Data Structures and Algorithms II

Assignment 4

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1 Task Description

Triangulation 3-coloring

Your are given a triangulation of a point set. Your task is to design an efficient algorithm that constructs a valid 3-coloring of the points of the triangulation or determines that such a 3-coloring does not exist. A 3-coloring of the points is valid if any two points that are connected with an edge have different colors. The n points of the triangulation are labeled with the integers $\{1, \ldots, n\}$. The triangulation is given by a list of edges with additional triangle points (see Figure 1 for an example):

- Every edge is given by the labels of its two end points (first the smaller point label, then the larger one).
- For every edge, the labels of the point(s) with which the edge forms a triangle (a bounded triangular face) in the triangulation is given (two labels for interior edges and one label for edges on the boundary of the convex hull).

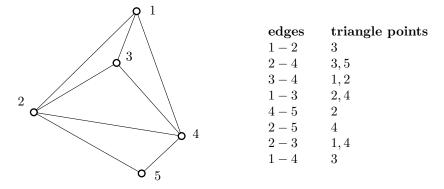


Figure 1: Example of a triangulation and a list of its edges with triangle points.

Explain and describe your algorithm in detail, analyze its runtime and memory requirements, and give reasons for the correctness of your solution.

2 Description of algorithm

Note: It is assumed from the example, that the edges are always given with the lower vertex number in the first place e.g. 1-5 instead of 5-1. If this is not a given, the edge representation could be changed to conform to the above constraint in linear time, thus not increasing the asymptotic runtime.

General: The algorithm takes a list of edges with additional triangle points EDGES (as described above) as input and outputs a 3-coloring of the graph COLORS if it is possible. If no valid 3-coloring of the given graph exists, the algorithm exits and indicates that no such coloring is possible (COLORS is not returned in this case).

The algorithm starts with the **Setup** step, then the Points on the first edge and it's triangle points are colored in **Start**, after which **Loop** takes care of the remaining Points. Afterwards the validity of the coloring is checked.

1. Setup:

First get number of Points. The Maximum is given, by the maximum (number) in triangle points. Use this number to create an array COLORS with this size for the colors of the vertices. Store edges (keys) and triangle points (values) in a hashmap EDGE_DIC for fast access. Setup counter counter which tracks how many vertices need to be colored in. Setup empty queue NEXTEDGES for neighboring edges.

2. Start:

An arbitrary start edge, for example the first in EDGES is chosen as $\operatorname{cur_edge}$. The two endpoints p_1 and p_2 of $\operatorname{cur_edge}$ are colored with c_1 and c_2 respectively. Then the triangle points are colored ¹ in. Finally the counter is decreased by the number of vertices which were colored in and $\operatorname{cur_edge}$ is deleted from EDGE_DIC.

3. **Loop:** The Loop is executed while counter is not 0.

All neighbors of cur_edge which were not visited before (meaning they were never cur_edge) are added to the queue NEXTEDGES. Neighbors to the cur_edge are edges which form a triangle with the cur_edge if the two endpoints of the so given path are connected. ² Now cur_edge is set to the last edge in NEXTEDGES (according to the FIFO-principle). The colors c_1 and c_2 of p_1 and p_2 of cur_edge are checked. If they are the same, algorithm terminates because no valid 3-coloring of the given graph exists. Otherwise the algorithm tries to color the triangle points of cur_edge (at least one [outer edge] and at most 2 triangle points for inner edges). If the triangle point is already colored with c_3 , it is check if the color is neither c_1 nor c_2 , if the color would match either c_1 or c_2 the algorithm terminates as in the aforementioned case c_1 equals c_2 . If the the triangle point is properly colored nothing happens and if applicable the second triangle point is checked. In the case that the triangle point isn't colored already, it is colored with c_3 such that c_3 is different than c_2 and c_1 . Finally the counter is decreased by the number of vertices which were colored in and cur_edge is deleted from EDGE_DIC. \rightarrow Loop

4. Check validity of coloring of remaining edges:

For the graph in Figure 1 without Point 5 (without edges 2-5 and 4-5) the algorithm could produce a impossible coloring and end. ³ To avoid these edge cases one could check all edges and their triangle points for matching colors as described in 'Loop' above. However color-checking only the remaining edge-triangle-point-pairs in EDGE_DIC is sufficient, because these are the edges which were never

¹Depending on the edge type either one (outer edge e.g. 1-2 in Figure 1) or a maximum of two triangle points (inner edge e.g. 1-3 in Figure 1) are colored in.

²This definition of neighbors guarantees that the so formed triangle already has two colored points, thus making the coloring of the third trivial.

Example: The edge 1-2 in Figure 1 has 2 neighbors (1-3 and 2-3) according to the above definition, whereas an inner edge has 4: e.g. 3-4 has 1-3, 1-4, 2-3 and 2-4 as neighbors

³The counter would reach 0 if the start edge would be 1-3 (The loop would be skipped and thus no checks would be done)

cur_edge. Asymptotically this reduction in remaining edge-triangle-point-pair color checks doesn't matter as we'll see below.

3 Space complexity / memory requirements

Note: As derived from Euler's formula in the lecture for a connected, simple, planar graph the following holds true for $v \ge 3$:

$$e \le 3v - 6 \tag{1}$$

Where e is the number of edges, and v the number of vertices in the graph. For this reason asymptotically the number of edges as well as the number of vertices are the same $(\mathcal{O}(e) = \mathcal{O}(v))$. For this reason the analysis in the current section, as well as section 4 will use the size of the input, more precisely the number of edges n in EDGES.

The memory requirements of the algorithm is given as follows:

- EDGES [input] stores all n edges of the graph which results in $\mathcal{O}(n)$ space complexity.
- COLORS [output] stores asymptotically (as shown above) $\mathcal{O}(n)$ colors of the vertices which results in $\mathcal{O}(n)$ space complexity
- EDGE_DIC stores all the edges from the [input] EDGES as key-value pair in a hashmap which requires $\mathcal{O}(n)$ space.
- NEXTEDGES stores at most n-1 edges ⁴ which results in $\mathcal{O}(n)$ space complexity.
- Local variables: counter and cur_edge have $\mathcal{O}(1)$ space complexity.

All together the data structures require $\mathcal{O}(n)$ space.

4 Runtime complexity

The runtime complexity analysis is based on the number of edges n in the input EDGES. As shown above in Equation 1 n, being the number of edges, is asymptotically the same as v the number of vertices.

The Analysis is split into the same four parts as in section 2:

1. Setup:

5 Correctness of the algorithm

TODO

 $^{^{4}}n-1$ is for example true in the trivial case with n=3