

Proper Orthogonal Decomposition (POD)

This Lab focuses on performing POD on the parametric system we saw together in the previous Lab.

Once again, we need *a lot* of FOM simulations this time. Let us import `gedim`!

```
In [1]: import sys  
sys.path.append('/content/CppToPython')
```

```
In [2]: import numpy as np  
import GeDiM4Py as gedim
```

```
In [3]: lib = gedim.ImportLibrary("/content/CppToPython/release/GeDiM4Py.so")  
  
config = { 'GeometricTolerance': 1.0e-8 }  
gedim.Initialize(config, lib)
```

The parametric version of the heat conductivity equation

The same problem of the other lab, we have two different parameter μ_1 , in the inner disk, and μ_2 outside. We have omogenous Dirichlet e Neumann on the border, but also non homogeneous one.

Solve the following equation on square $\Omega = (-1, +1) \times (-1, +1)$

$$\begin{cases} \nabla \cdot (k_\mu \nabla u) = 0 & \text{in } \Omega \\ k_\mu \nabla u \cdot n_1 = \mu_2 & \text{in } \Gamma_{base} \\ u = 0 & \text{in } \Gamma_{top} \\ k_\mu \nabla u \cdot n_2 = 0 & \text{otherwise} \end{cases}$$

where $k_\mu = \mu_1$ if $x^2 + y^2 \leq R^2$ and $k = 1$ otherwise. The parametric space is $\mathcal{P} = [0.1, 10] \times [-1, 1]$.

The parameter $\mu \in \mathcal{P}$ is physical and changes the features of the flow:

1. μ_1 the conductivity in Ω_1 ;
2. μ_2 describes the heat flux in the bottom part of the boundary.

First thing: we define two subdomains Ω_1 and Ω_2 , such that

1. Ω_1 is a disk in the origin with radius $r_0 = 0.5$, and
2. $\Omega_2 = \Omega / \overline{\Omega_1}$.
3. Γ_{base} to define where we will change the heat flux.

```
In [4]: def Heat_R():  
    return 0.5  
  
def Omega1(numPoints, points): # Inside  
    matPoints = gedim.make_nd_matrix(points, (3, numPoints), np.double)  
    values = np.ones(numPoints)  
    for p in range(0, numPoints):  
        if (matPoints[0,p] * matPoints[0,p] + matPoints[1,p] * matPoints[1,p]) > (Heat_R() * Heat_R() + 1.0e-16):  
            values[p] = 0.  
    return values.ctypes.data  
  
def Omega2(numPoints, points): # Outised  
    matPoints = gedim.make_nd_matrix(points, (3, numPoints), np.double)  
    values = np.ones(numPoints)  
    for p in range(0, numPoints):  
        if (matPoints[0,p] * matPoints[0,p] + matPoints[1,p] * matPoints[1,p]) <= (Heat_R() * Heat_R() + 1.0e-16):  
            values[p] = 0.  
    return values.ctypes.data  
  
def Gamma_base(numPoints, points):  
    values = np.ones(numPoints)  
    return values.ctypes.data  
  
##### needed for the inner product #####  
  
def Domain(numPoints, points): # We need something that is defined all over the domain  
    matPoints = gedim.make_nd_matrix(points, (3, numPoints), np.double)  
    values = np.ones(numPoints) # All the value setted as one  
    return values.ctypes.data
```

GOAL OF A MODEL ORDER REDUCTION: it's a double discretization strategy, that works for a fixed mesh, fixed degree of freedom.

Goal: build the ROM space where many simulations for several parameters can be performed in a smaller amount of time.

Strategy: $w(\mu) \xrightarrow{\text{FOM(dim}=\mathcal{N}\text{)}} w^{\mathcal{N}}(\mu) \xrightarrow[\|w(\mu)-w^{\mathcal{N}}(\mu)\|\rightarrow 0]{\text{ROM (dim }N\text{)}} w_N(\mu)$. Where \mathcal{N} is the $N\delta$, that is the bigger space, on the contrary N is the smaller space, so we have $N \ll \mathcal{N}$.

