Conference Paper Title*

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***Abstract*—**

I. Introduction

II. Methods

A. Data

B. Battery parameters

C. Baseline performance

1) Naive baseline:

2) Optimal baseline:

3) Optimal baseline with limited foresight:

D. Reinforcement learning model-based approach

$T(PRT_{t+1}|P_t, W_t, T_t) = E[PRT_{t+1}|P_t, W_t, T_t]$
$T(PRT_{t+1}|P_t, W_t, T_t) \sim N(E[PRT_{t+1}|P_t, W_t, T_t], \sigma^2)$

E. Reinforcement learning model-free approach

III. Results

IV. Discussion

V. Conclusion

VI. Tables and figures

TABLE I
Table Type Styles

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[a]Sample of a Table footnote.

Fig. 1. Example of a figure caption.

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References

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