

Assignment 3

Deadline: 23 April 2021, 12 noon

Total marks: 20

1 Uniformly distributed points on the disk [10 marks]

The goal of this exercise is to use inverse transform and rejection sampling for generating uniformly distributed points on the unit disk

$$D = \{x \in \mathbb{R}^2 \mid \|x\|_2 \leq 1\}.$$

1. Complete `randdisk_rejection()` such that it samples $X \sim \text{Uniform } D$ using rejection sampling with proposal distribution $\text{Uniform}[-1, 1]^2$.

Hint. You can check your answer using `plot_samples()`.

2. How many samples of $\text{Uniform}[-1, 1]^2$ does `randdisk_rejection()` require on average to produce a single sample of $\text{Uniform } D$?
3. Show that if $R \sim \text{PDF}(r \mapsto 2r \text{ on } [0, 1])$ and $\Phi \sim \text{Uniform}[0, 2\pi]$ independently, then

$$X(R, \Phi) = \begin{pmatrix} R \cos(\Phi) \\ R \sin(\Phi) \end{pmatrix} \sim \text{Uniform } D.$$

Hint. You may want to use that

$$\int_D f(x) dx = \int_0^1 \int_0^{2\pi} f(X(r, \phi)) r d\phi dr.$$

4. Complete `randdisk_transform()` such that it samples $X \sim \text{Uniform } D$ using the result from [Task 3](#).

Hint. You can check your answer using `plot_samples()`.

5. [unmarked] Which of `randdisk_rejection()` and `randdisk_transform()` do you think is faster? Check your answer using `performance_shootout()`.

2 Importance sampling for highly concentrated integrals [10 marks]

The goal of this task is to use Monte Carlo sampling to estimate the integral

$$\mathbb{E}[f(X)] = \int_0^1 f(x) dx \quad \text{where} \quad X \sim \text{Uniform}[0, 1].$$

1. Complete `uniform_sampling(f, N)` such that it estimates both

$$\mathbb{E}[f(X)] \quad \text{and} \quad \text{Var}[f(X)] = \mathbb{E}[(f(X) - \mathbb{E}[f(X)])^2]$$

using N Monte Carlo samples.

2. [Unmarked] The provided function `sin_integral()` uses `uniform_sampling()` to estimate

$$\int_0^1 \frac{\pi}{2} \sin(\pi x) dx = 1, \quad (1)$$

and `plot_histogram()` to visualise the accuracy of the estimates. Use this function to check your answer to [Task 1](#). If your answers are correct, you will observe that $\tilde{\mathbb{E}}_{100}[f(X)]$ lies within a distance 0.1 of the exact expectation with high probability.

3. [Unmarked] The provided function `concentrated_integral()` uses `uniform_sampling()` to estimate

$$\int_0^1 \frac{1}{0.0906401} \exp\left(-(20(x-0.5))^4\right) dx \approx 1. \quad (2)$$

Run this function and observe how the error in $\tilde{\mathbb{E}}_{100}[f(X)]$ increases to roughly 0.5 when applied to [\(2\)](#) instead of [\(1\)](#).

The problem in `concentrated_integral()` is that the integrand in [\(2\)](#) is highly concentrated (see `plot_integrand()`); hence it is far from constant and hence it has a high variance. We can improve the situation by replacing direct sampling with importance sampling with a sampling distribution PDF(q) such that new random variable

$$f(Y) \frac{p(Y)}{q(Y)}, \quad Y \sim \text{PDF}(q),$$

is as close to constant as possible. Put differently, this means that we want to estimate [\(2\)](#) through importance sampling with a sampling distribution which is as close to $f(x)p(x)$ as possible but which is also easily samplable. Looking at `plot_integrand()` once more, we conclude that choosing $q(x)$ to be an appropriately shifted and scaled Gaussian should achieve this goal.

4. Complete `importance_sampling(f,N,m,s)` such that it estimates both

$$\mathbb{E}\left[f(Y) \frac{p(Y)}{q(Y)}\right] \quad \text{and} \quad \text{Var}\left[f(Y) \frac{p(Y)}{q(Y)}\right]$$

using N Monte Carlo samples, where $Y \sim \text{Normal}(m, s^2)$ and

$$p(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1, \\ 0 & \text{otherwise,} \end{cases} \quad q(x) = \frac{1}{\sqrt{2\pi}s} \exp\left(-\frac{(x-m)^2}{2s^2}\right)$$

denote the PDFs of `Uniform[0, 1]` and `Normal(m, s2)`, respectively.

Hints. You can sample $Y \sim \text{Normal}(m, s^2)$ using `y = m + s*randn()`. The normal PDF $q(x)$ is implemented in `normal_pdf(m,s,x)`.

5. (Unmarked) Rerun `concentrated_integral()`, but this time change `importance = false` to `importance = true`. Observe how importance sampling achieves a much better accuracy than uniform sampling.