We want to compute

$\|w(\mu) - w_N(\mu)\| = \|w(\mu) - w^{\mathcal{N}}(\mu) + w^{\mathcal{N}}(\mu) - w_N(\mu)\| \leq \|w(\mu) - w^{\mathcal{N}}(\mu)\| + \|w^{\mathcal{N}}(\mu) - w_N(\mu)\| = 0 + \|w^{\mathcal{N}}(\mu) - w_N(\mu)\|$, using triangular inequality and w represents the solution.

A *snapshot* is a solution w for a fixed set of parameters μ .

The goal can be reached by means of several techniques.

Today we will focus on **POD**.

POD is an *explore* and *compress* algorithm based on two different stages:

1. we *explore* the information related to the solution varying with respect to μ (*snapshots*) in a finite dimensional set $\mathcal{P}_{train} \subset \mathcal{P}$.
2. We compress the redundant information and retain only the most significant "linear directions", building a linear subspace $\mathbb{V}_N \subset \mathbb{V}^{\mathcal{N}}$ of dimension $N \ll \mathcal{N}$.

Building the space and store the μ -independent quantities is the so called *offline phase* (possibly costly).

Once the space is built, a fast *online phase* occurs, where I can compute **many solutions in real-time**.

How is it possible? **Separations of variables**: by means of **the affine decomposition**! Indeed we know that our system can be written as

$$\sum_{i=1}^{q_a} \theta_i^a(\mu) a_i(u, v) = \sum_{i=0}^{q_f} \theta_i^f(\mu) f_i(v),$$

i.e., algebraic-wise

$$\sum_{i=1}^{q_a} \theta_i^a(\mu) \mathbf{A}_i = \sum_{i=0}^{q_f} \theta_i^f(\mu) \mathbf{f}_i,$$

where \mathbf{A}_i and \mathbf{f}_i are the assembled matrices and vectors of the system.

Now, let us imagine to have already built the reduced space and have collected the *basis functions* (always related to the snapshot, is a vector in the \mathcal{N} space) $\xi_i \in \mathbb{R}^{\mathcal{N}}$ for $i \in \{1, \dots, N\}$ ($\mathbb{V}_N = \text{span}\{\xi_i\}_{i=1}^N$) in a basis matrix

$$\mathbb{B} = [\xi_1 | \dots | \xi_N] \in \mathbb{R}^{\mathcal{N} \times N}.$$

in which ξ_j are concatenated orizzontally and $\xi_j \in \mathbb{R}^{\mathcal{N}} \forall j \in N$.

It is clear that we can recast the problem in the low-dimensional framework we built, we can pre-and-post multiply the FOM matrices for the basis matrix we have:

$$\mathbf{A}_i^N = \mathbb{B}^T \mathbf{A}_i \mathbb{B} \quad \text{and} \quad \mathbb{B}^T \mathbf{f}_i.$$

So we have just projected in a smallest space building this new matrix \mathbf{A}_i^N that is similar to the bigger one \mathbf{A}_i (think of Hilbert space).

Here is where the offline phase ends!!

Question time!: where did it start? It started when we look all the snapshot together, after we project in a smaller basis, and here it finishes.

Let us code the OFFLINE PHASE

```
In [ ]: ### order of the discretization ###
order = 1 # Linear finite element approximation

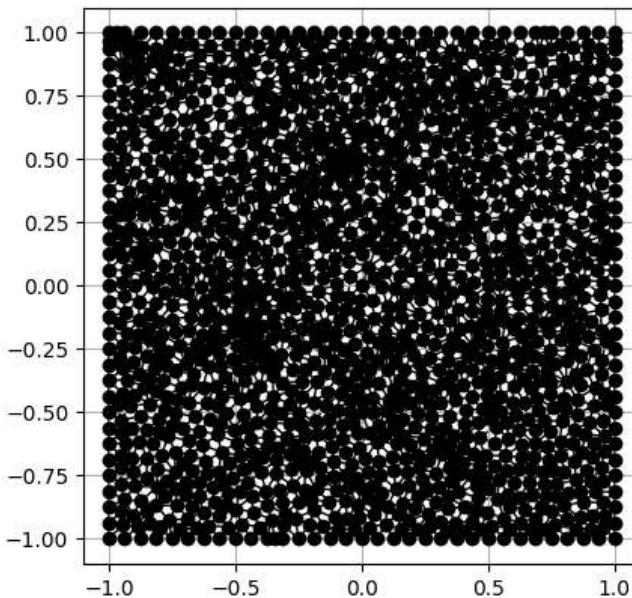
# Importing the mesh in the next cell
```

```
In [9]: %%writefile ImportMesh.csv
InputFolderPath
/content/CppToPython/Meshes/Mesh3
```

