-time scholarship award for the duration of the studies
- Thesis: The Contributions of Sensory Feedback in VR Teleoperation of Robotic Tasks of Varying Complexity

# University of Applied Sciences Kavala

Sep. 2011 - Sep. 2016

B.Sc., in Computer Science and Computer Engineering

Kavala, Greece

- Awarded with very good 7.37/10 (240 ECTS)
- ERASMUS internship in Audi AG, Ingolstadt, Germany
- Outstanding Project Award: Fully Autonomous Fire Detection Rover Vehicle
- Thesis: Fully Autonomous Navigation, Localization and Landing of a Quadcopter with a Monoscopic Camera

#### PROFESSIONAL EXPERIENCE

#### Telexistence Inc., Tokyo

Jul. 2022 – Oct. 2022

Software Engineer and Programmer (Internship)

Tokyo, Japan

- Solely responsible for the transition from a real-world company-built robot for drink replenishing purposes operating in the wider metropolitan Tokyo area, to a fully simulated environment (NVIDIA's ISAAC Sim)
- Minimisation of the Sim2Real gap in simulation via appropriate emulation and tuning of physical quantities to accurately match real-world pick and place tasks and increase learning-based skill transferability
- Successful presentation of the system at IROS 2022 in Kyoto, Japan with day-long operation at the conference

#### The University of Edinburgh

Sep. 2019 – Present

Teaching Assistant and Support

Edinburgh, United Kingdom

- Tutor and demonstrator for the course Robotics and Science Systems (R:SS)
- Marking of R:SS and Informatics-/Research Review and Research Proposal for M.Sc./M.Sc.R. dissertations
- Supervisor for writing a literature review and research proposal for M.Sc. and M.Sc.R. students

Hellenic Army Nov. 2016 – Jul. 2017

Military Service with the Rank of Private in the Infantry Division (9 Months Obligatory)

Multiple Locations, Greece

Responsible for military time and service management tools and classified digital document correspondence

Audi AG Nov. 2015 – May. 2016

Software Engineer and Programmer (Internship)

Ingolstadt, Germany

- Development of an innovative, state-of-the-art, virtual reality project in the Unity3D engine
- Integration of the latest mixed reality technologies into one system
- Design and programming with a strong emphasis on HCI, network communications and 3D modelling
- Demo presentation to internal and external industry partners Google, HTC (Vive) and Microsoft (HoloLens)
- Deployed a centralised monitoring environment to gather user performance metrics

### SELECTED ACADEMIC PUBLICATIONS (JOURNALS & PROCEEDINGS)

- E. Triantafyllidis et al., RObotic MAnipulation Network (ROMAN): Hybrid Hierarchical Learning for Solving Complex Sequential Tasks, 2023, in Nature Machine Intelligence (Accepted, to be featured)
- E. Triantafyllidis and Z. Li, The Challenges in Modeling Human Performance in 3D Space with Fitts' Law, in CHI Conference on Human Factors in Computing Systems (CHI '21). Association for Computing Machinery, May 8–13, 2021, Yokohama, Japan. ACM, New York, NY, USA. DOI: 10.1145/3411763.3443442
- E. Triantafyllidis and Z. Li, Considerations and Challenges of Measuring Operator Performance in Telepresence and Teleoperation Entailing Mixed Reality Technologies, in CHI Conference on Human Factors in Computing Systems Workshop CHI '21 (Evaluating User Experiences in Mixed Reality). Association for Computing Machinery, May 7, 2021, Yokohama, Japan. ACM, New York, NY, USA.
- E. Triantafyllidis, W. HU, C. McGreavy and Z. Li, Metrics for 3D Object Pointing and Manipulation in Virtual Reality: The Introduction and Validation of a Novel Approach in Measuring Human Performance, in IEEE Robotics & Automation Magazine, doi: 10.1109/MRA.2021.3090070.

  Paper Invitation: Invited for ICRA 2021 as a Conference Paper.
- E. Triantafyllidis, C. McGreavy, J. Gu and Z. Li, **Study of Multimodal Interfaces and the Improvements on Teleoperation**, *in IEEE Access*, vol. 8, pp. 78213-78227, 2020, DOI: 10.1109/ACCESS.2020.2990080.

#### RECENT ACHIEVEMENTS, AWARDS AND INVITATIONS

• Award: Best Student Case Study in the Centre for Doctoral Training in Robotics and Autonomous Systems, Edinburgh, 1<sup>st</sup> of October 2021, UK. Annual Review 2020/21, Pages: 62-63.

#### **LANGUAGES**

English: Proficient (C2 and IELTS: 7.5)
 German Proficient (Goethe C1: 87/100)

• **Greek:** Native Speaker

#### **SKILLS & INTERESTS**

- General Skills: Problem-solving; quantitative evaluation analysis; statistical evaluation methods; quality assurance; outreach and transferability of skills; ability to work in a team with leadership roles; effective use of language and concise transferability of ideas; effective use of PPT presentation slides in research meetings.
- **Programming:** C#, C++, Python, OCaml, Java, Visual C++/CLI (.NET), LaTeX. VHDL.
- Simulation and Physics Engines: Unity3D, Unreal Engine, MuJoCo, CryEngine.
- Familiarity with Libraries and SDKs: Oculus, LeapMotion, Tensorflow, Matplotlib, OpenCV, ML-Agents.
- Applications: IBM SPSS, Kdenlive, MATLAB, Autodesk, Blender, Photoshop, Visual Studio, Office.
- Interests: Running; Swimming; Reddit; Launching (mostly successfully) spacecraft in Kerbal Space Program.