Overwriting ImportMesh.csv

```
In [10]: [meshInfo, mesh] = gedim.ImportDomainMesh2D(lib)
```

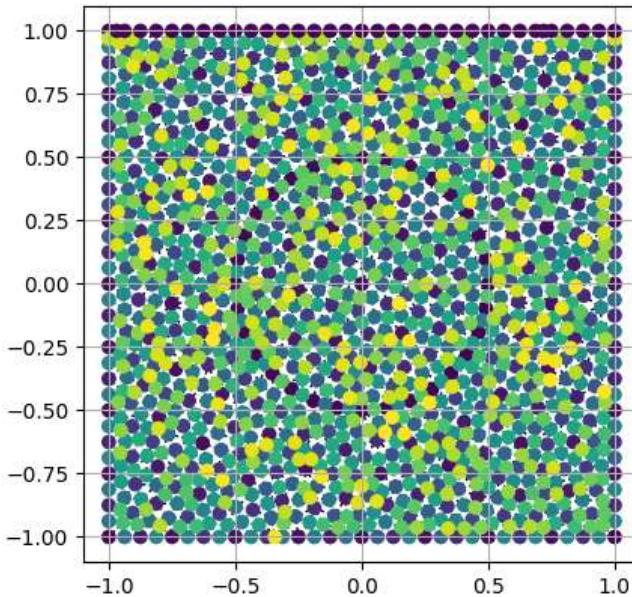
```
In [11]: gedim.PlotMesh(mesh)
```



FEM space (the High Fidelity approximation)

```
In [12]: discreteSpace = { 'Order': order, 'Type': 1, 'BoundaryConditionsType': [1, 3, 3, 2] }
[problemData, dofs, strongs] = gedim.Discretize(discreteSpace, lib)
```

```
In [13]: gedim.PlotDofs(mesh, dofs, strongs)
```



Assemble linear system exploiting affinity

We define everything that is parameter independent, i.e. $a_1(u, v)$, $a_2(u, v)$ and $f(v)$. We need also the matrix related to the scalar product of the problem at hand.

How to assemble the linear system?

$$\int_{\Omega_1} \nabla u \nabla v dx + \mu_1 \int_{\Omega_2} \nabla u \nabla v dx = \int_{\Gamma_{base}} \mu_2 v ds \forall v \in V$$

Recap Hilbert spaces.

- $L^2(\Omega) = \{ust|u \in L^2(\Omega) = \|u\|^2 = \langle u, u \rangle_{L^2(\Omega)} = \int_{\Omega} u^2 dx < +\infty\}$: means that contains all the functions that are integrable
- $H^1(\Omega) = \{u \in L^2 st \|\nabla u\| < +\infty\}$: means that contains functions that are integrable and also their gradients are gradient

We want to work now on H^1 space, using the inner product of H^1 .

```
In [ ]: # We assemble here the Linear system
[stiffness1, stiffnessStrong1] = gedim.AssembleStiffnessMatrix(Omega2, problemData, lib)
[stiffness2, stiffnessStrong2] = gedim.AssembleStiffnessMatrix(Omega1, problemData, lib)

weakTerm_down1 = gedim.AssembleWeakTerm(Gamma_base, 1, problemData, lib)

#### inner product
# ||u||^2 + ||grad(u)||^2
```

```
# [reaction, reactionStrong] = gedim.AssembleReactionMatrix(Domain, problemData, lib)
# Reaction = is the part related to  $L^2$ , so just the integration of  $u$ 
# Indeed, when we compute the inner product we have to focus on  $\|u\|^2$  (Reaction) and on  $\|\operatorname{grad}(u)\|^2$  (inner_product)

inner_product = stiffness1 + stiffness2 ##### semi-norm (equivalent)
```

We here define the finite parametric space \mathcal{P}_{train} with random uniform distributed realization of μ . The cardinality of \mathcal{P}_{train} is set to 100 and we call it M .

In []:

```
### define the training set

snapshot_num = 100 # (M = number of snapshot) we are search 100 solution
mu1_range = [0.1, 10.]
mu2_range = [-1., 1.]
P = np.array([mu1_range, mu2_range])

# Uniform distribution, I have the same probability to peak all the numbers
training_set = np.random.uniform(low=P[:, 0], high=P[:, 1], size=(snapshot_num, P.shape[0]))
```

We now need to define the *snapshot matrix*. The snapshot matrix is $\mathbb{U} \in \mathbb{R}^{M \times N}$

In []:

```
#### snapshot matrix creation
thetaA1 = 1.
snapshot_matrix = []

tol = 1. - 1e-7 # Pay attention: the tol is defined as 1 - 1e-7
N_max = 10

for mu in training_set: # For all the parameters (my 100)
    # I compute the integral that I write before
    thetaA2 = mu[0]
    thetaf1 = mu[1]

    stiffness = thetaA1*stiffness1 + thetaA2*stiffness2
    weakTerm_down = thetaf1*weakTerm_down1

    snapshot = gedim.LUSolver(stiffness, weakTerm_down, lib)

    snapshot_matrix.append(np.copy(snapshot))

snapshot_matrix = np.array(snapshot_matrix)

print(snapshot_matrix.shape) # All the snapshot x dimension of the space
```

(100, 1453)

It's time for the POD

We works with *correlation matrix*, that is defined as $\text{snapshot}_m \times \text{snapshot}_n$. **Positive things:** all the eigen value are positive and also ordinarie.

To build the N -dimesional framework we need, we define the correlation snapshot matrix $\mathbf{C} \in \mathbb{R}^{M \times M}$ and we solve the eigenvalue problem $\mathbf{C}\omega_n = \lambda_n\omega_n$ for $1 \leq n \leq M$, with $\|\omega_n\|_V = 1$. Due to the definition of correlation matrix, we can order the all-positive eigenvalues as $\lambda_1 > \dots > \lambda_M > 0$ and retain the first N eigenpairs (λ_n, ω_n) for $1 \leq n \leq N$.

Question Time: how can I choose M and N ? So how can i chose the number of snapshot? The more the best so that I can have more information, but i have to trade-off to the computational effort -> depends on the problems. And how to chose the number of basis? We have to look at the eigenvalues.

Looking at the eigenvalues! Indeed, defining as $P_N : \mathbb{V} \rightarrow \mathbb{V}_N$ the projector from \mathbb{V} onto \mathbb{V}_N , the following relation holds:

$$\sqrt{\frac{1}{M} \sum_{i=1}^M \|u^N(\mu_i) - P_N(u^N(\mu_i))\|_2^2} = \sqrt{\sum_{i=N+1}^M \lambda_m}. \quad (1)$$

Namely, a fast decay of the eigenvalue magnitude guarantees a good representation of the high-fidelity solution with a few basis functions. Where P_N is the projection.

So this theorem tells us that the error that we compute is very small if we do not take in consideration the eigenvalues that are really small.

Here, we can work with SVD or POD, it's better POD for the structure of the covariance matrix.

In []:

```
### covariance matrix
# What is the inner_product in between?
# 1.  $(u, v)_L^2 = u'v$  in  $L^2$  is a scalar number
# 2.  $(u, v)_A = u'Av$  is the inner product of a matrix A
# 3.  $(u, v)_H^1 = u'Xv$  where X is the inner product matrix
# --> I'm looking the solutions in this product, for that reason I need X = inner_product = stiffness1 + stiffness2

C = snapshot_matrix @ inner_product @ np.transpose(snapshot_matrix)

##### shape?? -> number_of_snapshot x number_of_snapshot #####
```

```

#### ALTERNATIVE: VM, L, VMT = np.linalg.svd((C))

L_e, VM_e = np.linalg.eig(C)
eigenvalues = []
eigenvectors = []

#### check

for i in range(len(L_e)):
    eig_real = L_e[i].real
    eig_complex = L_e[i].imag
    assert np.isclose(eig_complex, 0.) # We need a symmetric positive definite matrix: all eigenvalues real and positive
    eigenvalues.append(eig_real)
    eigenvectors.append(VM_e[i].real)

total_energy = sum(eigenvalues) # Sum of all the eigenvalues
retained_energy_vector = np.cumsum(eigenvalues) # Cumulative sum (summing until n)
relative_retained_energy = retained_energy_vector/total_energy # Percentage

# The IDEA is: we have a tol = 1 - 1e-7, the first time that relative_retained_energy
# (that is the sum of the eigenvalue) is
# bigger than the tol, I can stop the computation and study the problem in
# that number of dimension
# Hence, all the other eigenvalue (and so direction) are NOT relevant to
# compute the solution

# We want the first term for that the relative_retained_energy is less then 1 - 1e-7
if all(flag==False for flag in relative_retained_energy>= tol):
    N = N_max
else:
    N = np.argmax(relative_retained_energy >= tol) + 1 # Python works from 0, but the basis goes from 1

# I need 3 basis (see the result) to show everything, this means that with 3
# eigenvalues we reach the condition, and all the other are very very small (irrelevant)
print("The reduced dimension is", N)

```

The reduced dimension is 3

Comment the result of previous cell.

$$\text{relative_retained_energy} = \frac{\sum_i^N (\lambda_i)}{\sum_j^M (\lambda_j)}$$

where N is not fixed, but $N \in \{1, \dots, M\}$. The first time that we achieve $\text{relative_retained_energy} \geq \text{tol}$ we understand what is the number of the dimension in which we can reduce the space.

We still need to create the basis matrix \mathbb{B} . There are many ways to build the bases. We propose the following one to guarantee more stability:

$$\chi_n = \sum_{m=1}^M (\omega_m)_n u^N(\mu_m), \quad 1 \leq n \leq N,$$

and $\xi_n = \frac{\chi_n}{\|\chi_n\|_{\mathbb{V}}}$.

$P_N : \mathbb{V} \rightarrow \mathbb{V}_N$ is defined as

$$P_N(u^N(\mu)) = \sum_{i=1}^N (u^N(\mu), \xi_n) \xi_n,$$

or algebraically $\mathbb{P}_N = \mathbb{B}\mathbb{B}^T$.

```

In [ ]: # Create the basis function matrix
basis_functions = []
for n in range(N):
    eigenvector = eigenvectors[n]

    # basis = (1/np.sqrt(snapshot_num))*np.transpose(snapshot_matrix)@eigenvector
    # (This is the one of the book!!)

    basis = np.transpose(snapshot_matrix)@eigenvector
    norm = np.sqrt(np.transpose(basis) @ inner_product @ basis) # ||u||_H^1 = u'Xu

    basis /= norm # Normalizing
    basis_functions.append(np.copy(basis)) # Have all together all the basis

basis_functions = np.transpose(np.array(basis_functions))

```

The offline stage ends once the **reduced operators** are built, i.e. A_1^N, A_2^N and f_1^N thanks to the basis matrix projections.

```
In [ ]: ##### ASSEMBLE THE LINEAR SYSTEM ##### STILL OFFLINE
# Reduce operator
reduced_stiff1 = np.transpose(basis_functions) @ stiffness1 @ basis_functions
reduced_stiff2 = np.transpose(basis_functions) @ stiffness2 @ basis_functions

reduced_f = np.transpose(basis_functions) @ weakTerm_down1 # The reduced f

### shape? #####
```

Online Phase: a new parameter!

In the *online phase* we can use all the pre-assembled quantities to generate a new solution for a new parameter.

```
In [22]: # Define theta
thetaA2 = 2.
thetaf1 = 0.8
```

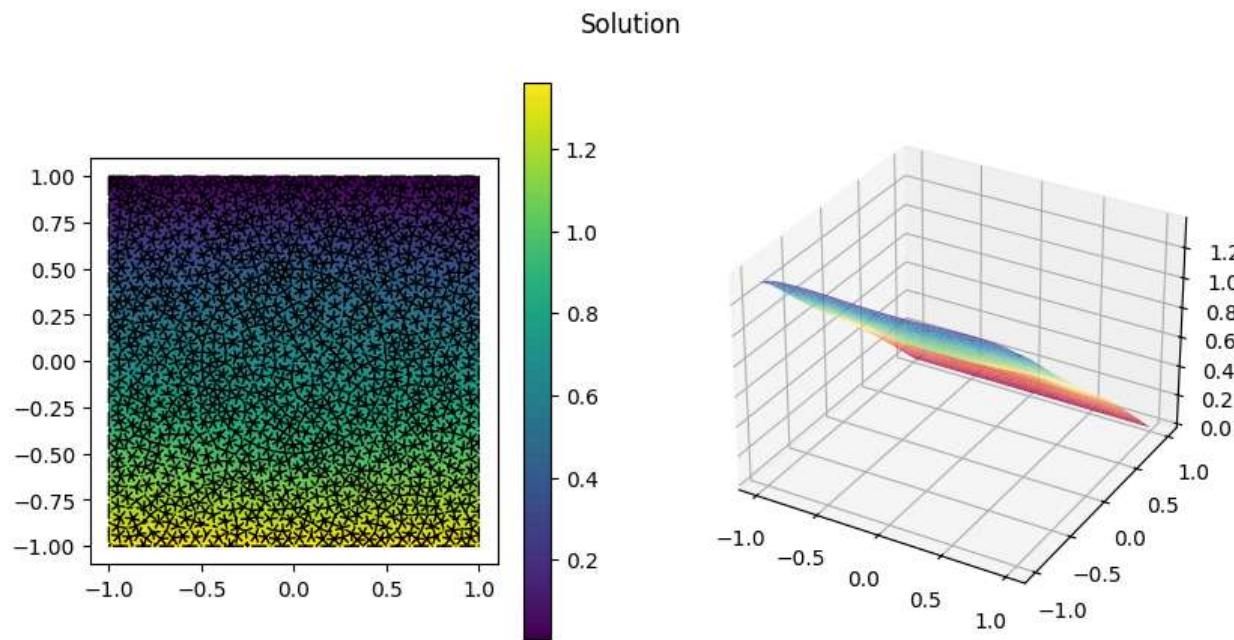
```
In [23]: # Work in the reduce space, everithing depends on the stored matrix that we build 3x3
reduced_rhs = thetaA1*reduced_stiff1 + thetaA2*reduced_stiff2
reduced_lhs = thetaf1*reduced_f
```

```
In [25]: ##### solve #####
reduced_solution = np.linalg.solve(reduced_rhs, reduced_lhs)
print(reduced_solution) # Vector of a 3 component
```

```
[ 0.34411647  0.86284147 -0.20314192]
```

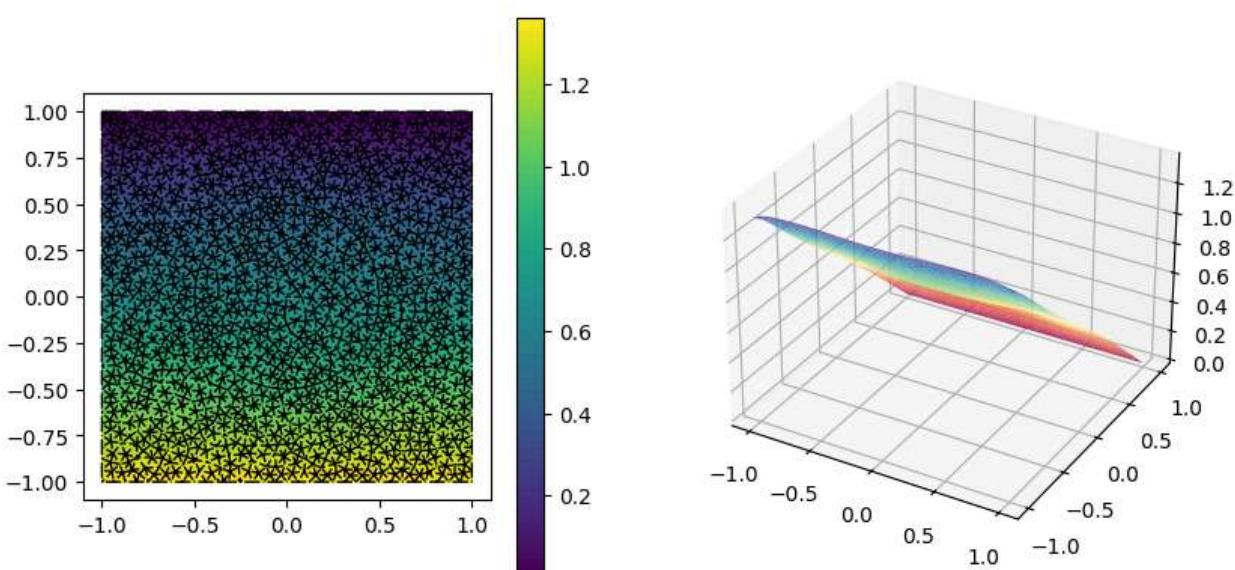
```
In [ ]: ##### plot #####
# I need to project reduced_solution back to the finite element space (calligraphic N)
proj_reduced_solution = basis_functions @ reduced_solution

# plot the reduce solution projected
gedim.PlotSolution(mesh, dofs, strongs, proj_reduced_solution, np.zeros(problemData['NumberStrongs']))
stiffness = thetaA1*stiffness1 + thetaA2*stiffness2
weakTerm_down = thetaf1*weakTerm_down1
```



```
In [29]: # Full solution
full_solution = gedim.LUSolver(stiffness, weakTerm_down, lib)
gedim.PlotSolution(mesh, dofs, strongs, full_solution, np.zeros(problemData['NumberStrongs']))
```

Solution



We can now compute an error analysis over the parametric space, together with a *speed-up* analysis.

The speed-up is an index that evaluated how many ROM solution I can obtain in the time of a FOM (Full Order Model) simulation.

```
In [ ]: #### compute error
# Take the ROM and FOM time and computer FOM/ROM time to undersand how faster ROM is
# We want to build a model that is
# 1. Accurate
# 2. Rapid

import time

abs_err = []
rel_err = []
testing_set = np.random.uniform(low=P[:, 0], high=P[:, 1], size=(100, P.shape[0]))
speed_up = []

print("Computing error and speedup analysis")

for mu in testing_set:
    # Compute the thetas
    thetaA2 = mu[0]
    thetaf1 = mu[1]

    ##### full #####
    stiffness = thetaA1*stiffness1 + thetaA2*stiffness2 # Separation of variables
    weakTerm_down = thetaf1*weakTerm_down1

    start_fom = time.time()
    full_solution = gdim.LUSolver(stiffness, weakTerm_down, lib)
    time_fom = time.time() - start_fom

    ##### reduced #####
    # Reduced assemble in the offline fase (already stored in my memory)
    reduced_rhs = thetaA1*reduced_stiff1 + thetaA2*reduced_stiff2
    reduced_lhs = thetaf1*reduced_f

    start_rom = time.time()
    reduced_solution = np.linalg.solve(reduced_rhs, reduced_lhs)
    time_rom = time.time() - start_rom

    speed_up.append(time_fom/time_rom) # FOM/ROM!

    proj_reduced_solution = basis_functions@reduced_solution

    ### computing error
    # ||u_delta - Bu_n||_H^1 = (u_delta-Bu_N)'X(u_delta-Bu_N)
    # Error of the solution that I computed in the reduced and full form
    # (how much they are distance)
    error_function = full_solution - proj_reduced_solution
    error_norm_squared_component = np.transpose(error_function) @ inner_product @ error_function
    absolute_error = np.sqrt(abs(error_norm_squared_component))
    abs_err.append(absolute_error)

    full_solution_norm_squared_component = np.transpose(full_solution) @ inner_product @ full_solution
    relative_error = absolute_error/np.sqrt(abs(full_solution_norm_squared_component))
    rel_err.append(relative_error)
```

Computing error and speedup analysis

```
In [33]: print("avarege relative error = ", np.mean(rel_err) )
print("avarege absolute error = ", np.mean(abs_err) )
print("avarege speed_up = ", np.mean(speed_up) )
```

```
avarege relative error =  0.00011780990130384037
avarege absolute error =  9.979139219046532e-05
avarege speed_up =  247.02001093009295
```

Exercise: solve the same problem but with $u = 3$ on Γ_{top} .